

# STEP MATHEMATICS 3

2018

Mark Scheme

1. (i)  $f(\beta) = \beta - \frac{1}{\beta} - \frac{1}{\beta^2}$

$$f'(\beta) = 1 + \frac{1}{\beta^2} + \frac{2}{\beta^3} = \frac{\beta^3 + \beta + 2}{\beta^3}$$

$$f'(\beta) = 0 \Rightarrow \beta^3 + \beta + 2 = 0$$

**M1**

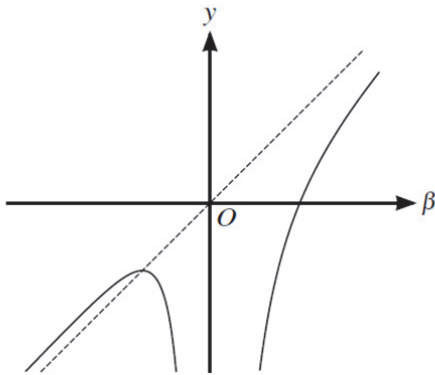
$$\beta^3 + \beta + 2 = (\beta + 1)(\beta^2 - \beta + 2)$$

$$\beta^2 - \beta + 2 \neq 0 \text{ as } \beta^2 - \beta + 2 = \left(\beta - \frac{1}{2}\right)^2 + \frac{7}{4} \geq \frac{7}{4} > 0 \text{ or discriminant} = -7$$

**E1**

So the only stationary point is  $(-1, -1)$

**A1**



**G2 (5)**

$$g(\beta) = \beta + \frac{3}{\beta} - \frac{1}{\beta^2}$$

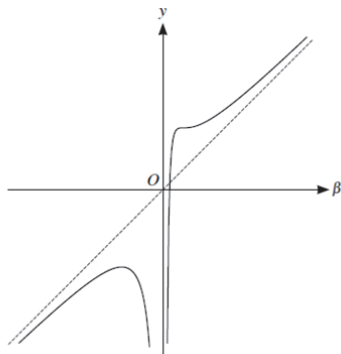
Then  $g'(\beta) = 1 - \frac{3}{\beta^2} + \frac{2}{\beta^3}$

$$1 - \frac{3}{\beta^2} + \frac{2}{\beta^3} = \frac{\beta^3 - 3\beta + 2}{\beta^3} = \frac{(\beta - 1)^2(\beta + 2)}{\beta^3}$$

**M1**

So the stationary points are  $\left(-2, -\frac{15}{4}\right)$  and  $(1, 3)$

**A1**



**G2 (4)**

(ii)  $u + v = -\alpha$  and  $uv = \beta$  so  $u + v + \frac{1}{uv} = -\alpha + \frac{1}{\beta}$

and  $\frac{1}{u} + \frac{1}{v} + uv = \frac{u+v}{uv} + uv = \frac{-\alpha}{\beta} + \beta$  **B1 (1)**

(iii)

$u + v + \frac{1}{uv} = -1 \Rightarrow -\alpha + \frac{1}{\beta} = -1$  so  $\alpha = 1 + \frac{1}{\beta}$

Thus  $\frac{1}{u} + \frac{1}{v} + uv = \frac{-\alpha}{\beta} + \beta = \beta - \frac{1}{\beta} - \frac{1}{\beta^2}$  **M1**

$u, v$  real  $\Leftrightarrow \alpha^2 - 4\beta \geq 0$

As  $\alpha^2 - 4\beta \geq 0$ ,  $\left(1 + \frac{1}{\beta}\right)^2 - 4\beta \geq 0$  and thus  $4\beta^3 - \beta^2 - 2\beta - 1 \leq 0$

$(\beta - 1)(4\beta^2 + 3\beta + 1) \leq 0$  **M1 A1**

$4\beta^2 + 3\beta + 1 = \left(2\beta + \frac{3}{4}\right)^2 + \frac{7}{16} \geq \frac{7}{16} > 0$  or discriminant =  $-7$  and positive quadratic so

$4\beta^2 + 3\beta + 1 > 0$ , **E1**

and so  $\beta \leq 1$  **B1**

Hence, from the sketch in part (i),  $f(\beta) = \beta - \frac{1}{\beta} - \frac{1}{\beta^2} = \frac{1}{u} + \frac{1}{v} + uv \leq -1$  as required. **E1 (6)**

(iv) If  $u + v + \frac{1}{uv} = 3 \Rightarrow -\alpha + \frac{1}{\beta} = 3$  so  $\alpha = \frac{1}{\beta} - 3$

Thus  $\frac{1}{u} + \frac{1}{v} + uv = \frac{-\alpha}{\beta} + \beta = \beta + \frac{3}{\beta} - \frac{1}{\beta^2}$  **M1**

$u, v$  real  $\Leftrightarrow \alpha^2 - 4\beta \geq 0$ , so  $\left(\frac{1}{\beta} - 3\right)^2 - 4\beta \geq 0$  and thus  $4\beta^3 - 9\beta^2 + 6\beta - 1 \leq 0$

