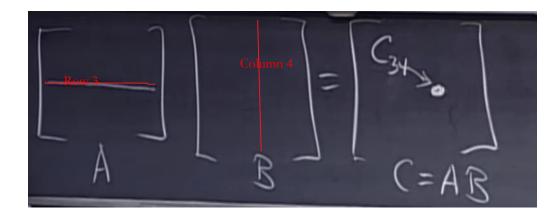
Matrix operations and inverses

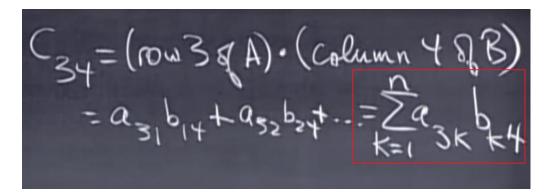
Sunday, October 22, 2017 9:28 PM

Topics:

- Matrix Multiplication
- Inverse of A AB A^T
- Gauss-Jordon or find A-1
- 1. Matrix Multiplication: Method 1

Revising the rules for matrix multiplication, the value of an element in the matrix C_{ij} , in specific, let's take C_{34}

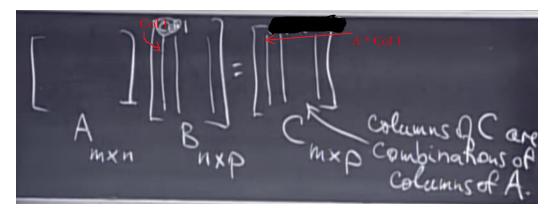




So the general rule is:

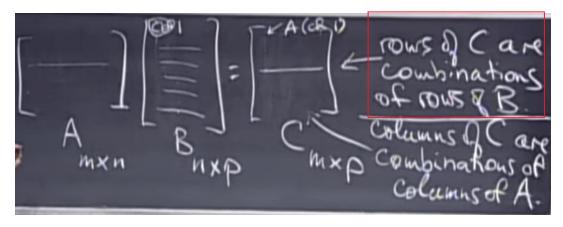
If A is size (m,n) then B should be of size (n,p) and C would be of size (m,p)

1. Matrix Multiplication: Method 2 - Column Wise



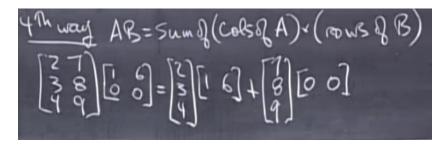
Matrix multiplication can be seen as combinations of columns of "A" to get product "C"

1. Matrix Multiplication: Method 3 - Row Wise

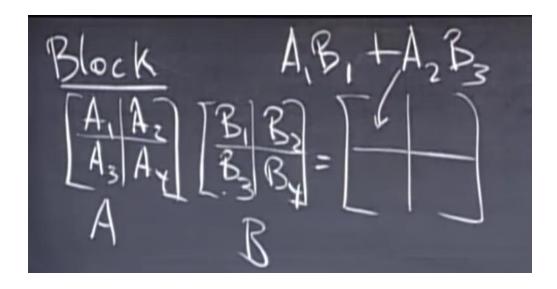


Matrix multiplication can be seen as combinations of rows of "B" to get product "C"

4. Matrix Multiplication: Method 4 - A*B = Sum of (columns of A) * (rows of B)

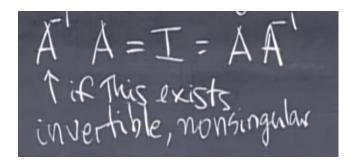


Block Multiplication:



Inverses:

1. Square Matrix



Note: For a square matrix, left A-1 and right A-1 are the same. But not so for rectangular matrices (the shape doesn't allow)

• Singular Case / No inverse:

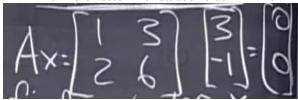
Consider matrix A:

1	3
2	6

The matrix A doesn't have an inverse because:

- The determinant is zero
- Since both the columns of A lie on the same line, it is not possible to get a combination of [1;0] columns which is required for identity matrix i.e,
 - A*P!= I where P is inverse

• A non-zero vector X exists such that A*X = 0



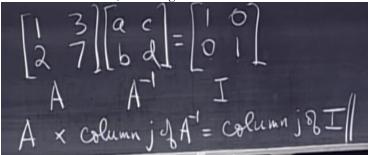
Reason:

Consider, AX = 0

on multiplying both sides by A^{-1} , we get LHS = $A^{-1}AX = X$ and RHS = $A^{-1}0 = 0$. Implies X = 0 which is not true.

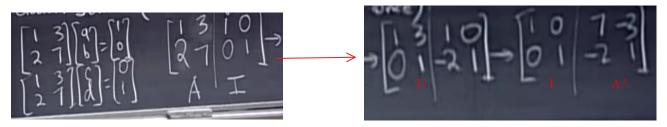
Clearly, RHS!= LHS. Hence if there exists a non-zero vector X such that AX = 0 then the A is non invertible

• Positive Case i.e., Non-Singular Case:



Solving inverse is like solving a system of linear equations.

Gauss-Jordan Method (Solving two equations at once):



Steps:

- 1. Augment the matrices A and I
- 2. Perform Eliminations on A till you get I, then
- 3. Gauss-Jordan method tells that, the augmented matrix is A-1

Proof:

Let "E" be the elimination matrix, then according to Gauss-Jordan method

 $>E(A*I) = I*A^{-1}$

>EA = I which means E is A⁻¹

