Implementing Abstractions Part Two

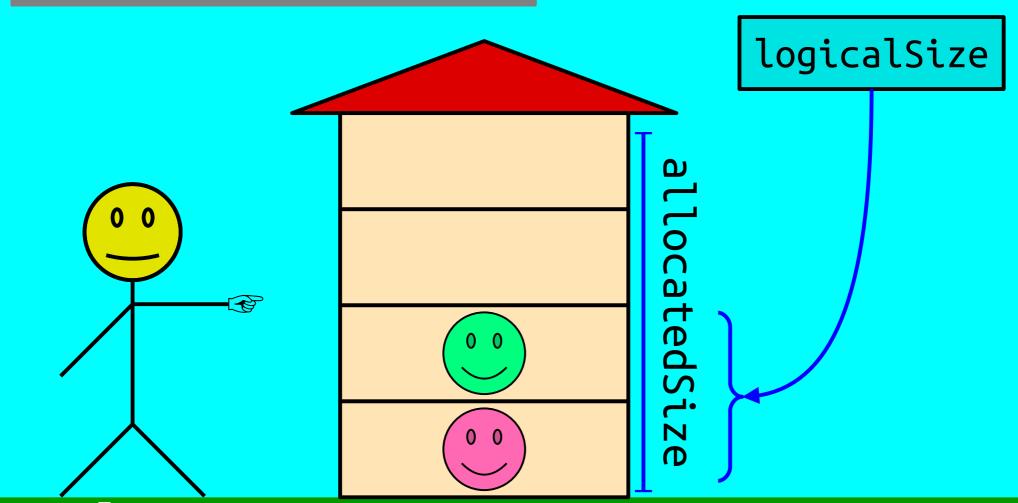
Previously, on CS106B...

```
class OurStack {
public:
    OurStack();
    void push(int value);
    int peek() const;
    int pop();
    int size() const;
    bool isEmpty() const;
private:
    int* elems;
    int allocatedSize;
    int logicalSize;
```

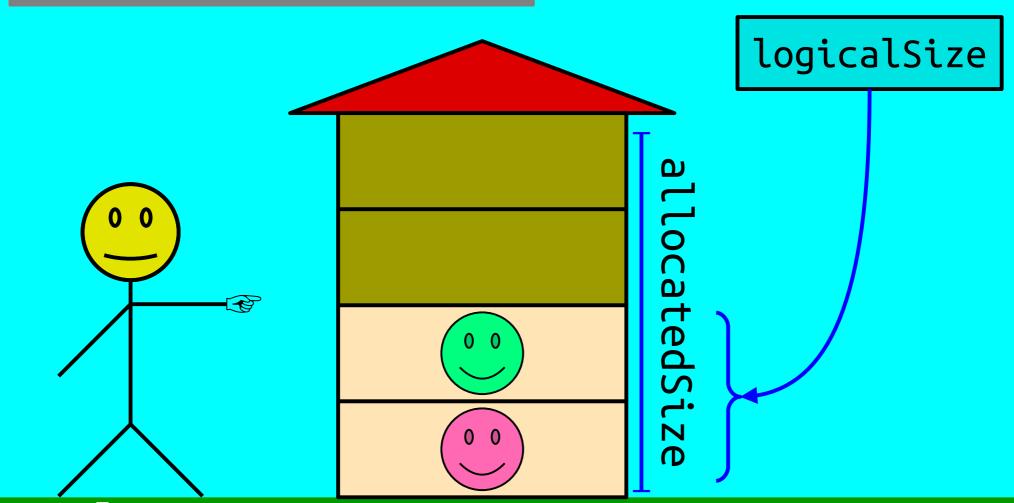
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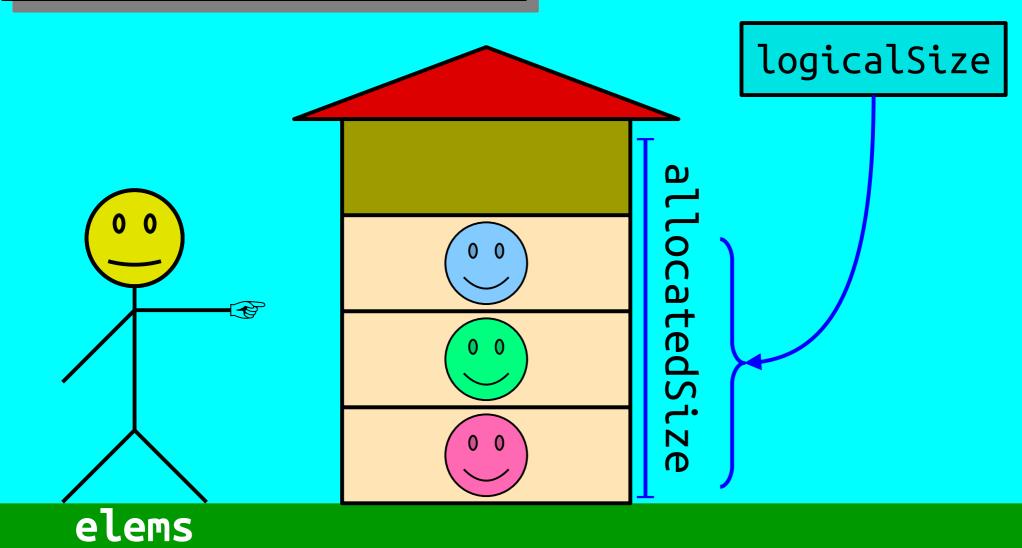


```
private:
    int* elems;
    int allocatedSize;
    int logicalSize;
```

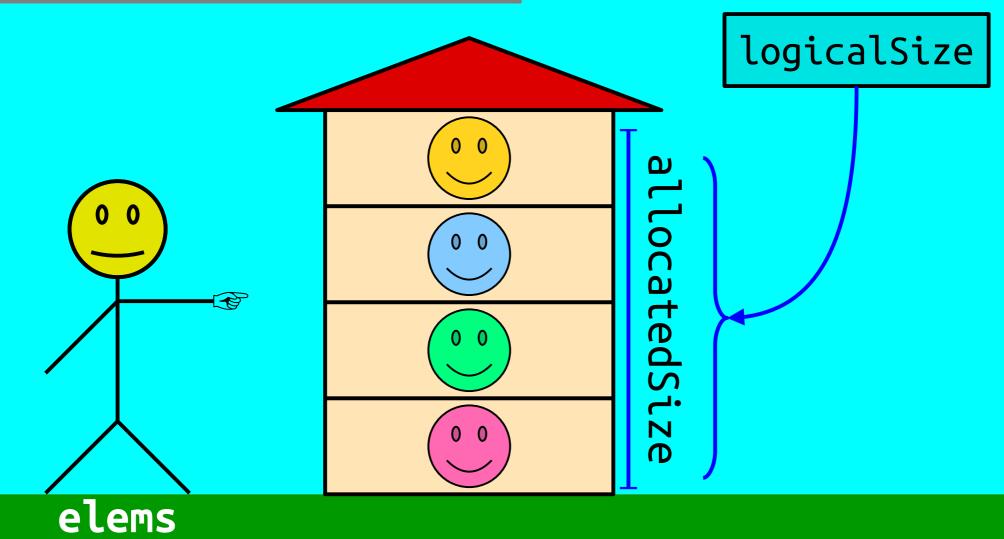


elems

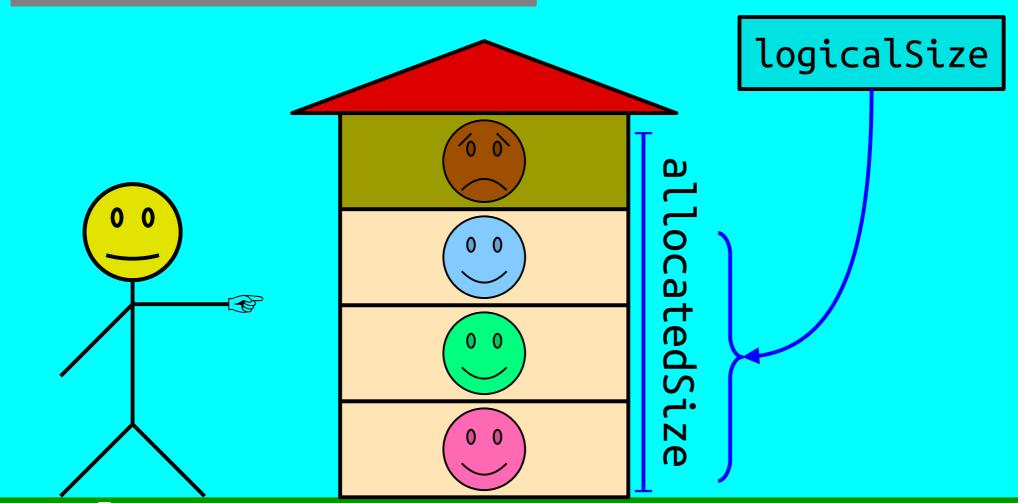
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private:
    int* elems;
    int allocatedSize;
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```



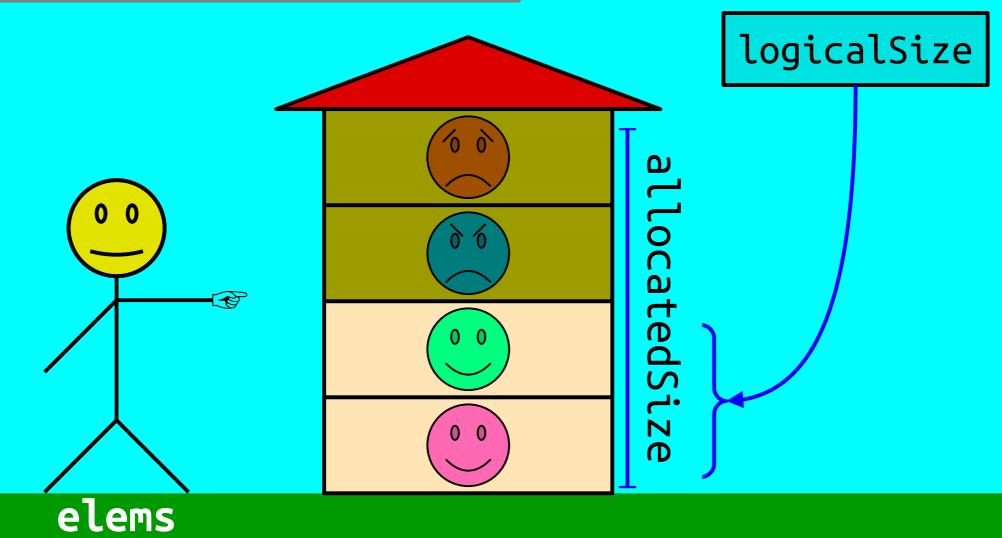
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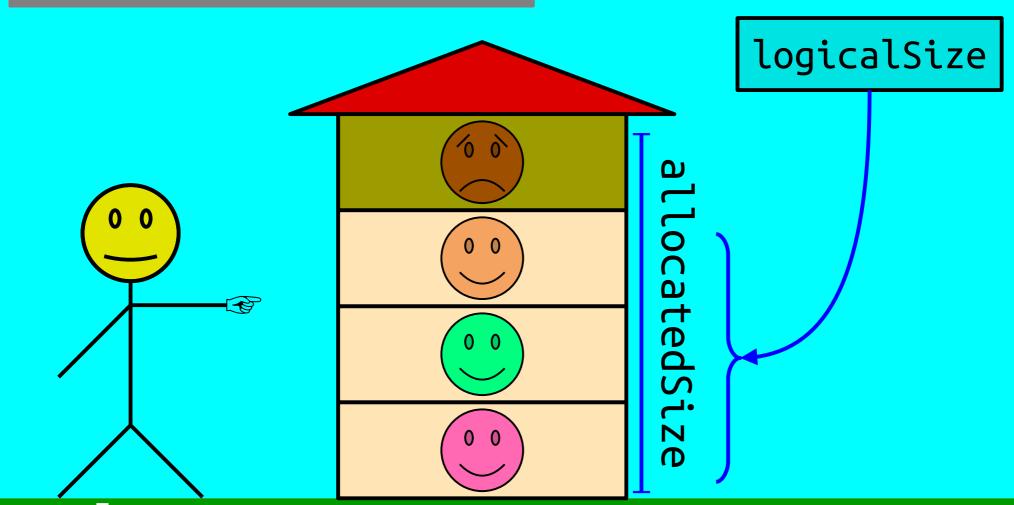
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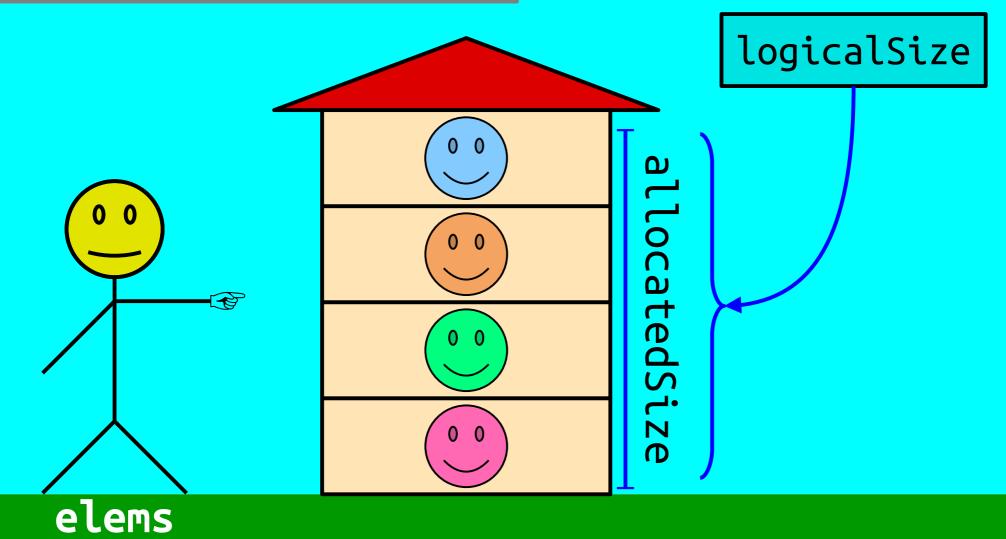


```
private:
    int* elems;
    int allocatedSize;
    int logicalSize;
```



elems

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private:
   int* elems;
   int allocatedSize;
   int logicalSize;
```



