



# Admissions Testing Service

## STEP Mark Scheme 2015

Mathematics

STEP 9465/9470/9475

October 2015



Test

1. (i)

$$\begin{aligned}
 I_n - I_{n+1} &= \int_0^\infty \frac{1}{(1+u^2)^n} du - \int_0^\infty \frac{1}{(1+u^2)^{n+1}} du = \int_0^\infty \frac{1+u^2-1}{(1+u^2)^{n+1}} du \\
 &= \int_0^\infty \frac{u^2}{(1+u^2)^{n+1}} du
 \end{aligned}$$

**B1**

$$= \int_0^\infty u \frac{u}{(1+u^2)^{n+1}} du = \left[ u \frac{-1}{2n(1+u^2)^n} \right]_0^\infty - \int_0^\infty \frac{-1}{2n(1+u^2)^n} du$$

integrating by parts

**M1 A1**

$$= 0 + \frac{1}{2n} \int_0^\infty \frac{1}{(1+u^2)^n} du = \frac{1}{2n} I_n$$

**A1\***

(4)

$$I_{n+1} = I_n - \frac{1}{2n} I_n = \frac{2n-1}{2n} I_n \quad \text{M1}$$

$$= \frac{(2n-1)(2n-3)\dots(1)}{(2n)(2n-2)\dots(2)} I_1 \quad \text{M1}$$

$$I_1 = \int_0^\infty \frac{1}{(1+u^2)} du = [\tan^{-1} u]_0^\infty = \frac{\pi}{2} \quad \text{B1}$$

$$\frac{(2n-1)(2n-3)\dots(1)}{(2n)(2n-2)\dots(2)} = \frac{(2n)(2n-1)(2n-2)(2n-3)\dots(2)(1)}{[(2n)(2n-2)\dots(2)]^2} = \frac{(2n)!}{[2^n n!]^2} = \frac{(2n)!}{2^{2n}(n!)^2} \quad \text{M1}$$

$$\text{Thus } I_{n+1} = \frac{(2n)!}{2^{2n}(n!)^2} \frac{\pi}{2} = \frac{(2n)! \pi}{2^{2n+1}(n!)^2} \quad \text{A1*} \quad (5)$$

(ii)

$$J = \int_0^\infty f((x-x^{-1})^2) dx = \int_0^\infty f((u^{-1}-u)^2) \cdot -u^{-2} du = \int_0^\infty x^{-2} f((x-x^{-1})^2) dx$$

using the substitution  $u = x^{-1}$ ,  $\frac{du}{dx} = -x^{-2}$  and then the substitution  $u = x$ ,  $\frac{du}{dx} = 1$  **M1A1\***

$$2J = \int_0^\infty f((x-x^{-1})^2) dx + \int_0^\infty x^{-2} f((x-x^{-1})^2) dx = \int_0^\infty f((x-x^{-1})^2)(1+x^{-2}) dx$$

$$\text{So } J = \frac{1}{2} \int_0^\infty f((x-x^{-1})^2)(1+x^{-2}) dx \quad \text{M1A1*}$$

Using the substitution  $u = x - x^{-1}$ ,  $\frac{du}{dx} = 1 + x^{-2}$ ,

$$J = \frac{1}{2} \int_0^\infty f((x - x^{-1})^2)(1 + x^{-2}) dx = \frac{1}{2} \int_{-\infty}^\infty f(u^2) du = \int_0^\infty f(u^2) du \quad \text{M1A1* (6)}$$

(iii)

$$\int_0^\infty \frac{x^{2n-2}}{(x^4 - x^2 + 1)^n} dx = \int_0^\infty \frac{x^{-2}}{(x^2 - 1 + x^{-2})^n} dx = \int_0^\infty \frac{x^{-2}}{((x - x^{-1})^2 + 1)^n} dx \quad \text{M1A1}$$

$$= \int_0^\infty \frac{1}{(u^2 + 1)^n} du \quad \text{M1}$$

So

$$\int_0^\infty \frac{x^{2n-2}}{(x^4 - x^2 + 1)^n} dx = \int_0^\infty \frac{1}{(u^2 + 1)^n} du = I_n \quad \text{M1}$$

$$= \frac{(2(n-1))! \pi}{2^{2(n-1)+1} ((n-1)!)^2} = \frac{(2n-2)! \pi}{2^{2n-1} ((n-1)!)^2} \quad \text{A1 (5)}$$

2. (i) True.

**B1**

$$m = 1000$$

**B1**

If  $n \geq 1000$ , then  $1000 \leq n$ , so  $1000n \leq n^2$ , i.e.  $(1000n) \leq (n^2)$

**M1A1 (4)**

(ii) False.

**B1**

E.G. Let  $s_n = 1$  and  $t_n = 2$  for  $n$  odd, and  $s_n = 2$  and  $t_n = 1$  for  $n$  even.

**B1**

Then  $\nexists m$  for which for  $n \geq m$ ,  $s_n \leq t_n$ , nor  $t_n \leq s_n$

**M1**

So it is not the case that  $(s_n) \leq (t_n)$ , but nor is it the case that  $(t_n) \leq (s_n)$

**A1 (4)**

(iii) True.

**B1**

$(s_n) \leq (t_n)$  means that there exists a positive integer, say  $m_1$ , for which for  $n \geq m_1$ ,  $s_n \leq t_n$ .

**E1**

$(t_n) \leq (u_n)$  means that there exists a positive integer, say  $m_2$ , for which for  $n \geq m_2$ ,  $t_n \leq u_n$ .

**E1**

Then if  $m = \max(m_1, m_2)$ ,

**B1**

for  $n \geq m$ ,  $s_n \leq t_n \leq u_n$ , and so  $(s_n) \leq (u_n)$

**A1 (5)**

(iv) True.

**B1**

$$m = 4$$

**B1**

Assume  $k^2 \leq 2^k$  for some value  $k \geq 4$ .

**B1**

Then  $(k+1)^2 = \left(\frac{k+1}{k}\right)^2 k^2 = \left(1 + \frac{1}{k}\right)^2 k^2 \leq \left(1 + \frac{1}{4}\right)^2 k^2 = \frac{25}{16}k^2 < 2k^2 \leq 2 \times 2^k = 2^{k+1}$

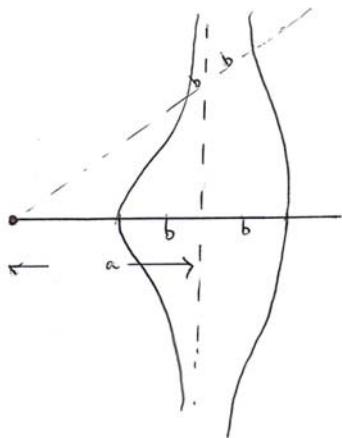
**M1A1**

$$4^2 = 2^4$$

**B1**

so by the principle of mathematical induction,  $n^2 \leq 2^n$  for  $n \geq 4$ , and thus  $(n^2) \leq (2^n)$  **A1 (7)**

3. (i)



Symmetry about initial line G1

Two branches G1

Shape and labelling G1 (3)

