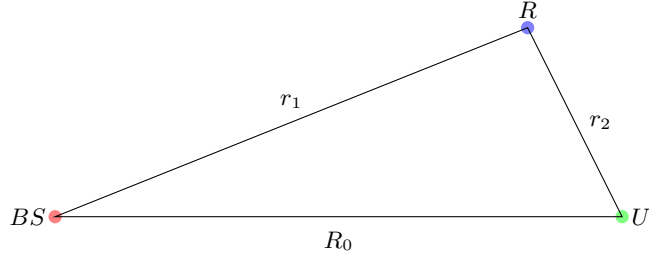
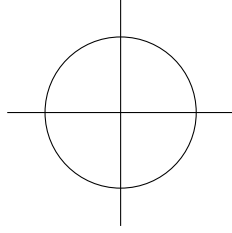


$$r_{11} = -r \cos(\theta - \alpha) + \sqrt{R_1^2 - r^2 \sin^2(\theta - \alpha)}$$

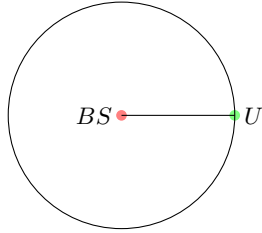
$$r_{12} = \frac{R_1 \cos \alpha - r \cos(\theta - \alpha) + \sqrt{[R_1 \cos \alpha - r \cos(\theta - \alpha)]^2 - r^2 \sin^2 \theta - [R_1 - r \cos \theta]^2 + R_2^2}}{2}$$

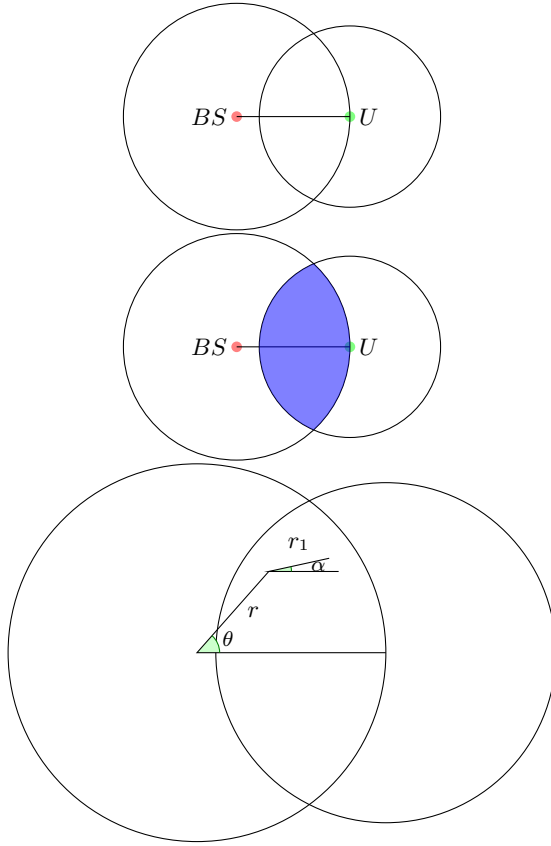
$$\begin{aligned} \rho(r, \theta) &= \int_{-\alpha_2}^{\alpha_1} f_\alpha(\alpha) \int_{r_{11}}^{\infty} f_l(l) dl d\alpha + \int_{\alpha_1}^{2\pi - \alpha_2} f_\alpha(\alpha) \int_{r_{12}}^{\infty} f_l(l) dl d\alpha \\ &= \int_{-\alpha_2}^{\alpha_1} \frac{1}{2\pi} e^{-\lambda \pi r_{11}^2} d\alpha + \int_{\alpha_1}^{2\pi - \alpha_2} \frac{1}{2\pi} e^{-\lambda \pi r_{12}^2} d\alpha \end{aligned}$$



$$\text{policy:} \{P^b r_1^{-\alpha} < P_b R_0^{-\alpha}, P_r r_2^{-\alpha} > P_b R_0^{-\alpha}\} \\ \{r_1 < R_0, r_2 < R_2\}$$

$$\text{where } R_2 = c R_0, c = \left(\frac{P_a}{P_b}\right)^{\frac{1}{\alpha}} < 1$$





$$a^2 = r^2 + r_1^2 - 2r_1r \cos(180 - \theta + \alpha)$$

$$b^2 = (r_1 \sin \alpha + r \sin \theta)^2 + (R_0 - r \cos \theta - r_1 \cos \alpha)^2$$

$$a^2 > R_0^2 \Rightarrow r_1 > r_{11}$$

$$b^2 > R_2^2 \Rightarrow r_1 > r_{12}$$

$$\beta_1 = \cos^{-1} \left( 1 - \frac{R_2^2}{2R_0^2} \right) - \theta$$

$$\beta_2 = \cos^{-1} \left( 1 - \frac{R_2^2}{2R_0^2} \right)$$

$$\alpha_1 = \theta + \tan^{-1} \left( \frac{R_0 \sin \beta_1}{R_0 \cos \beta_1 - r} \right)$$

$$\alpha_2 = \tan^{-1} \left( \frac{r \sin \theta + R_0 \sin \beta_2}{R_0 \cos \beta_2 - r \cos \theta} \right)$$

$$P = \begin{pmatrix} Q & R \\ \mathbf{0} & I_r \end{pmatrix}$$

$$N = \sum_{k=0}^{\infty} Q^k = (I - Q)^{-1}$$

$$Expected = \mathbf{t} = N\mathbf{1}$$

$$variance = (2N - I)\mathbf{t} - \mathbf{t}_{sq}$$