### CS330 - Operating Systems

# Virtual Memory

25-08-2025

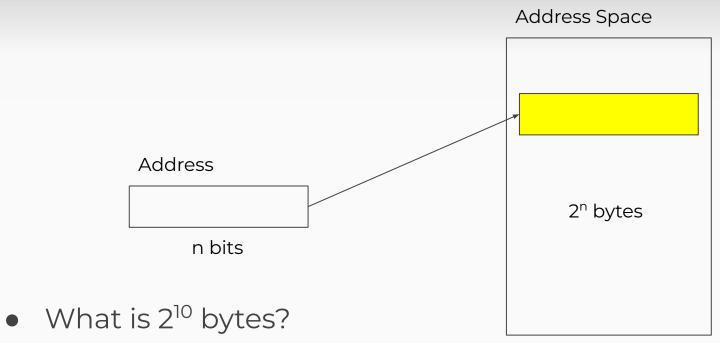
#### Virtualizing Resources

- Physical Reality:
  - Different processes/threads share the same hardware
  - Need to multiplex CPU (synchronization and scheduling)
  - Need to multiplex use of Memory (Address Spaces)
  - Need to multiplex disk and devices (...)
- Why worry about memory sharing?
  - working state of a process is defined by its data in memory
- Address Spaces
  - o the running program's view of memory in the system

### Goals of Virtualizing Memory

- Transparency
  - Physical memory is invisible to user program
  - Program thinks it has own private large memory
- Efficiency
  - Not taking very long
  - Not taking too much space
- Protection/Isolation
  - Protect processes from each other

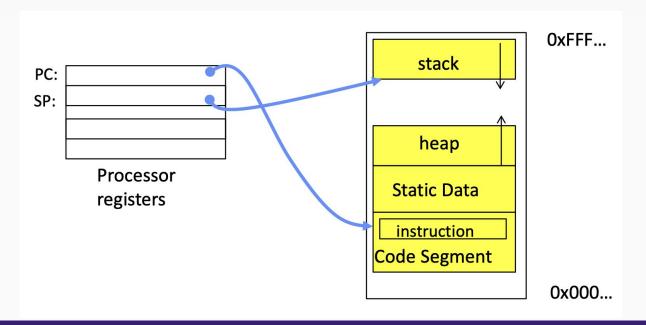
#### Address Spaces and Addresses



How many bits to address each byte of 4KB memory?

### Address Space

Set of accessible addresses +
 State associated with them



### Address Space

- All vCPU's share non-CPU resources
  - Memory, I/O devices
  - o Read/write memory

#### Address Space : Protection

- Simple multiplexing does not protect memory
- OS must protect user programs from one another
  - Prevent threads owned by one user from impacting threads owned by another user

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- OS must protect user programs from one another
  - Prevent threads owned by one user from impacting threads owned by another user
- OS must protect itself from user programs
  - Reliability (compromising OS generally causes it to crash)
  - Security (limit the scope of what threads can do)
  - Privacy (limit each thread to the data it is permitted to access)
  - Fairness (each thread should be limited to its appropriate share of system resources like CPU and memory)
- Can hardware help the OS protect itself?

### Memory Access

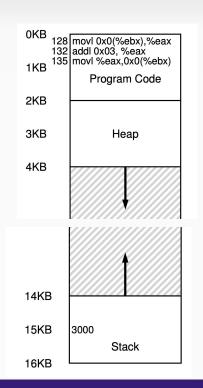
- malloc
- free

```
char *src = "hello";
char *dst;
strcpy(dst, src);
```

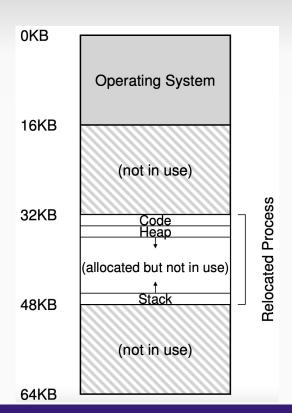
- Hardware transforms each memory access
  - Virtual address to physical address
- OS sets up the hardware for translations
- Programs share memory
  - CPUs switch between programs