If  $|r - a \sec \theta| = b$ , then  $r - a \sec \theta = b$  or  $r - a \sec \theta = -b$

So  $r = a \sec \theta + b$  or  $r = a \sec \theta - b$  M1A1

If  $\sec \theta < 0$ ,  $a \sec \theta + b < -a + b < 0$  as  $a > b$  and  $a \sec \theta - b < -a - b < 0$  as  $a$  and  $b$  are both positive, and thus in both cases,  $r < 0$  which is not permitted. B1

If  $\sec \theta > 0$ ,  $a \sec \theta + b > a + b > 0$  and  $a \sec \theta - b > a - b > 0$  giving  $r > 0$

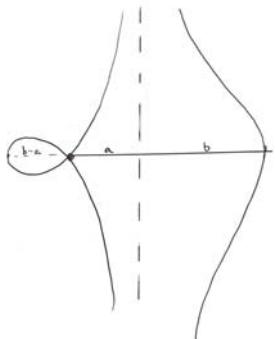
so  $\sec \theta > 0$  as required. B1 (4)

So  $r = a \sec \theta \pm b$ , thus points satisfying (\*) lie on a certain conchoid of Nicomedes with A being the pole (origin), B1

$d$  being  $b$ , B1

and L being the line  $r = a \sec \theta$ . B1 (3)

(ii)



Symmetry about initial line G1

Two branches G1

Loop, shape and labelling G1

If  $a < b$ , then the curve has two branches,  $r = a \sec \theta + b$  with  $\sec \theta > 0$  and  $r = a \sec \theta + b$  with  $\sec \theta < 0$ , the endpoints of the loop corresponding to  $\sec \theta = \frac{-b}{a}$ . **B1 (4)**

In the case  $a = 1$  and  $b = 2$ ,  $\sec \theta = \frac{-2}{1} = -2$  so  $\theta = \pm \frac{2\pi}{3}$

Area of loop

$$= 2 \times \frac{1}{2} \int_{-\frac{2\pi}{3}}^{\frac{\pi}{3}} (\sec \theta + 2)^2 d\theta \quad \text{M1A1}$$

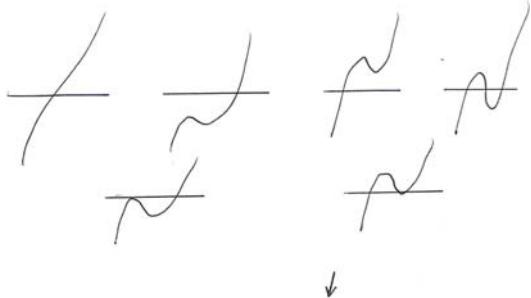
$$= \int_{-\frac{2\pi}{3}}^{\frac{\pi}{3}} \sec^2 \theta + 4 \sec \theta + 4 d\theta = [\tan \theta + 4 \ln |\sec \theta + \tan \theta| + 4\theta]_{-\frac{2\pi}{3}}^{\frac{\pi}{3}} \quad \text{M1A1}$$

$$= 4\pi - \left( -\sqrt{3} + 4 \ln |-2 - \sqrt{3}| + \frac{8\pi}{3} \right) = \frac{4\pi}{3} + \sqrt{3} - 4 \ln |2 + \sqrt{3}| \quad \text{M1A1 (6)}$$

4. (i)  $y = z^3 + az^2 + bz + c$  is continuous.

For  $z \rightarrow -\infty, y \rightarrow -\infty$  and for  $z \rightarrow \infty, y \rightarrow \infty$ . B1

So the sketch of this graph must be one of the following:-



↙

\_\_\_\_\_

↗

B1

Hence, it must intersect the  $z$  axis at least once, and so there is at least one real root of

$$z^3 + az^2 + bz + c = 0 \quad \text{B1 (3)}$$

$$(ii) \quad z^3 + az^2 + bz + c = (z - z_1)(z - z_2)(z - z_3) \quad \text{M1}$$

$$\text{Thus } a = (-z_1 - z_2 - z_3) = -S_1 \quad \text{span style="color:red">A1$$

$$b = (z_2 z_3 + z_3 z_1 + z_1 z_2) = \frac{(z_1 + z_2 + z_3)^2 - (z_1^2 + z_2^2 + z_3^2)}{2} = \frac{S_1^2 - S_2}{2} \quad \text{span style="color:red">A1$$

$$\text{and, as } z_1^3 + az_1^2 + bz_1 + c = 0, z_2^3 + az_2^2 + bz_2 + c = 0, z_3^3 + az_3^2 + bz_3 + c = 0$$

adding these three equations we have,

$$(z_1^3 + z_2^3 + z_3^3) + a(z_1^2 + z_2^2 + z_3^2) + b(z_1 + z_2 + z_3) + 3c = 0 \quad \text{span style="color:red">M1$$

(Alternatively,

$$(z_1 + z_2 + z_3)^3 =$$

$$(z_1^3 + z_2^3 + z_3^3) + 3(z_1^2 z_2 + z_2^2 z_3 + z_3^2 z_1 + z_1^2 z_3 + z_2^2 z_1 + z_3^2 z_2) + 6z_1 z_2 z_3$$

$$(z_1^2 + z_2^2 + z_3^2)(z_1 + z_2 + z_3) = (z_1^3 + z_2^3 + z_3^3) + (z_1^2 z_2 + z_2^2 z_3 + z_3^2 z_1 + z_1^2 z_3 + z_2^2 z_1 + z_3^2 z_2)$$

$$\text{So } S_3 - S_1 S_2 + \frac{S_1^2 - S_2}{2} S_1 + 3c = 0 \quad \text{span style="color:red">M1$$

$$\text{Thus } 6c = (3S_1 S_2 - S_1^3 - 2S_3) \quad \text{span style="color:red">A1* (6)$$

(iii) Let  $z_k = r_k(\cos \theta_k + i \sin \theta_k)$  for  $k = 1, 2, 3$

**M1**

Then  $z_k^2 = r_k^2(\cos 2\theta_k + i \sin 2\theta_k)$  and  $z_k^3 = r_k^3(\cos 3\theta_k + i \sin 3\theta_k)$  by de Moivre  
As

$$\sum_{k=1}^3 r_k \sin \theta_k = 0$$

$$\sum_{k=1}^3 r_k^2 \sin 2\theta_k = 0$$

$$\sum_{k=1}^3 r_k^3 \sin 3\theta_k = 0$$

$$Im\left(\sum_{k=1}^3 z_k\right) = 0$$

$$Im\left(\sum_{k=1}^3 z_k^2\right) = 0$$

$$Im\left(\sum_{k=1}^3 z_k^3\right) = 0$$

and so  $S_1$ ,  $S_2$ , and  $S_3$  are real,

**M1**

and therefore so are  $a$ ,  $b$ , and  $c$

**A1**

Hence, as  $z_1$ ,  $z_2$ , and  $z_3$  are the roots of  $z^3 + az^2 + bz + c = 0$  with  $a$ ,  $b$ , and  $c$  real, by part (i), at least one of  $z_1$ ,  $z_2$ , and  $z_3$  is real.

