# Formal Methods and Functional Programming

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#### Abstract

This document should give an overview over the types of exercises in the FMFP course and how to solve them. It also contains parts of theory and an overview of Haskell.

There is no guarantee for correctness or completeness, please refer to the course material.

Main sources are the course material and material provided by the course TA Max Schlegel on <a href="https://n.ethz.ch/~mschlegel/fmfp22/">https://n.ethz.ch/~mschlegel/fmfp22/</a>

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# **Functional Programming**

# 1 Haskell

Credits: Big parts of this section are copied from/inspired by https://n.ethz.ch/~mschlegel/fmfp22/, hence credits go to Max

#### 1.1 Basics

```
-- Basic function
-- Declaration, comparable to int mul(int a, int b){} in Java
mul :: Int -> Int -> Int
mul a b = a + b -- Definition
-- function composition
f(g x) = f.g x
-- dollar sign:
f  x = f x
f $ map g xs = f (map g xs) -- to avoid parentheses
-- functions can also be arguments
filter :: (a->Bool) -> [a] -> [a] -- first arg: function taking a returning Bool
-- Pattern matching
fib :: Int -> Int
fib 0 = 0
fib 1 = 1
fib n = fib (n-1) + fib (n-2)
-- Guards
myAbs :: Int -> Int
myAbs x
    | x < 0 = -x
    | otherwise = x
-- where
f :: Int -> Int
f x = 1 + magic
    where magic = sqrt x
-- let <def> in <expr> equal to <expr> where <def>
f :: Int -> Int
f x = (let magic = sqrt x in 1 + magic)
-- case expression (pattern matching)
case expression of pattern1 -> result1
                   pattern2 -> result2
div1byx :: Double -> Double
div1byx = case x of 0 \rightarrow 0.0
                    n \rightarrow 1/n
-- if else
if b then x else y -- returns either x or y
f x = if (prime x) then "PRIME" else "NOT"
1.2
    \operatorname{Lists}
[] -- empty list
x:xs -- first element is x, xs is rest of list
[a,b,c] -- syntactic sugar for a:b:c:[]
-- Basic pattern matching
f = 0
```

```
f (x:xs) = 2 + f xs
-- [1..x]
[1..4] -- [1,2,3,4]
[1,3..10] -- [1,3,5,7,9]
[5, 4..1] -- [5,4,3,2,1]
[5..1] -- []
[1,2...] -- [1,2,...], used with lazy evaluation
-- List comprehensions
[f x | x <- list , guard_1, ..., guard_n]
[2*x | x <- [1..20], x `mod` 2 == 1] -- [2,6,10,..38]
[(1,r)| 1 <- "abc", r <- "xyz"] -- all comb. of characters in "abc" & "xyz"
-- Quick sort, very pretty
q (p:xs) = q [x | x <- xs, x <= p] ++ [p] ++ q [x | x <- xs, x > p]
```

#### 1.3 Prelude functions

```
-- Basics
head [1,2,3] -- 1 :: Int
tail [1,2,3] -- [2,3] :: [Int]
last [1,2,3] -- 3 :: Int
init [1,2,3] -- [1,2] :: [Int]
length [1,2,3] -- 3 :: Int
take 3 [1,2,3,4,5] -- [1,2,3] :: [Int]
drop 3 [1,2,3,4,5] -- [4,5] :: [Int]
reverse [1,2,3] -- [3,2,1] :: [Int]
maximum [1,2,3] -- 1 :: Int
minimum [1,2,3] -- 3 :: Int
sum [1,2,3,4] -- 10 :: Int
product [1,2,3,4] -- 24 :: Int
4 `elem` [1,2,3] -- False
-- More interesting
zip :: [a] -> [b] -> [(a,b)]
zip [1, 2] ['a', 'b'] == [(1, 'a'), (2, 'b')]
filter :: (a->Bool) -> [a] -> [a]
filter odd [1, 2, 3] -- [1,3]
map :: (a -> b) -> [a] -> [b]
map f [x1, x2, ..., xn] == [f x1, f x2, ..., f xn]
zipWith :: (a->b->c) -> [a] -> [b] -> [c]
zipWith f [x1,x2,x3..] [y1,y2,y3..] == [f x1 y1, f x2 y2, f x3 y3..]
-- right associative
foldr :: (a -> b -> b) -> b -> [a] -> b
foldr f z [] = z
foldr f z (x:xs) = f x (foldr f z xs)
foldr f z (a:b:c:[]) = f a (f b (f c (f z [])))
foldr (+) 0 [1..4] =
-- left associative
fold1 :: (a -> b -> b) -> b -> [a] -> b
foldr f z [] = z
foldl f z xs = foldl f z . toList
foldl f z (a:b:c:[]) = f (f a (f b)) c
-- returns longest prefix of elements satisfying p and corresponding remainder of list
span :: (a \rightarrow Bool) \rightarrow [a] \rightarrow ([a], [a]) -- span p xs
span (< 3) [1,2,3,4,1,2,3,4] -- ([1,2], [3,4,1,2,3,4])
curry :: ((a,b)->c) -> a -> b -> c
```

```
curry f a b = f (a,b)
uncurry :: (a->b->c) -> (a,b) -> c
uncurry f (x,y) = f x y
```

# 1.4 Algebraic data types

Define new types

```
-- Structure: on the right side are value constructors
-- data type can have one of those different values
data keyword = constr1 | constr2 | ... | constrn
-- Option can be simple types
data Bool = False | True
-- New value constructors can be defined
-- Circle takes three floats as fields, rectangle 4
data Shape = Circle Float Float Float | Rectangle Float Float Float Float
-- ghci> :t Circle
Circle :: Float -> Float -> Float -> Shape
-- functions for data types
surface :: Shape -> Float
surface (Circle _ _ r) = pi * r ^ 2
surface (Rectangle x1 y1 x2 y2) = (abs $x2 - x1) * (abs $y2 - y1)
-- has argument of type a or b
data myType a b = myConstr a | myOtherConstructor b
-- definitions can be recursive
data myList a = Empty | Cons a (MyList a)
-- tree
data Tree t = Leaf | Node t (Tree t) (Tree t)
-- deriving keyword
-- typeclasses like Eq, Ord, Enum, Bounded, Show, Read can function as "interfaces"
-- Example: == and /= and can now be used to compare values
data Vector = Vector Int Int Int deriving (Eq. Show)
-- instance keyword
data TrafficLight = Red | Yellow | Green
instance Eq TrafficLight where
   Red == Red = True
    Green == Green = True
   Yellow == Yellow = True
    _ == _ = False
instance Show TrafficLight where
    show Red = "Red light"
    show Yellow = "Yellow light"
    show Green = "Green light"
-- fold for data types
-- data type:
data DType = C1 ... | C2 ... | ... | CN ...
-- fold
foldDType :: foldC1 -> foldC2 -> ... -> foldCN -> DType -> b
-- example
data Prop a = Var a | Not (Prop a) | And (Prop a) (Prop a) | Or (Prop a) (Prop a)
foldProp :: (a->b) -> (b->b) -> (b->b->b) -> (b->b->b) -> (Prop a) -> b
foldProp fVar fNot fAnd fOr prop = go prop
```

```
where
    go (Var v) = fVar v
    go (Not v) = fNot (go v)
    go (And v w) = fAnd (go v) (go w)
    go (Or v w) = fOr (go v) (go w)
```

# 2 Evaluation strategies

Lazy evaluation strategy of application t1 t2

- 1. Evaluate t1
- 2. The argument t2 is substituted in t1 without being evaluated
- 3. No evaluation inside lambda abstractions. In other words, in an abstraction \... -> f t, then f t is not evaluated

Eager evaluation strategy of application t1 t2

- 1. Evaluate t1
- 2. t2 is evaluated prior to substitution in t1
- 3. Evaluation is carried out inside lambda abstractions

# 2.1 Lazy evaluation in Haskell

Haskell: Lazy Evaluation

- argument only evaluated when no other steps possible
- left term is evaluated first
- argument made to fit pattern

#### 2.1.1 Sheet 1, Ex. 1

```
fibLouis :: Int -> Int
fibLouis 0 = 1
fibLouis 1 = 1
fibLouis n = fibLouis (n - 1) + fibLouis (n - 2)
fibEva :: Int -> Int
fibEva n = fst (aux n) where
   aux 0 = (0, 1)
   aux n = next (aux (n - 1))
   next (a, b) = (b, a + b)
```

#### Lazy Evaluation of fibLouis 4

```
fibLouis 4 =
fibLouis (4-1) + fibLouis (4-2) =
-- most left term is evaluated first
fibLouis 3 + fibLouis (4-2) =
(fibLouis (3-1) + fibLouis (3-2)) + fibLouis (4-2)
...
((fibLouis 1 + fibLouis (2-2)) + fibLouis (3-2)) + fibLouis (4-2) =
((1 + fibLouis (2-2)) + fibLouis (3-2)) + fibLouis (4-2) =
...
2 + fibLouis 2 =
2 + (fibLouis (2-1) + fibLouis (2-2))
... = 3
```

# Lazy Evaluation of fibEva 4

```
fibEva 4 =
fst (aux 4) =
fst (next (aux (4-1))) =
fst (next (aux 3)) =
fst (next (next (aux (3-1)))) =
fst (next (next (next (aux 2))) =
...
fst (next (next (next (next (0, 1))))) =
fst (next (next (next (1, 0+1)))) =
fst (next (next (0+1, 1+(0+1)))) =
fst (next (1+(0+1), (0+1)+(1+(0+1))))
...
-- pattern (0+1) is repeated
fst ((0+1)+(1+(0+1)), (1+(0+1))+((0+1)+(1+(0+1)))) =
(0+1)+(1+(0+1)) =
1 + (1 + 1) =
```

