# 18-661 Introduction to Machine Learning

Graphical Models II - Message-Passing (Belief Propagation) Algorithms

Fall 2020

ECE - Carnegie Mellon University

#### **Outline**

- 1. Review of Probabilistic Graphical Models
- 2. Review of Bayes Ball Theorem (d-separation)
- 3. Sum-Product Message-Passing to Find Marginals on Trees
- 4. Sum-Product Message-Passing to Find Posteriors
- 5. Forward-backward Algorithm for Hidden Markov Models

#### Midterm Information

Midterm will be on Tuesday, 10/20 in-class.

- Conducted as an online exam on Gradescope, with multiple-choice and short-answer questions
- Closed-book except for one double-sided letter-size handwritten page of notes that you can prepare as you wish.
- We will provide formulas for relevant probability distributions.
- You will not need a calculator. Only pen/pencil and scratch paper are allowed.

Will cover all topics up to and including Nearest Neighbors (10/15)

- (1) point estimation/MLE/MAP, (2) linear regression, (3) naive Bayes, (4) logistic regression, (5) SVMs, (6) Graphical Models, (7) Nearest Neighbors.
- Practice Midterm exam has been posted on Gradescope

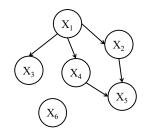
#### Homework

- Hw4 released due on Oct 25th, after the midterm
- To give you additional flexibility with the homeworks, your lowest homework score of the semester will not be considered in the final grade

# Review of Probabilistic Graphical Models

#### Directed Graphical Models (also called Bayesian Networks)

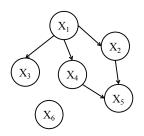
- Nodes represent random variables
- Edges represent conditional dependencies
- Directed acyclic graph no loops



#### Advantages

- 1. Compact way of describing a family of joint dist. (last lecture)
- 2. Enable us to visualize conditional dependencies (last lecture)
- 3. Enable us to perform inference using observed data (this lecture)

# Compact Way of Writing the Joint Distribution



Method to write the joint dist. described by any directed acyclic graph

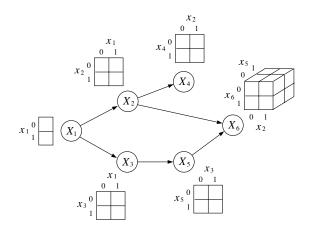
$$p(x_1, x_2, ..., x_n) = \prod_{i=1}^n p(x_i|x_{\pi_i})$$
  
=  $p(x_1)p(x_2|x_1)p(x_3|x_1)p(x_4|x_1)p(x_5|x_2, x_4)p(x_6)$ 

where  $x_{\pi_i}$  is the set of parents of node *i*. For example,

- $x_{\pi_1} = \{\}, x_{\pi_6} = \{\}$
- $x_{\pi_2} = \{x_1\}, x_{\pi_3} = \{x_1\}, x_{\pi_4} = \{x_1\}$
- $x_{\pi_5} = \{x_2, x_4\}$

# Storage Complexity of the Joint Distribution

- Due to conditional independencies, storage complexity is reduced
- ullet Each node with d parents needs to store a d+1 dimensional table

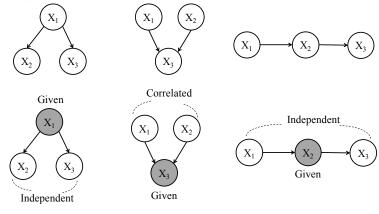


Review of Bayes Ball Theorem

(d-separation)

#### Finding Variable Dependencies from a Graphical Model

 For the three canonical graphs, we inferred the conditional independences



$$X_2 \perp \!\!\! \perp X_3 | X_1$$

$$X_2 \perp \!\!\! \perp X_3 | X_1 \qquad X_2 \perp \!\!\! \perp X_3 | X_1 \qquad X_1 \perp \!\!\! \perp X_3 | X_2$$

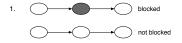
$$X_1 \perp \!\!\! \perp X_3 | X_2$$

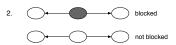
How do you identify these for a general graph?