**M1**

So for at least one value of  $k$ ,  $r_k(\cos \theta_k + i \sin \theta_k)$  is real and thus,  $\sin \theta_k = 0$ ,

and as  $-\pi < \theta_k < \pi$ ,  $\theta_k = 0$  as required.

**A1 (6)**

If  $\theta_1 = 0$  then  $z_1$  is real.  $z_2$  and  $z_3$  are the roots of  $(z - z_2)(z - z_3) = 0$

which is  $z^2 + (-z_2 - z_3)z + z_2 z_3 = 0$  (say  $z^2 + pz + q = 0$ )

$p = -z_2 - z_3 = a + z_1$  and  $q = z_2 z_3 = -\frac{c}{z_1}$  and so the quadratic of which  $z_2$  and  $z_3$  are the roots has real coefficients. Thus  $z_2$ ,  $z_3 = \frac{-p \pm \sqrt{p^2 - 4q}}{2}$ . ( $z_1 \neq 0$  because  $r_k > 0$ )

**B1**

If  $p^2 - 4q < 0$ ,

**M1**

Thus  $\cos \theta_2 = \cos \theta_3$ , and so  $\theta_2 = \pm \theta_3$ , as  $-\pi < \theta_k < \pi$ .

But  $\sin \theta_2 = -\sin \theta_3$  and so  $\theta_2 = -\theta_3$ .

**M1 A1**

If  $p^2 - 4q \geq 0$ , then  $z_2$  and  $z_3$  are real roots, so  $\sin \theta_2 = \sin \theta_3 = 0$ , and thus  $\theta_2 = \theta_3 = 0$ , so  $\theta_2 = -\theta_3$ .

**B1 (5)**



5. (i) Having assumed that  $\sqrt{2}$  is rational (step 1),  $\sqrt{2} = \frac{p}{q}$ , where  $p, q \in \mathbb{Z}, q \neq 0$  **B1**

Thus from the definition of  $S$  (step 2), as  $q \in \mathbb{Z}$  and  $\sqrt{2} = q \times \frac{p}{q} = p \in \mathbb{Z}$ , so  $q \in S$  proving step 3.  
**B1 (2)**

If  $k \in S$ , then  $k$  is an integer and  $k\sqrt{2}$  is an integer. **B1**

So  $(\sqrt{2} - 1)k = k\sqrt{2} - k$  is an integer, **B1**

and  $(\sqrt{2} - 1)k\sqrt{2} = 2k - k\sqrt{2}$  which is an integer and so  $(\sqrt{2} - 1)k \in S$  proving step 5. **B1 (3)**

$1 < \sqrt{2} < 2$  and so **M1**

$0 < \sqrt{2} - 1 < 1$ , and thus  $0 < (\sqrt{2} - 1)k < k$  **A1**

and thus this contradicts step 4 that  $k$  is the smallest positive integer in  $S$  as  $(\sqrt{2} - 1)k$  has been shown to be a smaller positive integer and is in  $S$ . **A1 (3)**

(ii) If  $2^{\frac{2}{3}}$  is rational, then  $2^{\frac{2}{3}} = \frac{p}{q}$ , where  $p, q \in \mathbb{Z}, q \neq 0$

So  $(2^{\frac{2}{3}})^2 = (\frac{p}{q})^2$ , that is  $2^{\frac{4}{3}} = \frac{p^2}{q^2}$ , which can be written  $2 \times 2^{\frac{1}{3}} = \frac{p^2}{q^2}$  **M1**

and hence  $2^{\frac{1}{3}} = \frac{p^2}{2q^2}$  proving that  $2^{\frac{1}{3}}$  is rational. **A1**

If  $2^{\frac{1}{3}}$  is rational, then  $2^{\frac{1}{3}} = \frac{p}{q}$ , where  $p, q \in \mathbb{Z}, q \neq 0$  **M1**

and so  $2^{\frac{2}{3}} = \frac{p^2}{q^2}$  proving that  $2^{\frac{2}{3}}$  is rational and that  $2^{\frac{1}{3}}$  is rational only if  $2^{\frac{2}{3}}$  is rational.

**A1 (4)**

Assume that  $2^{\frac{1}{3}}$  is rational.

Define the set  $T$  to be the set of positive integers with the following property:  $n$  is in  $T$  if and only if  $n2^{\frac{1}{3}}$  and  $n2^{\frac{2}{3}}$  are integers. **B1**

The set  $T$  contains at least one positive integer as if  $2^{\frac{1}{3}} = \frac{p}{q}$ , where  $p, q \in \mathbb{Z}, q \neq 0$ , then  $q^2 2^{\frac{1}{3}} = q^2 \times \frac{p}{q} = pq \in \mathbb{Z}$  and  $q^2 2^{\frac{2}{3}} = q^2 \times \frac{p^2}{q^2} = p^2 \in \mathbb{Z}$ , so  $q^2 \in T$ . **M1A1**

Define  $t$  to be the smallest positive integer in  $T$ . Then  $t2^{\frac{1}{3}}$  and  $t2^{\frac{2}{3}}$  are integers. **B1**

Consider  $t(2^{\frac{2}{3}} - 1)$ .  $t(2^{\frac{2}{3}} - 1) = t2^{\frac{2}{3}} - t$  which is the difference of two integers and so is itself an integer.  $t(2^{\frac{2}{3}} - 1) \times 2^{\frac{1}{3}} = 2t - t2^{\frac{1}{3}}$  which is an integer,

and  $t(2^{\frac{2}{3}} - 1) \times 2^{\frac{2}{3}} = 2^{\frac{4}{3}}t - t2^{\frac{2}{3}} = 2 \times 2^{\frac{1}{3}}t - t2^{\frac{2}{3}}$  which is an integer.

Thus  $t(2^{2/3} - 1)$  is in  $T$ .

**M1A1**

$1 < 2^{2/3} < 2$  and so  $0 < 2^{2/3} - 1 < 1$ , and thus  $0 < t(2^{2/3} - 1) < t$ , and thus this contradicts that  $t$  is the smallest positive integer in  $T$  as  $t(2^{2/3} - 1)$  has been shown to be a smaller positive integer and is in  $T$ .

