6.087 Lecture 9 – January 22, 2010

Review

- Using External Libraries
 - Symbols and Linkage
 - Static vs. Dynamic Linkage
 - Linking External Libraries
 - Symbol Resolution Issues
- Creating Libraries
- Data Structures
 - B-trees
 - Priority Queues



Review: Void pointers

• Void pointer – points to any data type:

```
int x; void * px = &x; /* implicit cast to (void *) */
float f; void * pf = &f;
```

• Cannot be dereferenced directly; void pointers must be cast prior to dereferencing:

```
printf("%d %f\n", *(int *)px, *(float *)pf);
```



Review: Function pointers

- Functions not variables, but also reside in memory (i.e. have an address) we can take a pointer to a function
- Function pointer declaration: int (*cmp)(void *, void *);
- Can be treated like any other pointer
- No need to use & operator (but you can)
- Similarly, no need to use * operator (but you can)



Review: Function pointers

```
int strcmp_wrapper(void * pa, void * pb) {
  return strcmp((const char *)pa, (const char *)pb);
}
```

Can assign to a function pointer:
 int (*fp)(void *, void *) = strcmp_wrapper; Or
 int (*fp)(void *, void *) = &strcmp wrapper;

 Can call from function pointer: (str1 and str2 are strings)

```
int ret = fp(str1, str2); Or
int ret = (*fp)(str1, str2);
```



Review: Hash tables

- Hash table (or hash map): array of linked lists for storing and accessing data efficiently
- Each element associated with a key (can be an integer, string, or other type)
- Hash function computes hash value from key (and table size); hash value represents index into array
- Multiple elements can have same hash value results in collision; elements are chained in linked list



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Symbols and libraries

- External libraries provide a wealth of functionality example: C standard library
- Programs access libraries' functions and variables via identifiers known as symbols
- Header file declarations/prototypes mapped to symbols at compile time
- Symbols linked to definitions in external libraries during linking
- Our own program produces symbols, too



• Consider the simple hello world program written below:

```
#include <stdio.h>
const char msg[] = "Hello, world.";
int main(void) {
  puts(msg);
  return 0;
}
```

What variables and functions are declared globally?



• Consider the simple hello world program written below:

```
#include <stdio.h>
const char msg[] = "Hello, world.";
int main(void) {
  puts(msg);
  return 0;
}
```

What variables and functions are declared globally?
 msg, main(), puts(), others in stdio.h



- Let's compile, but not link, the file hello.c to create hello.o: athena% gcc -Wall -c hello.c -o hello.o
 - -c: compile, but do not link hello.c; result will compile the code into machine instructions but not make the program executable
 - addresses for lines of code and static and global variables not yet assigned
 - need to perform link step on hello.o (using gcc or ld) to assign memory to each symbol
 - linking resolves symbols defined elsewhere (like the C standard library) and makes the code executable

Athena is MIT's UNIX-based computing environment. OCW does not provide access to it.



- Let's look at the symbols in the compiled file hello.o: athena% nm hello.o
- Output:

```
0000000000000000 T main
0000000000000000 R msg
U puts
```

- 'T' (text) code; 'R' read-only memory; 'U' undefined symbol
- Addresses all zero before linking; symbols not allocated memory yet
- Undefined symbols are defined externally, resolved during linking

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- Why aren't symbols listed for other declarations in stdio.h?
- Compiler doesn't bother creating symbols for unused function prototypes (saves space)
- What happens when we link?
 athena% gcc -Wall hello.o -o hello
 - Memory allocated for defined symbols
 - Undefined symbols located in external libraries (like libc for C standard library)

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• Let's look at the symbols now: athena%1 nm hello

Output: (other default symbols):

```
0000000000400524 T main
000000000040062c R msg
```

U puts@@GLIBC_2.2.5

- Addresses for static (allocated at compile time) symbols
- Symbol puts located in shared library GLIBC_2.2.5 (GNU C standard library)
- Shared symbol puts not assigned memory until run time

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Static and dynamic linkage

- Functions, global variables must be allocated memory before use
- Can allocate at compile time (static) or at run time (shared)
- Advantages/disadvantages to both
- Symbols in same file, other .o files, or static libraries (archives, .a files) – static linkage
- Symbols in shared libraries (.so files) dynamic linkage
- gcc links against shared libraries by default, can force static linkage using -static flag



Static linkage

- What happens if we statically link against the library?
 athena% gcc -Wall -static hello.o -o hello
- Our executable now contains the symbol puts:

```
:
0000000000004014c0 W puts
:
000000000000400304 T main
:
00000000000046cd04 R msg
.
```

'W': linked to another defined symbol

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Static linkage

- At link time, statically linked symbols added to executable
- Results in much larger executable file (static 688K, dynamic – 10K)
- Resulting executable does not depend on locating external library files at run time
- To use newer version of library, have to recompile