#### Bayes Ball Theorem (also called *d*-separation)

Checking conditional dependencies between two nodes i and j given the observed values of nodes in set S (can also be an empty set).

- ullet Shade the set of observed nodes  ${\cal S}$  in grey
- Imagine a ball placed at node i. We want to move it to j
- The ball's movement along each edge is governed by the rules







• If the ball does not reach  $X_j$ , then  $X_i \perp \!\!\! \perp X_j | X_S$ . Else  $X_i \not \perp \!\!\! \perp X_j | X_S$ 

#### Example of using the Bayes Ball algorithm

#### Graph 1

- $X_1 \perp \!\!\! \perp X_4 | \{X_2, X_3\}$
- X<sub>5</sub> ⊥⊥ X<sub>6</sub>
- Ques: Is  $X_1 \perp \!\!\! \perp X_6 | \{X_2, X_3\}$ ?

#### Graph 2

- $X_2 \perp \!\!\! \perp X_3 | X_1, X_6$
- $X_2 \not\perp \!\!\! \perp X_4 | X_1, X_6$
- Ques: Is  $X_2 \perp \!\!\! \perp X_3 | X_1$ ?

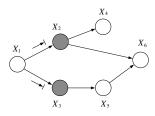


Figure 2.16: A ball cannot pass through  $X_2$  to  $X_6$  nor through  $X_3$ .

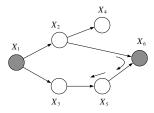
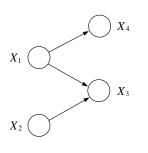


Figure 2.17: A ball can pass from  $X_2$  through  $X_6$  to  $X_5$ , and thence to  $X_3$ .

#### **Example of using the Bayes Ball algorithm**

#### List of all conditional independencies for this graph



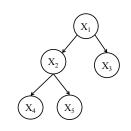
$$X_1 \perp \!\!\! \perp X_2$$
 $X_2 \perp \!\!\! \perp X_4$ 
 $X_2 \perp \!\!\! \perp X_4 \mid X_1$ 
 $X_3 \perp \!\!\! \perp X_4 \mid X_1$ 
 $X_2 \perp \!\!\! \perp X_4 \mid \{X_1, X_3\}$ 
 $\{X_2, X_3\} \perp \!\!\! \perp X_4 \mid X_1$ 

**Sum-Product Message-Passing** 

to Find Marginals on Trees

#### **Tree Graphical Models**

- $\bullet$  Each node (except for the root node) has exactly one parent. An N-node graph will have N 1 edges
- What is the joint distribution?



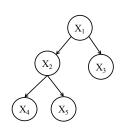
$$p(x_1, x_2, x_3, x_4, x_5) = p(x_1)p(x_2|x_1)p(x_3|x_1)p(x_4|x_2)p(x_5|x_2)$$

• What are the size of the conditional distribution tables at each node?  $O(|\mathcal{X}|^2)$ 

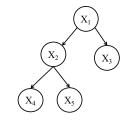
- Suppose we want to evaluate the marginal distribution of a node, say  $p(x_2)$  given the joint distribution  $p(x_1, x_2, x_3, x_4, x_5)$
- The naive approach is to sum over all other variables:

$$p(x_2) = \sum_{x_1, x_3, x_4, x_5 \in \mathcal{X}} p(x_1, x_2, x_3, x_4, x_5)$$

- How many operations does this take?  $O(|\mathcal{X}|^5)$  for each  $x_2 \in \mathcal{X}$  sum over  $|\mathcal{X}|^4$  possible values
- Complexity is exponential in the number of nodes
- Can we do better?