**M1A1 (8)**

6. (i)  $w, z \in \mathbb{R} \Rightarrow u, v \in \mathbb{R}$  B1

For  $w, z \in \mathbb{R}$ , we require to solve  $w + z = u$ ,  $w^2 + z^2 = v$  M1

$$w^2 + (u - w)^2 = v$$

$$2w^2 - 2uw + (u^2 - v) = 0$$

$$w = \frac{2u \pm \sqrt{4u^2 - 8u^2 + 8v}}{4} = \frac{u \pm \sqrt{2v - u^2}}{2}$$

$$z = \frac{u \mp \sqrt{2v - u^2}}{2}$$

M1A1

So for  $w, z \in \mathbb{R}$ , as  $u = w + z$  must be real,  $v = w^2 + z^2$  must be real, and  $2v - u^2 \geq 0$

i.e.  $u^2 \leq 2v$  B1\* (5)

(ii)  $u = w + z \Rightarrow u^2 = w^2 + z^2 + 2wz$  so if  $w^2 + z^2 - u^2 = -\frac{2}{3}$ , then  $-2wz = -\frac{2}{3}$

so  $3wz = 1$  M1A1

$$w^3 + z^3 = (w + z)(w^2 + z^2 - wz) = u(u^2 - 3wz) = u(u^2 - 1)$$

M1A1

Thus if  $w^3 + z^3 - \lambda u = -\lambda$ ,  $u(u^2 - 1) = \lambda(u - 1)$  M1A1

Thus  $(u - 1)(u(u + 1) - \lambda) = 0$ , M1

$$(u - 1)(u^2 + u - \lambda) = 0$$
 M1A1

$$\text{Thus } u = 1 \text{ or } u = \frac{-1 \pm \sqrt{1+4\lambda}}{2}$$

So as  $\lambda \in \mathbb{R}$  and  $\lambda > 0$ , the values of  $u$  are real. B1

There are three distinct values of  $u$  unless  $\frac{-1 \pm \sqrt{1+4\lambda}}{2} = 1$  in which case  $\pm \sqrt{1+4\lambda} = 3$ , i.e.  $\lambda = 2$

M1A1 (12)

For  $w, z \in \mathbb{R}$ , from (i) we require  $u \in \mathbb{R}$  which it is,  $u^2 - \frac{2}{3} \in \mathbb{R}$  which it is, and  $u^2 \leq 2\left(u^2 - \frac{2}{3}\right)$  in other words  $u^2 \geq \frac{4}{3}$ . M1

So  $w$  and  $z$  need not be real. A counterexample would be  $u = 1$  B1

for then  $w + z = 1$ ,  $w^2 + z^2 = \frac{1}{3}$ , so  $w^2 + (1 - w)^2 = \frac{1}{3}$ , i.e.  $2w^2 - 2w + \frac{2}{3} = 0$  in which case the discriminant is  $-\frac{4}{3} < 0$  so  $w \notin \mathbb{R}$ . B1 (3)

$$7. \quad D^2x^a = D(D(x^a)) = D\left(x \frac{d}{dx}(x^a)\right) = D(xax^{a-1}) \quad \text{M1}$$

$$= D(ax^a) = x \frac{d}{dx}(ax^a) = xa^2x^{a-1} = a^2x^a \quad \text{M1A1 (3)}$$

(i) Suppose  $D^k P(x)$  is a polynomial of degree  $r$  i.e.  $D^k P(x) = a_r x^r + a_{r-1} x^{r-1} + \dots + a_0$  for some integer  $k$ . B1

$$\text{Then } D^{k+1} P(x) = D(a_r x^r + a_{r-1} x^{r-1} + \dots + a_0) = x \frac{d}{dx}(a_r x^r + a_{r-1} x^{r-1} + \dots + a_0)$$

$$= x(ra_r x^{r-1} + (r-1)a_{r-1} x^{r-2} + \dots + a_1) = ra_r x^r + (r-1)a_{r-1} x^{r-1} + \dots + a_1 x$$

which is a polynomial of degree  $r$ . M1A1

Suppose  $P(x) = b_r x^r + b_{r-1} x^{r-1} + \dots + b_0$ , then

$$DP(x) = x \frac{d}{dx}(b_r x^r + b_{r-1} x^{r-1} + \dots + b_0) = rb_r x^r + (r-1)b_{r-1} x^{r-1} + \dots + b_1 x \text{ so the result is true for } n = 1, \quad \text{M1A1}$$

and we have shown that if it is true for  $n = k$ , it is true for  $n = k + 1$ . Hence by induction, it is true for any positive integer . B1 (6)

(ii) Suppose  $D^k(1-x)^m$  is divisible by  $(1-x)^{m-k}$  i.e.  $D^k(1-x)^m = f(x)(1-x)^{m-k}$  for some integer  $k$ , with  $k < m - 1$ . B1

$$\text{Then } D^{k+1}(1-x)^m = D(f(x)(1-x)^{m-k}) = x \frac{d}{dx}(f(x)(1-x)^{m-k})$$

$$= x(f'(x)(1-x)^{m-k} - (m-k)f(x)(1-x)^{m-k-1})$$

$$= x(1-x)^{m-k-1} \left( f'(x)(1-x) - (m-k)f(x) \right) \text{ which is divisible by } (1-x)^{m-(k+1)}. \quad \text{M1A1}$$

$$D(1-x)^m = x \frac{d}{dx}((1-x)^m) = -mx(1-x)^{m-1} \text{ so result is true for } n = 1. \quad \text{M1A1}$$

We have shown that if it is true for  $n = k$ , it is true for  $n = k + 1$ . Hence by induction, it is true for any positive integer  $< m$ . B1 (6)

(iii)

$$(1-x)^m = \sum_{r=0}^m \binom{m}{r} (-x)^r = \sum_{r=0}^m (-1)^r \binom{m}{r} x^r \quad \text{M1}$$

So

$$D^n(1-x)^m = \sum_{r=0}^m (-1)^r \binom{m}{r} D^n x^r = \sum_{r=0}^m (-1)^r \binom{m}{r} r^n x^r \quad \text{M1A1}$$

But by (ii),  $D^n(1-x)^m$  is divisible by  $(1-x)^{m-n}$  and so  $D^n(1-x)^m = g(x)(1-x)^{m-n}$ , and thus if  $x = 1$ ,  $D^n(1-x)^m = 0$ , and hence

$$\sum_{r=0}^m (-1)^r \binom{m}{r} r^n = 0 \quad \text{M1A1* (5)}$$

$$8. \text{ (i)} \quad x = r \cos \theta \Rightarrow \frac{dx}{d\theta} = -r \sin \theta + \frac{dr}{d\theta} \cos \theta \quad \text{M1A1}$$

$$\text{and } y = r \sin \theta \Rightarrow \frac{dy}{d\theta} = r \cos \theta + \frac{dr}{d\theta} \sin \theta \quad \text{M1A1}$$

$$\text{Thus } (y+x) \frac{dy}{dx} = y-x \text{ becomes } (r \sin \theta + r \cos \theta) \frac{\frac{r \cos \theta + \frac{dr}{d\theta} \sin \theta}{r \sin \theta + \frac{dr}{d\theta} \cos \theta}}{r \sin \theta - r \cos \theta} = r \sin \theta - r \cos \theta \quad \text{M1}$$

$$\text{That is } (\sin \theta + \cos \theta) \left( r \cos \theta + \frac{dr}{d\theta} \sin \theta \right) = (\sin \theta - \cos \theta) \left( -r \sin \theta + \frac{dr}{d\theta} \cos \theta \right)$$

as  $r > 0, r \neq 0$

Multiplying out and collecting like terms gives

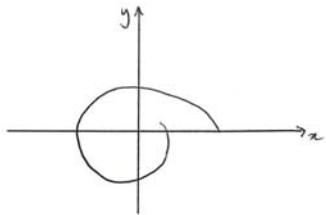
$$r(\cos^2 \theta + \sin^2 \theta) + \frac{dr}{d\theta}(\sin^2 \theta + \cos^2 \theta) = 0$$