Dynamic linkage

- Dynamic linkage occurs at run-time
- During compile, linker just looks for symbol in external shared libraries
- Shared library symbols loaded as part of program startup (before main())
- Requires external library to define symbol exactly as expected from header file declaration
 - changing function in shared library can break your program
 - version information used to minimize this problem
 - reason why common libraries like libc rarely modify or remove functions, even broken ones like gets()



Linking external libraries

- Programs linked against C standard library by default
- To link against library libnamespec.so or libnamespec.a, use compiler flag -lnamespec to link against library
- Library must be in library path (standard library directories + directories specified using -L directory compiler flag
- Use -static for force static linkage
- This is enough for static linkage; library code will be added to resulting executable



Loading shared libraries

- Shared library located during compile-time linkage, but needs to be located again during run-time loading
- Shared libraries located at run-time using linker library ld.so
- Whenever shared libraries on system change, need to run ldconfig to update links seen by ld.so
- During loading, symbols in dynamic library are allocated memory and loaded from shared library file



Loading shared libraries on demand

- In Linux, can load symbols from shared libraries on demand using functions in dlfcn.h
- Open a shared library for loading:

 void * dlopen(const char *file, int mode);
 values for mode: combination of RTLD_LAZY (lazy loading of library), RTLD_NOW (load now), RTLD_GLOBAL (make symbols in library available to other libraries yet to be loaded), RTLD_LOCAL (symbols loaded are accessible only to your code)



Loading shared libraries on demand

- Get the address of a symbol loaded from the library:
 void * dlsym(void * handle, const char * symbol_name);
 handle from call to dlopen; returned address is pointer to
 variable or function identified by symbol name
- Need to close shared library file handle after done with symbols in library:
 int dlclose(void * handle);
- These functions are not part of C standard library; need to link against library libdl: -ldl compiler flag



Symbol resolution issues

- Symbols can be defined in multiple places
- Suppose we define our own puts () function
- But, puts () defined in C standard library
- When we call puts (), which one gets used?



Symbol resolution issues

- Symbols can be defined in multiple places
- Suppose we define our own puts () function
- But, puts () defined in C standard library
- When we call puts (), which one gets used?
- Our puts() gets used since ours is static, and puts() in C standard library not resolved until run-time
- If statically linked against C standard library, linker finds two puts() definitions and aborts (multiple definitions not allowed)



Symbol resolution issues

- How about if we define puts() in a shared library and attempt to use it within our programs?
- Symbols resolved in order they are loaded
- Suppose our library containing puts () is libhello.so, located in a standard library directory (like /usr/lib), and we compile our hello.c code against this library: athena% gcc -g -Wall hello.c -lhello -o hello.o
- Libraries specified using -1 flag are loaded in order specified, and before C standard library
- Which puts() gets used here?
 athena% gcc -g -Wall hello.c -lc -lhello -o hello.o

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Creating Libraries

- Data Structures
 - B-trees
 - Priority Queues



Creating libraries

- Libraries contain C code like any other program
- Static or shared libraries compiled from (un-linked) object files created using gcc
- Compiling a static library:
 - compile, but do not link source files: athena% gcc -g -Wall -c infile.c -o outfile.o
 - collect compiled (unlinked) files into an archive: athena% ar -rcs libname.a outfile1.o

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Creating shared libraries

- Compile and do not link files using gcc: athena% gcc -g -Wall -fPIC -c infile.c -o outfile.o
- -fPIC option: create position-independent code, since code will be repositioned during loading
- Link files using 1d to create a shared object (.so) file: athena% 1d -shared -soname libname.so -o libname.so.version -lc outfile1.o outfile2.o ...
- If necessary, add directory to LD_LIBRARY_PATH environment variable, so ld.so can find file when loading at run-time
- Configure ld.so for new (or changed) library: athena% ldconfig -v



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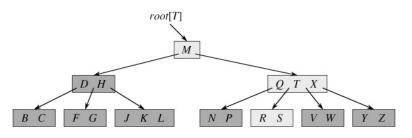
Data structures

- Many data structures designed to support certain algorithms
- B-tree generalized binary search tree, used for databases and file systems
- Priority queue ordering data by "priority," used for sorting, event simulation, and many other algorithms



B-tree structure

- Binary search tree with variable number of children (at least t, up to 2t)
- Tree is balanced all leaves at same level
- Node contains list of "keys" divide range of elements in children



[Cormen, Leiserson, Rivest, and Stein. *Introduction to Algorithms*, 2nd ed. MIT Press, 2001.]