```
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    void push(int value);
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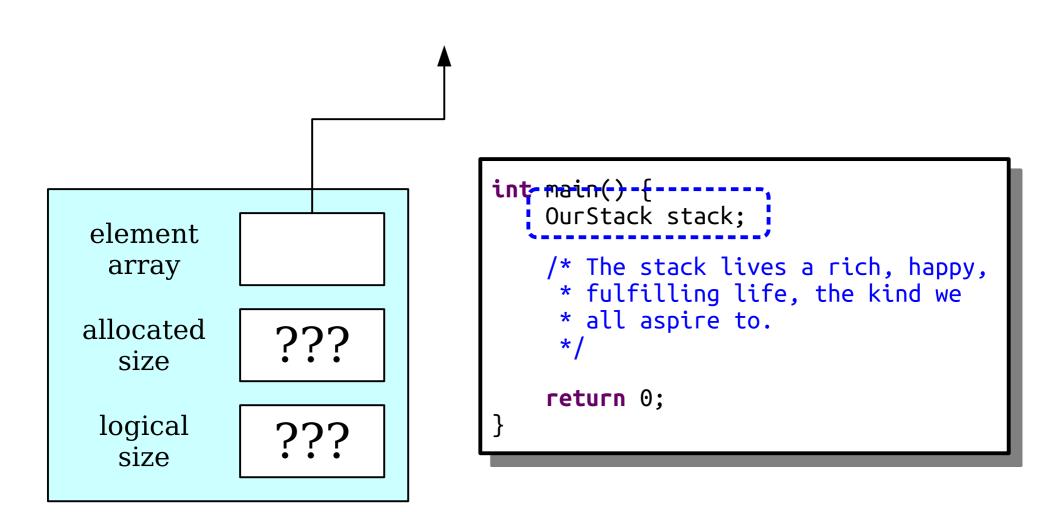
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public:
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    void push(int value);
   int peek() const;
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   int size() const;
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private:
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```

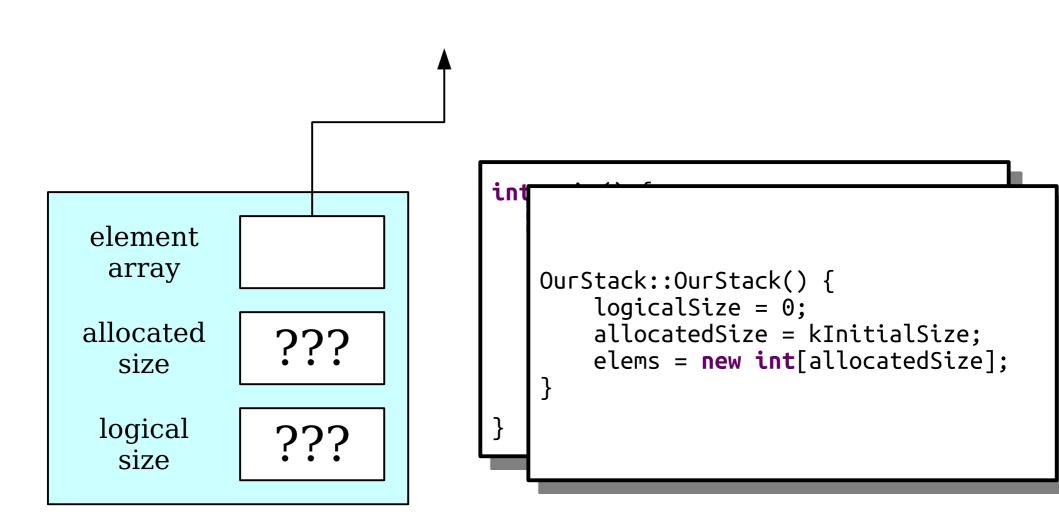
```
int main() {
   OurStack stack;

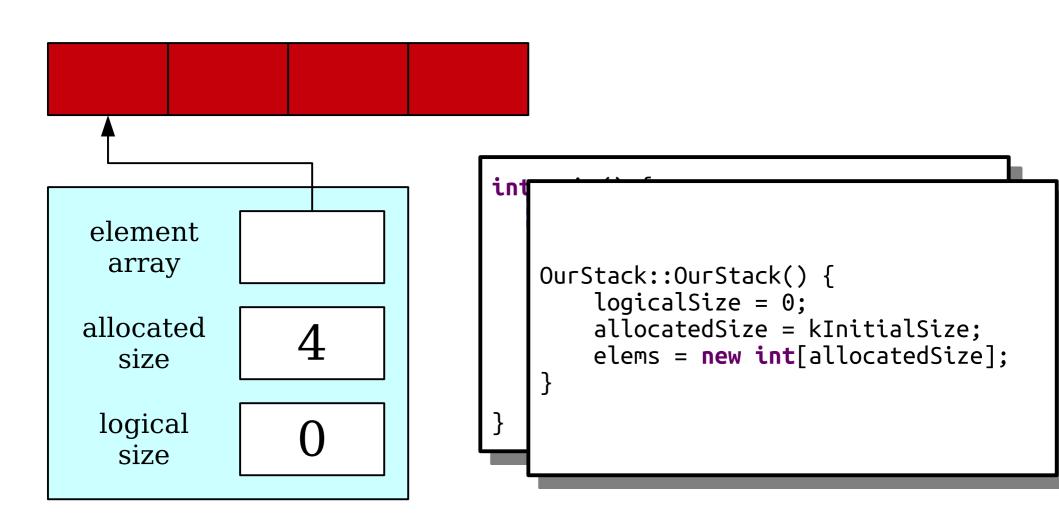
   /* The stack lives a rich, happy,
    * fulfilling life, the kind we
    * all aspire to.
    */
   return 0;
}
```

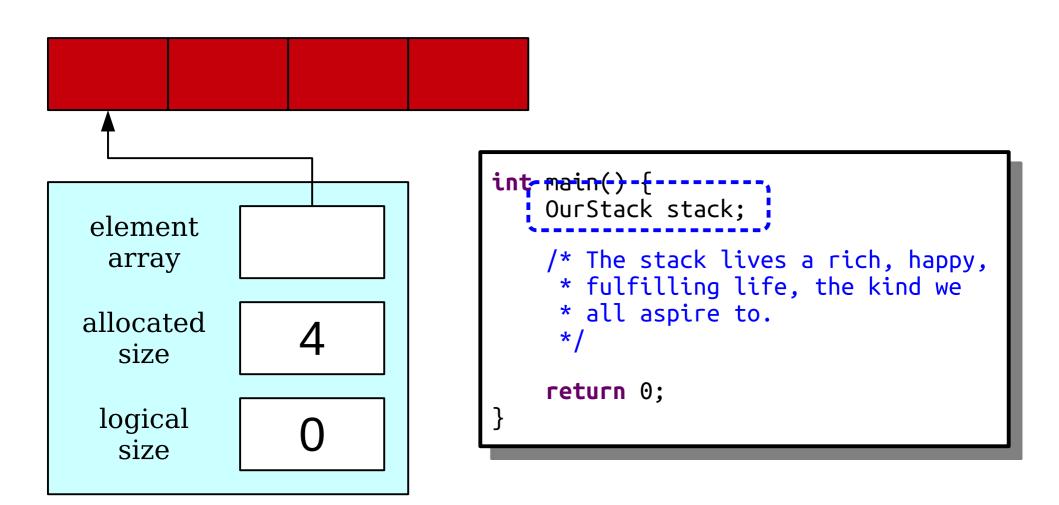
```
int main() -{
    OurStack stack;

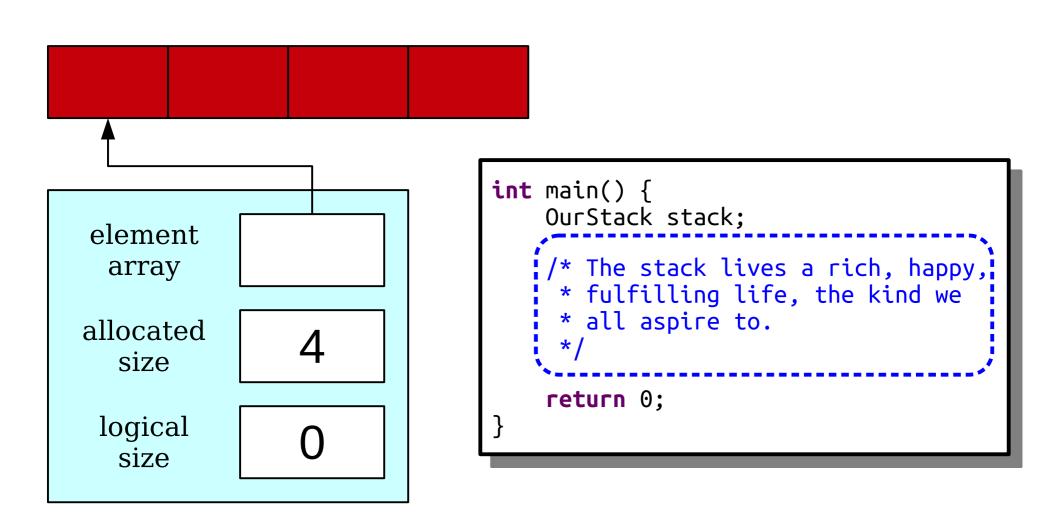
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    */
    return 0;
}
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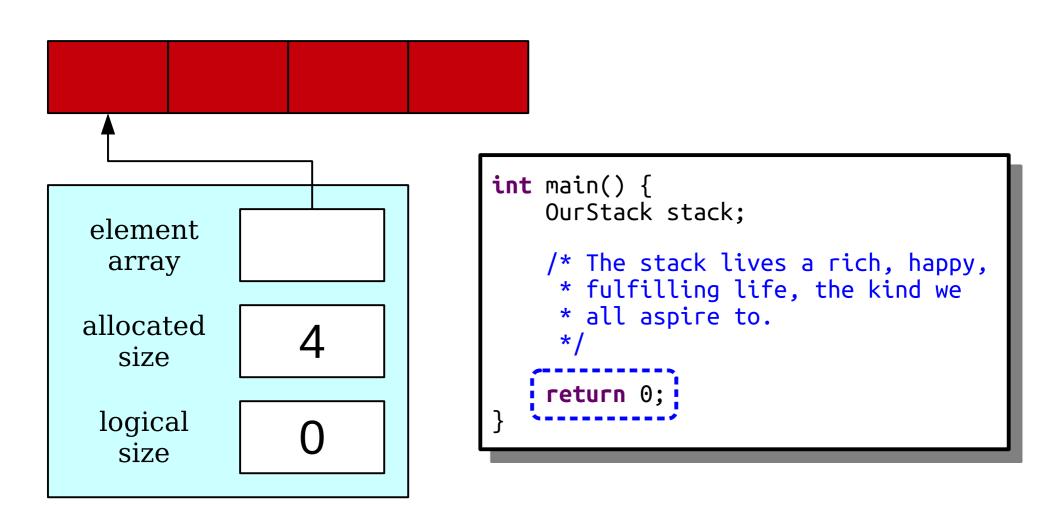












```
int main() {
   OurStack stack;

   /* The stack lives a rich, happy,
    * fulfilling life, the kind we
    * all aspire to.
    */
   return 0;
}
```



```
int main() {
   OurStack stack;

   /* The stack lives a rich, happy,
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    * all aspire to.
    */

   return 0;
}
```

Cleaning Up our Messes

Destructors

- A destructor is a special member function responsible for cleaning up an object's memory.
- It's automatically called whenever an object's lifetime ends (for example, if it's a local variable that goes out of scope.)
- The destructor for a class named *ClassName* has signature

```
~ClassName();
```

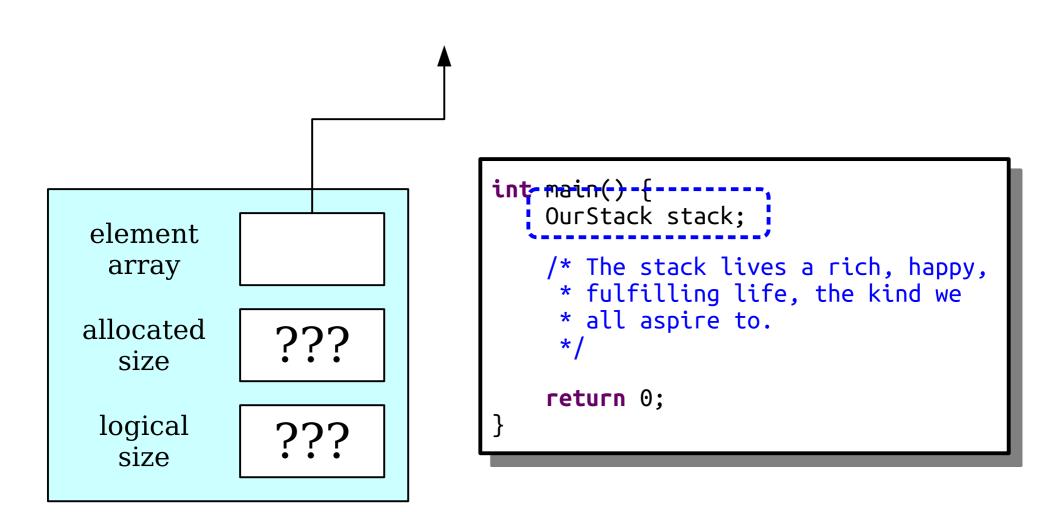
```
class OurStack {
public:
    OurStack();
    ~OurStack();
    void push(int value);
         peek() const;
    int
    int pop();
    int size() const;
    bool isEmpty() const;
private:
    int* elems;
    int allocatedSize;
    int logicalSize;
```

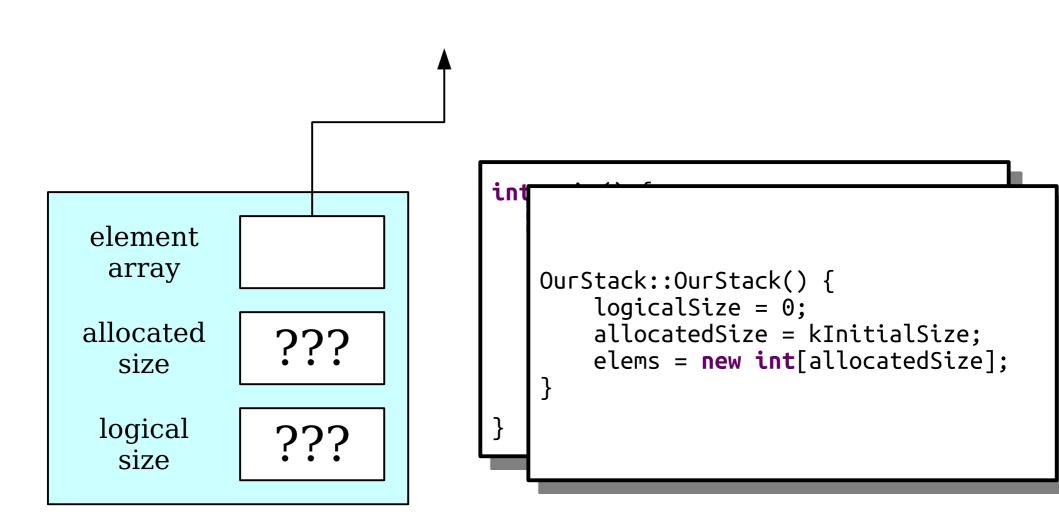
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int main() {
   OurStack stack;

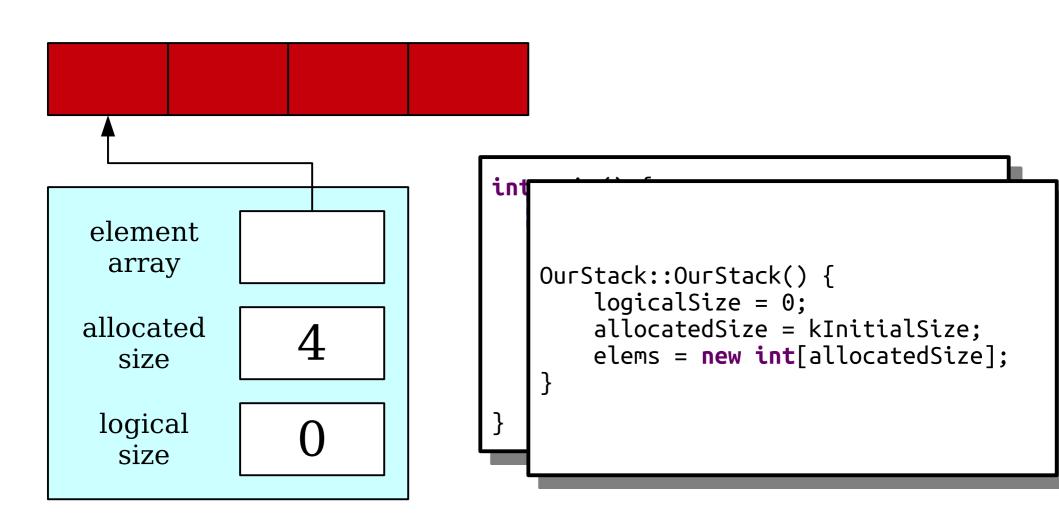
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    */
   return 0;
}
```