$$\text{which is } r + \frac{dr}{d\theta} = 0. \quad \text{M1A1* (7)}$$

$$\text{So } re^\theta + \frac{dr}{d\theta} e^\theta = 0 \quad \text{M1}$$

$$\text{and thus } re^\theta = k, \quad \text{A1}$$

$$r = ke^{-\theta} \quad \text{A1}$$



**G1 (4)**

$$(\text{or alternatively } \int \frac{1}{r} dr = \int -d\theta \text{ M1 so } \ln|r| = -\theta + c \text{ A1 and hence } r = ke^{-\theta} \text{ A1})$$

$$\text{(ii)} \quad (y + x - x(x^2 + y^2)) \frac{dy}{dx} = y - x - y(x^2 + y^2)$$

$$\text{becomes } (r \sin \theta + r \cos \theta - r^3 \cos \theta) \frac{\frac{r \cos \theta + \frac{dr}{d\theta} \sin \theta}{r \sin \theta + \frac{dr}{d\theta} \cos \theta}}{r \sin \theta - r \cos \theta - r^3 \sin \theta} = r \sin \theta - r \cos \theta - r^3 \sin \theta$$

that is

$$(\sin \theta + \cos \theta - r^2 \cos \theta) \left( r \cos \theta + \frac{dr}{d\theta} \sin \theta \right) = (\sin \theta - \cos \theta - r^2 \sin \theta) \left( -r \sin \theta + \frac{dr}{d\theta} \cos \theta \right)$$

Multiplying out and collecting like terms gives

$$r(\cos^2 \theta + \sin^2 \theta - r^2(\cos^2 \theta + \sin^2 \theta)) + \frac{dr}{d\theta}(\sin^2 \theta + \cos^2 \theta) = 0 \quad \text{M1}$$

which is  $r - r^3 + \frac{dr}{d\theta} = 0$ . A1

$$\int \frac{1}{r^3 - r} dr = \int d\theta$$

$$\int \frac{1}{r^3 - r} dr = \int \frac{1}{r(r^2 - 1)} dr = \int \frac{1}{r(r-1)(r+1)} dr = \int d\theta \quad \text{M1}$$

So  $\int d\theta = \int \frac{1/2}{r-1} + \frac{-1}{r} + \frac{1/2}{r+1} dr$  A1

$$\theta + k = \frac{1}{2} \ln \left| \frac{(r-1)(r+1)}{r^2} \right| \quad \text{A1}$$

So

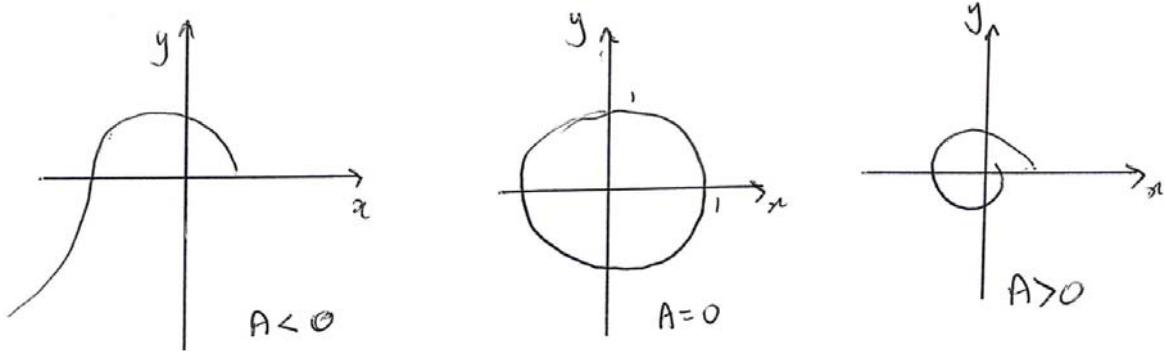
$$\left| \frac{r^2 - 1}{r^2} \right| = C e^{2\theta}$$

with  $C > 0$

$$r^2 = \frac{1}{1 \mp C e^{2\theta}}$$

that is

$$r^2 = \frac{1}{1 + A e^{2\theta}} \quad \text{A1*}$$



G1 G1 G1 (9)

9. If the initial position of  $P$  is , then at time  $t$  ,  $OP^2 = a^2 + x^2$  , so conserving energy,

$$\frac{1}{2}mv^2 = \frac{1}{2}m\dot{x}^2 + \frac{\lambda}{2a}\left(\sqrt{a^2 + x^2} - a\right)^2$$

**M1 A1 A1**

Thus,

$$\dot{x}^2 = v^2 - \frac{\lambda}{ma}\left(\sqrt{a^2 + x^2} - a\right)^2$$

**M1**

i.e.

$$\dot{x}^2 = v^2 - k^2\left(\sqrt{a^2 + x^2} - a\right)^2$$

**A1\* (5)**

The greatest value,  $x_0$  , attained by  $x$  , occurs when  $\dot{x} = 0$ . **M1**

$$\text{Thus } v^2 = k^2\left(\sqrt{a^2 + x_0^2} - a\right)^2$$

$$\text{So } \sqrt{a^2 + x_0^2} - a = \frac{v}{k} \text{ (negative root discounted as all quantities are positive)}$$

Thus

$$x_0^2 = \left(\frac{v}{k} + a\right)^2 - a^2 = \frac{v^2}{k^2} + \frac{2av}{k}$$

and

$$x_0 = \sqrt{\frac{v^2}{k^2} + \frac{2av}{k}}$$

**M1 A1 (3)**

As

$$\dot{x}^2 = v^2 - k^2\left(\sqrt{a^2 + x^2} - a\right)^2$$

differentiating with respect to  $t$

$$2\ddot{x}\dot{x} = -2k^2\left(\sqrt{a^2 + x^2} - a\right)\frac{1}{2}(a^2 + x^2)^{-\frac{1}{2}}2x\dot{x}$$

**M1 A1**

Thus

$$\ddot{x} = -xk^2 \frac{\left(\sqrt{a^2 + x^2} - a\right)}{\sqrt{a^2 + x^2}}$$

**A1**

So when  $x = x_0$ , the acceleration of  $P$  is

$$-x_0 k^2 \frac{v}{\frac{k}{k+a}} = -\sqrt{\frac{v^2}{k^2} + \frac{2av}{k}} k^2 \frac{v}{\frac{v}{k+a}} = -\frac{kv\sqrt{v^2 + 2akv}}{v+ak}$$

**M1 A1 (5)**

$$\dot{x} = \left[ v^2 - k^2 (\sqrt{a^2 + x^2} - a) \right]^{\frac{1}{2}}$$

That is

$$\frac{dx}{dt} = \left[ v^2 - k^2 (\sqrt{a^2 + x^2} - a) \right]^{\frac{1}{2}}$$

and thus

$$\int_0^{\tau/4} dt = \int_0^{x_0} \frac{1}{\left[ v^2 - k^2 (\sqrt{a^2 + x^2} - a) \right]^{\frac{1}{2}}} dx$$

where  $\tau$  is the period.