# 3 Natural Deduction

# 3.1 Parenthesizing formulas

- $\land$  binds stronger than  $\lor$  stronger than  $\rightarrow$
- $\rightarrow$  associates to right;  $\land$  and  $\lor$  to the left
- Negation binds stronger than binary operators
- Quantifiers extend to the right as far as possible: end of line or )

```
\begin{array}{lll} p \vee q \wedge \neg r \rightarrow p \vee q & (p \vee (q \wedge (\neg r))) \rightarrow (p \vee q) \\ p \rightarrow q \vee p \rightarrow r & p \rightarrow ((q \vee p) \rightarrow r) \\ p \wedge \forall x. q(x) \vee r & p \wedge (\forall x. (q(x) \vee r)) \\ \neg \forall x. p(x) \wedge \forall x. q(x) \wedge r(x) \wedge s & \neg (\forall x. (p(x) \wedge (\forall x. ((q(x) \wedge r(x)) \wedge s)))) \end{array}
```

# 3.2 Natural Deduction without quantifiers

If you cannot continue, try to add assumptions by using  $\vee E$ 

#### **3.2.1** Example

**Exercise:** 
$$P = (\neg A) \land (A \lor B) \to B$$
 is a tautology First step: Parenthesizing  $\Rightarrow P \equiv ((\neg A) \land (A \lor B)) \to B$  Let  $\Gamma \equiv (\neg A) \land (A \lor B)$ 

$$\frac{\frac{\Gamma,A \vdash (\neg A) \land (A \lor B)}{\Gamma,A \vdash A \lor B} \stackrel{ax}{\land} ER}{\frac{\Gamma,A \vdash A}{\land} ER} \xrightarrow{\frac{\Gamma,A \vdash (\neg A) \land (A \lor B)}{\Gamma,A \vdash B} \neg E} \stackrel{ax}{\land} EL}{\frac{\Gamma,B \vdash B}{\vdash (\neg A) \land (A \lor B) \rightarrow B} \rightarrow I}$$

# 3.3 Natural Deduction with quantifiers

If you cannot continue, try to add assumptions by using  $\exists E$  Always check side conditions

# 3.3.1 Sheet 2, Ex. 3b

**Exercise**: Proof 
$$(\exists x.P \land Q) \rightarrow ((\exists x.P) \lor (\exists x.Q))$$
  
Let  $\Gamma \equiv \exists x.P \land Q, P \land Q$ 

$$\frac{\frac{\overline{\Gamma \vdash P \land Q}}{\Gamma \vdash P} \stackrel{ax}{\exists I}}{(\exists x.P \land Q) \vdash (\exists x.P \land Q)} \stackrel{ax}{\Rightarrow ax} \frac{\overline{\Gamma \vdash P \land Q}}{\frac{\Gamma \vdash \exists x.P}{\Gamma \vdash \exists x.P}} \stackrel{ax}{\exists I} \frac{\overline{\Gamma \vdash P \land Q}}{\frac{\Gamma \vdash Q}{\Gamma \vdash \exists x.Q}} \stackrel{ax}{\Rightarrow I} \frac{(\exists x.P \land Q) \vdash (\exists x.P) \land (\exists x.P) \land (\exists x.Q)}{\land I}}{\frac{(\exists x.P \land Q) \vdash (\exists x.P) \land (\exists x.Q)}{\vdash (\exists x.P \land Q) \rightarrow ((\exists x.P) \land (\exists x.Q))} \rightarrow I} \exists E^{**}$$
on OK: x not free in  $\exists x.P. \land Q$  nor  $(\exists x.P) \lor (\exists x.Q)$ 

# Binding and $\alpha$ -conversion

Bound: Each occurrence of a variable is bound or free: A variable occurrence x in a formula A is bound if x occurs within a sub formula B of A of the form  $\exists x.B$  or  $\forall x.B$ .

Alpha-conversion: bound variables can be renamed to names not yet used

# Examples

•		$\alpha$ -convertible
$\forall x. \exists y. p(x,y)$	$\forall y. \exists x. p(y, x)$	yes
$\exists z. \forall y. p(z, f(y))$	$\exists y. \forall y. p(y, f(y))$	no
$(\forall x. p(x)) \lor (\exists x. q(x))$	$(\forall z.p(z)) \lor (\exists y.q(y))$	yes
$p(x) \to \forall x. p(x)$	$p(y) \to \forall y. p(y)$	no

#### 5 Induction

For proofs with [], 0. Leaf or similar, you may first have to proof a generalised statement with induction and then simply plug in your values.

#### 5.1Induction on natural numbers

Induction scheme:

$$\frac{\Gamma \vdash P[n \mapsto 0] \qquad \Gamma, P[n \mapsto m] \vdash P[n \mapsto m+1]}{\Gamma \vdash \forall n : Nat.P} m \text{ not free in P}$$

#### 5.1.1 Sheet 3, Ex. 1b

```
(Important parts/"framework" of proof)
Lemma: \forall n : Nat \text{ aux n} = \text{(fibLouis n, fibLouis (n+1))}
Proof. Let P:=(aux n = (fibLouis n, fibLouis (n+1)))
Base case. Show P[n \mapsto 0]
     aux 0 = \dots
         = (fibLouis 0, fibLouis (0+1))
Step case: Let m: Nat be arbitrary.
\mathbf{I.H.} : P[n \mapsto m]
Show P[n \mapsto (m+1)].
Assume aux m = (fibLouis m, fibLouis (m+1))
     aux (m+1) = ...
              = (fibLouis (m+1), fibLouis ((m+1)+1))
```

<sup>\*\*</sup> side condition OK: x not free in  $\exists x.P \land Q$  nor  $(\exists x.P) \lor (\exists x.Q)$ 

# 5.2 Induction on lists

Induction scheme:

$$\frac{\Gamma \vdash P[xs \mapsto []] \qquad \Gamma, P[xs \mapsto ys] \vdash P[xs \mapsto (y:ys)]}{\Gamma \vdash \forall xs :: [a].P} \ y, ys \text{ not free in P}$$

#### 5.2.1 Sheet 3, Ex. 2b

```
(Important parts/"framework" of proof)
Lemma: foldr (:) [] xs = xs
```

*Proof.* Let P:= (foldr (:) [] xs = xs).

We prove by induction over lists that  $\forall xs :: [a]$ . P holds.

Base case. Show  $P[xs \mapsto []]$ 

```
foldr (:) [] = []
```

Step case: Let y::a, ys::[a] be arbitrary.

 $\mathbf{I.H.:} \; \texttt{P[xs} \; \mapsto \; \texttt{ys]}$ 

Show  $P[xs \mapsto (y:ys)]$ 

Assume foldr (:) [] ys = ys

#### 5.2.2 Sheet 4, Ex. 1

```
(Important parts/"framework" of proof)
```

*Proof.* Let P' := rev (xs ++ rev ys') = ys' ++ rev xs. We show that  $\forall$  ys'.  $\forall$  xs..

Fix an arbitrary ys and let  $P := [ys' \mapsto ys]$ . We show that  $\forall xs \ P$ .

(This implies ∀ys'.∀xs.P')

Base case: We show  $P[xs \mapsto []]$ 

Step case: Let z::a, zs::[a] be arbitrary.

Fix arbitrary y::a, ys::[a].

We show  $P[xs \mapsto (z:zs)]$ .

#### 5.3 Induction on Trees

Induction scheme:

$$\frac{\Gamma \vdash P[x \mapsto \operatorname{Leaf}] \qquad \Gamma, P[x \mapsto l], P[x \mapsto r] \vdash P[x \mapsto \operatorname{Node} \ a \ l \ r]}{\Gamma \vdash \forall xs :: \operatorname{Tree} \ t.P} \ a, l, r \ \operatorname{not} \ \operatorname{free} \ \operatorname{in} \ \operatorname{P}$$

```
5.3.1 Sheet 6, Ex. 1
```

```
(Important parts/"framework" of proof)
mapTree f Leaf = Leaf
mapTree f (Node x t1 t2) = Node (f x) (mapTree f t1) (mapTree f t2)
For arbitrary f :: a \rightarrow b and g :: b \rightarrow c
\forall t :: Tree a. mapTree g (mapTree f t) = mapTree (g . f) t
Proof. Let f :: a -> b and g :: b -> c be arbitrary functions.
Let P := mapTree g (mapTree f t) = mapTree (g . f) t, and we prove by induction that \forall t :: (Tree
a).P
Base Case: Show P[t \mapsto Leaf]
         mapTree g (mapTree f Leaf) = ..
                 = mapTree (g . f) Leaf
Step case: Let x::a, 1::Tree a, r::Tree a be arbitrary.
I.H.1: P[t \mapsto 1]
I.H.2: P[t \mapsto r]
We show P[t \mapsto Node \times l \ r]
         mapTree g (mapTree f (Node x l r)) = \dots
                  = mapTree (g . f) (Node x l r)
```

# 6 Types and typing inference

```
f :: a -> b -> c -> d:
```

- same as f :: a -> (b -> (c -> d)) (arrows are right associative)
- f x y z implies x::a, y::b, z::c
- f.e. f x :: b -> c -> d

# 6.1 Types

- Detect function applications, f.e.  $f x \Rightarrow f::a->b$ , x::a
- Detect prelude functions such as map, filter, foldr etc.
- "Match" types of different function, f.e. f :: (a->b) -> [a] -> b for  $f x \Rightarrow x :: (a->b)$
- Don't forget things like Num a, Eq b => ...