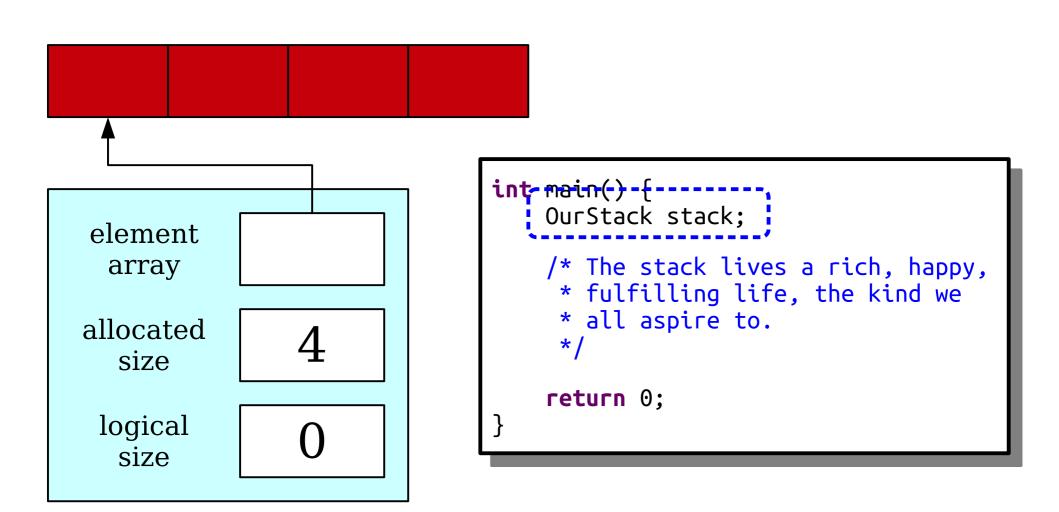
```
int main() -{
    OurStack stack;

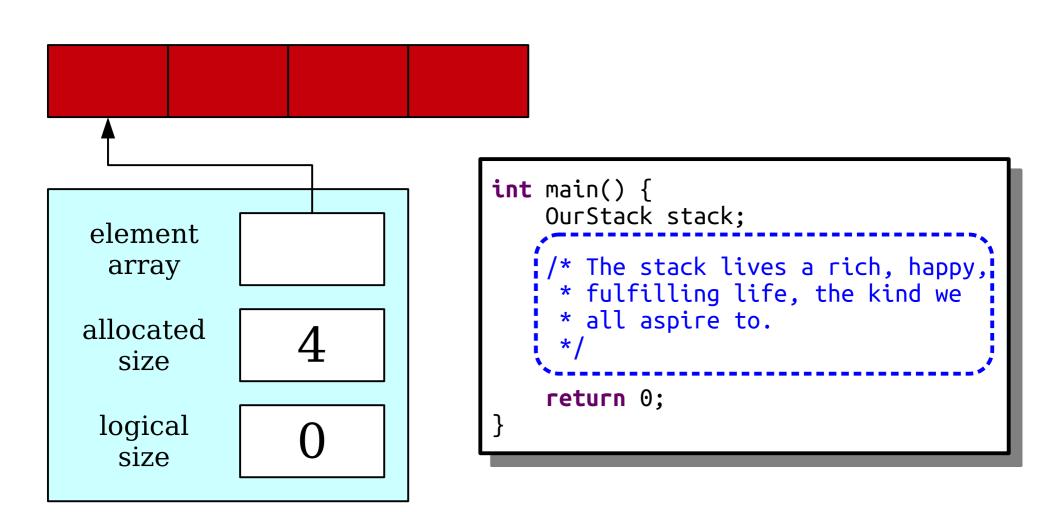
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    */
    return 0;
}
```

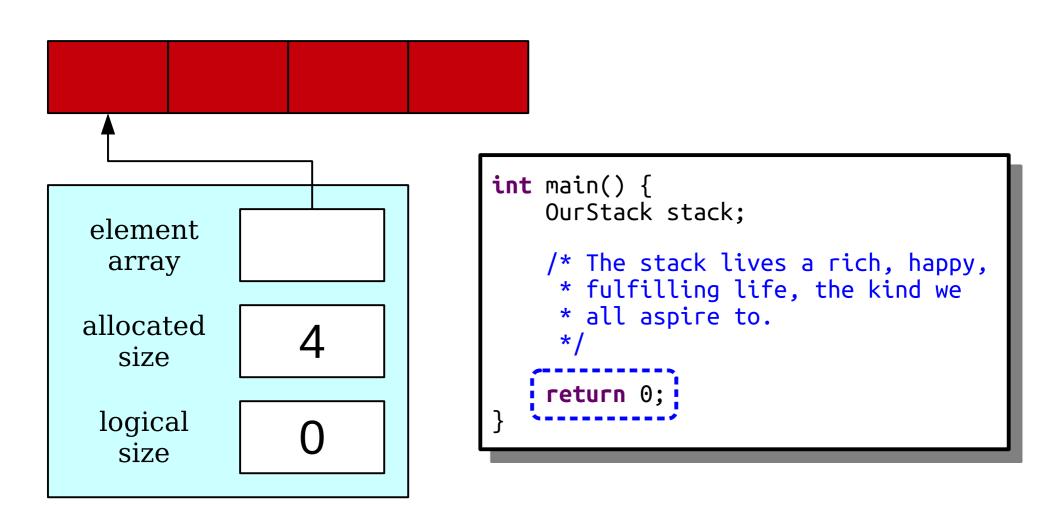


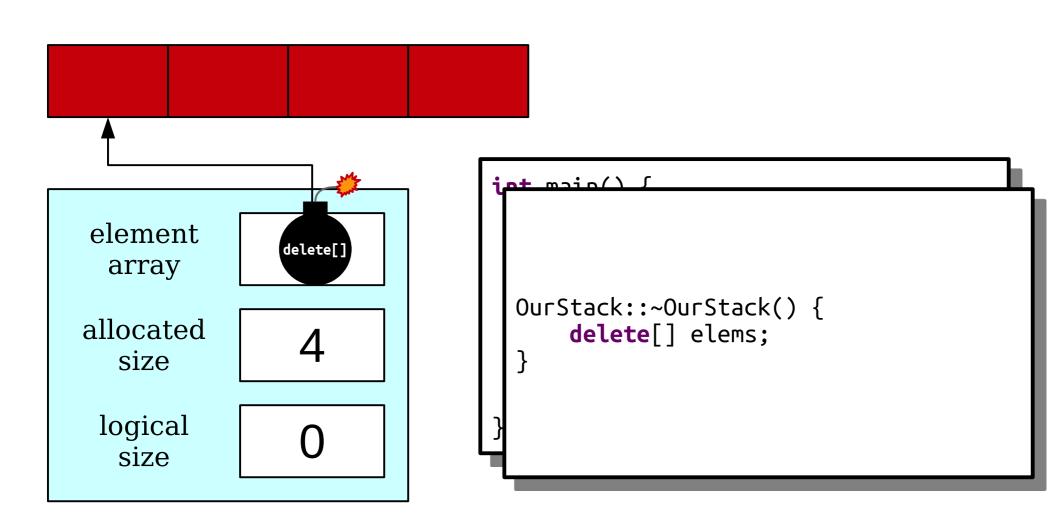


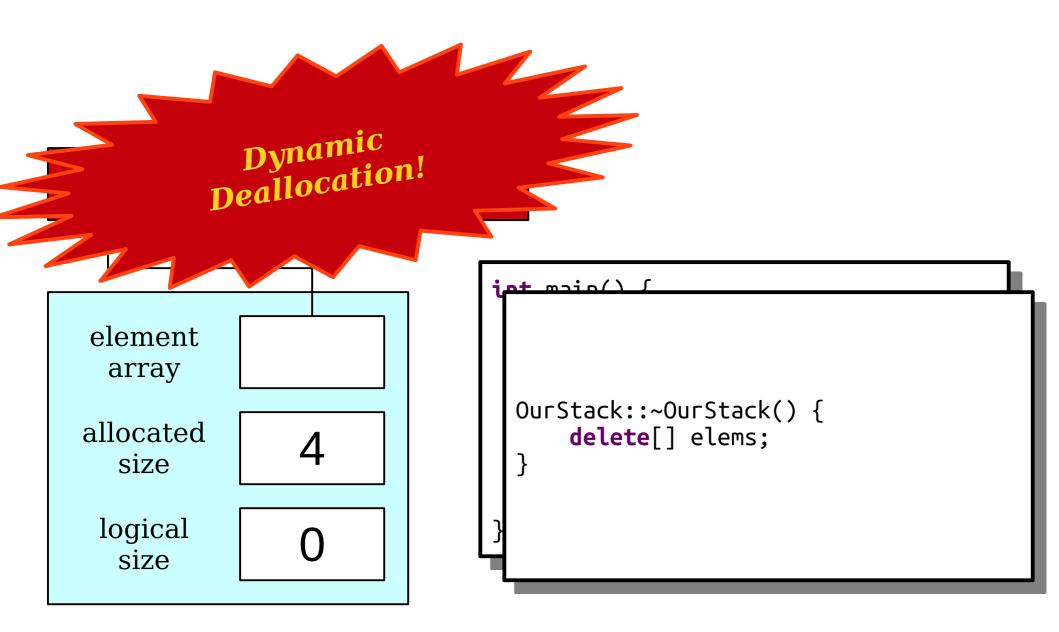


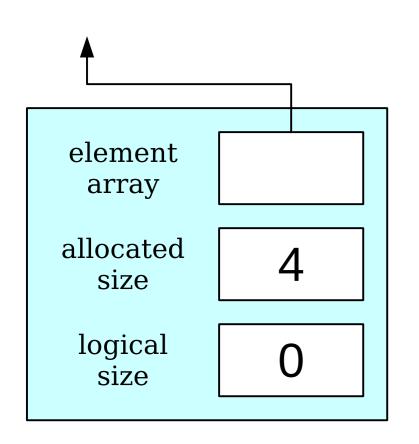




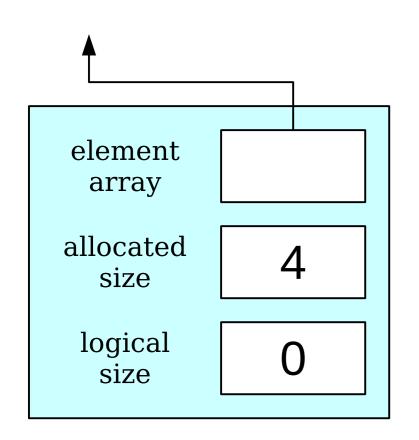








```
int main() {
   OurStack::~OurStack() {
     delete[] elems;
   }
}
```



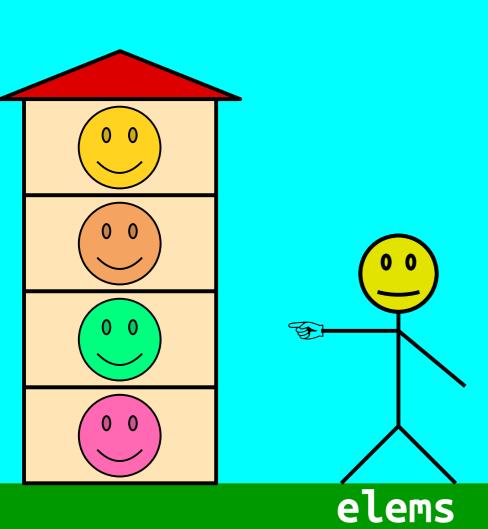
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int main() {
   OurStack stack;