**M1 A1**

So

$$\tau = 4 \int_0^{x_0} \frac{1}{\left[ v^2 - k^2 (\sqrt{a^2 + x^2} - a) \right]^{\frac{1}{2}}} dx$$

$$\tau = \frac{4}{v} \int_0^{\sqrt{\frac{v^2 + 2av}{k}}} \frac{1}{\left[ 1 - \frac{k^2 (\sqrt{a^2 + x^2} - a)}{v^2} \right]^{\frac{1}{2}}} dx$$

Let

$$u^2 = \frac{k(\sqrt{a^2 + x^2} - a)}{v}$$

**B1**

then

$$a^2 + x^2 = \left( \frac{vu^2}{k} + a \right)^2$$

and so

$$x^2 = \frac{v^2 u^4 + 2kavu^2}{k^2}$$

$$x = \sqrt{2kav} \frac{u}{k} \left(1 + \frac{v}{2ka} u^2\right)^{\frac{1}{2}} \approx \sqrt{2kav} \frac{u}{k}$$

as  $v \ll ka$

Thus

$$\frac{dx}{du} \approx \frac{1}{k} \sqrt{2kav}$$

**M1A1**

and so

$$\tau \approx \frac{4}{v} \int_0^1 \frac{1}{\sqrt{1-u^4}} \frac{1}{k} \sqrt{2kav} du = \sqrt{\frac{32a}{kv}} \int_0^1 \frac{1}{\sqrt{1-u^4}} du$$

as required.

**M1 A1\* (7)**

10. The position vector of the upper particle is

$$\begin{pmatrix} x + a \sin \theta \\ y + a \cos \theta \end{pmatrix}$$

**B1 B1**

so differentiating with respect to time, its velocity is

$$\begin{pmatrix} \dot{x} + a \dot{\theta} \cos \theta \\ \dot{y} - a \dot{\theta} \sin \theta \end{pmatrix}$$

**E1\* (3)**

Its acceleration, by differentiating with respect to time, is thus

$$\begin{pmatrix} \ddot{x} + a \ddot{\theta} \cos \theta - a \dot{\theta}^2 \sin \theta \\ \ddot{y} - a \ddot{\theta} \sin \theta - a \dot{\theta}^2 \cos \theta \end{pmatrix}$$

**M1 A1 A1**

so by Newton's second law resolving horizontally and vertically

$$\begin{pmatrix} -T \sin \theta \\ -T \cos \theta - mg \end{pmatrix} = m \begin{pmatrix} \ddot{x} + a \ddot{\theta} \cos \theta - a \dot{\theta}^2 \sin \theta \\ \ddot{y} - a \ddot{\theta} \sin \theta - a \dot{\theta}^2 \cos \theta \end{pmatrix}$$

**M1 A1**

That is

$$m \begin{pmatrix} \ddot{x} + a \ddot{\theta} \cos \theta - a \dot{\theta}^2 \sin \theta \\ \ddot{y} - a \ddot{\theta} \sin \theta - a \dot{\theta}^2 \cos \theta \end{pmatrix} = -T \begin{pmatrix} \sin \theta \\ \cos \theta \end{pmatrix} - mg \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

The other particle's equation is

$$m \begin{pmatrix} \ddot{x} - a \ddot{\theta} \cos \theta + a \dot{\theta}^2 \sin \theta \\ \ddot{y} + a \ddot{\theta} \sin \theta + a \dot{\theta}^2 \cos \theta \end{pmatrix} = T \begin{pmatrix} \sin \theta \\ \cos \theta \end{pmatrix} - mg \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

**B1 (6)**

Adding these two equations we find

$$2m \begin{pmatrix} \ddot{x} \\ \ddot{y} \end{pmatrix} = -2mg \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

i.e.  $\ddot{x} = 0$  and  $\ddot{y} = -g$  **M1 A1\***

Thus

$$m \begin{pmatrix} -a \ddot{\theta} \cos \theta + a \dot{\theta}^2 \sin \theta \\ a \ddot{\theta} \sin \theta + a \dot{\theta}^2 \cos \theta \end{pmatrix} = T \begin{pmatrix} \sin \theta \\ \cos \theta \end{pmatrix}$$

i.e.  $m(-a \ddot{\theta} \cos \theta + a \dot{\theta}^2 \sin \theta) = T \sin \theta$  and  $m(a \ddot{\theta} \sin \theta + a \dot{\theta}^2 \cos \theta) = T \cos \theta$

Multiplying the second of these by  $\sin \theta$  and the first by  $\cos \theta$  and subtracting,

$ma\ddot{\theta} = 0$  and so  $\ddot{\theta} = 0$ .

**M1A1\* (4)**

Thus  $\dot{\theta} = a$  constant and as initially  $2a\dot{\theta} = u$ ,  $\dot{\theta} = \frac{u}{2a}$  **M1 A1**

Therefore the time to rotate by  $\frac{1}{2}\pi$  is given by  $\tau\dot{\theta} = \frac{1}{2}\pi$ , so  $\tau = \frac{1}{2}\pi \div \frac{u}{2a} = \frac{\pi a}{u}$  **A1**

As  $\ddot{y} = -g$  and initially  $\dot{y} = v$ , at time  $t$ ,  $\dot{y} = v - gt$ , and so  $y = vt - \frac{1}{2}gt^2 + h$  as the centre of the rod is initially  $h$  above the table. **M1 A1**

Hence, given the condition that the particles hit the table simultaneously,

$$0 = v\pi a/u - 1/2 g(\pi a/u)^2 + h$$

Hence  $0 = 2\pi uva - \pi^2 a^2 g + 2hu^2$ , or  $2hu^2 = \pi^2 a^2 g - 2\pi uva$  as required. **M1 A1\* (7)**

11. (i) Suppose that the force exerted by  $P$  on the rod has components  $X$  perpendicular to the rod and  $Y$  parallel to the rod. Then taking moments for the rod about the hinge,  $Xd = 0$ , **M1**

which as  $d \neq 0$  yields  $X = 0$  and hence the force exerted on the rod by  $P$  is parallel to the rod.