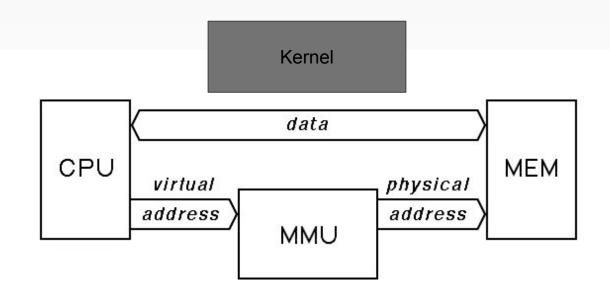
```
void func() {
   int x = 3000;
  x = x + 3;
128: movl 0x0(%ebx), %eax; load 0+ebx into eax
132: addl $0x03, %eax ; add 3 to eax register
135: movl %eax, 0x0(%ebx); store eax back to mem
```

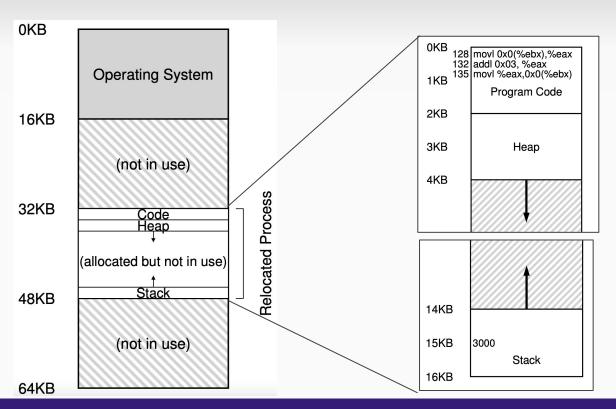
- Fetch instruction at address 128
- Execute this instruction (load from address 15 KB)
- Fetch instruction at address 132
- Execute this instruction (no memory reference)
- Fetch the instruction at address 135
- Execute this instruction (store to address 15 KB)



- OS itself is the first program mostly
- Program actually located at 32KB
- May need to relocate (when it blocks)



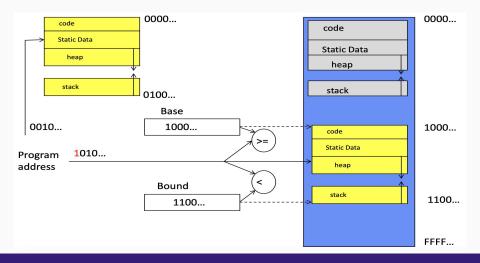




#### Dynamic Relocation - Base & Bound

- Process is assigned contiguous segment of memory
- Loads physical address into base and bound (limit may also be size depending on the type of architecture)

physical address = virtual address + base



#### Base & Bound

128: movl 0x0(%ebx), %eax

Base: 32 KB

Bounds: 64 KB

#### Base & Bound

- Allows address space to be anywhere in memory
- Ensures process accesses its own space
- OS decides where in physical address to load the address space
- Relocation happens at runtime can change even after creation

#### Base & Bound - OS and H/W Requirements

#### H/W

- Privileged Mode
  - Instructions to update base and bound
  - Register exception handlers
- Base & bounds registers
- Translate VA and check bounds
- Allow raising exceptions

#### OS

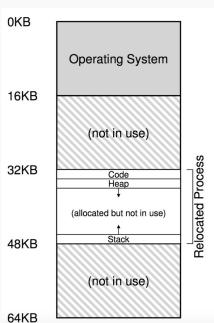
- Manage memory
- Manage registers
- Handle exceptions

#### Base & Bound - Cons

- Contiguous block of memory needed in physical memory
  - Internal Fragmentation

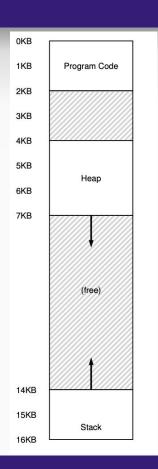
#### Segmentation

- Base & bounds pair per logical segment
- Segment is continuous memory portion
  - Code
  - Stack
  - Heap
- Each segment separate in memory



### Segmentation

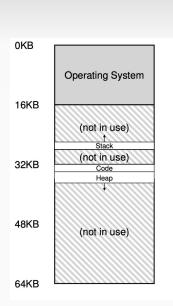
- Base & bounds pair per logical segment
- Segment is continuous memory portion
  - Code
  - Stack
  - Heap
- Each segment separate in memory
- Hardware structure in MMU
  - Set of three base & bound registers

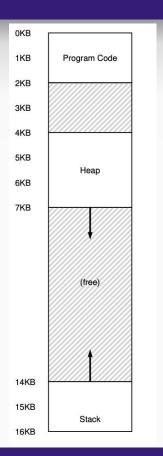


# Segmentation - Example

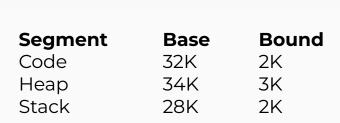
Base	Bound
32K	2K
34K	3K
28K	2K
	32K 34K

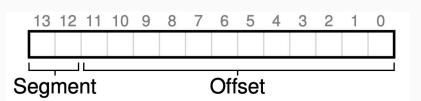
What is the size of the address in bits?