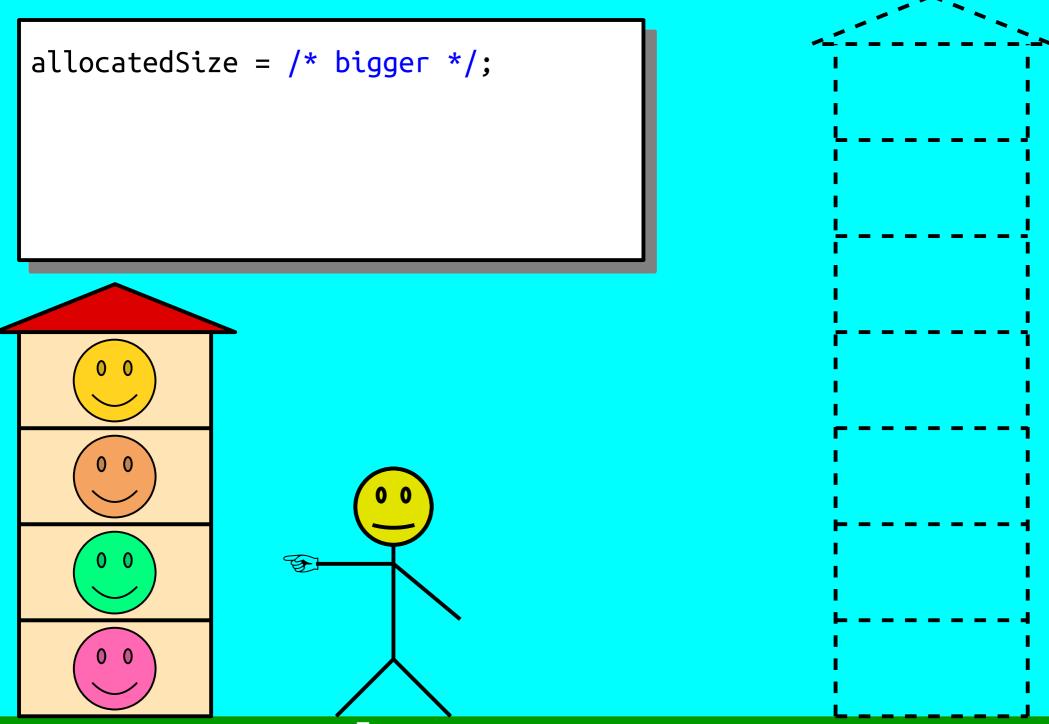
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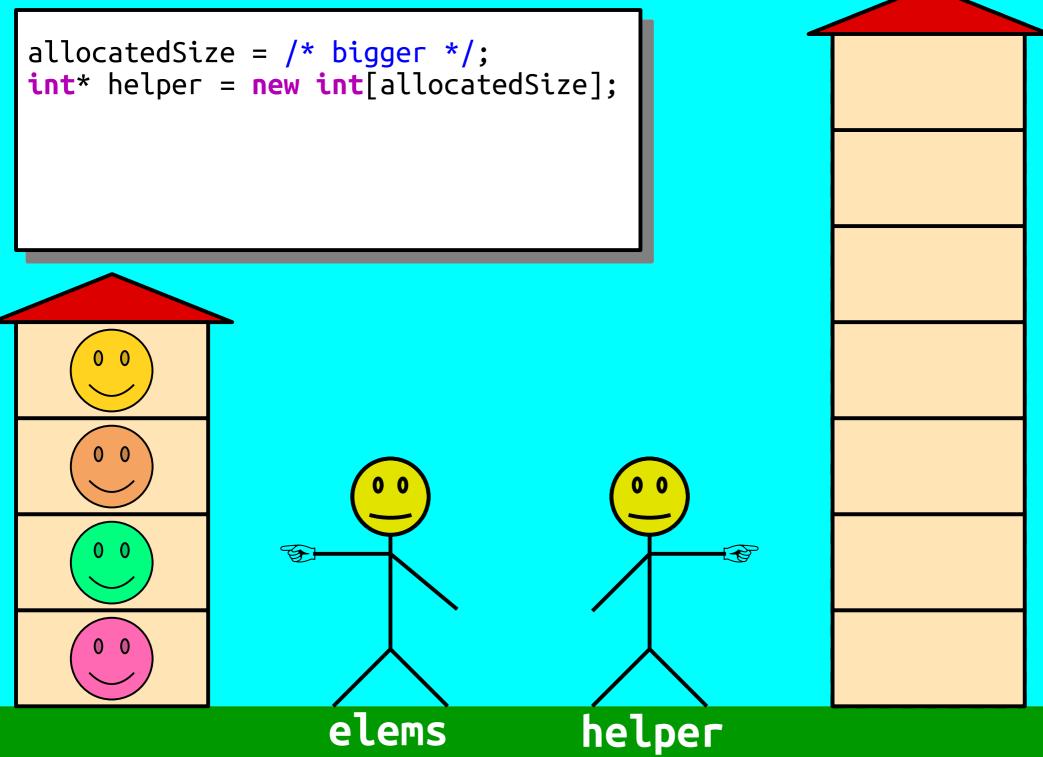
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   /* The stack lives a rich, happy,
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    * all aspire to.
    */
   return 0;
}
```

Getting More Space







```
allocatedSize = /* bigger */;
int* helper = new int[allocatedSize];
/* ... move elements over ... */
```

helper

```
allocatedSize = /* bigger */;
int* helper = new int[allocatedSize];
/* ... move elements over ... */
delete[] elems;
  Dynamic
Deallocation!
                delete[]
```

elems helper

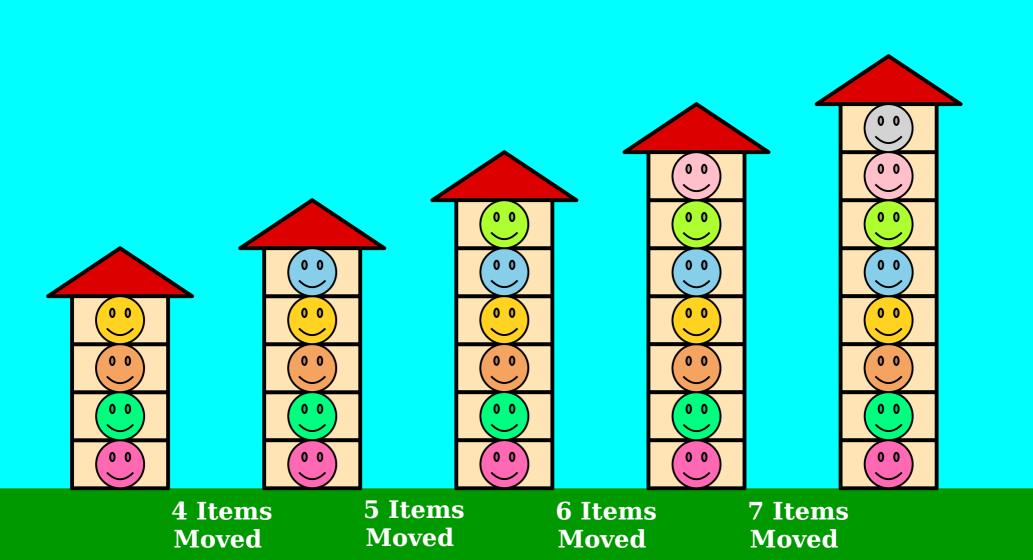
```
allocatedSize = /* bigger */;
int* helper = new int[allocatedSize];
/* ... move elements over ... */
delete[] elems;
                                   helper
```

```
allocatedSize = /* bigger */;
int* helper = new int[allocatedSize];
/* ... move elements over ... */
delete[] elems;
elems = helper;
                                    helper
```

