Лабораторная работа №7

Автоассоциативные сети с узким горлом

Вариант 23

Целью работы является исследование свойств автоассоциативных сетей с узким горлом, алгоритмов обучения, а также применение сетей для выполнения линейного и нелинейного анализа главных компонент набора данных.

```
In [1]:
        import numpy as np
        import pickle
        from torch.autograd import Variable
        from torchvision import datasets
        import torch.nn as nn
        import torch.nn.functional as F
        import torch.optim as optim
        import torch.utils.data as data_utils
        import torch
        import matplotlib.pyplot as plt
        from IPython.display import clear_output
        import os
        import pandas as pd
        import skimage.io
        import tqdm
        from time import time
        from sklearn.model selection import train test split
        from skimage.transform import resize
        %matplotlib inline
```

Скачаю датасет.

```
In [2]: device = torch.device('cuda' if torch.cuda.is_available() else 'cpu')
    device
Out[2]: device(type='cuda')
```

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```
--2022-12-21 15:21:29-- https://www.cs.toronto.edu/~kriz/cifar-10-python.ta
        r.gz (https://www.cs.toronto.edu/~kriz/cifar-10-python.tar.gz)
        Resolving www.cs.toronto.edu (www.cs.toronto.edu)... 128.100.3.30, 128.100.1.
        Connecting to www.cs.toronto.edu (www.cs.toronto.edu) | 128.100.3.30 | :443... co
        nnected.
        HTTP request sent, awaiting response... 200 OK
        Length: 170498071 (163M) [application/x-gzip]
        Saving to: 'cifar-10-python.tar.gz.2'
        in 4m 19s
        2022-12-21 15:25:50 (643 KB/s) - 'cifar-10-python.tar.gz.2' saved [170498071/
        170498071]
In [4]: !tar -xzf cifar-10-python.tar.gz
In [3]: def unpickle(file):
           import pickle
           with open(file, 'rb') as f:
               obj = pickle.load(f, encoding='latin1')
           return obj
        def load_train_data(path, target_label):
            data_dict = unpickle(path)
           datas = data_dict['data']
           labels = data_dict['labels']
           dataset = []
           for data, label in zip(datas, labels):
               if label == target label:
                   image = np.asarray(data, dtype=np.float32)
                   image = (image-127.5)/127.5
                   image = image.reshape([3, 32, 32])
                   dataset += [image]
            return dataset
        def plain_to_image(image):
            image = (image+1)/2
           # image = np.transpose(image)
           return image
```

In [3]: !wget https://www.cs.toronto.edu/~kriz/cifar-10-python.tar.gz

Создам DataLoader, в котором будут только картинки автомобилей.

Реализую автоэнкодер на сверточных слоях.

```
In [5]: dim_code = 64
        class Autoencoder(nn.Module):
            def __init__(self):
                super(Autoencoder, self).__init__()
                # encoder
                self.encoder = nn.Sequential(
                    nn.Conv2d(3, 8, kernel_size=(3, 3), stride = (1, 1) , padding=(1,
                    nn.BatchNorm2d(8),
                    nn.ReLU(inplace=True),
                    nn.Conv2d(8, 16, kernel_size=(3, 3), stride = (1, 1), padding=(1,
                    nn.BatchNorm2d(16),
                    nn.ReLU(inplace=True),
                    nn.Conv2d(16, 32, kernel\_size=(3, 3), stride = (1, 1), padding=(1, 1)
                    nn.BatchNorm2d(32),
                    nn.ReLU(inplace=True),
                    nn.Flatten(start_dim=1, end_dim=-1),
                    nn.Linear(32768, 128),
                    nn.ReLU(inplace=True),
                    nn.Linear(128, dim_code),
                    nn.ReLU(inplace=True)
                )
                # decoder
                self.decoder = nn.Sequential(
                    nn.Linear(dim_code, 128),
                    nn.ReLU(),
                    nn.Linear(128, 32768),
                    nn.ReLU(),
                    nn.Unflatten(dim=1, unflattened_size=(32, 32, 32)),
                    nn.ConvTranspose2d(32, 16, kernel_size=(3, 3), stride=(1, 1), padd
                    nn.BatchNorm2d(16),
                    nn.ReLU(inplace=True),
                    nn.ConvTranspose2d(16, 8, kernel_size=(3, 3), stride=(1, 1), paddi
                    nn.BatchNorm2d(8),
                    nn.ReLU(inplace=True),
                    nn.ConvTranspose2d(8, 3, kernel_size=(3, 3), stride=(1, 1), paddin
                    nn.BatchNorm2d(3),
                )
            def forward(self, x):
                latent_code = self.encoder(x)
                reconstruction = self.decoder(latent_code)
                return reconstruction, latent_code
```

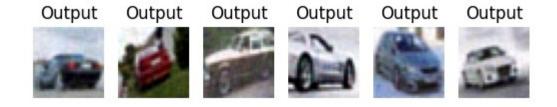
```
In [6]: def train(model, opt, loss_fn, epochs, data_tr):
          train_loss_history = []
          val_loss_history = []
          for epoch in range(epochs):
            tic = time()
            print('* Epoch %d/%d' % (epoch+1, epochs))
            avg_loss = 0
            model.train() # train mode
            for X_batch in data_tr:
              # data to device
              X_batch = X_batch.to(device)
              # set parameter gradients to zero
              opt.zero_grad()
              # forward
              reconstruction, latent_code = model(X_batch)
              loss = loss_fn(X_batch, reconstruction) # forward-pass
              loss.backward() # backward-pass
              opt.step() # update weights
              # calculate loss to show the user
              avg_loss += loss / len(data_tr)
            toc = time()
            print('loss: %f' % avg_loss)
            train_loss_history += [avg_loss.cpu().detach().item()]
            # show intermediate results
            X_val = next(iter(data_tr))
            X_val = X_val.to(device)
            reconstruction, latent_code = model(X_val)
            reconstruction = reconstruction.cpu().detach().numpy()
            X_val = plain_to_image(X_val)
            reconstruction = plain_to_image(reconstruction)
            # Visualize tools
            clear_output(wait=True)
            for k in range(6):
              plt.subplot(2, 6, k+1)
              plt.imshow(np.rollaxis(X_val[k].cpu().numpy(), 0, 3))
              plt.title('Real')
              plt.axis('off')
              plt.subplot(2, 6, k+7)
              plt.imshow(np.rollaxis(np.clip(reconstruction[k], 0, 1), 0, 3))
              plt.title('Output')
              plt.axis('off')
            plt.suptitle('%d / %d - loss: %f' % (epoch+1, epochs, avg_loss))
            plt.show()
          return train_loss_history, val_loss_history
```

Обучу модель.