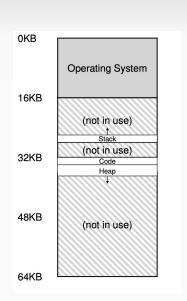


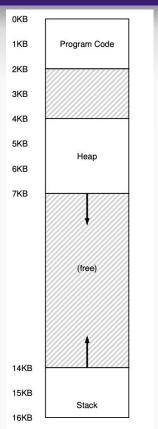


# Segmentation - Segments and Offsets



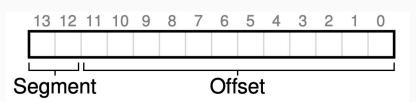


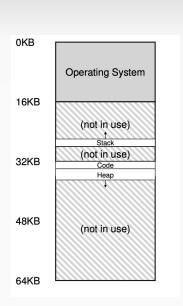


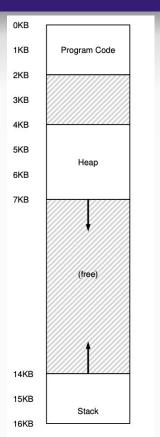


# Segmentation - Example

Segment	Base	<b>Bound</b>	Grows +ve
Code	32K	2K	1
Неар	34K	3K	1
Stack	28K	2K	0



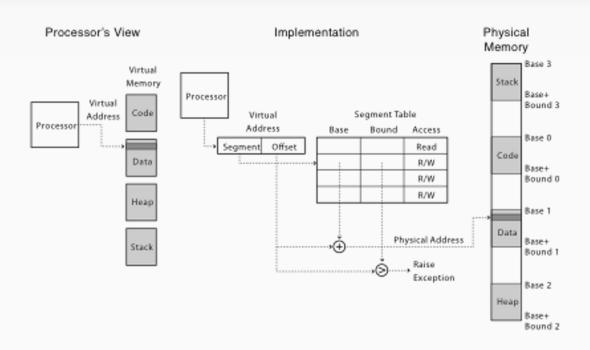




#### Segmentation

- Each segment has:
  - Start virtual address (VA)
  - Base physical address
  - Bound
- Virtual Address is OK if it inside some segment:
   Segment Start < V.A. < Segment Start + Segment Bound</li>
- For the segment that contains this virtual address:
   Physical Address = (V.A. Segment Start) + Base

#### Segmentation - Overview



### OS Support for Segmentation

- What should the OS do on context switch?
- What should the OS do when segments grow?
- How does the OS manage free space?

#### OS Support for Segmentation

- What should the OS do on context switch?
  - Save segment table and register values
- What should the OS do when segments grow?
  - o Add more memory if needed or throw an exception
- How does the OS manage free space?
  - Rearrange processes in physical memory
  - Manage free-list more effectively

### Segmentation Summary

#### Pros?

- Can share code/data segments between processes.
- Can protect code segment from being overwritten
- Can transparently grow stack/heap as needed

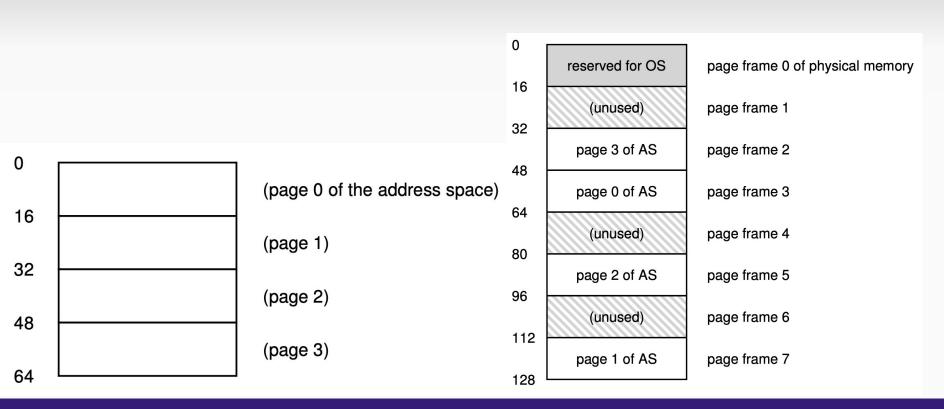
#### Cons?