```
allocatedSize = /* bigger */;
int* helper = new int[allocatedSize];
/* ... move elements over ... */
delete[] elems;
elems = helper;
```

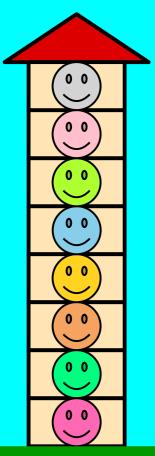
helper

What is the big-O cost of a push? What is the big-O cost of *n* pushes?



Every push beyond the first few requires moving all *n* elements from the old array to the new array.

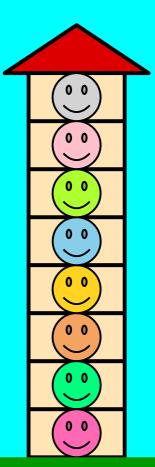
Cost of a single push: O(n).

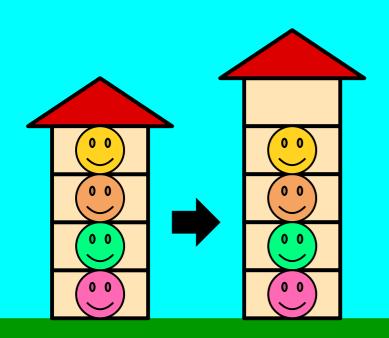


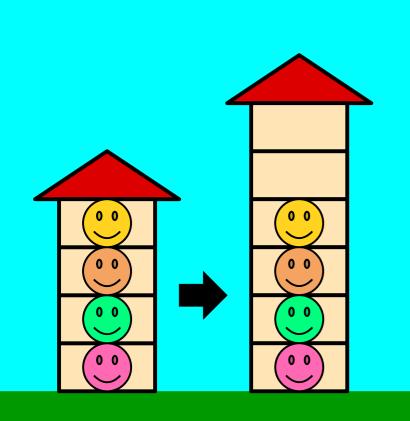
Every push beyond the first few requires moving all *n* elements from the old array to the new array.

Cost of doing n pushes: $4 + 5 + 6 + ... + n = O(n^2)$.

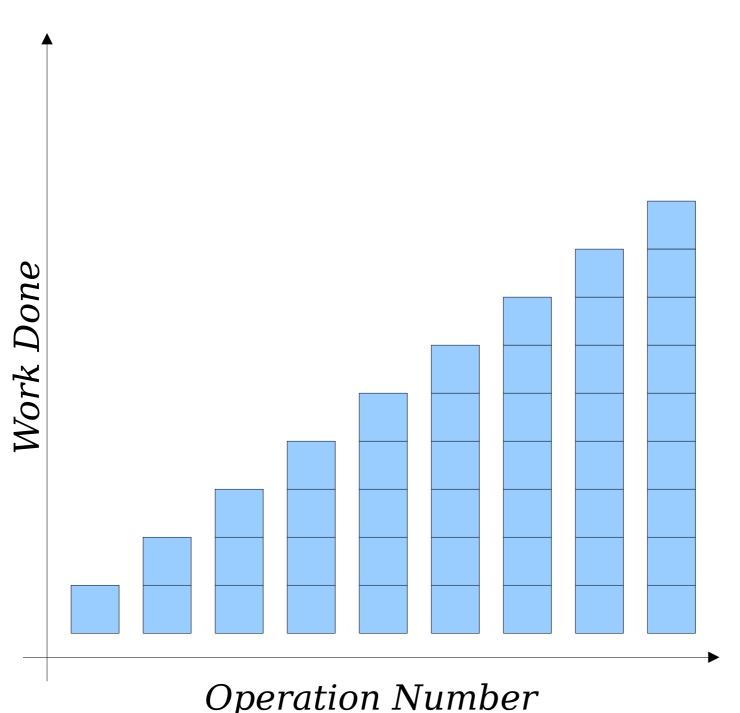
Question: How do we speed this up?



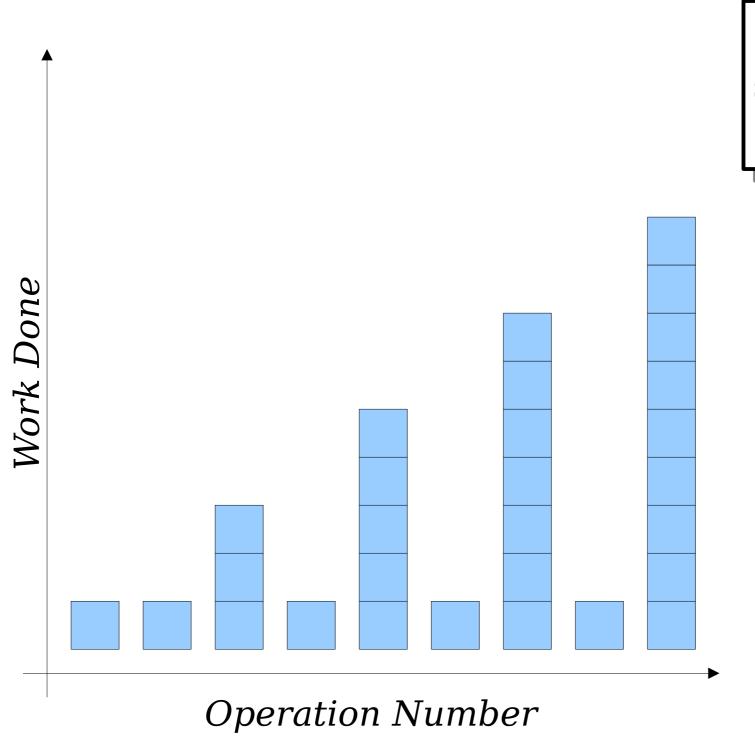


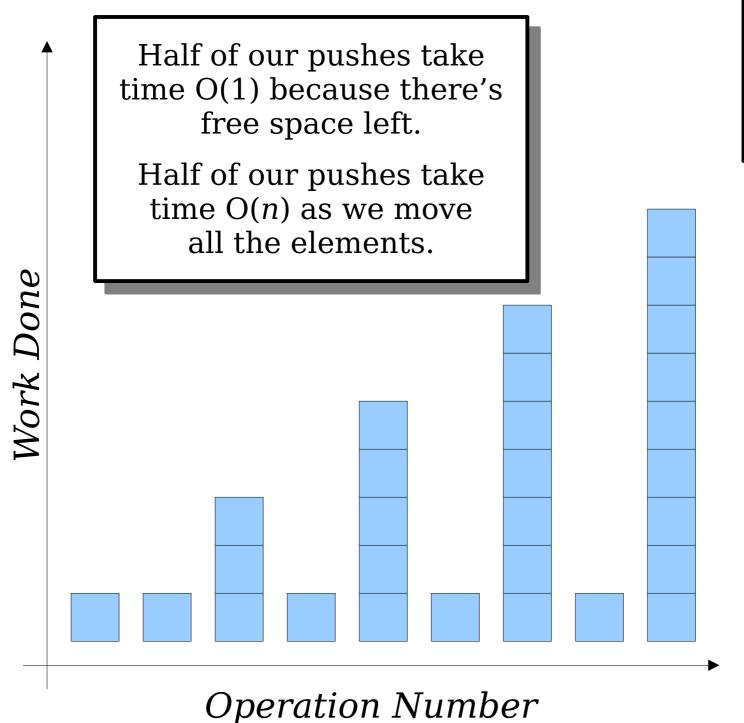


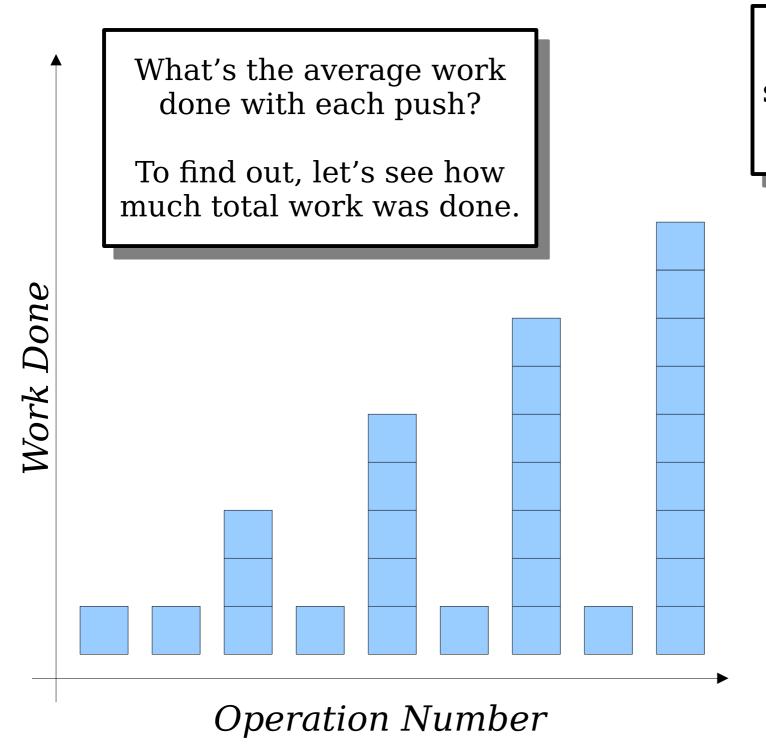
Now, only half the pushes we do will require moving everything to a new array.

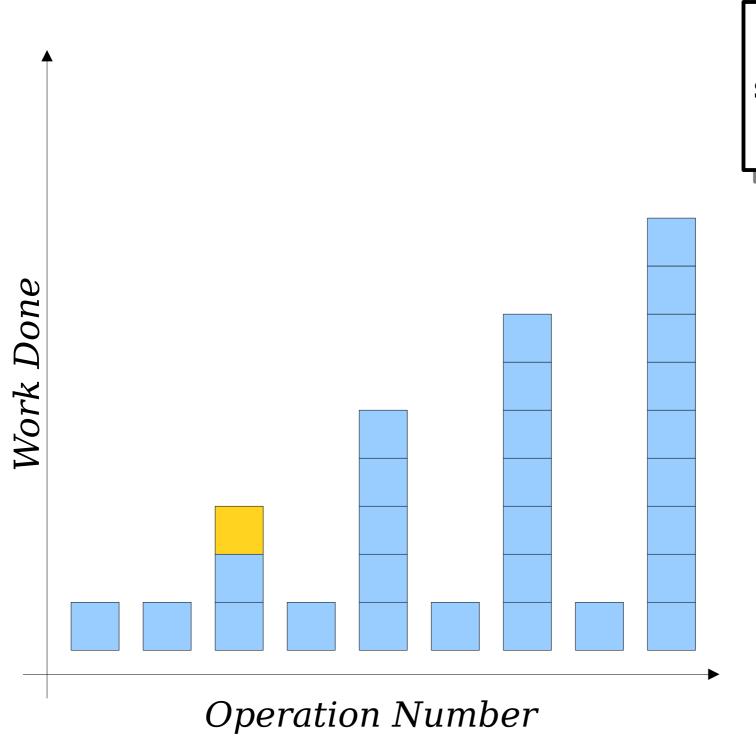


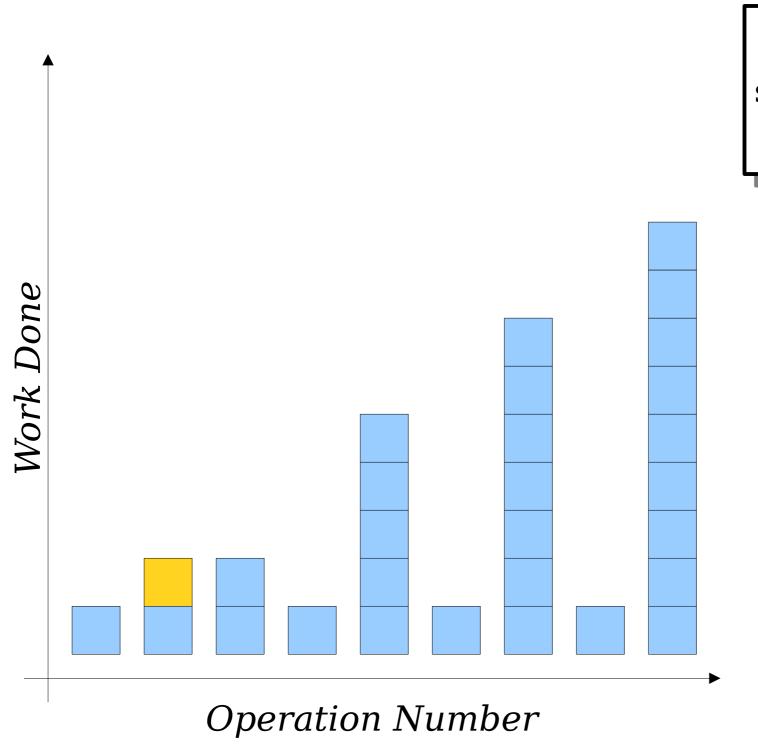