#### 6.1.1 Sheet 5

 $1a \setminus x y z \rightarrow (x y) z$ 

- 1. Three arguments, one return value
- 2. (x y) :: a -> b and z :: a
- 3.  $x :: c \rightarrow (a -> b)$  and y :: c

**2a.4** (.).(.) (the end boss)

1. (.) ::  $(b\rightarrow c) \rightarrow (a\rightarrow b) \rightarrow a \rightarrow c$ 

- 2. Rewrite: (.).(.) = .(.)(.) = f g h
- 3. Definition of (.):

4. g is first argument of f:

$$g :: b \rightarrow c$$
  
 $\Rightarrow b = n \rightarrow o (I) \text{ and } c = (m \rightarrow n) \rightarrow m \rightarrow o (II)$ 

5. h is first argument of f g:

f g :: 
$$(a->b) -> a -> c$$
  
 $\Rightarrow h :: a -> b$   
 $\Rightarrow a = q -> r (III)$   
 $b = (p->q) -> p -> r (IV)$ 

- 6. (I) and (IV)  $\Rightarrow$  n = p -> q (V) and o = p -> r
- 7. After "taking" two arguments, we have the following type

# 6.2 Typing proof and inference

Solving type inference constraints

- 1. Remove trivial equations like t = t
- 2. Transform equations of form  $\{f(s_0,...,s_k) = g(t_0,...,s_m)\}$  into  $\{s_0 = t_0,...,s_k = t_k\}$  if f = g and k = m, else there is no solution
- 3. Substitute one equation into the others

#### 6.2.1 Sheet 5, Ex. 3

a Proof  $\lambda x$ . (x 1 True, x 0) :: (Int -> Bool -> a) -> (a, Bool -> a): Try to match left and right side with typing rule and apply it, should be straight forward b Infer the type of  $(\lambda x. \lambda y. (y \text{ (iszero } (y x))))$  True

$$\frac{\overline{x:\tau_{1},y:\tau_{2}\vdash y::\tau_{4}\rightarrow\tau_{3}}\ Var^{1}}{\frac{x:\tau_{1},y:\tau_{2}\vdash y\ (\mathbf{iszero}\ (y\ x))::\tau_{3}}{x:\tau_{1}\vdash\lambda y.(y\ (\mathbf{iszero}\ (y\ x)))::\tau_{0}}\ Abs^{1}}{\frac{\vdash\lambda x.\lambda y.(y\ (\mathbf{iszero}\ (y\ x)))::\tau_{1}\rightarrow\tau_{0}}{\vdash(\lambda x.\lambda y.(y\ (\mathbf{iszero}\ (y\ x))))\ True}::\tau_{0}} \xrightarrow{App}$$

 $T_2$ :

$$\frac{ x:\tau_{1},y:\tau_{2} \vdash y::\tau_{5} \rightarrow Int \ Var^{2} \quad \overline{x:\tau_{1},y:\tau_{2} \vdash x::\tau_{5}}}{x:\tau_{1},y:\tau_{2} \vdash yx::Int \atop \overline{x:\tau_{1},y:\tau_{2} \vdash \mathbf{iszero} \ (y\ x)::\tau_{4}}} \frac{Var^{3}}{App}$$

Finding out  $\tau_0$ :

d Infer type of iszero(fst (3+5))

Collected type constraints:  $\tau_0 = Bool$  from iszero,  $(Int = (Int, \tau_1))$  from BinOp, second constraint does not unify, meaning this doesn't type

# Formal Methods

# 1 Introduction to language semantics

#### 1.1 States

State as a function:

State:  $Var \rightarrow Val$ 

Zero state:

$$\sigma_{zero}(x) = 0$$
 for all  $x$ 

Updating states:

$$(\sigma[y \mapsto v](x)) = \begin{cases} v & \text{if } x \equiv y\\ \sigma(x) & x \not\equiv y \end{cases}$$

Two states are equal:

$$\sigma_1 = \sigma_2 \Leftrightarrow \forall x. (\sigma_1(x) = \sigma_2(x))$$

# 1.2 Semantics of arithmetic expression

Semantic function:

$$\mathcal{A}: Aexp \to State \to Val$$

Mapping

$$\mathcal{A}[\![x]\!]\sigma = \sigma(x) 
\mathcal{A}[\![n]\!]\sigma = \mathcal{N}[\![n]\!] 
\mathcal{A}[\![e_1 op e_2]\!]\sigma = \mathcal{A}[\![e_1]\!] \overline{op} \mathcal{A}[\![e_2]\!]$$

with  $\overline{op}$  the relation Val × Val corresponding to op

# 1.3 Semantics of boolean expression

Semantic function:

$$\mathcal{B}: \operatorname{Bexp} \to \operatorname{State} \to \operatorname{Val}$$

Mapping

$$\mathcal{B}\llbracket e_1 \, op \, e_2 \rrbracket \sigma \qquad = \begin{cases} \mathsf{tt} & \text{if } \mathcal{A}\llbracket e_1 \rrbracket \sigma \, \overline{op} \, \mathcal{A}\llbracket e_2 \rrbracket \sigma \\ \mathsf{ff} & \text{otherwise} \end{cases}$$

$$\mathcal{B}\llbracket b_1 \, \text{ or } b_2 \rrbracket \sigma \qquad = \begin{cases} \mathsf{tt} & \text{if } \mathcal{B}\llbracket b_1 \rrbracket \sigma = \mathsf{tt} \text{ or } \mathcal{B}\llbracket b_2 \rrbracket \sigma = \mathsf{tt} \\ \mathsf{ff} & \text{otherwise} \end{cases}$$

$$\mathcal{B}\llbracket b_1 \, \text{ and } b_2 \rrbracket \sigma \qquad = \begin{cases} \mathsf{tt} & \text{if } \mathcal{B}\llbracket b_1 \rrbracket \sigma = \mathsf{tt} \text{ and } \mathcal{B}\llbracket b_2 \rrbracket \sigma = \mathsf{tt} \\ \mathsf{ff} & \text{otherwise} \end{cases}$$

$$\mathcal{B}\llbracket \mathsf{not} \, b \rrbracket \sigma \qquad = \begin{cases} \mathsf{tt} & \text{if } \mathcal{B}\llbracket b \rrbracket \sigma = \mathsf{ff} \\ \mathsf{ff} & \text{otherwise} \end{cases}$$

with  $\overline{op}$  the relation Val × Val corresponding to op

# 1.4 Free variables

```
FV(e_1 op e_2)
                                               = FV(e_1) \cup FV(e_2)
FV(n)
                                               =\emptyset
FV(x)
                                               = \{x\}
FV(\text{not }b)
                                               = FV(b)
FV(b_1 \text{ or } b_2)
                                               =FV(b_1)\cup FV(b_2)
FV(b_1 \text{ and } b_2)
                                               = FV(b_1) \cup FV(b_2)
FV(\mathtt{skip})
FV(x := e)
                                               = \{x\} \cup FV(e)
FV(s_1; s_2)
                                              = FV(s_1) \cup FV(e_2)
FV(\text{if } b \text{ then } s_1 \text{ else } s_2 \text{ end}) = FV(b) \cup FV(s_1) \cup FV(s_2)
FV(\text{while } b \text{ do } s \text{ end})
                                              = FV(b) \cup FV(s)
```

#### 1.5 Substitution

$$\begin{array}{ll} (e_1 \, op \, e_2)[x \mapsto e] & \equiv (e_1[x \mapsto e]) \\ n[x \mapsto e] & \equiv n \\ \\ y[x \mapsto e] & \equiv \begin{cases} e & \text{if } x \equiv y \\ y & \text{otherwise} \end{cases} \\ (\text{not } b)[x \mapsto e] & \text{not } (b[x \mapsto e]) \\ (b_1 \, \text{or } b_2)[x \mapsto e] & (b_1[x \mapsto e] \, \text{or } b_2[x \mapsto e]) \\ (b_1 \, \text{and } b_2)[x \mapsto e] & (b_1[x \mapsto e] \, \text{and } b_2[x \mapsto e]) \end{array}$$

Substitution Lemma:

$$\mathcal{B}\llbracket b[x\mapsto e] \rrbracket \sigma = \mathcal{B}\llbracket b \rrbracket (\sigma[x\mapsto \mathcal{A}\llbracket e \rrbracket \sigma])$$

# 1.6 Structural induction on arithmetic and boolean expressions

#### 1.6.1 Session sheet 10, Ex. 2

```
Statement: \forall \sigma, e, e', x \mathcal{A}[\![e]\![x \mapsto e']\!]] \sigma = \mathcal{A}[\![e]\!](\sigma[x \mapsto \mathcal{A}[\![e']\!]\sigma])
```

*Proof.* Let  $\sigma, x, e'$  be arbitrary.

Let 
$$P(e) \equiv (\mathcal{A}[\![e]\![x \mapsto e']\!]]\sigma = \mathcal{A}[\![e]\!](\sigma[x \mapsto \mathcal{A}[\![e']\!]\sigma]).$$

We prove  $\forall e.P(e)$  by strong structural induction on e.

We want to show P(e) for some arbitrary e and assume  $\forall e'' \sqsubseteq e P(e')$  (I.H.)

Case  $e \equiv n$  for some numerical value n:

. . .

Case  $e \equiv y$  for some variable y:

. .

Case  $e \equiv e_1 \ op \ e_2$  for some arithmetic expressions  $e_1, e_2$ :

. . .

# 1.6.2 Sheet 10, Ex. 2

Statement:  $\forall \sigma, e, e', x (\mathcal{B}[\![b[x \mapsto e]\!]] \sigma = \mathcal{B}[\![b]\!] (\sigma[x \mapsto \mathcal{A}[\![e]\!]\sigma]))$ 

*Proof.* Let  $\sigma, x, e$  be arbitrary.