```
In [7]: criterion = nn.MSELoss()
    autoencoder = Autoencoder().to(device)
    optimizer = torch.optim.Adam(autoencoder.parameters(), lr = 1e-3) # <Baw любим</pre>
```

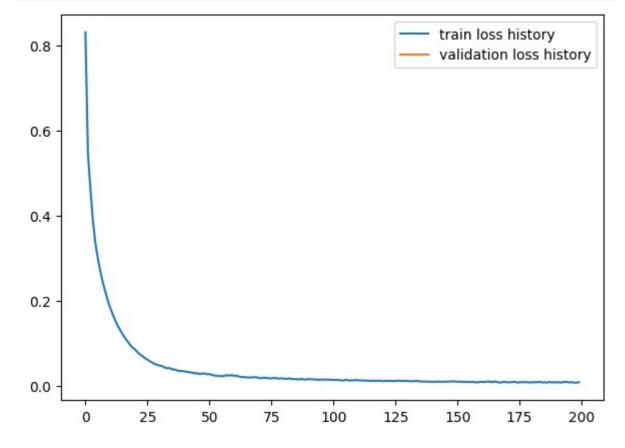
Отрисую результаты восстановления на случайных картинках из датасета.





Отрисую историю ошибки.

```
In [9]: fig,ax = plt.subplots(1,1, sharey=True, figsize=(7,5))
    ax.plot(train_loss_history, label='train loss history')
    ax.plot(val_loss_history, label='validation loss history')
    plt.legend()
    plt.show()
```



Попробую изменять случайные значения скрытого представления картинки.

```
In [29]: sample = next(iter(train_loader))
    sample = sample.to(device)

latent_code = autoencoder.encoder(sample)
    reconstruction = autoencoder.decoder(latent_code)

random_features = np.random.randint(dim_code, size=2)
    shifts = np.linspace(-100, 100, num=9)
    sample = plain_to_image(sample)
    latent_code[0, random_features]
```

Out[29]: tensor([57.9186, 73.2407], device='cuda:0', grad_fn=<IndexBackward0>)

Взгляну на результаты.

```
In [30]: |id = 2|
         plt.figure(figsize=(20,10))
         for k in range(9):
              plt.subplot(3, 9, k+1)
              plt.imshow(np.rollaxis(sample[id].cpu().numpy(), 0, 3))
              plt.title('Real')
              plt.axis('off')
              cur_latent_code = latent_code.clone()
              cur_latent_code[id, random_features[0]] += shifts[k]
              cur_reconstruction = autoencoder.decoder(cur_latent_code)
              cur_reconstruction = cur_reconstruction.cpu().detach().numpy()
              cur_reconstruction = plain_to_image(cur_reconstruction)
              plt.subplot(3, 9, k+10)
              plt.imshow(np.rollaxis(np.clip(cur_reconstruction[id], 0, 1), 0, 3))
              plt.title('Output')
              plt.axis('off')
              cur_latent_code = latent_code.clone()
              cur_latent_code[id, random_features[1]] += shifts[k]
              cur_reconstruction = autoencoder.decoder(cur_latent_code)
              cur_reconstruction = cur_reconstruction.cpu().detach().numpy()
              cur_reconstruction = plain_to_image(cur_reconstruction)
              plt.subplot(3, 9, k+19)
              plt.imshow(np.rollaxis(np.clip(cur_reconstruction[id], 0, 1), 0, 3))
              plt.title('Output')
              plt.axis('off')
         plt.show()
             Real
                                Real
                                         Real
                                                  Real
                                                           Real
                                                                    Real
                                                                              Real
                                                                                       Real
                                                           Output
                                                                    Output
                                                                             Output
                                                           Output
                                                                    Output
                                                                             Output
```

Вывод: В ходе выполнения работы был реализован автоэнкодер для изображения 32 на 32 пикселя. Модель была обучена на изображениях автомобилей. Восстановленные

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картинки не идеально совпадают с оригиналами, но в целом очень похожи. Изменение случайных значений в векторе скрытого представления изменяет результат восстановления, но какого-то смысла каждое, отдельно взятое значение вектора смысла изменения усты в совемущиести формируют нейки набор призначения.

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