- Want to evaluate the marginal dist.  $p(x_2)$
- Let us substitute the joint distribution of the tree to see if we can reduce the complexity



$$p(x_2) = \sum_{x_1, x_3, x_4, x_5 \in \mathcal{X}} p(x_1) p(x_2 | x_1) p(x_3 | x_1) p(x_4 | x_2) p(x_5 | x_2)$$

$$= \sum_{x_1 \in \mathcal{X}} p(x_1) p(x_2 | x_1) \left( \sum_{x_3 \in \mathcal{X}} p(x_3 | x_1) \right) \left( \sum_{x_4 \in \mathcal{X}} p(x_4 | x_2) \right) \left( \sum_{x_5 \in \mathcal{X}} p(x_5 | x_2) \right)$$

• Observe that the last three sums (corresponding to summing over the leaf nodes  $x_3$ ,  $x_4$ ,  $x_5$ ) can be evaluated separately

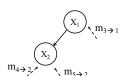
- ullet Want to evaluate the marginal dist.  $p(x_2)$
- Simplifying the expression further

$$\begin{array}{c} X_1 \\ X_2 \\ X_3 \\ X_4 \\ X_5 \end{array}$$

$$\begin{split} p(x_2) &= \sum_{x_1 \in \mathcal{X}} p(x_1) p(x_2 | x_1) \underbrace{\left(\sum_{x_3 \in \mathcal{X}} p(x_3 | x_1)\right)}_{m_{3 \to 1}(x_1)} \underbrace{\left(\sum_{x_4 \in \mathcal{X}} p(x_4 | x_2)\right)}_{m_{4 \to 2}(x_2)} \underbrace{\left(\sum_{x_5 \in \mathcal{X}} p(x_5 | x_2)\right)}_{m_{5 \to 2}(x_2)} \\ &= \sum_{x_1 \in \mathcal{X}} p(x_1) p(x_2 | x_1) m_{3 \to 1}(x_1) m_{4 \to 2}(x_2) m_{5 \to 2}(x_2) \end{split}$$

- Can think of  $m_{5\rightarrow 2}(x_2)$  as a "message" vector sent by node 5 to 2
- For each  $x_2$ ,  $m_{5\to 2}(x_2)$  is the sum of  $p(x_5|x_2)$  over all possible  $x_5\in\mathcal{X}$
- Similarly for  $m_{3\to 1}(x_1)$  and  $m_{4\to 2}(x_2)$

 Now we can remove nodes 3, 4, 5 because their information is already captured in their messages

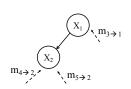


• Now group the terms containing  $x_1$ 

$$p(x_2) = m_{4\to 2}(x_2)m_{5\to 2}(x_2)\underbrace{\left(\sum_{x_1\in\mathcal{X}}p(x_1)p(x_2|x_1)m_{3\to 1}(x_1)\right)}_{m_{1\to 2}(x_1)}$$
$$= m_{4\to 2}(x_2)m_{5\to 2}(x_2)m_{1\to 2}(x_1)$$

 The marginal distribution p(x<sub>2</sub>) is simply the product of incoming messages from all neighbors

- To find other marginals  $p(x_3)$ ,  $p(x_4)$ , etc., we can reuse many of these messages
- In fact, if we pre-compute the two-way messages
   m<sub>i→j</sub> and m<sub>j→i</sub> for each edge (i, j) of the tree,
   then we can evaluate any marginal in terms of
   them



Now group the terms containing x<sub>1</sub>

$$p(x_2) = m_{4\to 2}(x_2)m_{5\to 2}(x_2)\underbrace{\left(\sum_{x_1\in\mathcal{X}}p(x_1)p(x_2|x_1)m_{3\to 1}(x_1)\right)}_{m_{1\to 2}(x_1)}$$

 $=m_{4\rightarrow2}(x_2)m_{5\rightarrow2}(x_2)m_{1\rightarrow2}(x_1),$  the product of incoming messages

 Why is it called sum-product? The message m<sub>i→j</sub> is the product of incoming messages from all neighbors of i except j