Let  $P(b) \equiv (\mathcal{B}[\![b]\![x \mapsto e]\!]]\sigma = \mathcal{B}[\![b]\!](\sigma[x \mapsto \mathcal{A}[\![e]\!]\sigma]).$ 

We prove  $\forall b.P(b)$  by strong structural induction on e.

We want to show P(e) for some arbitrary b and assume  $\forall b'' \sqsubset b P(b')$  (I.H.)

Case  $b \equiv b_1$  or  $b_2$  for some boolean expressions  $b_1, b_2$ :

Case  $b \equiv b_1$  and  $b_2$  for some boolean expressions  $b_1, b_2$ :

. . .

Case  $b \equiv \text{not } b'$  for some boolean expression b':

. .

Case  $b \equiv e_1 \ op \ e_2$  for some arithmetic expressions  $e_1, e_2$ :

•••

# 2 Operational Semantics

# 2.1 Properties

### 2.1.1 Big step semantics

The execution of a statement s in state  $\sigma$ 

- terminates successfully iff  $\exists \sigma' \text{ st} \vdash \langle s, \sigma \rangle \rightarrow \sigma'$
- fails to terminate iff  $\nexists \sigma'$  st  $\vdash \langle s, \sigma \rangle \rightarrow \sigma'$

**Semantic equivalence**:  $s_1$  and  $s_2$  are semantically equivalent iff:

$$\forall \sigma, \sigma'. (\vdash \langle s_1, \sigma \rangle \to \sigma' \Leftrightarrow \langle s_2, \sigma \rangle \to \sigma')$$

### 2.1.2 Small step semantics

The execution of a statement s in state  $\sigma$ 

- terminates successfully iff  $\exists \sigma' \text{ st} \vdash \langle s, \sigma \rangle \rightarrow_1^* \sigma'$
- fails to terminate iff  $\nexists \sigma'$  st  $\vdash \langle s, \sigma \rangle \rightarrow_1^* \sigma'$

**Semantic equivalence**:  $s_1$  and  $s_2$  are semantically equivalent iff for all  $\sigma$ :

- for all stuck or terminal configurations  $\gamma: \langle s_1, \sigma \rangle \to_1^* \gamma$  if and only if  $\langle s_2, \sigma \rangle \to_1^* \gamma$
- there is an infinite derivation sequence starting in  $\langle s_1, \sigma \rangle$  if and only if there is one starting in  $\langle s_2, \sigma \rangle$

**Lemma**: The small-step semantics of IMP are **deterministic**:  $\vdash \langle s, \sigma \rangle \rightarrow_1 \gamma \land \langle s, \sigma \rangle \rightarrow_1 \gamma' \Rightarrow \gamma = \gamma'$ 

# 2.2 Applying big-step semantics

# 2.2.1 Example

Let s= if x>y then (x:=y+1;y:=x-2) else skip end. We want to prove  $\langle s,\sigma\rangle\to\sigma'$  for  $\sigma$  with  $\sigma(x)=4,\,\sigma(y)=2$  and  $\sigma'=\sigma[x,y\mapsto 3,1]$ 

$$\frac{ \frac{\langle x := y+1, \sigma \rangle \to \sigma[x \mapsto 3]}{\langle x := y+1, \sigma \rangle \to \sigma[x \mapsto 3]} \overset{\text{ASS}_{\text{NS}}}{\text{SEQ}_{\text{NS}}} }{\frac{\langle (x := y+1; y := x-2), \sigma \rangle \to \sigma'}{\langle s, \sigma \rangle \to \sigma'}} \overset{\text{ASS}_{\text{NS}}}{\text{SEQ}_{\text{NS}}}$$

# 2.3 Applying small-step semantics

#### **2.3.1** Example

Let s= if x>y then  $\left(x:=y+1;y:=x-2\right)$  else skip end.

We want to prove  $\langle s, \sigma \rangle \to_1^* \sigma'$  for  $\sigma$  with  $\sigma(x) = 4$ ,  $\sigma(y) = 2$  and  $\sigma' = \sigma[x, y \mapsto 3, 1]$  Derivation sequence:

$$\langle s, \sigma \rangle$$

$$\to_1^1 \langle (x := y + 1; y := x - 2), \sigma \rangle$$

$$\to_1^1 \langle y := x - 2, \sigma[x \mapsto 3] \rangle$$

$$\to_1^1 \sigma[x, y \mapsto 3, 1]$$

with the following derivation trees justifying the steps

$$\frac{\overline{\langle s, \sigma \rangle} \to_1 \langle (x := y + 1; y := x - 2), \sigma \rangle} \text{ IFT}_{SOS}$$

$$\frac{\overline{\langle x := y + 1, \sigma \rangle} \to_1 \sigma[x \mapsto 3]}{\overline{\langle (x := y + 1; y := x - 2), \sigma \rangle} \to_1 \overline{\langle y := x - 2, \sigma[x \mapsto 3] \rangle}} \text{ SEQ1}_{SOS}$$

$$\frac{\overline{\langle y := x - 2, \sigma[x \mapsto 3] \rangle} \to_1 \sigma[x, y \mapsto 3, 1]} \text{ ASS}_{SOS}$$

# 2.4 Induction on shape of derivation tree

General idea:

- 1. Prove that for all  $\sigma, \sigma'$ , (var. in  $s_1$ ), if  $\vdash \langle s_1, \sigma \rangle \to \sigma'$  then P for some property  $P \Rightarrow \text{Let } P(T) \equiv \forall \sigma, \sigma'$ , (var. in  $s_1$ )  $(root(T) \equiv \langle s_1, \sigma \rangle \to \sigma' \Rightarrow P)$ Goal: Prove  $\forall T.P(T)$  by induction on the shape of a derivation tree
- 2. Induction hypothesis: For arbitrary T,  $\forall T' \sqsubset T.P(T')$
- 3. Let  $\sigma, \sigma'$ , (var. in  $s_1$ ) be arbitrary, assume  $\langle s_1, \sigma \rangle \to \sigma'$
- 4. Do case analysis of last rule applied in T
- 5. Derive subtrees of T and properties about  $\sigma$ , like  $\mathcal{B}[\![e]\!]\sigma = \mathsf{tt}$
- 6. Use subtrees, properties of  $\sigma$  and induction hypothesis to prove P

Option: Simply do case distinction, I.H. doesn't have to be applied

#### 2.4.1 Session sheet 11, Ex.4

$$\frac{\langle s,\sigma\rangle \to \sigma'}{\langle \text{repeat } s \text{ until } b,\sigma\rangle \to \sigma'} \text{ (RepT}_{\text{NS}}) \text{ if } \mathcal{B}[\![b]\!] \sigma' = \text{tt}$$

$$\frac{\langle s,\sigma\rangle \to \sigma'' \qquad \langle \text{repeat } s \text{ until } b,\sigma''\rangle \to \sigma'}{\langle \text{repeat } s \text{ until } b,\sigma\rangle \to \sigma'} \text{ (RepF}_{\text{NS}}) \text{ if } \mathcal{B}[\![e]\!] \sigma'' = \text{ff}$$

Prove that for all  $\sigma$ ,  $\sigma$ , b, s, if

$$\vdash \langle \text{repeat } s \text{ until } b, \sigma \rangle \rightarrow \sigma'$$

then

$$\vdash \langle s; \mathtt{while} \ \mathtt{not} \ b \ \mathtt{do} \ s \ \mathtt{end}, \sigma \rangle \to \sigma'$$

Proof.

$$\begin{split} P(T) \equiv & \forall \sigma, \sigma', b, s \; (root(T) \equiv \texttt{repeat} \; \; s \; \, \texttt{until} \; \; b, \sigma \rangle \rightarrow \sigma' \\ \Rightarrow & \vdash \langle s; \texttt{while} \; \; \texttt{not} \; \; b \; \; \texttt{do} \; \; s \; \; \texttt{end}, \sigma \rangle \rightarrow \sigma') \end{split}$$

We prove  $\forall T.P(T)$  by induction on the shape of a derivation tree **Induction hypothesis**: For arbitrary T,  $\forall T' \sqsubset T.P(T')$ 

Let  $\sigma, \sigma', b, s$  be arbitrary, assume (repeat s until  $b, \sigma$ )  $\to \sigma'$ .

Case analysis of last rule applied in T:

Case (REPT) Then T has the form:

$$\frac{\mathbf{T_1}}{\langle s,\sigma\rangle \to \sigma'} \\ \hline \langle \mathtt{repeat} \ s \ \mathtt{until} \ b,\sigma\rangle \to \sigma' \ (\mathtt{RepT}_{\mathrm{NS}})$$

for some derivation tree  $T_1$  and we must have  $\mathcal{B}[\![b]\!]\sigma' = \mathsf{tt}$ , hence  $\mathcal{B}[\![\mathsf{not}\ b]\!]\sigma' = \mathsf{ff}$ . We can construct following tree:

$$\frac{\mathbf{T_1}}{\frac{\langle s,\sigma\rangle\to\sigma'}{\langle s; \texttt{while not } b \texttt{ do } s \texttt{ end},\sigma'\rangle\to\sigma'}} \underbrace{\text{(WHF}_{\mathrm{NS}})}_{\text{(SEQ}_{\mathrm{NS}})}$$

Case (REPF) Then T has the form:

$$\frac{\mathbf{T_1}}{\frac{\langle s,\sigma\rangle \to \sigma''}{\langle \texttt{repeat } s \texttt{ until } b,\sigma''\rangle \to \sigma'}} \frac{\mathbf{T_2}}{\langle \texttt{repeat } s \texttt{ until } b,\sigma\rangle \to \sigma'} (\text{RepF}_{NS})$$

for some state  $\sigma''$  and derivation trees  $T_1, T_2$ , where  $\mathcal{B}[\![e]\!]\sigma'' = ff$ .