**A1\* (2)**

Resolving perpendicular to the rod for  $P$ ,  $mg \sin \alpha = m(r - d \sin \alpha)\omega^2 \cos \alpha$  **M1 A1**

$$\text{Dividing by } m\omega^2 \sin \alpha, \frac{g}{\omega^2} = (r - d \sin \alpha) \cot \alpha$$

That is  $a = r \cot \alpha - d \cos \alpha$  or in other words  $r \cot \alpha = a + d \cos \alpha$  as required. **M1 A1\* (4)**

The force exerted by the hinge on the rod is along the rod towards  $P$ , **B1**

and if that force is  $F$ , then resolving vertically for  $P$ ,  $F \cos \alpha = mg$  **M1 A1**

$$\text{so } F = mg \sec \alpha. \quad \text{A1 (4)}$$

(ii) Suppose that the force exerted by  $m_1$  on the rod has component  $X_1$  perpendicular to the rod towards the axis, that the force exerted by  $m_2$  on the rod has component  $X_2$  perpendicular to the rod towards the axis, **B1**

then resolving perpendicular to the rod for  $m_1$ ,  $m_1 g \sin \beta + X_1 = m_1(r - d_1 \sin \beta)\omega^2 \cos \beta$

**M1A1**

and similarly for  $m_2$ ,  $m_2 g \sin \beta + X_2 = m_2(r - d_2 \sin \beta)\omega^2 \cos \beta$

**M1A1**

Taking moments for the rod about the hinge,  $X_1 d_1 + X_2 d_2 = 0$  **M1A1**

So multiplying the first equation by  $d_1$ , the second by  $d_2$  and adding we have

$$m_1 g d_1 \sin \beta + m_2 d_2 g \sin \beta = m_1 d_1 (r - d_1 \sin \beta) \omega^2 \cos \beta + m_2 d_2 (r - d_2 \sin \beta) \omega^2 \cos \beta$$

$$\text{Dividing by } (m_1 d_1 + m_2 d_2) \omega^2 \sin \beta, \frac{g}{\omega^2} = r \cot \beta - \left( \frac{m_1 d_1^2 + m_2 d_2^2}{m_1 d_1 + m_2 d_2} \right) \cos \beta \quad \text{M1A1}$$

$$\text{That is } r \cot \beta = a + b \cos \beta, \text{ where } b = \frac{m_1 d_1^2 + m_2 d_2^2}{m_1 d_1 + m_2 d_2} \quad \text{A1 (10)}$$

12. (i) The probability distribution function of  $S_1$  is

$S_1$	1	2	3	4	5	6
$p$	$1/6$	$1/6$	$1/6$	$1/6$	$1/6$	$1/6$

so the probability distribution function of  $R_1$  is

$R_1$	0	1	2	3	4	5
$p$	$1/6$	$1/6$	$1/6$	$1/6$	$1/6$	$1/6$

and thus  $G(x) = \frac{1}{6}(1 + t + t^2 + t^3 + t^4 + t^5)$ . B1

The probability distribution function of  $S_2$  is

$S_2$	2	3	4	5	6	7	8	9	10	11	12
$p$	$1/36$	$2/36$	$3/36$	$4/36$	$5/36$	$6/36$	$5/36$	$4/36$	$3/36$	$2/36$	$1/36$

M1

so the probability distribution function of  $R_2$  is

$R_2$	0	1	2	3	4	5
$p$	$6/36$	$6/36$	$6/36$	$6/36$	$6/36$	$6/36$

A1

which is the same as for  $R_1$  and hence its probability generating function is also  $G(x)$ . A1\*

Therefore, the probability generating function of  $R_n$  is also  $G(x)$  B1

and thus the probability that  $S_n$  is divisible by 6 is  $1/6$ . B1 (6)

(ii) The probability distribution function of  $T_1$  is

$T_1$	0	1	2	3	4
$p$	$1/6$	$2/6$	$1/6$	$1/6$	$1/6$

and thus  $G_1(x) = \frac{1}{6}(1 + 2x + x^2 + x^3 + x^4)$

**M1 A1**

$G_2(x)$  would be  $(G_1(x))^2$  except that the powers must be multiplied congruent to modulus 5.

$$G_1(x) = \frac{1}{6}(1 + 2x + x^2 + x^3 + x^4) = \frac{1}{6}(x + 1 + x + x^2 + x^3 + x^4) = \frac{1}{6}(x + y) \quad \text{B1}$$

Thus  $G_2(x)$  would be  $\frac{1}{36}(x + y)^2$

$$\text{except } xy = x(1 + x + x^2 + x^3 + x^4) = x + x^2 + x^3 + x^4 + 1 = y \quad \text{M1A1}$$

$$\text{and } y^2 = (1 + x + x^2 + x^3 + x^4)(1 + x + x^2 + x^3 + x^4) = (1 + x + x^2 + x^3 + x^4) + (x + x^2 + x^3 + x^4 + 1) + (x^2 + x^3 + x^4 + 1 + x) + (x^3 + x^4 + 1 + x + x^2) + (x^4 + 1 + x + x^2 + x^3) = 5y \quad \text{A1}$$

$$\text{So } G_2(x) = \frac{1}{36}(x + y)^2 = \frac{1}{36}(x^2 + 2xy + y^2) = \frac{1}{36}(x^2 + 2y + 5y) = \frac{1}{36}(x^2 + 7y) \quad \text{M1A1* (8)}$$

$$G_3(x) = \frac{1}{6^3}(x + y)^3 = \frac{1}{6^3}(x + y)(x^2 + 7y) = \frac{1}{6^3}(x^3 + yx^2 + 7xy + 7y^2)$$

That is

$$G_3(x) = \frac{1}{6^3}(x^3 + yx^2 + 7xy + 7y^2) = \frac{1}{6^3}(x^3 + y + 7y + 35y) = \frac{1}{6^3}(x^3 + 43y)$$

We notice that the coefficient of  $y$  inside the bracket in  $G_n(x)$  is  $(1 + 6 + 6^2 + \dots + 6^{n-1})$

This can be shown simply by induction. It is true for  $n = 1$  trivially.

$$\text{Consider } (x + y)(x^r + (1 + 6 + 6^2 + \dots + 6^{k-1})y) = x^{r+1} + yx^r + (1 + 6 + 6^2 + \dots + 6^{k-1})xy + (1 + 6 + 6^2 + \dots + 6^{k-1})y^2$$

$$\begin{aligned} &yx^r + (1 + 6 + 6^2 + \dots + 6^{k-1})xy + (1 + 6 + 6^2 + \dots + 6^{k-1})y^2 \\ &= y + (1 + 6 + 6^2 + \dots + 6^{k-1})y + 5(1 + 6 + 6^2 + \dots + 6^{k-1})y \end{aligned}$$

$$5(1 + 6 + 6^2 + \dots + 6^{k-1}) = (6 - 1)(1 + 6 + 6^2 + \dots + 6^{k-1}) = 6^k - 1$$

$$\text{So } y + (1 + 6 + 6^2 + \dots + 6^{k-1})y + 5(1 + 6 + 6^2 + \dots + 6^{k-1})y = (1 + 6 + 6^2 + \dots + 6^k)y$$

as required. **M1**

However, this coefficient is the sum of a GP and so  $G_n(x) = \frac{1}{6^n}\left(x^{n-5p} + \frac{6^n-1}{5}y\right)$  where  $p$  is an integer such that  $0 \leq n - 5p \leq 4$ . **M1 A1**

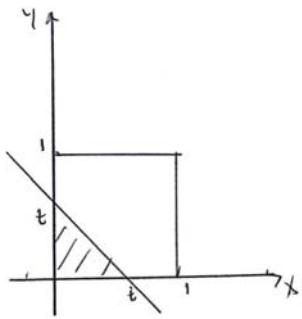
So if  $n$  is not divisible by 5, the probability that  $S_n$  is divisible by 5 will be the coefficient of  $x^0$  which in turn is the coefficient of  $y$ , namely  $\frac{1}{6^n}\left(\frac{6^n-1}{5}\right) = \frac{1}{5}\left(1 - \frac{1}{6^n}\right)$  as required. **B1\***