# Computational Complexity of the Sum-Product Algorithm

$$p(x_{2}) = \sum_{x_{1} \in \mathcal{X}} p(x_{1})p(x_{2}|x_{1}) \underbrace{\left(\sum_{x_{3} \in \mathcal{X}} p(x_{3}|x_{1})\right)}_{m_{3 \to 1}(x_{1}), O(|\mathcal{X}|)} \underbrace{\left(\sum_{x_{4} \in \mathcal{X}} p(x_{4}|x_{2})\right)}_{m_{4 \to 2}(x_{2}), O(|\mathcal{X}|)} \underbrace{\left(\sum_{x_{5} \in \mathcal{X}} p(x_{5}|x_{2})\right)}_{m_{5 \to 2}(x_{2}), O(|\mathcal{X}|)}$$

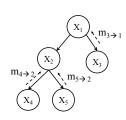
$$= \underbrace{\sum_{x_{1} \in \mathcal{X}} p(x_{1})p(x_{2}|x_{1})m_{3 \to 1}(x_{1})m_{4 \to 2}(x_{2})m_{5 \to 2}(x_{2}))}_{O(|\mathcal{X}|) \text{ operations}}$$

- For each  $x_2$ , we need  $(n-1)O(|\mathcal{X}|)$  operations, where n is the number of nodes. Thus, just  $nO(|\mathcal{X}|^2)$  in total
- Much smaller than  $O(|\mathcal{X}|^n)$  with the brute-force approach, where n is the number of nodes

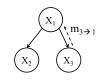
#### General Sum-Product Procedure of any *n*-node Tree

To find the marginal  $p(x_i)$  of any node i

- Decide an elimination ordering of all other nodes, starting from the leaves, and moving towards node i
- To remove node i, compute its outgoing message by summing the joint distribution over x<sub>i</sub>
- Continue removing nodes until only node i remains



#### **Example: Sum-Product Algorithm**





- $X_1$ ,  $X_2$ ,  $X_3$  are binary,  $p(x_1) = [0.5, 0.5]$ , and  $p(x_3 = 0 | x_1 = 0) = 0.3, p(x_3 = 0 | x_1 = 1) = 0.6.$  $p(x_2 = 0|x_1 = 0) = 0.6$ ,  $p(x_2 = 0|x_1 = 1) = 0.2$ .
- Find the marginal distribution  $p(x_2)$

• Find the marginal distribution 
$$p(x_2)$$

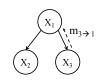
$$p(x_2) = \sum_{x_1, x_3 \in \mathcal{X}} p(x_1)p(x_2|x_1)p(x_3|x_1) \quad \text{Eliminate node 3}$$

$$= \sum_{x_1 \in \mathcal{X}} p(x_1)p(x_2|x_1) \sum_{x_3 \in \mathcal{X}} p(x_3|x_1)$$

$$= \sum_{x_1 \in \mathcal{X}} p(x_1)p(x_2|x_1)m_{3 \to 1}(x_1) \quad \text{Eliminate node 1}$$

$$= m_{1 \to 2}(x_2)$$

#### **Example: Sum-Product Algorithm**





- $X_1$ ,  $X_2$ ,  $X_3$  are binary,  $p(x_1) = [0.5, 0.5]$ , and  $p(x_3 = 0 | x_1 = 0) = 0.3$ ,  $p(x_3 = 0 | x_1 = 1) = 0.6$ ,  $p(x_2 = 0 | x_1 = 0) = 0.6$ ,  $p(x_2 = 0 | x_1 = 1) = 0.2$ .
- Find the marginal distribution  $p(x_2)$

$$p(x_{2}) = \sum_{x_{1} \in \mathcal{X}} p(x_{2}|x_{1})p(x_{1}) \underbrace{\sum_{x_{3} \in \mathcal{X}} p(x_{3}|x_{1})}_{m_{3 \to 1}(x_{1})}$$

$$= \begin{bmatrix} 0.6 & 0.2 \\ 0.4 & 0.8 \end{bmatrix} \left( \begin{bmatrix} 0.5 \\ 0.5 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right)$$