 $T_2$  is a proper subtree of T, hence  $P(T_2)$  holds by I.H.. This implies that there's a derivation tree  $T_3$  with  $root(T_3) \equiv \langle s; \text{while not } b \text{ do } s \text{ end}, \sigma'' \rangle \rightarrow \sigma'$ . The last rule applied in  $T_3$  must be SEQ<sub>NS</sub>, so  $T_3$  has the form:

$$\frac{\mathbf{T_4}}{\frac{\langle s,\sigma'\rangle \to \sigma'''}{\langle s; \texttt{while not } b \texttt{ do } s \texttt{ end}, \sigma'''\rangle \to \sigma'}}{\langle s; \texttt{while not } b \texttt{ do } s \texttt{ end}, \sigma'''\rangle \to \sigma'}} (SEQ_{NS})$$

for some state  $\sigma'''$  and derivation trees  $T_4, T_5$ .

We can now construct following derivation tree

$$\frac{\mathbf{T_1}}{\frac{\langle s,\sigma\rangle \to \sigma''}{}} \frac{\frac{\mathbf{T_4}}{\langle s,\sigma'\rangle \to \sigma'''} \quad \frac{\mathbf{T_5}}{\langle \mathtt{while not } b \ \mathtt{do} \ s \ \mathtt{end},\sigma'''\rangle \to \sigma'}}{\langle \mathtt{while not } b \ \mathtt{do} \ s \ \mathtt{end},\sigma''\rangle \to \sigma'} (\mathtt{WHT_{NS}})} \\ \frac{\langle s; \mathtt{while not } b \ \mathtt{do} \ s \ \mathtt{end},\sigma''\rangle \to \sigma'}{\langle s; \mathtt{while not } b \ \mathtt{do} \ s \ \mathtt{end},\sigma\rangle \to \sigma'}}$$

#### 2.4.2 Session sheet 12/Sheet 12: Proof of equivalence lemmas

#### Direction big step to small step semantics:

Use derivation tree of big step semantic to get a derivation sequence for the small step semantic.

Proof.

$$P(T) \equiv \forall \sigma, \sigma', s \; (root(T) \equiv (\langle s, \sigma \rangle \rightarrow \sigma') \Rightarrow \langle s, \sigma \rangle \rightarrow_1^* \sigma')$$

We prove  $\forall T.P(T)$  by induction on the shape of a derivation tree

**Induction hypothesis**: For arbitrary T,  $\forall T' \sqsubset T.P(T')$ 

Let  $\sigma, \sigma', s$  be arbitrary, assume  $\langle s, \sigma \rangle \to \sigma'$ .

Case distinction by last rule applied in T:

Case (WHFNS) Then T has the form:

$$\frac{}{\text{(while }b\text{ do }s'\text{ end},\sigma
angle
ightarrow\sigma'}}$$
  $(\mathrm{WHF_{NS}})$ 

for some b, s' such that  $s \equiv \text{while } b \text{ do } s' \text{ end and } \mathcal{B}[\![e]\!] \sigma = \text{ff.}$ 

We can construct following derivation sequence:

$$\langle \mathtt{while}\ b\ \mathtt{do}\ s'\ \mathtt{end}, \sigma 
angle \ 
ightarrow_1^* \ldots \ 
ightarrow_1^1 \sigma$$

Case (IFT<sub>NS</sub>) Then T has the form:

$$\frac{\mathbf{T_1}}{\langle s_1, \sigma \rangle \to \sigma'}$$

$$\frac{\langle \text{if } b \text{ then } s_1 \text{ else } s_2 \text{ end}, \sigma \rangle \to \sigma'}{\langle \text{if } b \text{ then } s_1 \text{ else } s_2 \text{ end}, \sigma \rangle \to \sigma'}$$

for some  $b, s_1, s_2, T_1$  such that  $s \equiv \text{if } b$  then  $s_1$  else  $s_2$  end and  $\mathcal{B}[\![e]\!]\sigma = \text{tt}$ . From  $P(T_1)$  we learn  $\langle s_1, \sigma \rangle \to_1^* \sigma'$  We can construct following derivation sequence:

$$\langle \text{if } b \text{ then } s_1 \text{ else } s_2 \text{ end}, \sigma \rangle \\ \to_1^1 \langle s_1, \sigma \rangle \\ \to_1^* \sigma$$

... (other cases)

# 2.5 Proving properties of derivation sequences

General idea:

- 1. Prove  $\gamma \to_1^* \gamma' \Rightarrow P$  for some property P
- 2. Define  $P(k) \equiv (\gamma \to_1^k \gamma' \Rightarrow P)$  to do a strong induction over k
- 3. Deal with case k = 0 (if applicable)
- 4. Deal with case k > 0 by splitting off first execution step  $\sigma \to_1^1 \delta \to_1^{k-1} \gamma$ 
  - Get information by case distinction of first execution step
  - Apply induction hypothesis to remaining steps

# 2.5.1 Session sheet 12/Sheet 12: Proof of equivalence lemmas

Direction small step to big step semantics:

Proof.

$$Q(k) \equiv (\forall \sigma, \sigma', s \ (\langle s, \sigma \rangle \to_1^k \sigma') \Rightarrow \vdash \langle s, \sigma \rangle \to \sigma')$$

Using strong induction, we prove  $\forall k \ Q(k)$ .

 $\mathbf{k} = \mathbf{0}$ : Trivially,  $\sigma$  must be and end state.

 $\mathbf{k} > \mathbf{0}$ : Assume  $\langle s, \sigma \rangle \to_1^k \sigma'$ .

The derivation sequence is unrolled to  $\langle s, \sigma \rangle \to_1^1 \gamma \to_1^{k-1} \sigma'$ . Let T be the derivation tree justifying the first transition. We do a case distinction on the last rule applied in T:

Case ( $ASS_{SOS}$ ): T has the form

$$\overline{\langle x := e, \sigma \rangle \to_1 \sigma'}$$
 (ASS<sub>SOS</sub>)

for some x, e such that  $s \equiv x := e$  and  $\gamma = \sigma[x \mapsto \mathcal{A}[\![e]\!]\sigma]$ . Since  $\gamma$  is a final state there is no further derivation sequence (k=1), and hence  $\sigma' = \gamma = \sigma[x \mapsto \mathcal{A}[\![e]\!]\sigma]$ . We can construct the following derivation tree:

$$\overline{\langle x := e, \sigma \rangle \to \sigma'}$$
 (ASS<sub>NS</sub>)

... (other cases)

# 3 Axiomatic semantics

Meaning of  $\{P\}$  s  $\{Q\}$ :

- If P evaluates to true in an initial state  $\sigma$ , and if the execution of s from  $\sigma$  terminates in a state  $\sigma'$  then Q will evaluate to true in  $\sigma'$ .
- This describes **partial correctness**, that is, termination is not an essential property

Two statements  $s_1$  and  $s_2$  are provably equivalent if:

$$\forall P, Q :: \vdash \{P\} \ s_1 \ \{Q\} \iff \{P\} \ s_2 \ \{Q\}$$

**Meaning** of  $\{P\}$  s  $\{ \Downarrow Q \}$ :

- If P evaluates to true in an initial state  $\sigma$ , if the execution of s from  $\sigma$  terminates in a state  $\sigma'$  and Q will evaluate to true in  $\sigma'$ .
- This describes **total correctness**, that is, termination is not an essential property

Termination is proved using loop variants

- Loop variant is an expression that evaluates to a value in a well-founded set (for instance, N)
- Each loop iteration must decrease the value of the loop variant
- The loop has to terminate when a minimal value of the well-founded set is reached (or earlier)

Total correctness derivation rule for loops:

$$\frac{\{n \land P \land e = Z\} \ s \ \{ \Downarrow P \land e < Z \}}{\{P\} \ \text{while} \ b \ \text{do} \ s \ \text{end} \ \{ \Downarrow \neg b \land P \}} \ (\text{WHTOT}_{\text{Ax}}) \ \text{if} \ b \land P \vDash 0 \leq e$$

where Z is a fresh logical variable (not used in P)

The derivation system for partical correctness of IMP programs is sound or complete

- Soundness: if a property can be proved it does indeed hold
- Completeness: if a property holds it can be proved

# 3.1 Induction on shape of derivation trees

(Not in exercises, but in slides and old exam) Same technique as with big-step semantics

#### 3.1.1 Example from slides

Statement:  $\forall P, Q. \{P\} \text{ skip } \{Q\} \Rightarrow P \vDash Q$ 

Proof.

$$P(T) \equiv \forall P, Q. \ root(T) \equiv (\{P\} \ \text{skip} \ \{Q\}) \ \Rightarrow \ P \vDash Q$$

where T is a derivation tree with axiomatic semantic rules applied.

We want to prove  $\forall T. P(T)$  by strong structural induction on the shape of a derivation tree.

We do a case distinction by the last rule applied in T:

...