Operation Number

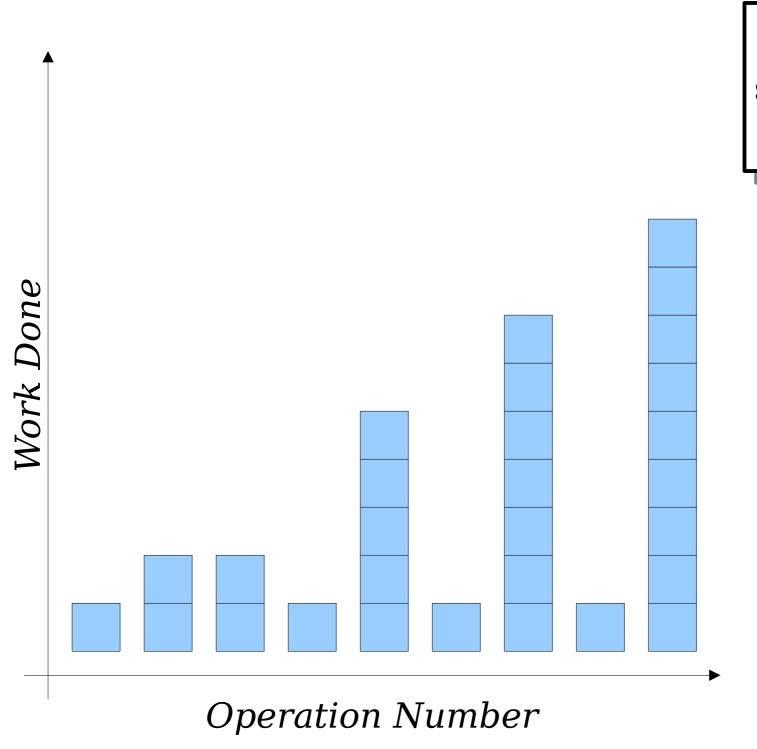


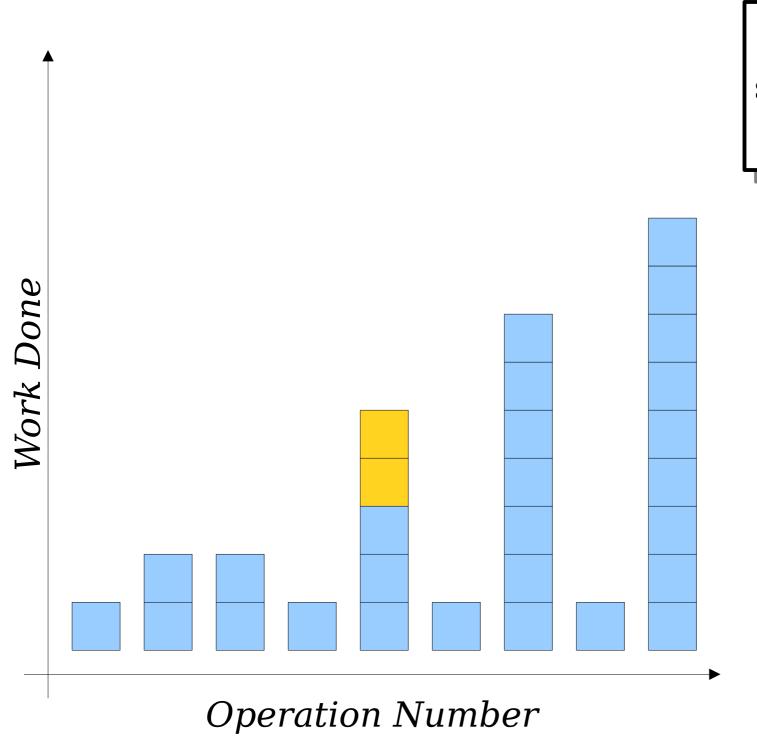


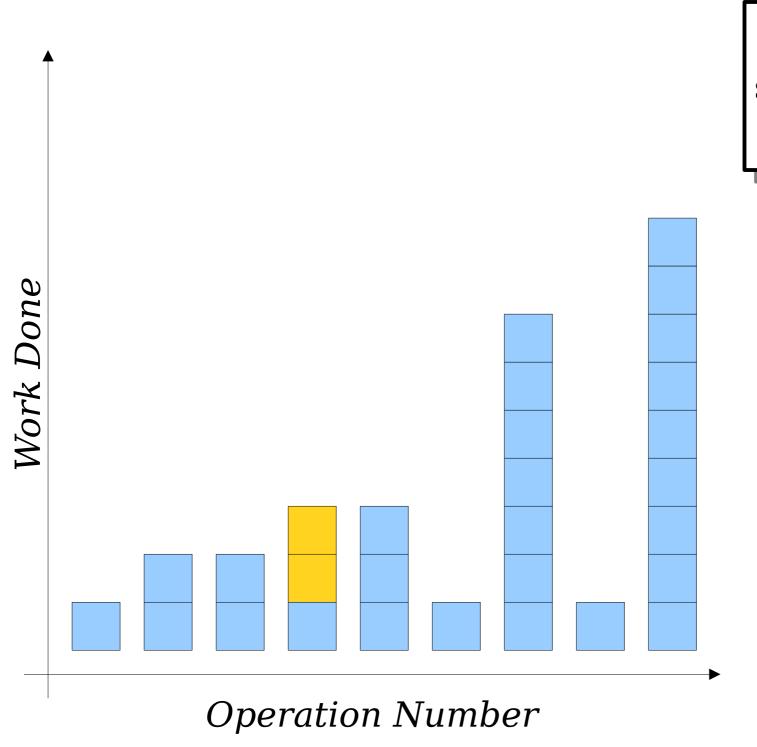


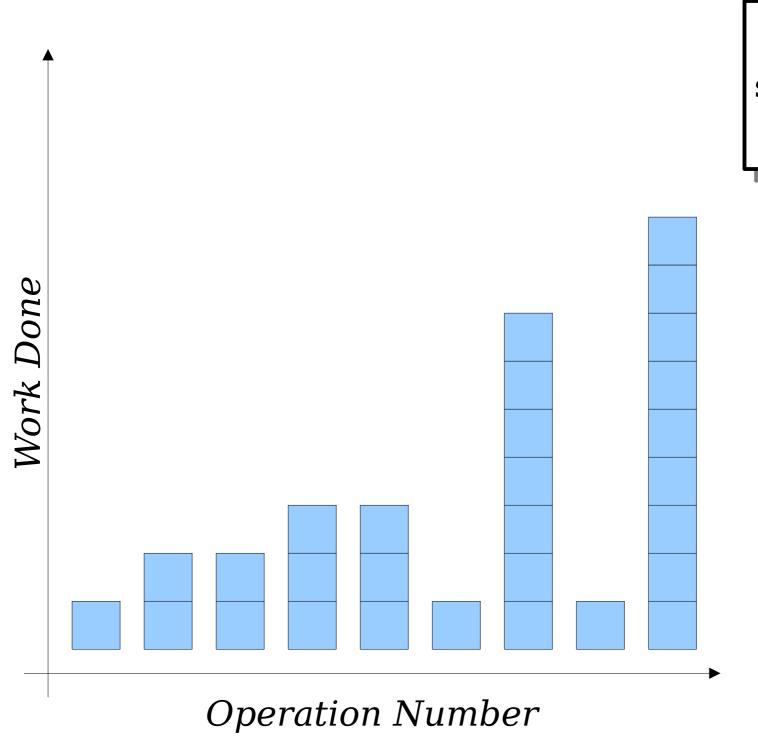


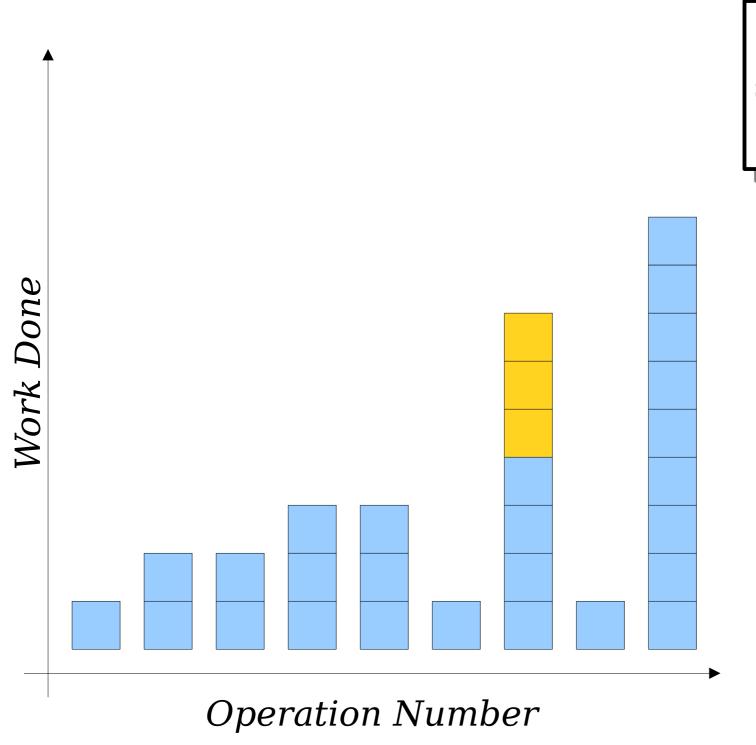


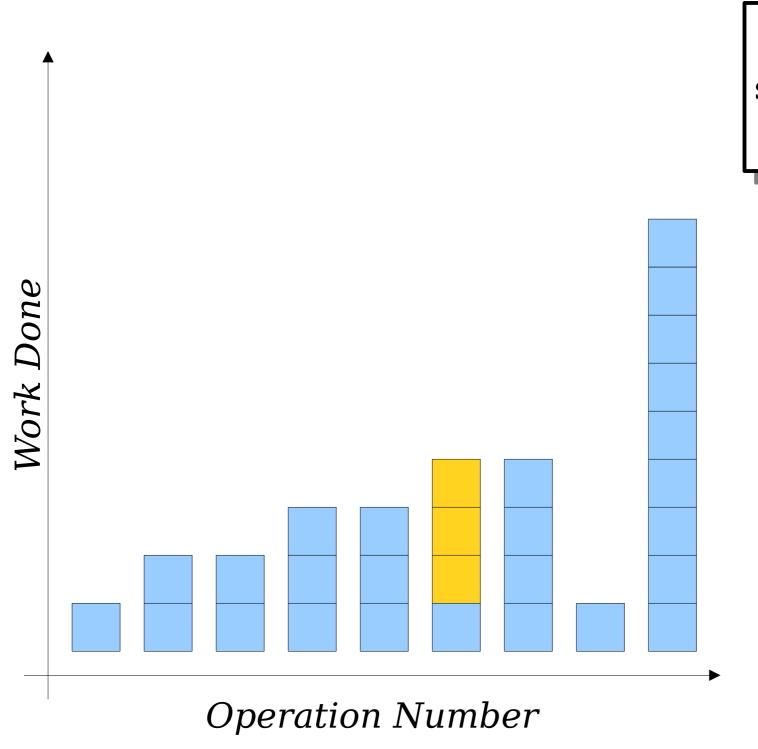


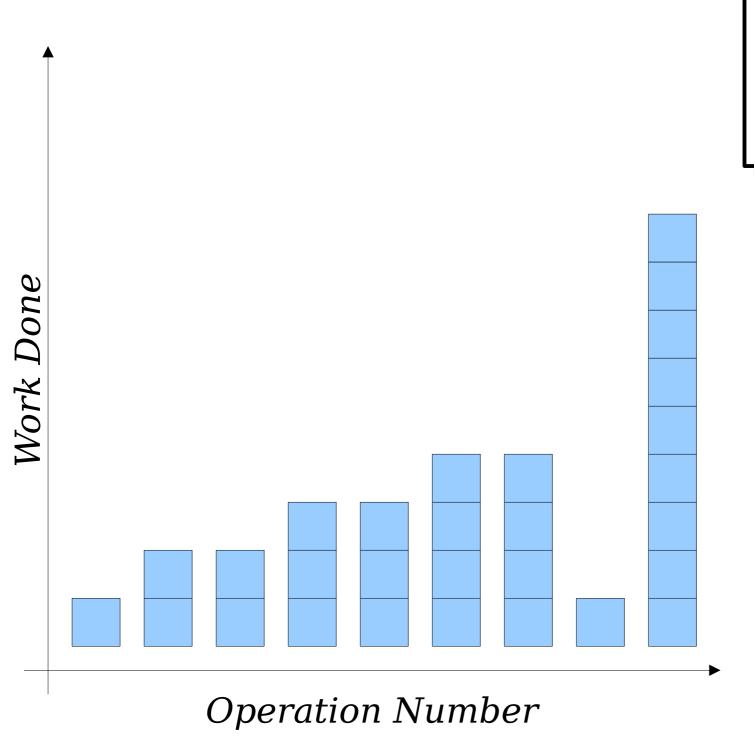


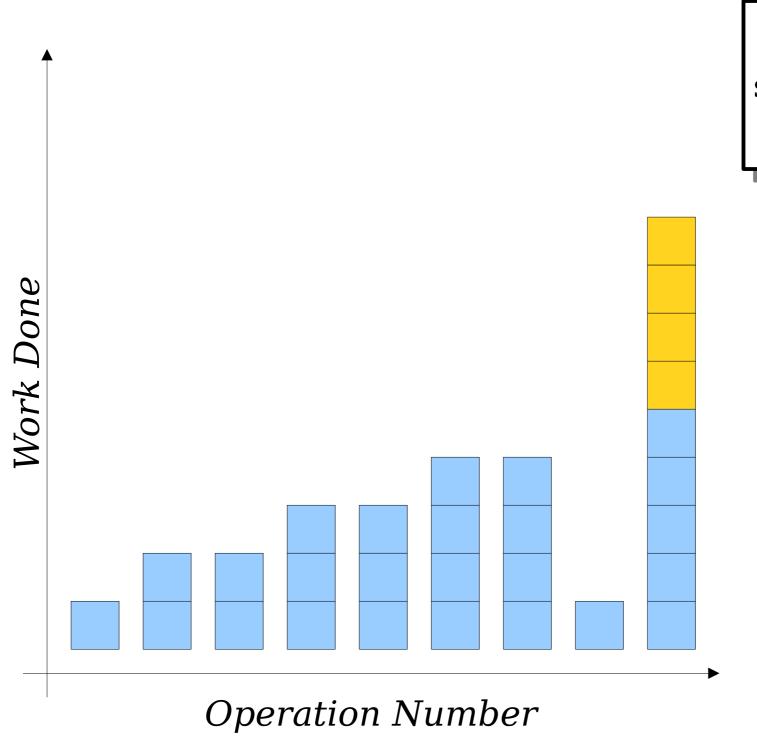


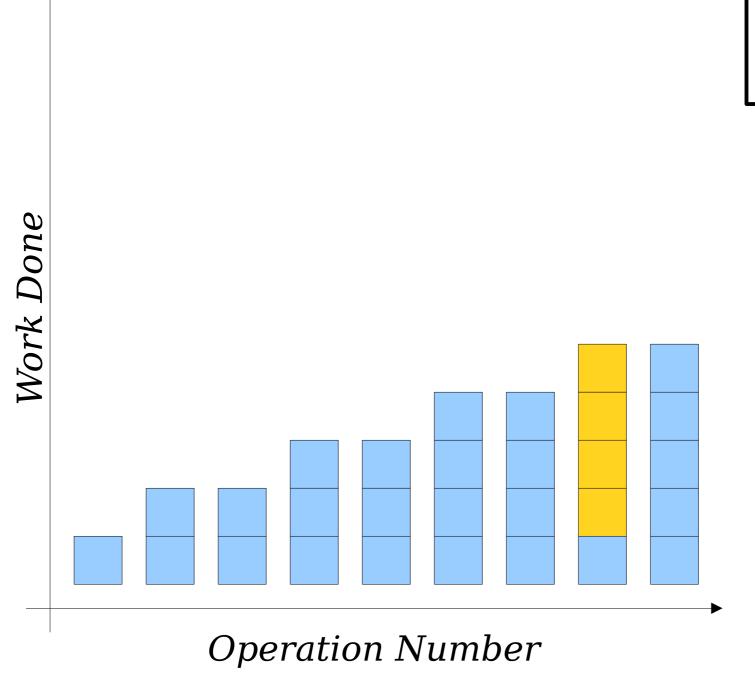


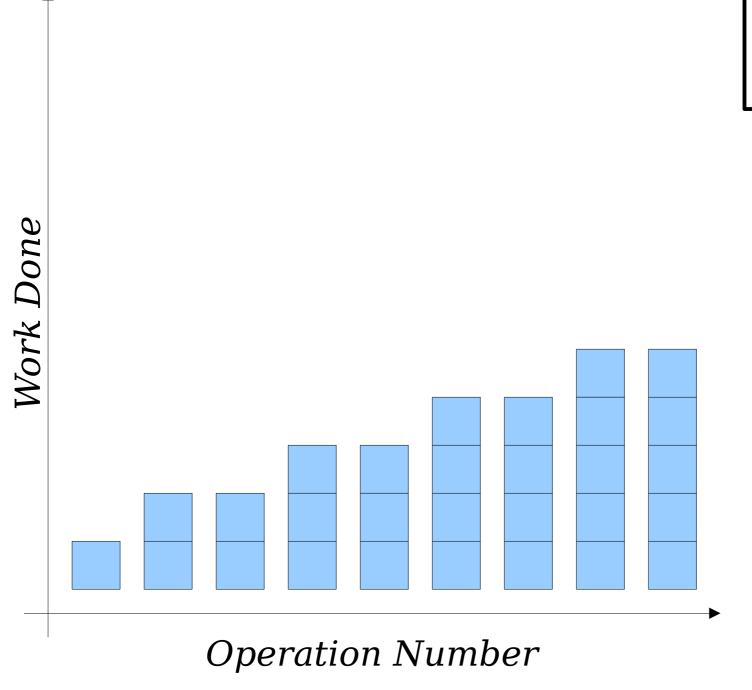


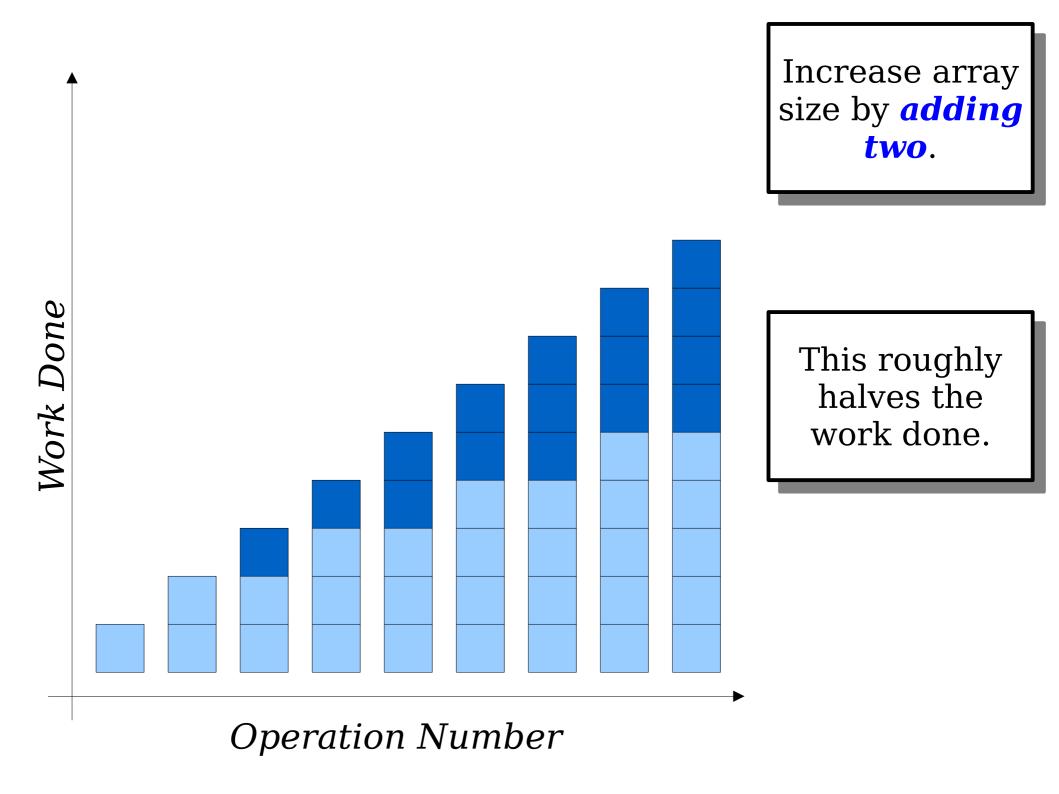


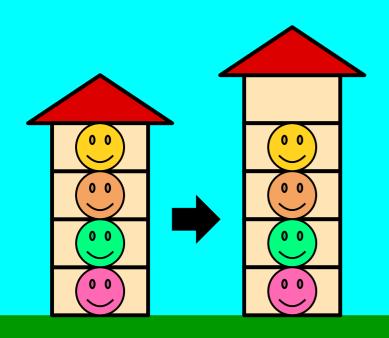


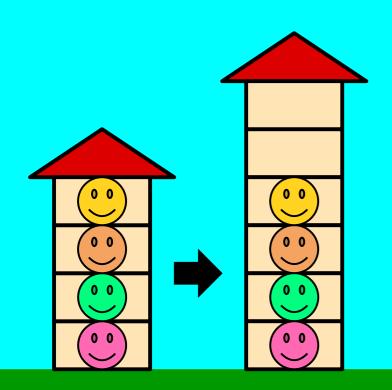


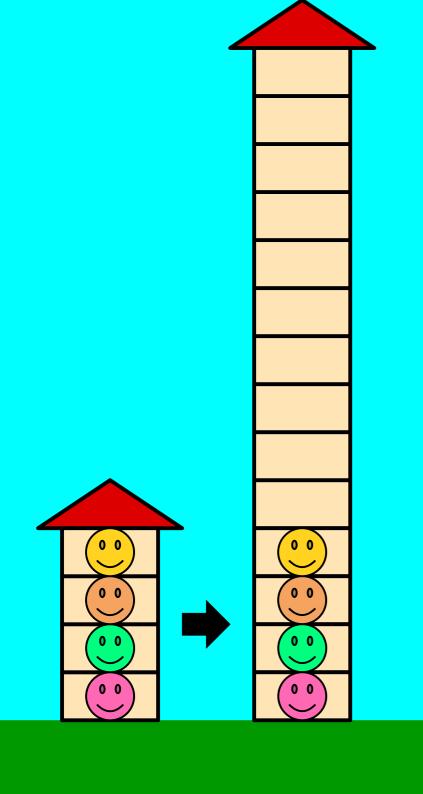






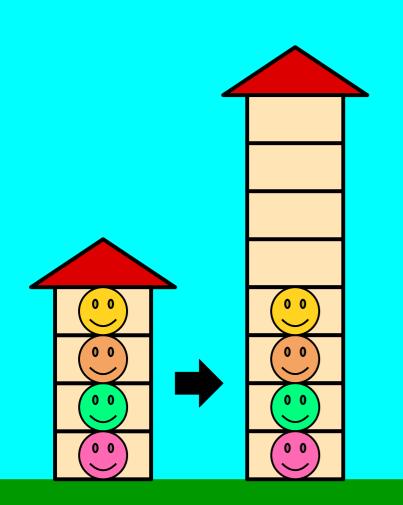






If we make the new array too big, we're might not make use of all the new space.

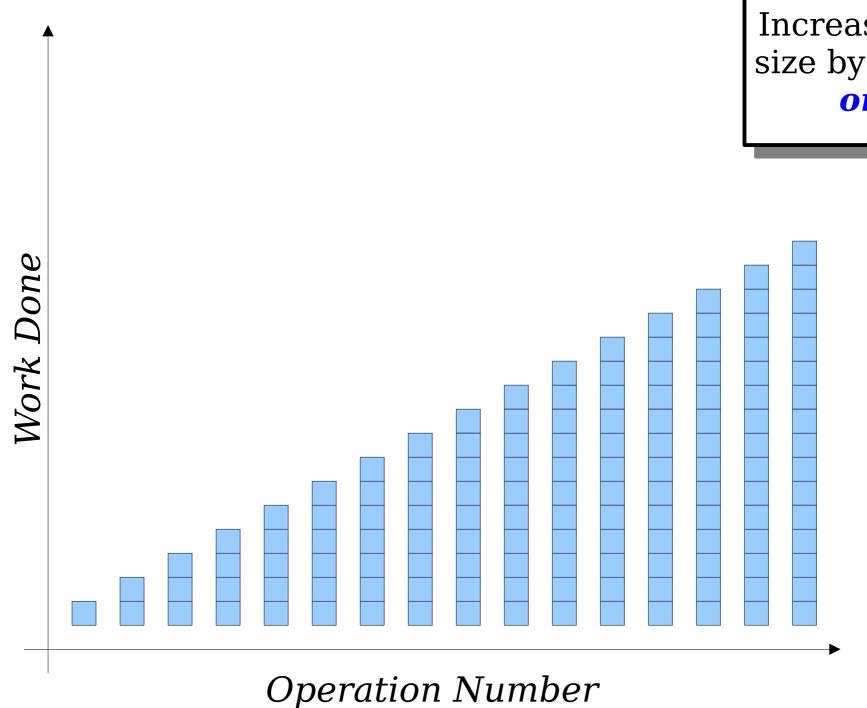
What's a good compromise?



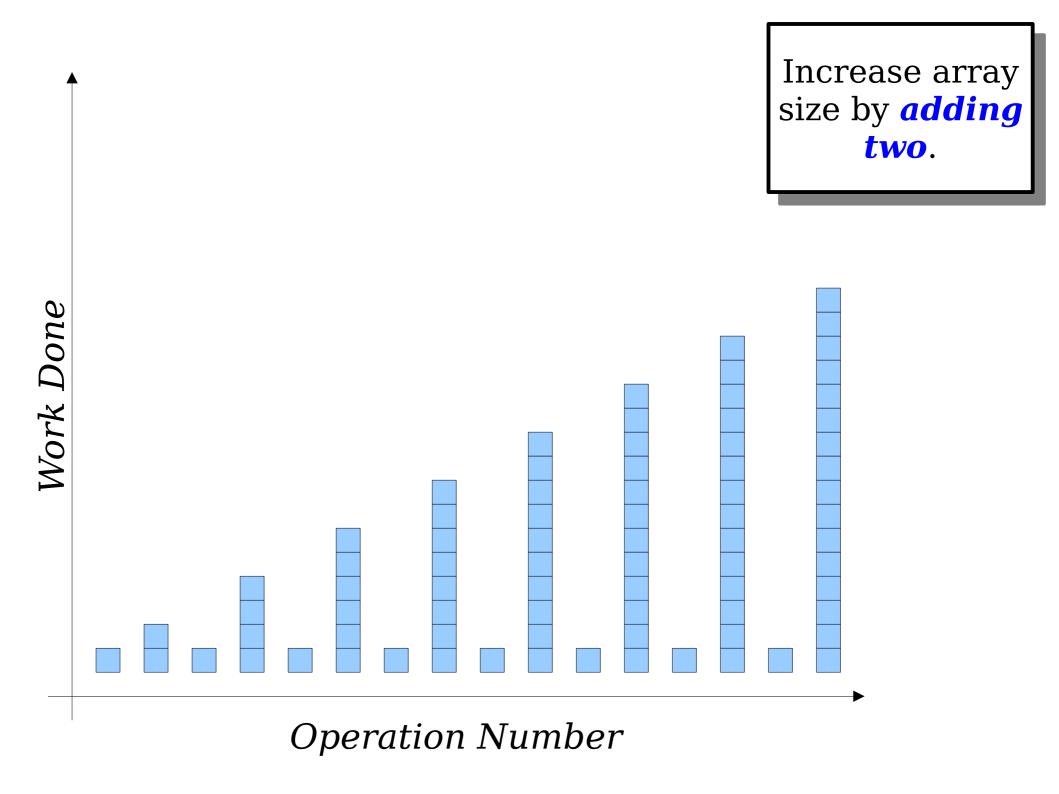
Idea: Make the new array twice as big as the old one.

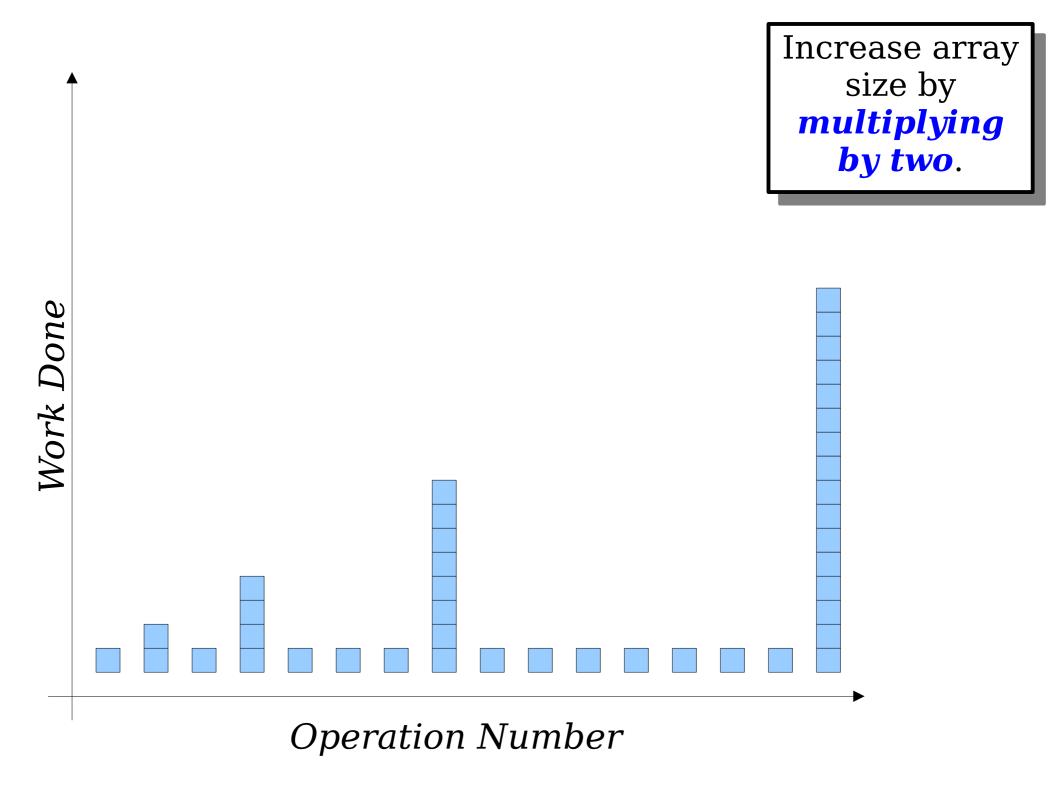
This gives us a lot of free space, and we never use more than twice the space we need.

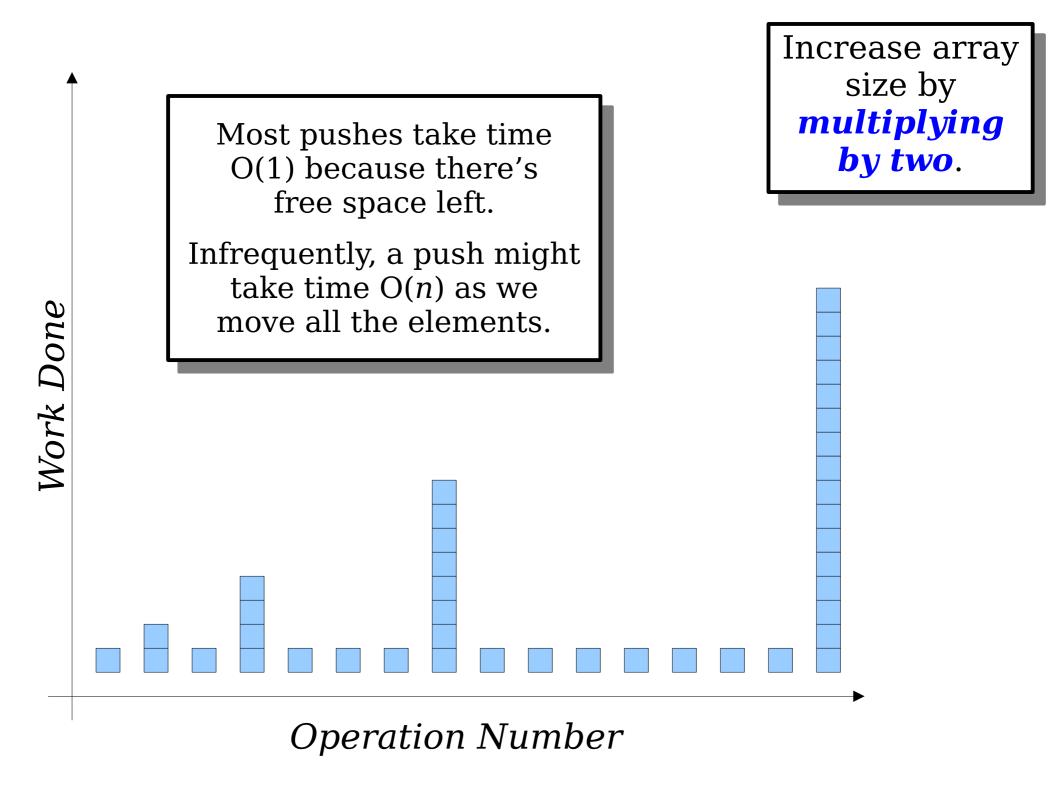