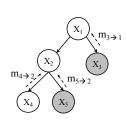
$$\begin{bmatrix} p(x_{2} = 0) \\ p(x_{2} = 1) \end{bmatrix} = \begin{bmatrix} 0.4 \\ 0.6 \end{bmatrix}$$

**Sum-Product Message-Passing** 

to Find Posteriors

#### **Sum-Product Algorithm to Find Posteriors**

- Instead of finding marginals, suppose we want to find the posterior distribution
   p(x<sub>i</sub>|x<sub>j</sub> = a, x<sub>k</sub> = b) of a node i, given observed values of nodes x<sub>i</sub> and x<sub>k</sub>
- We can use the same sum-product algorithm.
   But instead of summing over all possible values of x<sub>j</sub> and x<sub>k</sub>, we just replace them by their observed values a and b



#### **Example: Sum-Product Algorithm to Find Posteriors**

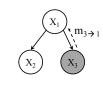
- $X_1$ ,  $X_2$ ,  $X_3$  are binary,  $p(x_1) = [0.5, 0.5]$ , and  $p(x_3 = 0 | x_1 = 0) = 0.3$ ,  $p(x_3 = 0 | x_1 = 1) = 0.6$ ,  $p(x_2 = 0 | x_1 = 0) = 0.6$ ,  $p(x_2 = 0 | x_1 = 1) = 0.2$ .
- Find the posterior distribution  $p(x_2)$  given the observation  $x_3 = 0$

$$p(x_2) \propto \sum_{x_1, x_3 \in \mathcal{X}} p(x_1) p(x_2 | x_1) p(x_3 | x_1) \quad \text{Eliminate node 3}$$

$$= \sum_{x_1 \in \mathcal{X}} p(x_1) p(x_2 | x_1) \underbrace{p(x_3 = 0 | x_1)}_{m_{3 \to 1}(x_1)}$$

$$=\sum_{\mathsf{x}_1\in\mathcal{X}}p(\mathsf{x}_1)p(\mathsf{x}_2|\mathsf{x}_1)m_{3 o 1}(\mathsf{x}_1)$$
 Eliminate node  $1$ 

$$=m_{1\rightarrow 2}(x_2)$$





# **Example: Sum-Product Algorithm to Find Posteriors**

- $X_1$ ,  $X_2$ ,  $X_3$  are binary,  $p(x_1) = [0.5, 0.5]$ , and  $p(x_3 = 0 | x_1 = 0) = 0.3$ ,  $p(x_3 = 0 | x_1 = 1) = 0.6$ ,  $p(x_2 = 0 | x_1 = 0) = 0.6$ ,  $p(x_2 = 0 | x_1 = 1) = 0.2$ .
- Find the posterior distribution  $p(x_2)$  given the observation  $x_3 = 0$

$$p(x_2) \propto \sum_{x_1 \in \mathcal{X}} p(x_2|x_1) p(x_1) \underbrace{p(x_3 = 0|x_1)}_{m_{3 \to 1}(x_1)}$$

$$= \begin{bmatrix} 0.6 & 0.2 \\ 0.4 & 0.8 \end{bmatrix} \begin{bmatrix} 0.5 \\ 0.5 \end{bmatrix} \cdot \begin{bmatrix} 0.3 \\ 0.6 \end{bmatrix}$$

$$= \begin{bmatrix} 0.6 & 0.2 \\ 0.4 & 0.8 \end{bmatrix} \begin{bmatrix} 0.15 \\ 0.3 \end{bmatrix}$$

$$\begin{bmatrix} p(x_2 = 0) \\ p(x_2 = 1) \end{bmatrix} \propto \begin{bmatrix} 0.09 + 0.06 \\ 0.06 + 0.24 \end{bmatrix} \propto \begin{bmatrix} 1/3 \\ 2/3 \end{bmatrix}$$