# 3.1.2 FS19, Task 6b

$$\overline{\{\exists n. P[x \mapsto n]\}}$$
 guess  $x$   $\{P\}$  (GUESS<sub>Ax</sub>) where  $n$  is a numeral and does not occur in  $P$ 

$$\overline{\{b \wedge P\}}$$
 assert  $x \{P\}$  (ASSERT<sub>Ax</sub>)

Statement:  $\forall P, Q. \{P\} \text{ x } := \text{ e } \{Q\} \Rightarrow \vdash \{P\} \text{ guess } x; \text{ assert } x = e \{Q\}$ 

Proof.

$$P(T) := \forall P, Q, x, e. \ (root(T) \equiv \{P\} \ \mathbf{x} := \mathbf{e} \ \{Q\} \Rightarrow \vdash \{P\} \ \mathbf{guess} \ x; \ \mathbf{assert} \ x = e \ \{Q\})$$

where T is a derivation tree with axiomatic semantic rules applied.

Proof by induction over the shape of the derivation tree T.

Let T be arbitrary. Assume  $\forall T' \sqsubset T. P(T')$  (I.H). Let P, Q, x, e be arbitrary.

Case distinction on the rule applied in T:

 $\bullet$  Case  $\mathrm{ASS}_{\mathrm{Ax}} :$  T has the form

$$\overline{\{Q[x \mapsto e]\} \times := e \{Q\}}$$
 (ASS<sub>Ax</sub>)

We can build a proof outline as follows:

$${Q[x \mapsto e]}$$

 $\models$  (can be shown by picking  $n := \mathcal{A}\llbracket e \rrbracket$ )

$$\{\exists n. \ n = e \land Q[x \mapsto n]\}$$

 $\vDash$  (works by def. of substitution and uses the fact that  $x \notin FV(e)$ )

$$\{\exists n.\ (n=e \land Q)[x \mapsto n]\}$$

guess x;

 $\{x = e \wedge Q\}$ 

assert x=e

 $\{Q\}$ 

• Case  $CONS_{Ax}$ : T has the form

$$\frac{\mathbf{T_1}}{\frac{\{P'\} \mathbf{x} := \mathbf{e} \{Q'\}}{\{P\} \mathbf{x} := \mathbf{e} \{Q\}}} (CONS_{Ax})$$

for some P', T' such that  $P \models P', Q \models Q'$  and a derivation tree  $T_1$ .

By I.H. P(T') holds, therefore  $\exists T_2$  with  $root(T_2) \equiv \{P'\}$  guess x; assert  $x = e \{Q'\}$ .

With this we can build the following derivation tree:

$$\frac{\mathbf{T_2}}{\{P'\} \text{ guess } x; \text{ assert } x = e \{Q'\}}$$
$$\{P\} \text{ guess } x; \text{ assert } x = e \{Q\}$$

# 3.2 Proof outlines

#### 3.2.1 Notations

$$\{P\} \\ \text{skip} \\ \{P\} \\ \{P\} \\ \text{skip} \\ \{P\} \\ \{P\} \\ \end{tabular} \begin{cases} \{P[x \mapsto e]\} \\ s_1 \\ \{Q\} \\ s_2 \\ \{P\} \\ \end{tabular} \begin{cases} \{P\} \\ s_1 \\ \{Q\} \\ else \\ s_2 \\ \{R\} \\ \end{tabular} \begin{cases} \{P\} \\ \text{while } b \text{ do} \\ \{b \land P\} \\ s_1 \\ \{b \land P\} \\ s_1 \\ \{P\} \\ \{\neg b \land P\} \\ \{\neg b \land P\} \end{cases}$$

# 3.2.2 Finding loop invariants and variants

Finding an invariant:

- Include relationships between input and loop variables/variables changed in loop
- If the goal of a program is to f.e. compute the gcd or compute a sum, include this in the invariant, i.e.  $gcd(a,b) = gcd(x,y), \sum_{i=0}^{k} (...) = ...$
- Write constant values like x = X
- Add conditions like x > 0 if it's important for the computation of a variable
- Optional: Implications for if-statements

Finding a variant:

- Find loop variable that decreases
- Find difference/sum of loop variables that decreases

# Session sheet 13: GCD algorithm

IMP program s:

```
b := x
c := y
while b # c do
    if b < c then
        c := c - b
    else
        b := b-c
    end
end
z := b</pre>
```

Goal: Prove Hoare Triple  $\{x = X \land y = Y \land X > 0 \land Y > 0\}$   $s \{ \Downarrow z = gcd(X, Y) \}$ Suitable loop invariant:  $gcd(x, y) = gcd(b, c) \land b > 0 \land c > 0 \land x = X \land y = Y$ 

- Computation goal of loop: gcd(x,y) = gcd(a,b)
- Conditions important for computation of gcd:  $b > 0 \land c > 0$
- Constant values: x = X

Suitable loop variant: b + c (either b or c) increases

# FS10, Ex. 7

IMP program s:

```
while x < y do
    t := x
    x := y
    y := t
end</pre>
```

Goal: Prove Hoare Triple  $\{x = X \land y = Y\}$  s  $\{ \Downarrow x = \max(X, Y) \}$ Suitable loop invariant:  $\max(x, y) = \max(X, Y) \land x = X \land y = Y$  Suitable loop variant: y - x

#### 3.2.3 Sheet 13, Ex. 2

IMP program s:

```
y := 0
z := 0
while y * y < n do
    y := y+1
    if y * y <= n then
        z := z+1
    else
        skip
    end
end</pre>
```

Goal: Prove Hoare Triple  $\{n=N \land n \geq 0\}$  s  $\{z^2 \leq N \land N < (z+1)^2\}$  Suitable loop invariant:

$$(y^2 \le n \Rightarrow y = z) \land (y^2 > n \Rightarrow y = z + 1) \land (z^2 \le N) \land (n = N) \land (z \ge 0)$$

- Computation goal of loop:  $(y^2 \le n \Rightarrow y = z) \land (y^2 > n \Rightarrow y = z + 1) \land z^2 \le N$
- Conditions important for computation:  $z \ge 0$
- Constant values: n = N

Suitable loop variant:  $n - y^2$ 

#### Proof outline:

$$\left\{ \begin{array}{l} n = N \wedge n \geq 0 \right\} \\ \vDash \\ \left\{ \begin{array}{l} \left( 0^2 \leq n \Rightarrow 0 = 0 \right) \wedge \left( 0^2 > n \Rightarrow 0 = 0 + 1 \right) \wedge 0^2 \leq n \wedge n = N \wedge 0 \geq 0 \end{array} \right\} \\ \boxed{y := 0} \\ \left\{ \begin{array}{l} \left( y^2 \leq n \Rightarrow y = 0 \right) \wedge \left( y^2 > n \Rightarrow y = 0 + 1 \right) \wedge 0^2 \leq n \wedge n = N \wedge 0 \geq 0 \end{array} \right\} \\ \boxed{z := 0} \\ \left\{ \begin{array}{l} \left( y^2 \leq n \Rightarrow y = z \right) \wedge \left( y^2 > n \Rightarrow y = z + 1 \right) \wedge z^2 \leq n \wedge n = N \wedge z \geq 0 \end{array} \right\} \\ \boxed{\text{while } y * y < n } \text{ do} \\ \left\{ \begin{array}{l} y^2 < n \wedge \left( y^2 \leq n \Rightarrow y = z \right) \wedge \left( y^2 > n \Rightarrow y = z + 1 \right) \wedge z^2 \leq n \wedge n = N \wedge z \geq 0 \wedge n - y^2 = V \end{array} \right\} \\ \vDash \left( 1 \right) \\ \left\{ \left( y + 1 - 1 \right)^2 < n \wedge y + 1 = z + 1 \wedge z^2 \leq n \wedge n = N \wedge z \geq 0 \wedge n - (y + 1)^2 < V \end{array} \right\} \\ \boxed{y := y+1} \\ \left\{ \left( y - 1 \right)^2 < n \wedge y = z + 1 \wedge z^2 \leq n \wedge n = N \wedge z \geq 0 \wedge n - y^2 < V \end{array} \right\} \\ \boxed{\text{if } y * y <= n } \text{ then} \\ \left\{ y^2 \leq n \wedge (y - 1)^2 < n \wedge y = z + 1 \wedge z^2 \leq n \wedge n = N \wedge z \geq 0 \wedge n - y^2 < V \end{array} \right\}$$

```
 \left\{ \begin{array}{l} y^2 \leq n \ \wedge (y-1)^2 < n \wedge y = z + 1 \wedge (z+1-1)^2 \leq n \wedge n = N \wedge z + 1 \geq 0 \wedge n - y^2 < V \ \right\} \\ \hline z := z+1 \\ \left\{ \begin{array}{l} y^2 \leq n \ \wedge (y-1)^2 < n \wedge y = z \wedge (z-1)^2 \leq n \wedge n = N \wedge z \geq 0 \wedge n - y^2 < V \ \right\} \\ \hline \models (2) \\ \left\{ (y^2 \leq n \Rightarrow y = z) \wedge (y^2 > n \Rightarrow y = z + 1) \wedge z^2 \leq n \wedge n = N \wedge z \geq 0 \wedge n - (y-1)^2 < V \ \right\} \\ \hline \\ \text{else} \\ \left\{ \neg (y^2 \leq n) \ \wedge (y-1)^2 < n \wedge y = z + 1 \wedge z^2 \leq n \wedge n = N \wedge z \geq 0 \wedge n - y^2 < V \ \right\} \\ \hline \\ \text{skip} \\ \left\{ \neg (y^2 \leq n) \ \wedge (y-1)^2 < n \wedge y = z + 1 \wedge z^2 \leq n \wedge n = N \wedge z \geq 0 \wedge n - y^2 < V \ \right\} \\ \hline \\ \text{e} (2) \\ \left\{ (y^2 \leq n \Rightarrow y = z) \wedge (y^2 > n \Rightarrow y = z + 1) \wedge z^2 \leq n \wedge n = N \wedge z \geq 0 \wedge n - y^2 < V \ \right\} \\ \hline \\ \text{end} \\ \left\{ \psi \ (y^2 \leq n \Rightarrow y = z) \wedge (y^2 > n \Rightarrow y = z + 1) \wedge z^2 \leq n \wedge n = N \wedge z \geq 0 \wedge n - y^2 < V \ \right\} \\ \hline \\ \text{end} \\ \left\{ \psi \ \neg (y^2 < n) \ \wedge (y^2 \leq n \Rightarrow y = z) \wedge (y^2 > n \Rightarrow y = z + 1) \wedge z^2 \leq N \wedge n = N \wedge z \geq 0 \ \right\} \\ \hline \\ \text{end} \\ \left\{ \psi \ \neg (y^2 < n) \ \wedge (y^2 \leq n \Rightarrow y = z) \wedge (y^2 > n \Rightarrow y = z + 1) \wedge z^2 \leq N \wedge n = N \wedge z \geq 0 \ \right\} \\ \hline \\ \text{end} \\ \left\{ \psi \ \neg (y^2 < n) \ \wedge (y^2 \leq n \Rightarrow y = z) \wedge (y^2 > n \Rightarrow y = z + 1) \wedge z^2 \leq N \wedge n = N \wedge z \geq 0 \ \right\} \\ \hline \\ \text{e1} (3) \\ \left\{ \psi \ z^2 \leq N \wedge N < (z+1)^2 \right\} \\ \end{array}
```