Therefore  $(\beta - 1)^2(4\beta - 1) \leq 0$  and so  $\beta = 1$  or  $\beta \leq \frac{1}{4}$  **M1 A1**

From the graph of  $g(\beta)$  we can deduce that the greatest value of  $\frac{1}{u} + \frac{1}{v} + uv$  is 3 **E1 (4)**

2. (i)

$$\frac{dy_n}{dx} = \frac{d}{dx} \left( (-1)^n \frac{1}{z} \frac{d^n z}{dx^n} \right) = (-1)^n \left[ 2xe^{x^2} \frac{d^n z}{dx^n} + \frac{1}{z} \frac{d^{n+1} z}{dx^{n+1}} \right] \quad \text{M1}$$

$$= 2x(-1)^n \frac{1}{z} \frac{d^n z}{dx^n} - (-1)^{n+1} \frac{1}{z} \frac{d^{n+1} z}{dx^{n+1}} \quad \text{M1}$$

$$= 2xy_n - y_{n+1}$$

as required.

**A1\* (3)**

(ii) Suppose  $y_{k+1} = 2xy_k - 2ky_{k-1}$  for some  $k$  **B1**

$$\frac{dy_{k+1}}{dx} = 2x \frac{dy_k}{dx} + 2y_k - 2k \frac{dy_{k-1}}{dx} \quad \text{M1}$$

So using (i)

$$2xy_{k+1} - y_{k+2} = 2x(2xy_k - y_{k+1}) + 2y_k - 2k(2xy_{k-1} - y_k) \quad \text{M1}$$

$$= 4x^2 y_k - 2xy_{k+1} + 2y_k + 2ky_k - 2x(2xy_k - y_{k+1}) \quad \text{M1}$$

$$= 4x^2 y_k - 2xy_{k+1} + 2y_k + 2ky_k - 4x^2 y_k + 2xy_{k+1} \\ = 2y_k + 2ky_k$$

Thus  $y_{k+2} = 2xy_{k+1} - 2(k+1)y_k$  which is the required result for  $k+1$  **A1**

$$y_0 = 1$$

$$y_1 = (-1) \frac{1}{z} \frac{dz}{dx} = -1e^{x^2} \frac{d}{dx} (e^{-x^2}) = -e^{x^2} \cdot -2xe^{-x^2} = 2x \quad \text{B1}$$

$$y_2 = (-1)^2 \frac{1}{z} \frac{d^2 z}{dx^2} = e^{x^2} \frac{d^2 (e^{-x^2})}{dx^2} = e^{x^2} \left[ \frac{d}{dx} (-2xe^{-x^2}) \right] = e^{x^2} (-2e^{-x^2} + 4x^2 e^{-x^2}) \\ = -2 + 4x^2 \quad \text{M1A1}$$

$$2xy_1 - 2 \times 1y_0 = 2x(2x) - 2 = 4x^2 - 2 \quad \text{so result true for } n = 1 \quad \text{A1}$$

Hence  $y_{n+1} = 2xy_n - 2ny_{n-1}$  for  $n \geq 1$  by induction. **A1 (10)**

As  $y_{n+1} = 2xy_n - 2ny_{n-1}$ ,  $y_{n+2} = 2xy_{n+1} - 2(n+1)y_n$  **M1**

Eliminating  $x$ ,

$$(y_{n+1})^2 - y_n y_{n+2} = 2(n+1)(y_n)^2 - 2ny_{n-1}y_{n+1}$$

**M1**

Thus

$$y_{n+1}(y_{n+1} + 2ny_{n-1}) = y_n(y_{n+2} + 2(n+1)y_n)$$

So

$$y_{n+1}^2 - y_n y_{n+2} = 2n(y_n^2 - y_{n-1}y_{n+1}) + 2y_n^2$$

**A1 (3)**

(iii) Suppose  $y_k^2 - y_{k-1}y_{k+1} > 0$  for some  $k \geq 1$  **B1**

Then, as  $2y_k^2 \geq 0$ ,  $2k(y_k^2 - y_{k-1}y_{k+1}) + 2y_k^2 > 0$ , i.e. by (ii)  $y_{k+1}^2 - y_k y_{k+2} > 0$  **E1**

Consider  $k = 1$

$$y_1^2 - y_0 y_2 = (2x)^2 - 1 \times (-2 + 4x^2) = 4x^2 + 2 - 4x^2 = 2 > 0$$

**B1**

Hence the result  $y_n^2 - y_{n-1}y_{n+1} > 0$  for  $n \geq 1$

**B1 (4)**

3.

$$x^a(x^b(x^c y)')' = x^a[x^b(x^c y' + cx^{c-1}y)]'$$

**M1**

$$\begin{aligned} &= x^a[x^{b+c}y' + cx^{b+c-1}y]' \\ &= x^a[x^{b+c}y'' + cx^{b+c-1}y' + (b+c)x^{b+c-1}y' + c(b+c-1)x^{b+c-2}y] \\ &= x^{a+b+c}y'' + (b+2c)x^{a+b+c-1}y' + c(b+c-1)x^{a+b+c-2}y \end{aligned}$$

