Reading Note: Chapter 6

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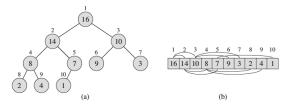
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1 Introduction

Chapter 5 gives a introduction to another sorting algorithm: **heapsort**. A new data structure, *heap*, is first introduced and its properties are explained. With this background in mind, we can see the algorithm of heapsort and its complexity in time and space.

2 Key Note

- The (binary) *heap* data structure is an array object that we can view as a nearly complete binary tree.
 - A complete k-ary tree is a k-ary tree in which all leaves have the same depth and all internal nodes have degree k. The number of leaves at depth h is k^h . Consequently, the number of internal nodes of a complete k-ary tree of height h is: $1+k+k^2+...+k^{h-1}=\sum_{i=0}^{h-1}k^i=\frac{k^h-1}{k-1}$. Thus a complete binary tree has 2^h-1 internal nodes.
 - An array A that represents a heap has two attributes: A.length (number of elements in the array), A.heap-size (represents how many elements in the heap are stored within array A)



- Given the index i of a node, we can easily compute: $PARENT(i) = \lfloor i/2 \rfloor$, LEFT(i) = 2i, RIGHT(i) = 2i + 1.
 - These procedures can be implemented as shifting operation as "macros" or "inline" procedures.

- Heap property: In a max-heap, $A[PARENT(i)] \ge A[i]$. In a min-heap, $A[PARENT(i)] \le A[i]$
- MAX-HEAPIFY: to maintain the heap property
 - Given an array A and an index i into the array (assume that the subtrees rooted at LEFT(i) and RIGHT(i) are max-heaps, but not sure about A[i]), we need to "float down" A[i] if it violate the max-heap property.
 - The procedure mainly compares A[i] with A[LEFT(i)] and A[RIGHT(i)] and swap A[i] with the largest one if needed. The procedure is called recursively and the running time is $O(\lg n)$, deduced from recurrence $T(n) \leq T(2n/3) + \Theta(1)$.
- BUILD-MAX-HEAP: to build a heap
 - Begin with each of $A[(\lfloor n/2 \rfloor + 1)...n]$ as 1-element heap, then runs MAX-HEAPIFY on each of remaining ones.
 - The tight upper bound of the procedure is O(n): we can build a max-heap from an unordered array in linear time.
- The **heapsort** algorithm
 - We use max-heap in heapsort algorithm.
 - Start by building a max-heap on A[1...n]. Exchange the largest element A[1] with A[n] and discard it from the heap. Call MAX-HEAPIFY(A,1). Loop for these procedures.
 - The algorithm takes time $O(n \lg n)$, and it is a *in place* algorithm (only a constant number of elements of the input array are ever stored outside the array).
- Heap data structure can be used as an efficient **priority queue**. For a max-priority queue, it supports following operations:
 - MAXIMUM(S): returns the element of S with the largest key. Solution: return the first element in the heap. $(\Theta(1) \text{ time})$
 - EXTRACT-MAX(A): removes and return the largest element. Solution: similar to heapsort procedure, after popping the first element, substitute with the last one and call MAX-HEAPIFY(A,1).
 - INCREASE-MAX(S,x,k): increases the value of element x's key to the new value k. Solution: similar to INSERTION-SORT, traverses a simple path from the updated node to ward the root to find a proper place.
 - INSERT(S,x): inserts the element x into set S. Solution: insert the new element to the end of S with negative infinity key value, then call INCREASE-MAX.

3 Algorithms

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• Heapsort Algorithm * (Time: O(nlgn), Space: O(1))
def MAX-HEAPIFY(A, i):
    1 = LEFT(i)
    r = RIGHT(i)
    if l \le A.heap-size and A[l] > A[i]:
         largest = 1
    else:
         largest = i
    if r \le A.heap-size and A[r] > A[largest]:
         largest = r
    if not largest == i:
         exchange A[i] with A[largest]
        MAX-HEAPIFY(A, largest)
def BUILD-MAX-HEAP(A):
    for i = A. length/2 downto 1:
        M\!AX\!\!-\!\!HEAPIFY(A,\ i\ )
def HEAPSORT(A):
    BUILD-MAX-HEAP(A)
    for i = A.length downto 2:
         exchange A[1] with A[i]
        A. heap-size -= 1
        MAX-HEAPIFY(A, 1)
```

^{*} Sample codes implemented in Codes folder