# PRUTHAK UTPAL JOSHI

pruthakj@g.ucla.edu, pruthakjoshi@gmail.com | pruthakjoshi.github.io | 310-694-2856

## Education

## University of California, Los Angeles

Master of Science in Mechanical Engineering, GPA: 3.9/4

Present

Los Angeles, USA

## **Indian Institute of Technology Bombay**

B. Tech. + M. Tech. (Dual Degree) in Mechanical Engineering, GPA: 9.12/10

Specialization: Computer-Aided Design and Automation

# Mumbai, India

## Research Experience

## Design of MR-compatible Robotic System for Abdominal Interventions

September 2022 - Present

Advisor: Prof. Tsu-Chin Tsao, Mechanical and Aerospace Engineering Department, UCLA

- Designing, modeling, and prototyping a 3-DoF MR-compatible robot for teleoperated abdominal interventions inside a 70 cm bore diameter MRI machine using remote centre of motion mechanism and linear guides
- $\bullet \ \ {\rm Developing} \ \ {\rm a} \ \ {\bf hydrostatic} \ \ {\bf actuation} \ \ {\rm and} \ \ {\rm transmission} \ \ {\rm network} \ \ {\rm to} \ \ {\rm create} \ \ {\rm MRI-safe} \ \ {\rm and} \ \ {\rm low} \ \ {\rm friction} \ \ {\rm actuation}$
- Created a testing setup to characterize the force and motion transmission across actuators using **precision linear stages** with the aim to develop a model using parameters such as back pressure, tubing length, and amplitude and frequency of motion
- Developing an anthropomorphic motion phantom to imitate human respiration for evaluating image-guided interventions

## Smart Machining: Data Collection, Sensing, and Monitoring

December 2022 - Present

Advisor: Prof. Tsu-Chin Tsao, Mechanical and Aerospace Engineering Department, UCLA

- Conducting machining operations to gather vibration and power data across a spectrum of machining parameters, aimed at constructing a predictive model during drilling and milling procedures utilizing Haas TM2P CNC machine
- Investigated the impact of machining parameters, including spindle speed, depth of cut, and feed rate, on power consumption
- <u>Poster:</u> Chi Yitian, **Joshi Pruthak**, Panda Shivam, Korambath Prakashan, Tsao Tsu-Chin, Li Xiaochun, Jawed M.Khalid. **Smart Machining - Sensing and Monitoring. Smart Manufacturing Symposium**; 2023 September 29

## Modelling and Characterization of a Soft Robotic Finger | Master's Thesis

May 2021 - June 2022

Guide: Prof. Abhishek Gupta, Department of Mechanical Engineering, IIT Bombay

- Examined two models for a 3-link, 3-joint tendon-actuated soft robotic finger to formulate model-based control strategies
- Experimentally verified the accuracy of the RRR model in predicting the fingertip position across various trajectories, resulting in a correlation of 0.9722 in the x-coordinate, and 0.9330 in the y-coordinate
- Corroborated the dynamic behavior of the finger through image processing and simulations in MATLAB and Simulink

# Work Experience

## Engineering Intern - Seating Systems | Lear Corporation

April 2020 - June 2020

Global automotive technology leader in Seating and E-Systems | Ranked 147<sup>th</sup> in 2019 Fortune-500 rankings

- Delivered a design guideline by benchmarking 10+ side valance designs currently in practice using a2mac1
- Analyzed the properties of 15+ plastic materials used in the automotive industry and documented the engineering analysis
- Performed **calculations** for comparing the strain generated through bending and compression due to side and frontal impact loads in the ribbing patterns of the automotive side valance to arrive at a structure with optimal shape and dimensions
- Studied the frontal and side impact tests performed on vehicles to visualize the failure modes of the side valance
- Developed an Excel based calculator for calculating deformation in the ribs based on the input design variables

## Leadership and Mentoring Roles

# Team Leader and Lead Mechanical Engineer $\mid$ IITB Mars Rover Team

April 2020 - April 2021

- Led the team to 4th position in IRDC-2020 among 28 international teams from 7 countries (best position to date)
- Raised funds and managed resources worth INR 1.38 Million+ acquired through the institute STP Committee
- Designed using SolidWorks a 3-link, 6-DOF robotic arm capable of reaching heights upto 1.2m and lifting upto 5 kg weights
- Implemented ANSYS to perform structural and multibody dynamics analyses of the design and achieved a 30% weight reduction and 5% increase in strength by using carbon fiber links over Al and SS alloys

## Scholastic Achievements and Accolades

 $\bullet$  Secured an All India Rank of 425 among 0.17 million candidates in JEE Advanced

• Achieved an All India Rank of 191 among 1.2 million candidates in JEE Main

2017

2017

# Technical Skills

**Programming**: C++, Python

Modeling and Analysis Software: SolidWorks, ANSYS, ADAMS, Abaqus, Siemens NX, AutoCAD, Fusion 360

Scientific Tools: MATLAB, Simulink, GCode, Arduino