- (1)  $y^2 < n$  and  $y^2 \le n \Rightarrow y = z$  implies  $y = z, y \le 0$  must hold for  $n y^2 > n (y + 1)^2$
- (2) As either  $y^2 > n$  or  $y^2 \le n$  are false, they immediately imply the right hand side
- (3)  $N < (z+1)^2$  can be shown by case distinction on y: Case  $y \le n$ : As  $y^2 \ge n$ , this case is not possible Case  $y^2 = n$ :  $y^2 = n \land (y^2 \le n \implies y = z)$  implies  $y^2 = z^2$  and then  $N = n = y^2 = z^2 < (z+1)^2$ (last step requires  $z \ge 0$ ) Case  $y^2 > n$ :  $y^2 > n \land (y^2 > n \Rightarrow y = z+1)$  implies y = z+1 and then  $N = n < y^2 = (z+1)^2$

#### 3.2.4 Session sheet 13, Ex. 2

IMP program s:

```
b := x
c := y
while b # c do
    if b < c then
        c := c - b
    else
        b := b-c
    end
end
z := b</pre>
```

Goal: Prove Hoare Triple  $\{x=X \land y=Y \land X>0 \land Y>0\}$  s  $\{ \Downarrow z=gcd(X,Y) \}$  Suitable loop invariant:  $gcd(x,y)=gcd(b,c) \land b>0 \land c>0 \land x=X \land y=Y$  Suitable loop variant: b+c

# Proof outline step by step

- 1. "Preparation"
  - Put pre- and postcondition at beggining/end
  - Put loop invariant before, at the beginning and at the end of the loop

- Put while condition at start of loop and negated while condition after loop
- Put if condition at start of if block and negated if condition at start
- Put variant at start and end of the loop, like  $\cdots = V$  and  $\cdots < V$ . Put terminating symbol in all conditions just before and of loop.

```
P = \{x = X \land y = Y \land X > 0 \land Y > 0\}
b := x
{}
с := у
\{ gcd(x,y) = gcd(a,b) \land b > 0 \land c > 0 \land x = X \land y = Y \}
while b # c do
\{ b \neq c \land gcd(x,y) = gcd(a,b) \land b > 0 \land c > 0 \land x = X \land y = Y \land b + c = V \}
   if b < c
\{ b < c \}
      c := c - b
    else
\{ \neg (b < c) \}
      b := b-c
    end
\{ \Downarrow b + c < V \}
end
\{ \Downarrow \neg (b \neq c) \land gcd(x, y) = gcd(a, b) \land b > 0 \land c > 0 \land x = X \land y = Y \}
z := b
\overline{Q} = \{ \Downarrow z = gcd(X, Y) \}
```

2. Build proof from botton up using axiomatic semantic rules

```
P = \{x = X \land y = Y \land X > 0 \land Y > 0\}
Justify \models
\models(1)

Using assignment rule:
\{gcd(x,y) = gcd(x,y) \land x > 0 \land y > 0 \land x = X \land y = Y\}
\boxed{\mathbf{b} := \mathbf{x}}
Using assignment rule:
\{gcd(x,y) = gcd(b,y) \land b > 0 \land y > 0 \land x = X \land y = Y\}
\boxed{\mathbf{c} := \mathbf{y}}
Justified using while rule:
\{gcd(x,y) = gcd(b,c) \land b > 0 \land c > 0 \land x = X \land y = Y\}
\boxed{\mathbf{while}}
\boxed{\mathbf{b} \neq \mathbf{c}}
\boxed{\mathbf{do}}
Justified using if rule:
\{b \neq c \land gcd(x,y) = gcd(b,c) \land b > 0 \land c > 0 \land x = X \land y = Y\}
\boxed{\mathbf{b} \neq c}
\boxed{\mathbf{b} \neq c}
\boxed{\mathbf{c} \Rightarrow \mathbf{c} \Rightarrow
```

Try to match condition with condition coming before if-statement, meaning here the condition at start of loop

$$\{ \begin{array}{c|c} b \neq c \\ \end{array} \land \begin{array}{c|c} b < c \\ \end{array} \land \begin{array}{c|c} gcd(x,y) = gcd(b,c) \land b > 0 \land c > 0 \land x = X \land y = Y \\ \end{array} \land \begin{array}{c|c} b + c = V \\ \end{array} \}$$
 Justify  $\vDash$ 

```
=(2)
```

Using assignment rule:

$$\{\gcd(x,y)=\gcd(b,c-b) \land b>0 \land c-b>0 \land x=X \land y=Y \land \ b+(c-b) < V \ \}$$

Using if rule:

$$\{gcd(x,y) = gcd(b,c) \land b > 0 \land c > 0 \land x = X \land y = Y \land \ b+c < V \ \}$$

else

Try to match condition with condition coming before if-statement, meaning here the condition at start of loop

$$\left\{ \begin{array}{c|c} b \neq c & \land & \neg (b < c) & \land & \gcd(x,y) = \gcd(b,c) \land b > 0 \land c > 0 \land x = X \land y = Y & \land & b+c=V \end{array} \right\}$$
 Justify  $\vDash$   $\vDash$   $(3)$ 

Using assignment rule:

$$\left\{ gcd(x,y) = gcd(b-c,c) \wedge b - c > 0 \wedge c > 0 \wedge x = X \wedge y = Y \wedge \ (b-c) + c < V \ \right\}$$

Using if rule:

$$\{ \gcd(x,y) = \gcd(b,c) \land b > 0 \land c > 0 \land x = X \land y = Y \land \ b+c < V \ \}$$

end

Using while rule:

$$\{gcd(x,y) = gcd(b,c) \land b > 0 \land c > 0 \land x = X \land y = Y \land b+c < V \}$$

Justify ⊨

 $\models^{(4)}$ 

Using assignment rule:

- (1)  $x = X \land X > 0 \Rightarrow x > 0$ , same for y. gcd(x,y) = gcd(x,y) trivially true, and  $P \models P \land true$
- (2)  $b < c \land b > 0 \land c > 0 \Rightarrow gcd(x,y) = gcd(b,c) = gcd(b,c-b)$ .  $b < c \Rightarrow c-b > 0$ . For the variant:  $b > 0 \Rightarrow c = b + (c-b) < b + c = V$
- (3)  $b \neq c \land \neg(b < c) \Rightarrow b > c$ .  $b > c \land b > 0 \land c > 0 \Rightarrow gcd(x,y) = gcd(b,c) = gcd(b-c,c)$ .  $b > c \Rightarrow b-c > 0$ . For the variant:  $c > 0 \Rightarrow b = (b-c) + b < b+c = V$
- $(4) \quad \neg(b \neq c) \equiv b = c \Rightarrow \gcd(x,y) = \gcd(b,c) = b. \ \ x = X \land y = Y \Rightarrow \gcd(X,Y) = \gcd(x,y) = b$

# 4 Modeling

# 4.1 Overview

Process:

- 1. Modeling phase: Model the system under consideration using the description language of your choice; Formalize the properties to be checked
- 2. Running phase: Run the model checker to check the validity of the property in the system model
- 3. Analysis Phase: if the property is satisfied, celebrate and move on; if the property is violated, analyze counterexample; If out of memory, reduce model and try again

Main Purposes of Model checking:

- Model checking is mainly used to analyze system designs
- Typical properties to be analyzed include: Deadlocks, reachability of undesired states, protocol violations

Modeling concurrent systems:

- Systems are modelled as finite transition systems
- We model systems as **communicating sequential processes** (agents): Finite number of processes, interleaved process execution
- Processes can communicate via: shared variables, synchronous message passing, asynchronous message passing

#### 4.2 Promela

#### 4.2.1 Syntax

• Constant declarations:

```
#define N 5
mtype = { ack, req };
```

- Structure declarations: typedef vector int x; int y;
- Global channel declarations: chan buf = [2] of int;
- Global variable declarations: byte counter;
- Process declarations: proctype myProc(int p) ...
- skip: does not change state (except the location counter), always executable
- timeout: does not change state (except the location counter), executable if all other statements in the system are blocked
- assert(e): aborts execution if expression E evaluates to zero, otherwise equivalent to skip; always executable
- Sequential compositions: s1;s2 is executable if s1 is executable
- Expression statement: evaluates expression E, executable if E evaluates to value different from zero, E must not change state (no side effects)
- Selection: executable if at least one of its options is executable, chooses an option non-deterministically
  and executes it, statement else is executable if no other option is executable

```
if

:: x > 0 -> x = x + 1

:: x < 0 -> x = x - 1

:: y > 0 -> y = y + 1

:: y < 0 -> y = y - 1

:: color = color + 1
```