Initializing a B-tree

- Initially, B-tree contains root node with no children (leaf node), no keys
- Note: root node exempt from minimum children requirement



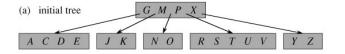
Inserting elements

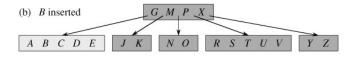
- Insertion complicated due to maximum number of keys
- At high level:
 - traverse tree down to leaf node
 - 2. if leaf already full, split into two leaves:
 - (a) move median key element into parent (splitting parent already full)
 - (b) split remaining keys into two leaves (one with lower, one with higher elements)
 - add element to sorted list of keys
- Can accomplish in one pass, splitting full parent nodes during traversal in step 1

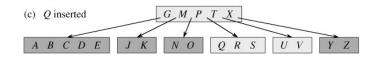


Inserting elements

B-tree with t = 3 (nodes may have 2–5 keys):







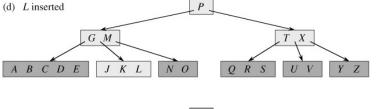
[Cormen, Leiserson, Rivest, and Stein. Introduction to Algorithms, 2nd ed.

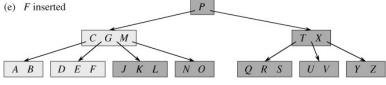
MIT Press, 2001.]



Inserting elements

More insertion examples:





[Cormen, Leiserson, Rivest, and Stein. Introduction to Algorithms, 2nd ed.

MIT Press, 2001.]



Searching a B-tree

- Search like searching a binary search tree:
 - 1. start at root.
 - 2. if node empty, element not in tree
 - 3. search list of keys for element (using linear or binary search)
 - 4. if element in list, return element
 - 5. otherwise, element between keys, and repeat search on child node for that range
- Tree is balanced search takes $O(\log n)$ time

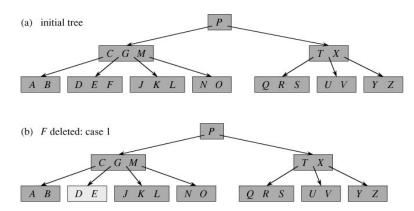


Deletion

- Deletion complicated by minimum children restriction
- When traversing tree to find element, need to ensure child nodes to be traversed have enough keys
 - if adjacent child node has at least t keys, move separating key from parent to child and closest key in adjacent child to parent
 - if no adjacent child nodes have extra keys, merge child node with adjacent child
- When removing a key from a node with children, need to rearrange keys again
 - if child before or after removed key has enough keys, move closest key from child to parent
 - if neither child has enough keys, merge both children
 - if child not a leaf, have to repeat this process



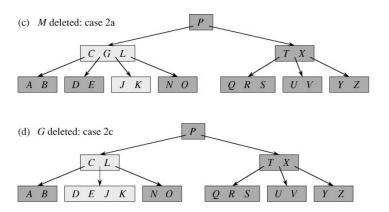
Deletion examples



[Cormen, Leiserson, Rivest, and Stein. *Introduction to Algorithms*, 2nd ed. MIT Press, 2001.]



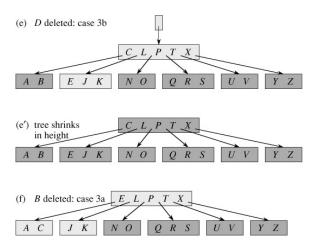
Deletion examples



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Deletion examples



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Priority queue

- · Abstract data structure ordering elements by priority
- Elements enqueued with priority, dequeued in order of highest priority
- Common implementations: heap or binary search tree
- Operations: insertion, peek/extract max-priority element, increase element priority



Heaps

- Heap tree with heap-ordering property: priority(child)
 priority(parent)
- More sophisticated heaps exist e.g. binomial heap, Fibonacci heap
- We'll focus on simple binary heaps
- Usually implemented as an array with top element at beginning
- Can sort data using a heap − O(n log n) worst case in-place sort!



Extracting data

- Heap-ordering property ⇒ maximum priority element at top of heap
- Can peek by looking at top element
- Can remove top element, move last element to top, and swap top element down with its children until it satisfies heap-ordering property:
 - start at top
 - find largest of element and left and right child; if element is largest, we are done
 - otherwise, swap element with largest child and repeat with element in new position

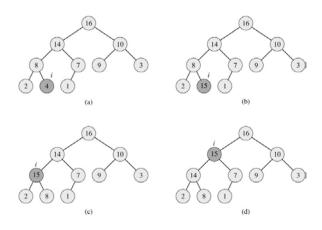


Inserting data/increasing priority

- Insert element at end of heap, set to lowest priority $-\infty$
- Increase priority of element to real priority:
 - 1. start at element
 - 2. if new priority less than parent's, we are done
 - 3. otherwise, swap element with parent and repeat



Example of inserting data



[Cormen, Leiserson, Rivest, and Stein. *Introduction to Algorithms*, 2nd ed. MIT Press, 2001.]



Summary

Topics covered:

- Using external libraries
 - · symbols and linkage
 - static vs. dynamic linkage
 - linking to your code
 - · symbol clashing
- · Creating libraries
- Data structures
 - B-tree
 - priority queue



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