If  $n$  is divisible by 5, the probability that  $S_n$  is divisible by 5 will be  $\frac{1}{6^n}\left(1 + \frac{6^n-1}{5}\right)$  as  $x^{n-5p} = x^0$

That is  $\frac{1}{5} \left( 1 + \frac{4}{6^n} \right)$

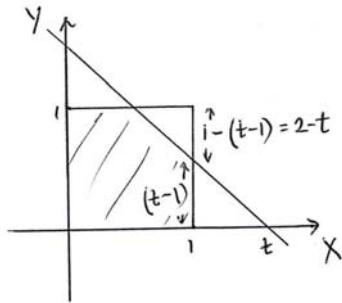
**M1A1 (6)**

13. (i)



**G1**

$$P(X + Y < t) = \frac{1}{2}t^2 \text{ if } 0 \leq t \leq 1 \quad \text{B1}$$



**G1**

$$\text{and } P(X + Y < t) = 1 - \frac{1}{2}(2-t)^2 \text{ if } 1 < t \leq 2 \quad \text{B1}$$

$$P(X + Y < t) = 0 \text{ if } t < 0 \text{ and } P(X + Y < t) = 1 \text{ if } t > 2$$

$$\text{So } F(t) = \begin{cases} 0 & \text{for } t < 0 \\ \frac{1}{2}t^2 & \text{for } 0 \leq t \leq 1 \\ 1 - \frac{1}{2}(2-t)^2 & \text{for } 1 < t \leq 2 \\ 1 & \text{for } t > 2 \end{cases}$$

**B1 (5)**

$$\text{Thus } P((X + Y)^{-1} < t) = P\left(X + Y > \frac{1}{t}\right) = 1 - P\left(X + Y < \frac{1}{t}\right)$$

$$= \begin{cases} 1 - \frac{1}{2t^2} & \text{for } 1 \leq t \\ \frac{1}{2}\left(2 - \frac{1}{t}\right)^2 & \text{for } \frac{1}{2} \leq t < 1 \\ 0 & \text{for } t < \frac{1}{2} \end{cases}$$

**M1 A1**

$$\text{So as } f(t) = \frac{dF(t)}{dt},$$

$$f(t) = \begin{cases} 0 & \text{for } t < \frac{1}{2} \\ \frac{1}{t^2} \left(2 - \frac{1}{t}\right) & \text{for } \frac{1}{2} \leq t < 1 \\ \frac{1}{t^3} & \text{for } 1 \leq t \end{cases}$$

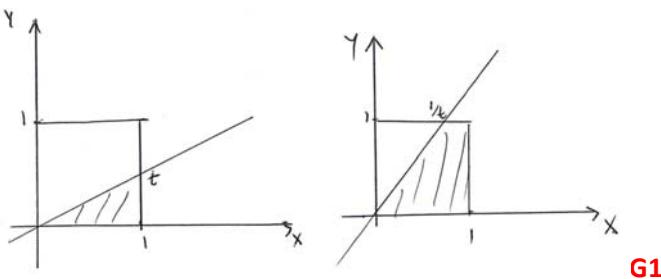
as required.

**M1A1\* (4)**

$$\begin{aligned} E\left(\frac{1}{X+Y}\right) &= \int_{\frac{1}{2}}^1 t(2t^{-2} - t^{-3})dt + \int_1^\infty t \cdot t^{-3} dt = [2\ln t + t^{-1}]_{\frac{1}{2}}^1 + [-t^{-1}]_1^\infty \\ &= 1 - 2\ln\frac{1}{2} - 2 + 1 = 2\ln 2 \end{aligned}$$

**M1 A1 (2)**

(ii)



**G1**

$$P\left(\frac{Y}{X} < t\right) = \begin{cases} \frac{1}{2}t & \text{for } 0 \leq t \leq 1 \\ 1 - \frac{1}{2}t^{-1} & \text{for } t > 1 \end{cases}$$

**B1 (2)**

Thus

$$P\left(\frac{X}{X+Y} < t\right) = P\left(\frac{X+Y}{X} > \frac{1}{t}\right) = P\left(1 + \frac{Y}{X} > \frac{1}{t}\right) = P\left(\frac{Y}{X} > \frac{1}{t} - 1\right) = 1 - P\left(\frac{Y}{X} < \frac{1}{t} - 1\right)$$

So

$$F(t) = \begin{cases} 1 - \frac{1}{2}\left(\frac{1}{t} - 1\right) & \text{for } \frac{1}{2} \leq t \leq 1 \\ \frac{1}{2}\left(\frac{1}{t} - 1\right)^{-1} & \text{for } 0 \leq t < \frac{1}{2} \end{cases}$$

i.e.

$$F(t) = \begin{cases} \frac{1}{2}(3 - t^{-1}) & \text{for } \frac{1}{2} \leq t \leq 1 \\ \frac{1}{2}\left(\frac{t}{1-t}\right) & \text{for } 0 \leq t < \frac{1}{2} \end{cases}$$

**M1A1**

So as  $f(t) = \frac{dF(t)}{dt}$ ,

$$f(t) = \begin{cases} \frac{1}{2}t^{-2} & \text{for } \frac{1}{2} \leq t \leq 1 \\ \frac{1}{2}(1-t)^{-2} & \text{for } 0 \leq t < \frac{1}{2} \end{cases}$$

**M1A1 (4)**

$E\left(\frac{X}{X+Y}\right) = \frac{1}{2}$  because, by symmetry,  $E\left(\frac{X}{X+Y}\right) = E\left(\frac{Y}{X+Y}\right)$

and  $E\left(\frac{X}{X+Y}\right) + E\left(\frac{Y}{X+Y}\right) = E\left(\frac{X+Y}{X+Y}\right) = E(1) = 1$  **B1**

$$\begin{aligned} E\left(\frac{X}{X+Y}\right) &= \int_0^{\frac{1}{2}} \frac{1}{2}t(1-t)^{-2} dt + \int_{\frac{1}{2}}^1 t \times \frac{1}{2}t^{-2} dt \\ &= \left[ \frac{1}{2}t(1-t)^{-1} \right]_0^{\frac{1}{2}} - \int_0^{\frac{1}{2}} \frac{1}{2}(1-t)^{-1} dt + \left[ \frac{1}{2}\ln t \right]_{\frac{1}{2}}^1 \\ &= \frac{1}{2} - \left[ -\frac{1}{2}\ln(1-t) \right]_0^{\frac{1}{2}} - \frac{1}{2}\ln\frac{1}{2} \\ &= \frac{1}{2} + \frac{1}{2}\ln\frac{1}{2} - \frac{1}{2}\ln\frac{1}{2} = \frac{1}{2} \end{aligned}$$

as required.

**M1A1 (3)**