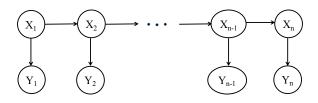




# Hidden Markov Models

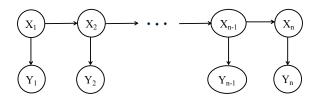
Forward-backward Algorithm for

#### Hidden Markov Model (HMM)



- Eg. Suppose there are two forms of exercise a person A does: Y = running (outdoor) or Y = yoga (indoor) each day. Their choice is governed by the weather, which can be X = rainy or sunny.
- Given that the weather  $X_i$  on the i-th day is rainy, A is more likely to do yoga  $(P(Y_i = \text{yoga}|X_i) \text{ is larger})$
- Tomorrow's weather depends on today's weather

#### Joint Distribution of the HMM

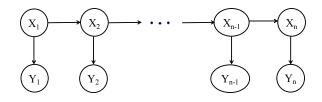


Joint distribution of the HMM is

$$p(x_1,\ldots,x_n,y_1,\ldots,y_n) = p(x_1) \prod_{j=1}^n p(y_j|x_j) \prod_{i=2}^n p(x_i|x_{i-1})$$

GOAL of the Forward-Backward Algorithm: Find the posterior distribution  $p(x_i|y_1, y_2, ..., y_n)$  of a state  $x_i$  given all the observations  $y_1, y_2, ..., y_n$ 

#### Simplifying the Posterior Expression



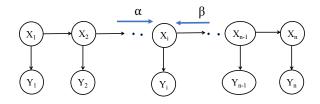
$$p(x_{i}|y_{1},...,y_{n}) = \frac{p(x_{i},y_{1},...,y_{n})}{p(y_{1},...,y_{n})}$$

$$= \frac{p(x_{i},y_{1},...,y_{i})p(y_{i+1},...,y_{n}|x_{i})}{p(y_{1},...,y_{n})}$$

$$= \frac{p(x_{i},y_{1},...,y_{i})p(y_{i+1},...,y_{n}|x_{i})}{\sum_{x_{i}}p(x_{i},y_{1},...,y_{i})p(y_{i+1},...,y_{n}|x_{i})}$$

$$= \frac{\alpha_{i}(x_{i})\beta_{i}(x_{i})}{\sum_{x_{i}}\alpha_{i}(x_{i})\beta_{i}(x_{i})}$$

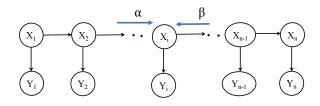
#### Simplifying the Posterior Expression



$$p(x_i|y_1,\ldots,y_n) = \frac{p(x_i,y_1,\ldots y_i)p(y_{i+1},\ldots y_n|x_i)}{\sum_{x_i}p(x_i,y_1,\ldots y_i)p(y_{i+1},\ldots y_n|x_i)}$$
$$= \frac{\alpha_i(x_i)\beta_i(x_i)}{\sum_{x_i}\alpha_i(x_i)\beta_i(x_i)}$$

- Define  $\alpha_i(x_i) \triangleq p(x_i, y_1, \dots y_i)$ , the forward messages
- Define  $\beta_i(x_i) \triangleq p(y_{i+1}, \dots y_n | x_i)$ , the backward messages
- The Forward-Backward Algorithm is an efficient (recursive) method to compute  $\alpha_i(x_i)$  and  $\beta_i(x_i)$

#### Visualizing the Messages and the Posterior



- Define  $\alpha_i(x_i) \triangleq p(x_i, y_1, \dots y_i)$ , the forward messages
- Define  $\beta_i(x_i) \triangleq p(y_{i+1}, \dots y_n | x_i)$ , the backward messages
- The Forward-Backward Algorithm is an efficient (recursive) method to compute  $\alpha_i(x_i)$  and  $\beta_i(x_i)$