- Complex memory management
  - Need to find chunk of a particular size
- May need to rearrange memory from time to time to make room for new segment or growing segment
  - External fragmentation: wasted space between chunks

- Manage memory in fixed size units, or pages
  - In physical memory, these are called frames

- Manage memory in fixed size units, or pages
  - In physical memory, these are called frames
- Finding a free page is easy
  - Bitmap allocation: 0011111100000001100
  - Each bit represents one physical page frame
- Each process has its own page table
  - Stored in physical memory
  - Hardware registers
    - pointer to page table start
    - page table length

# Paging - Example



### Paged Translation

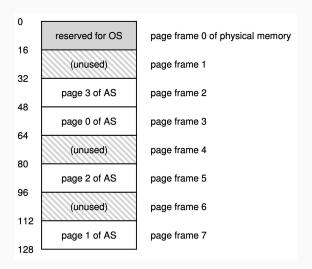
- Page table
  - Per-process data structure

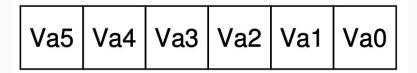
```
movl 21, %eax
```

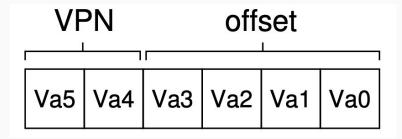
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- Page table
  - Per-process data structure

movl 21, %eax



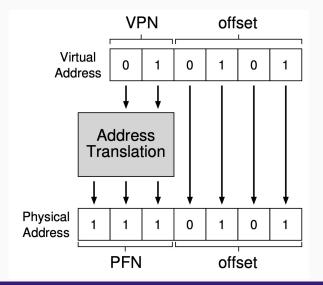


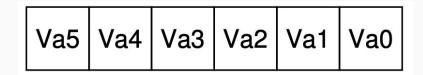


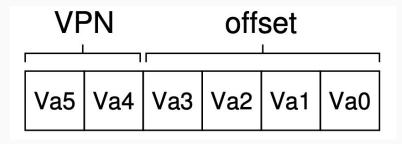
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- Page table
  - Per-process data structure

movl 21, %eax

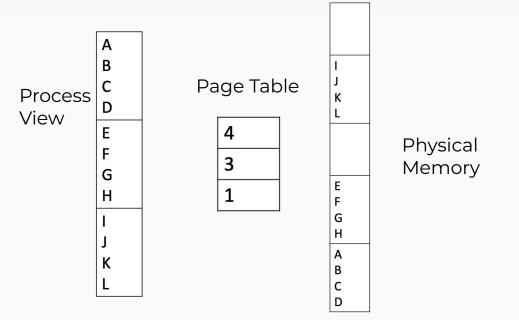






### Paged Translation - Example

- Suppose page size is 4 bytes
- Where is VA 6?



 With paging, what is saved/restored on a process context switch?

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  - Pointer to page table, size of page table
  - Page table itself is in main memory
- What if page size is very small?
- What if page size is very large?

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  - Pointer to page table, size of page table
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- What if page size is very small?
- What if page size is very large?
  - Internal fragmentation: if we don't need all of the space inside a fixed size chunk

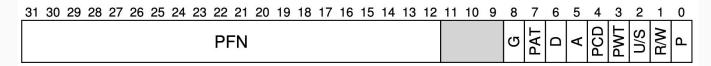
### Page Tables

- Stores virtual-to-physical address translations
- One page table per process
- Where are page tables stored?

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- Where are page tables stored?
  - Can get large

Page table entry



#### Slowness of Paging

```
VPN = (VirtualAddress & VPN_MASK) >> SHIFT
PTEAddr = PageTableBaseRegister + (VPN * sizeof(PTE))

offset = VirtualAddress & OFFSET_MASK
PhysAddr = (PFN << SHIFT) | offset</pre>
```

movl 21, %eax

#### Summary of Paging

- Manage memory in fixed size units, or pages
- Each process has its own page table
  - Stored in physical memory
  - Hardware registers
    - pointer to page table start
    - page table length
- Cons
  - Too slow
  - Too much memory