

cost function

$$\underset{w, b}{\text{minimize}} \quad \frac{\|w\|}{2}$$

constraint

$$|y_i - w^T x_i| \leq \epsilon$$

If the data points are falling within the marginal plane.

cost function, to handle the data points that are away from the marginal plane

(Real world case)

$$\underset{w, b}{\text{minimize}} \quad \frac{\|w\|}{2} + C \sum_{i=1}^n h_i$$

$\Rightarrow$  hinge loss.

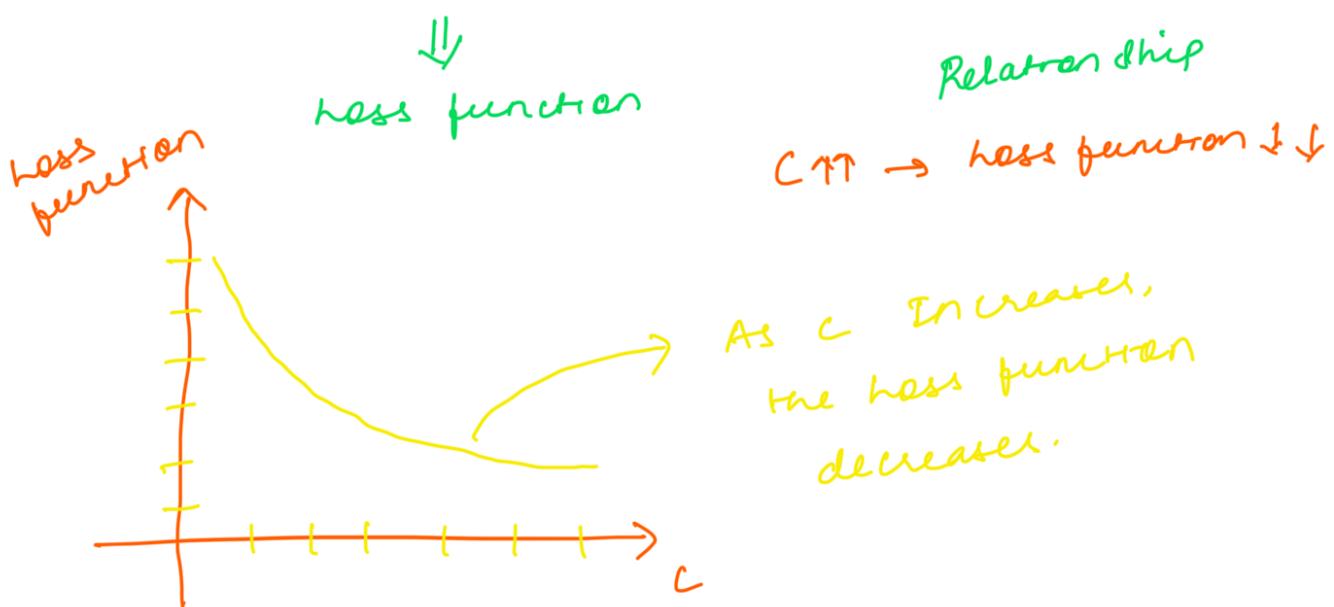
$h_i$  → hyper parameter.

$h_i$  → is the deviation of the data points from the top marginal plane and the bottom marginal plane.

, the constraint will be

hence

$$\{y_i - w_i \cdot u_i\} \leq \epsilon_i$$



$\epsilon$  → Marginal error

$b$  → Error above the marginal plane.

these two parameters will be used to create the best fit line.