How do we analyze this?

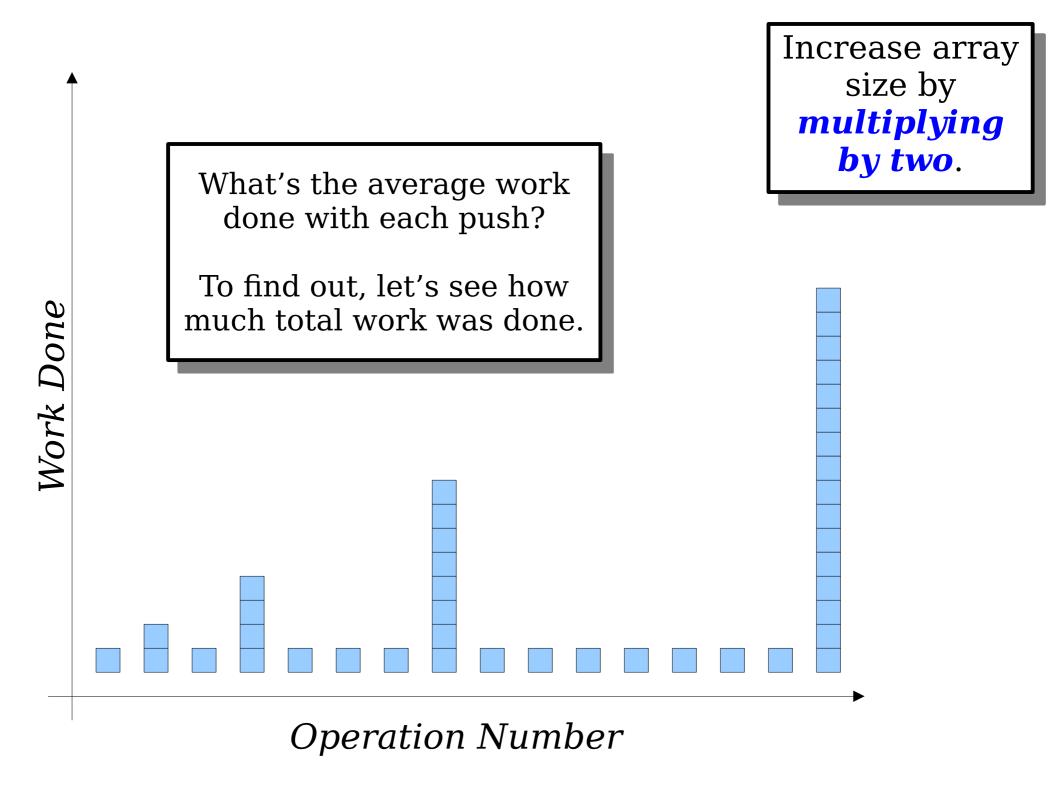


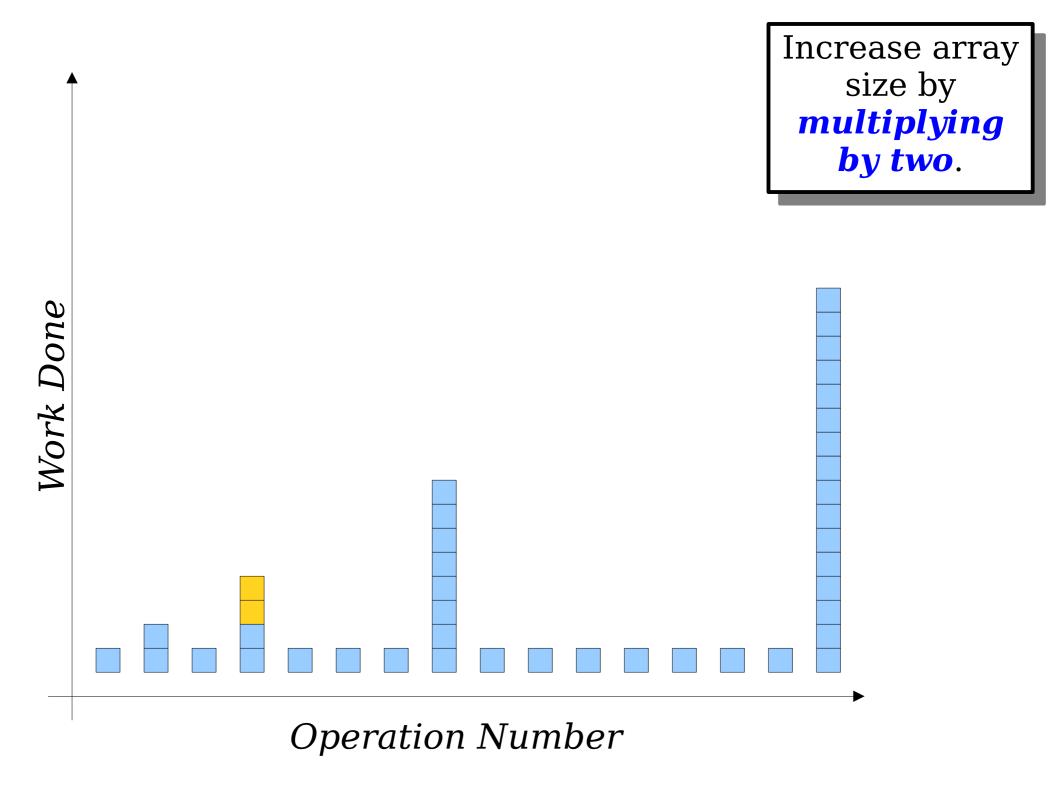
Increase array size by *adding one*.

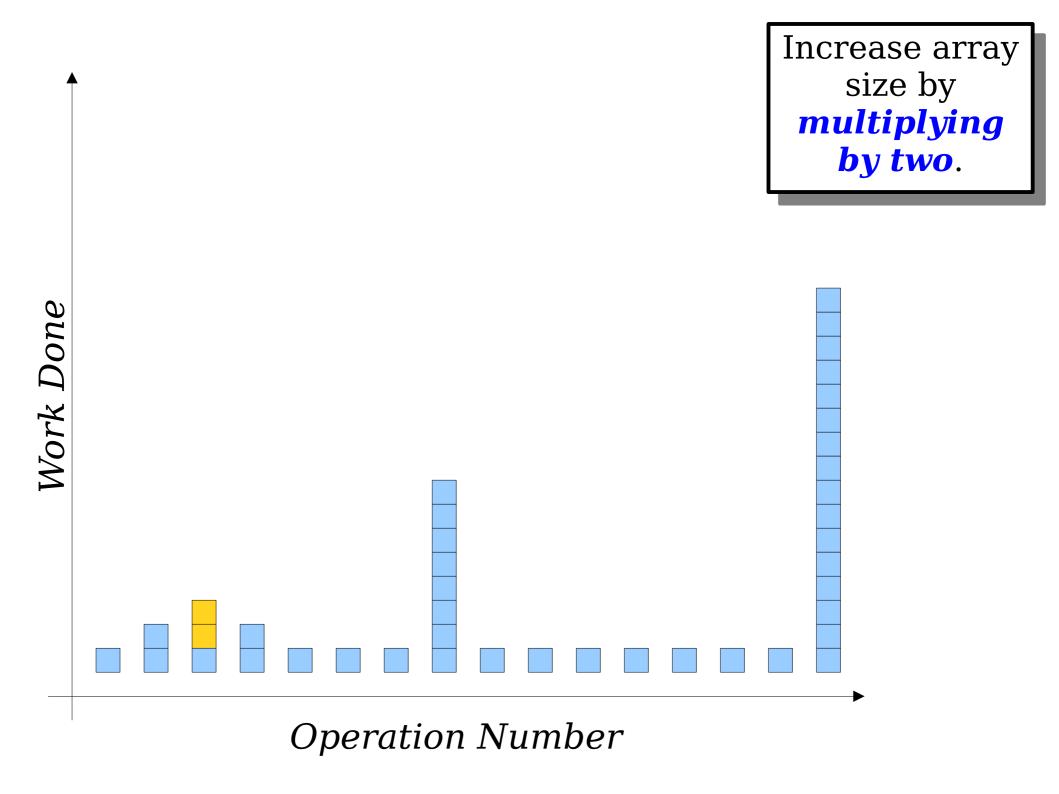


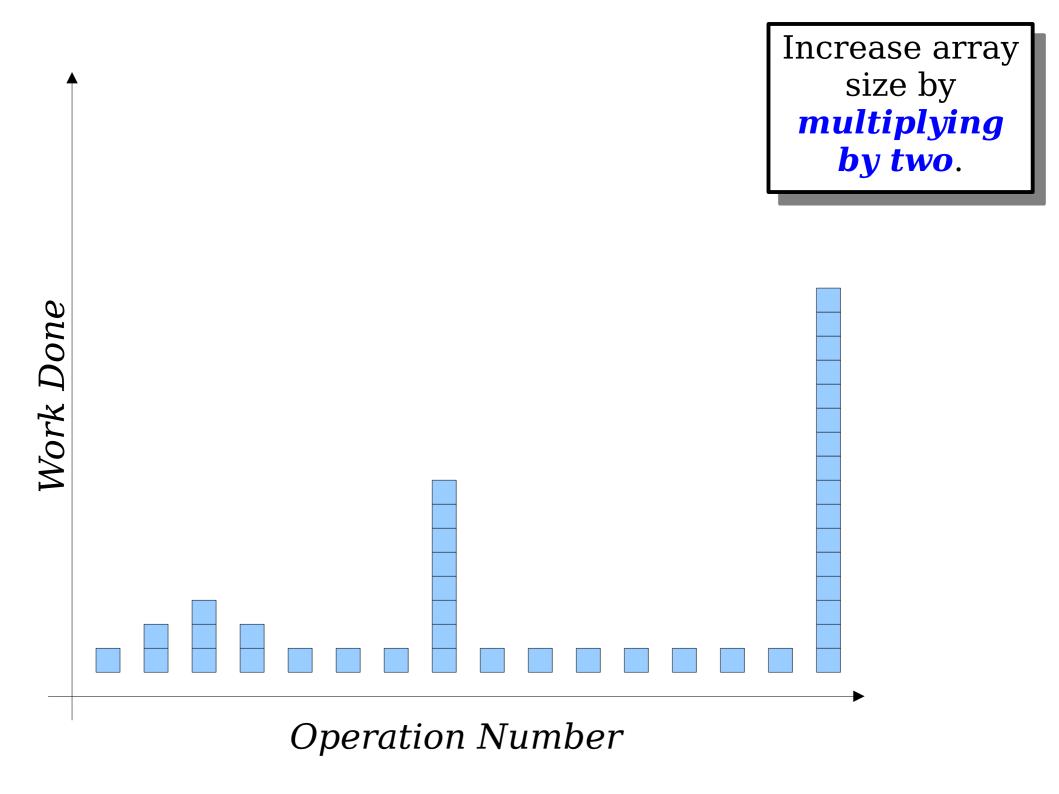


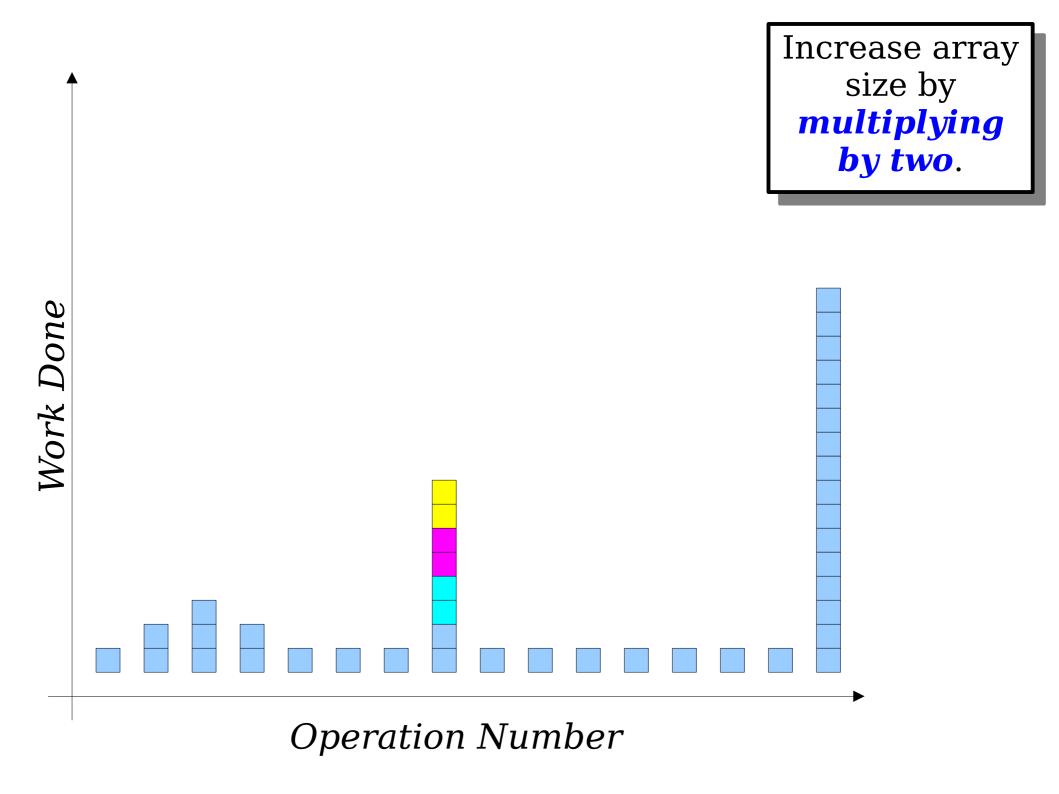


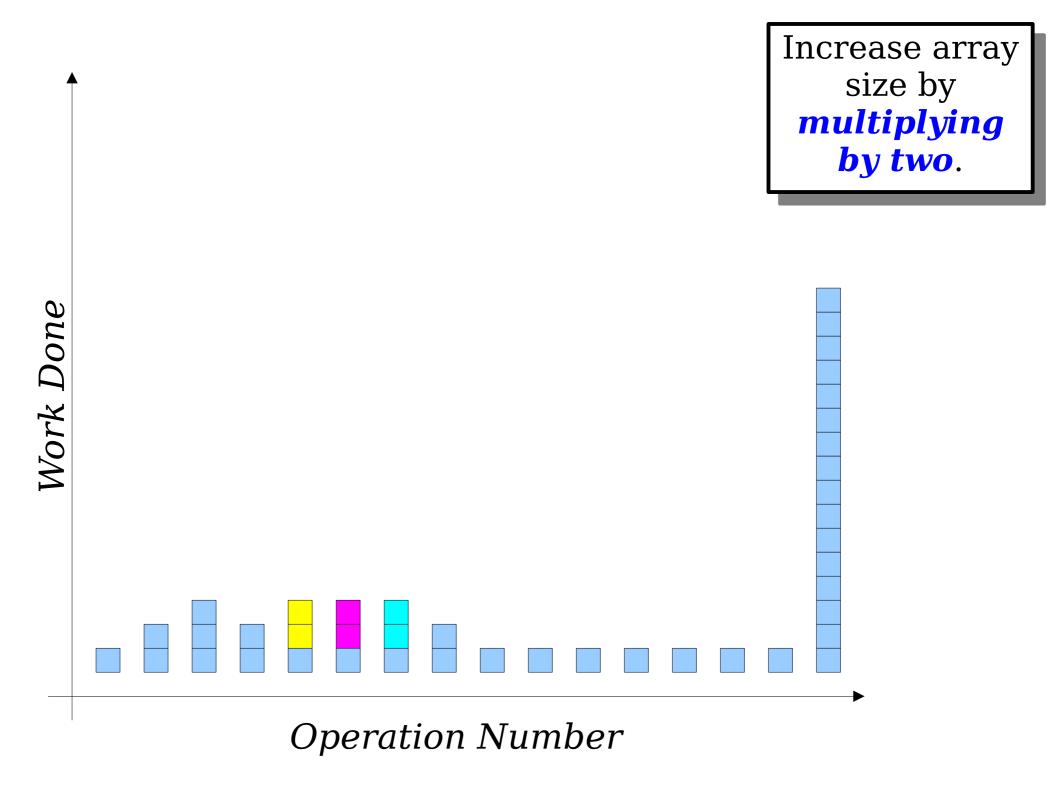


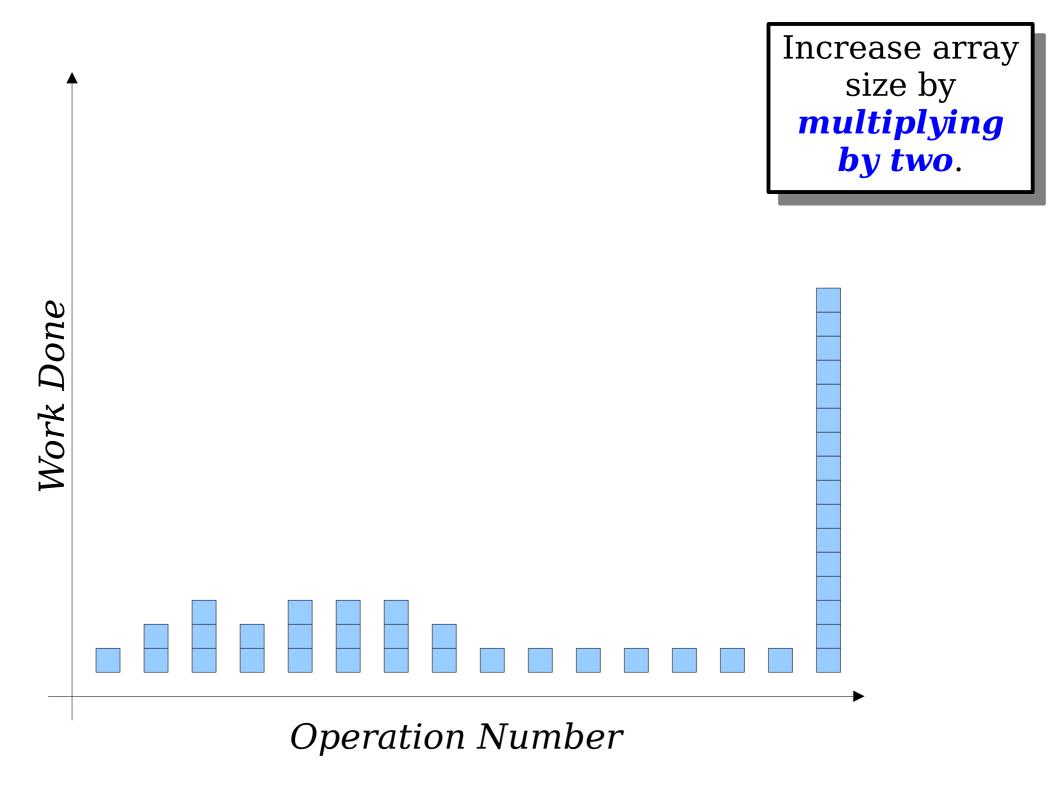


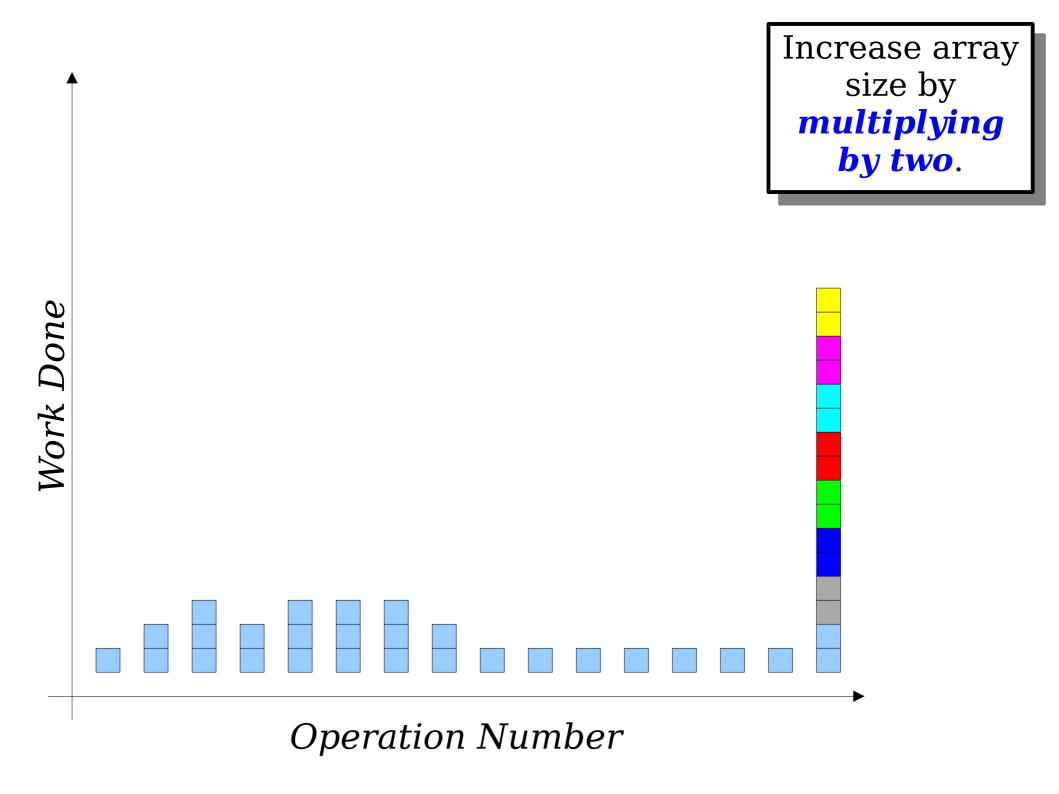




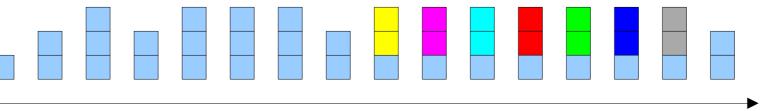




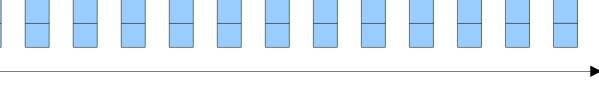




Increase array size by multiplying by two.



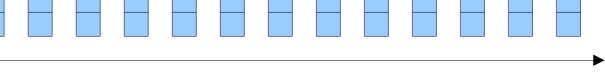
Increase array size by multiplying by two.



Increase array size by multiplying by two.

Average cost of a push: **O(1)**.

Total cost of doing n pushes: O(n).



Operation Number

Amortized Analysis

- The analysis we have just done is called an amortized analysis.
- We reason about the total work done by allowing ourselves to backcharge work to previous operations, then look at the "average" amount of work done per operation.
- In an amortized sense, our implementation of the stack is extremely fast!
- This is one of the most common approaches to implementing Stack (and Vector, for that matter).

Summary for Today

- We can make our stack grow by creating new arrays any time we run out of space.
- Growing that array by one extra slot or two extra slots uses little memory, but makes pushes expensive (average cost O(n)).
- Doubling the size of the array when we run out of space uses more memory, but makes pushes cheap (amortized cost O(1)).
- In practice, it's worth paying this slight space cost for a marked improvement in runtime.

Your Action Items

Read Chapter 11 and Chapter 12.1

 There's a lot of useful information there about dynamic memory allocation and class design.

• Start Assignment 5.

- Slow and steady progress is the name of the game here.
- Ask for help if you need it! That's what we're here for.

Next Time

- No Class Monday
- Then, When We Get Back...
 - Hash Functions
 - A magical and wonderful gift from the world of mathematics.
 - Hash Tables
 - How do we implement Map and Set?