Repetions: executable if at least one of its options is executable, chooses repeatedly an option nondeterministically and executes it, terminates when a break or goto is executed

```
do
:: n > 1 -> r = r*n; n = n-1
:: else -> break
od
```

- Atomic: atomic { s }, executable if first statement of s is executable
- Macros: inline func(x), defines replacement text for symbolix name, no new variable scopes, recursion or return values

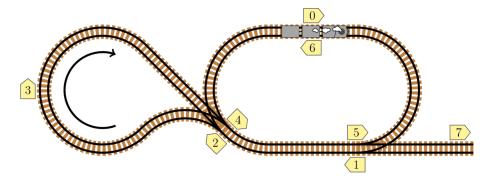
# 4.2.2 Examples from session sheet 13

```
1.2: x := 1 [] x := 2; x + 2 will result in a state \sigma where either \sigma(x) = 1 or \sigma(x) = 4
int x
init{
    if
    :: x = 1
    :: x = 2; x = x + 2
    assert (x == 1 || x == 4)
}
1.4*: y = 1 (x := 1 par (x := 2; x + 2)) will result in a state \sigma where either \sigma(x) \in \{1, 3, 4\}
int x,y
proctype left(){
    x = 1
proctype right(){
    x = 2
    x = x + 2
}
init{
    y = 1
    atomic{
         run left()
         run right()
    // wait for processes to terminate
    _nr_pr == 1
    assert(x == 1 || x == 3 || x == 4)
}
```

# 4.3 Examples

# 4.3.1 FS18, Task 8

Train track: Loop on the right can be travelled in both directions, loop on the left clock-wise. Cannot travel further from position 7.



8a Promela model for train system

```
byte pos = 0; // train position
init {
    do
        :: pos >= 0 && pos <= 5 -> pos = pos + 1
        :: pos == 2 -> pos = 0
        :: pos == 5 -> pos = 7
        :: pos == 6 -> pos = 4
        :: pos == 7 -> break; // end point
    end
}
```

8b assert-statements can be used to test safety properties: can check if the "bad thing" happened up to that point. For a liveness property we would have to know what happens after.

**8c** For the four statements: Can you modify the promela code using assert statements to check this property? If yes, state how, if no, state why not.

- 1. "The train will never reach position 6":
   Change ::pos == 6 -> pos = 4 to ::pos == 6 -> assert (false);
- 2. "The train is guaranteed to eventually position 7": Liveness property, cannot be checked
- 3. "It is possible for the train to reach position 7":
   Change ::pos == 5 -> pos = 7 to ::pos == 5 -> assert (false); pos = 7;
- 4. "The train cannot reach position 7 without first visiting position 3":
  Add pos == 3 -> break;. Change ::pos == 7 -> break; to ::pos == 7 -> assert (false);.
  Change ::pos >= 0 && pos <= 5 -> break; to ::pos >= 0 && pos <= 2 -> pos = pos + 1; and
  ::pos >= 4 && pos <= 5 -> pos = pos + 1;. You can't continue after visiting 3. If the assertion does not get triggered then there is no way to reach 7 without first visiting 3.

# 5 Linear temporal logic

# 5.1 Properties

A finite transition system is a tuple  $(\Gamma, \Sigma_I, \rightarrow)$ 

- $\Gamma$ : a finite set of configurations
- $\sigma_I \in \Gamma$ : an initial congiguration
- $\rightarrow \subseteq \Gamma \times \Gamma$ : a transition relation
- ommiting terminal configurations

 $\gamma \in \Gamma^{\omega}$  ( $\Gamma^{\omega}$  set of infinite sequences) is a **computation** of a transition system if:

- $\gamma_{[0]} = \sigma_I$
- $\gamma_{[i]} \to \gamma_{[i+1]} \text{ (for all } i \ge 0)$

Linear-time property P over  $\Gamma$ : subset of  $\Gamma^{\omega}$ 

**Atomic proposition** AP: proposition containing no logical connectives

**Labling function**:  $L: \Gamma \mapsto \mathcal{P}(AP)$ , we call  $L(\sigma)$  an abstract state

Trace  $t \in \mathcal{P}(AP)^{\omega}$ : Abstraction of a computation,  $t = L(\gamma_{[0]})L(\gamma_{[1]})L(\gamma_{[2]})...$  for a transition system

# Liveness property

• Intuition: if the thing has not happened yet, it could happen in the future

- A liveness property does not rule out any prefix
- Every finite prefix can be extended to an infinite sequence that is in P
- Liveness properties are violated in infinite time

# Safety property

- Intuition: Something bad is never allowed to happen (and can't be fixed)
- If in a finite prefix a property is violated, all sequences with this prefix violate the property
- Liveness properties are violated in finite time

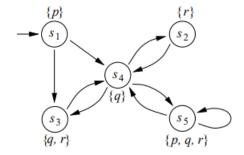
# 5.2 Operators

For a trace  $t \in \mathcal{P}(AP)^{\omega}$ 

```
t \models p
                      iff p \in t_{[0]}
                                                                                                                     now
t \vDash \neg \phi
                      iff not \phi \in t_{[0]}
                                                                                                                     not now
                    iff t \vDash \phi and t \vDash \psi
t \vDash \phi \land \psi
                                                                                                                     and
                    iff \exists k \geq 0 with t_{\geq k} \vDash \psi and t_{\geq j} \vDash \phi \ \forall 0 \leq j < k
t \vDash \phi \cup \psi
                                                                                                                     until
t \models \bigcirc \phi
                     iff t_{[1]} \vDash \phi
                                                                                                                     next
                      \equiv true U \psi
t \models \Diamond \phi
                                                                                                                     eventually
t \vDash \Box \phi
                     iff \equiv \neg(\lozenge(\neg\phi))
                                                                                                                     always (from now)
```

#### 5.2.1 Sheet 13, Ex.2

Transition system T with atomic propositions  $P = \{p, q, r\}$ 



- **2.1** Which of the following LTL formulas are satisfied in T?
- $\varphi_1 = \Diamond \Box r$  "=" eventually always  $r: T \nvDash \varphi_1$ , counter example  $\gamma = s_1 s_4 s_5 s_4 s_5 s_4 \ldots$
- $\varphi_2 = \Box \Diamond r$  "=" always eventually r:  $T \vDash \varphi_2$  since there is no loop in which r does not hold at some point
- $\varphi_3 = \bigcirc \neg r \Rightarrow \bigcirc \bigcirc r$  "=" next not r implies second next r:  $T \vDash \varphi_3$ ,  $\neg r$  holds in  $s_4$  and  $s_1$ .  $s_1$  cannot be reached as next state. From  $s_4$  we transition to one of  $s_2, s_3, s_5$ , where r holds
- $\varphi_4 = \Box p$  "=" always  $p: T \nvDash \varphi_4$ , counter example  $\gamma = s_1 s_4 s_5 s_4 s_5 s_4 \dots$
- $\varphi_5 = p \cup (q \vee r)$  "=" p until always q or r: after starting at  $s_1$  where p holds, the state changes between  $s_2, s_3, s_4, s_5$ , where  $q \vee p$  holds
- $\varphi_6 = (\bigcirc \bigcirc q) \cup (q \vee r)$  "=" second next q until q or r:  $T \nvDash \varphi_6$ , counter example  $\gamma = s_1 s_4 s_2 s_4 s_2 s_4 \dots$
- $\varphi_7 = \Diamond \Box \bigcirc q$  "=" eventually always q as next:  $T \nvDash \varphi_7$ , counter example  $\gamma = s_1 s_4 s_2 s_4 s_2 s_4 \dots$
- $\varphi_8 = (\Diamond \Box p) \Rightarrow (\Diamond \Box r)$  "=" if eventually always r holds, then eventually always t holds:  $(\Diamond \Box p)$  holds only if the trace goes into a loop  $s_5s_5s_5...$  For those traces  $\Diamond \Box r$  holds. If  $(\Diamond \Box p)$  does not hold, the implication holds trivially

2.2	Formalize	the	following	properties	in	LTL
-----	-----------	-----	-----------	------------	----	-----

- 1. Eventually, it will not be possible for the system to go to state  $s_1$ :  $\Diamond \Box \neg (p \land \neg q \land \neg r)$
- 2. Whenever the system is in a state that satisfies r, then the next state satisfies  $q: \Box(r \Rightarrow \bigcirc q)$
- 3. p always implies r except perhaps in the initial state:  $\bigcirc \Box (p \Rightarrow r)$  (possible alternative solution:  $\Box (p \land (q \lor r) \Rightarrow r))$
- 4. Whenever the system is in state  $s_5$ , it will remain there until r becomes false:  $\Box ((p \land q \land r) \Rightarrow ((p \land q \land r) \cup \neg r))$
- 5. q will be true at least twice:  $\Diamond (q \land \bigcirc \Diamond q)$
- 6. q will be true infinitely often:  $\Box \Diamond q$
- 7. If p is true only at the initial state of a trace, then r is false infinitely many times in that trace:  $(p \land \bigcirc \Box \neg p) \Rightarrow (\Box \lozenge \neg r)$
- 8. s4 can never be repeated (there is no transition from s4 to itself):  $\Box (\neg p \land q \land \neg r \Rightarrow \bigcirc \neg (\neg p \land q \land \neg r))$