# Recursively computing the forward messages $\alpha_i(x_i)$

The first message  $\alpha_1(x_1) = p(x_1, y_1)$ . Now let us compute  $\alpha_i(x_i)$  in terms of  $\alpha_{i-1}(x_{i-1})$  for all i = 2, ..., n:

$$\alpha_{i}(x_{i}) = p(x_{i}, y_{1}, \dots y_{i})$$

$$= \sum_{x_{i-1}} p(x_{i-1}, x_{i}, y_{1}, \dots y_{i})$$

$$= \sum_{x_{i-1}} p(x_{i-1}y_{1}, \dots y_{i-1}) p(x_{i}, y_{i}|x_{i-1}, y_{1}, \dots y_{i-1})$$

$$= \sum_{x_{i-1}} p(x_{i-1}y_{1}, \dots y_{i-1}) p(x_{i}, y_{i}|x_{i-1})$$

$$= \sum_{x_{i-1}} p(x_{i-1}, y_{1}, \dots y_{i-1}) p(x_{i}|x_{i-1}) p(y_{i}|x_{i})$$

$$= \sum_{x_{i-1}} \alpha_{i-1}(x_{i-1}) p(x_{i}|x_{i-1}) p(y_{i}|x_{i})$$

# Recursively computing the backward messages $\beta_i(x_i)$

The last message  $\beta_n(x_n) = 1$ . Now let us compute  $\beta_i(x_i)$  in terms of  $\beta_{i+1}(x_{i+1})$  for all i = 1, ..., n-1:

$$\beta_{i}(x_{i}) = p(y_{i+1}, \dots, y_{n}|x_{i})$$

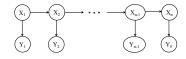
$$= \sum_{x_{i+1}} p(x_{i+1}, y_{i+1}, \dots, y_{n}|x_{i})$$

$$= \sum_{x_{i+1}} p(y_{i+1}, \dots, y_{n}|x_{i}, x_{i+1}) p(x_{i+1}|x_{i})$$

$$= \sum_{x_{i+1}} p(y_{i+2}, \dots, y_{n}|x_{i+1}) p(x_{i+1}|x_{i}) p(y_{i+1}|x_{i+1})$$

$$= \sum_{x_{i+1}} \beta_{i+1}(x_{i+1}) p(x_{i+1}|x_{i}) p(y_{i+1}|x_{i+1})$$

#### Putting it all together: Forward-Backward Algorithm



Given the following:

$$p(x_1)$$
 $p(x_i|x_{i-1})$  for all  $i=2,\ldots n$ 
 $p(y_i|x_i)$  for all  $i=1,\ldots n$ 

the goal is to find

$$p(x_i|y_1, y_2, \dots y_n)$$
 for some  $i$ 

# Putting it all together: Forward-Backward Algorithm



1. Find all the forward messages

$$\alpha_1(x_1) = p(x_1)p(y_1|x_1)$$

$$\alpha_i(x_i) = \sum_{x_{i-1}} \alpha_{i-1}(x_{i-1})p(x_i|x_{i-1})p(y_i|x_i) \text{ for } i = 2, ..., n$$

2. Find all the backward messages

$$\beta_n(x_n) = 1$$

$$\beta_i(x_i) = \sum_{x_{i+1}} \beta_{i+1}(x_{i+1}) p(x_{i+1}|x_i) p(y_{i+1}|x_{i+1}) \text{ for } i = n-1, \dots, 1$$

3. Output the posterior probability

$$p(x_i|y_1,y_2,\ldots y_n) = \frac{\alpha_i(x_i)\beta_i(x_i)}{\sum_{x_i}\alpha_i(x_i)\beta_i(x_i)}$$

#### Mini-summary of Graphical Models

#### You should know

- How to write the joint distribution corresponding to a given graphical model
- How to draw the graphical model corresponding to a joint dist.
- Checking conditional independence of variables using the Bayes Ball algorithm
- Sum-product algorithm on trees to find marginals and posteriors
- Forward-backward algorithm for hidden Markov models