## **Daniel Johnson**

M.A.Sc., B.A.Sc. 142 Wood St. Apt B Kitchener, ON June 17, 2015 dan@ddajohnson.com (226)-989-0511 http://ddajohnson.com

**Goal:** To work with a team solving interesting problems in mechatronics and robotics. My fourth year design project was to develop 3-D 6 degree of freedom SLAM algorithm for the NASA Sample Return Challenge and I'd be excited to return to that area of work at Clearpath.

### Skills

- Modeling: 2-D and 3-D Dynamics and simulation of multibody systems.
- Control Systems: Practical experience with optimal control of biomechanical models using Pontryagin's Minimum Principle. Theoretical training in multi-variate, adaptive, and optimal control and state estimation techniques
- **Development:** C/C++, Python, MATLAB, Git, Objective-C, ROS, Linux
- **Experimentation:** Designed and executed experiments involving human subjects and processed the resulting data to estimate parameters for system modelling and control
- **Autonomous Systems:** Designed and developed a 3D 6DoF SLAM algorithm for the NASA Sample Return Challenge using ROS, Gazebo, Python, and C++.
- Communication: Excels at writing clear and concise documents and explaining ideas
- Learning: Love to learn new things and explore new ideas. Quick to pick up new skills and technologies as required

### Education

### **University of Waterloo**

Waterloo, ON

Masters of Applied Science - Systems Design Engineering

2012-2015

- Created a comprehensive, 3-D, forward dynamic, golfer swing model using MapleSim and Matlab on Linux. The model is optimally controlled to allow for evaluation of golf club designs.
- Delivered the completed model to an industry partner along with complete documentation.
- Excelled in courses in multivariate, adaptive, and optimal control systems.
- Managed Linux server for the lab including web sites, file shares, and wiki pages.

### **University of Waterloo**

Waterloo, ON

B.A.Sc. - Systems Design Engineering, Dean's Honour List, Co-operative Program

2007 - 2012

- 4th Year Design Project SLAM for NASA Sample Return Challenge
  - Combined Kalman Filters, Iterative Closest Point (ICP), and GraphSLAM algorithms to develop a novel approach for 6 degree of freedom simultaneous location and mapping without the use of GPS
  - Improved on the performance of these methods individually by performing GraphSLAM in the background and updating the pose information after its completion.

## Work Experience

### University of Waterloo (Vision and Image Processing Lab)

Waterloo, ON

Research Assistant - vip.uwaterloo.ca/website-package

May-Aug 2011

- Developed algorithms for processing SAR imagery of sea-ice in the Canadian North
- Implemented algorithms within existing image processing software in Visual C++.
- Supervised and assisted a co-op student building a website for the lab using Drupal resulting in a package for building research group websites that was released as open-source
- Administered linux web server for hosting the lab website

Apple Inc. Cupertino, CA

Software Engineering Intern - iOS Location Software

Jan-Apr 2010 and Sep-Dec 2010

- Designed and implemented a testing framework for location algorithms on iPhones and iPads in the form of an iOS application, Mac application, and accompanying server-side code. This application was used by the iOS Location team to develop and test indoor positioning systems.
- Developed an improved location algorithm using Kalman Filters for determining an iOS device's location during indoor positioning.

Trimble Navigation Christchurch, NZ

GPS Software Tester

May-Aug 2009

- Developed and performed experiments on software keyboards for mobile devices using C#.
- Developed embedded micro-controller code for RF chamber test rig for handheld GPS devices.
- Tested hand held GPS devices for accuracy and interface usability.

CREZ Basketball Waterloo, ON

Software developer

Jan-Apr 2007 and Sep-Dec 2007

- ullet Developed statistics software for basketball coaches in Visual Basic .NET and C#
- Implemented client-side code for livestreaming basketball statistics to a web service.
- Packaged and released software to clients using InstallShield.
- Provided technical support through direct interaction with customers and written documentation

# **Personal Projects**

### **Bearded Baritones Website**

nodeJS, Javascript, HTML & CSS

github.com/proverbialsunrise/baritonesWebsite

2015 Python

github.com/proverbialsunrise/pySTL

2014

### Hymnal Mobile Application

Objective-C, C++, Java

github.com/proverbialsunrise/hymnalapp

2010

#### Personal

## Crash Ultimate - KW Guelph Competitive Ultimate

crashultimate.ca

Captain

pySTL

2013-

• Elected captain of National Championship winning team in 2014

Hobbies: Singing (A Cappella and Barbershop in particular), Ultimate Frisbee, Soccer, Basketball