**M1A1**

This is of the required form if

$$a + b + c = 2$$

$$b + 2c = 1 - 2p$$

$$c(b + c - 1) = p^2 - q^2$$

**M1**

Thus

$$c(1 - 2p - 2c + c - 1) = p^2 - q^2$$

$$c^2 + 2pc + p^2 = q^2$$

$$c + p = \pm q$$

**M1**

Thus it is possible if

$$c = q - p, \quad b = 1 - 2q, \quad a = 1 + p + q$$

or

$$c = -q - p, \quad b = 1 + 2q, \quad a = 1 + p - q$$

**A1 (6)**

$$(i) \quad x^2 y'' + (1 - 2p)xy' + (p^2 - q^2)y = 0$$

So

$$x^a(x^b(x^c y)')' = 0$$

$$(x^b(x^c y)')' = 0$$

$$x^b(x^c y)' = A$$

**M1**

$$(x^c y)' = Ax^{-b}$$

$$x^c y = \frac{Ax^{-b+1}}{-b+1} + B \quad \text{unless } b = 1$$

**B1**

$$y = \frac{Ax^{-b-c+1}}{-b+1} + Bx^{-c}$$

$b \neq 1 \Rightarrow q \neq 0$  in which case

$$y = \frac{Ax^{p \pm q}}{\pm 2q} + Bx^{p \pm q}$$

That is

$$y = Cx^{p+q} + Dx^{p-q}$$

**M1A1**

However, if  $b = 1$ ,  $x^c y = A \ln x + B$

**M1**

so  $y = Ax^{-c} \ln x + Bx^{-c}$

So if  $q = 0$ ,  $y = Ax^p \ln x + Bx^p$

**M1A1 (7)**

(ii)  $x^2 y'' + (1 - 2p)xy' + p^2 y = x^n$

Thus  $q = 0$ , and  $c = -p$ ,  $b = 1$ ,  $a = 1 + p$

**B1**

$$x^a (x(x^c y)')' = x^n$$

$$(x(x^c y)')' = x^{n-a}$$

$$x(x^c y)' = \frac{x^{n+1-a}}{n+1-a} + A \text{ for } n+1-a \neq 0 \text{ or } x(x^c y)' = \ln x + A \text{ for } n+1-a = 0 \quad \text{M1 B1}$$

$$n+1-a = 0 \Rightarrow n = p$$

$$\text{Thus } (x^c y)' = \frac{x^{n-a}}{n+1-a} + Ax^{-1} \text{ or } (x^c y)' = x^{-1} \ln x + Ax^{-1}$$

$$\text{So } x^c y = \frac{x^{n+1-a}}{(n+1-a)^2} + A \ln x + B \text{ or } x^c y = \frac{(\ln x)^2}{2} + A \ln x + B$$

**M1 M1**

$$\text{So for } n \neq p, y = \frac{x^n}{(n-p)^2} + Ax^p \ln x + Bx^p \quad \text{A1}$$

$$\text{and for } n = p, y = x^n \frac{(\ln x)^2}{2} + Ax^n \ln x + Bx^n \quad \text{A1 (7)}$$

4.

$$\frac{x^2}{a^2} - \frac{y^2}{b^2} = 1$$

$$\frac{2x}{a^2} - \frac{2y}{b^2} \frac{dy}{dx} = 0$$

**M1**

(Alternatively,

$$\frac{dy}{dx} = \frac{dy/d\theta}{dx/d\theta} = \frac{b \sec^2 \theta}{a \sec \theta \tan \theta}$$

also earns **M1**)

Thus at P

$$\frac{dy}{dx} = \frac{a \sec \theta}{a^2} \frac{b^2}{b \tan \theta} = \frac{b}{a \sin \theta}$$

**A1**

So the tangent at P is

$$y - b \tan \theta = \frac{b}{a \sin \theta} (x - a \sec \theta)$$

**M1**

Hence

$$ay \sin \theta - ab \frac{\sin^2 \theta}{\cos \theta} = bx - ab \frac{1}{\cos \theta}$$

So

$$bx - ay \sin \theta = ab \left( \frac{1}{\cos \theta} - \frac{\sin^2 \theta}{\cos \theta} \right) = ab \frac{\cos^2 \theta}{\cos \theta} = ab \cos \theta$$

as required.

**A1\* (4)**

(i) S is the intersection of  $bx - ay \sin \theta = ab \cos \theta$  and  $\frac{x}{a} = \frac{y}{b}$

So  $bx - bx \sin \theta = ab \cos \theta$

**M1**

Thus, S is  $\left( \frac{a \cos \theta}{1 - \sin \theta}, \frac{b \cos \theta}{1 - \sin \theta} \right)$

**A1**

Similarly, T is the intersection of  $bx - ay \sin \theta = ab \cos \theta$  and  $\frac{x}{a} = -\frac{y}{b}$

So T is  $\left( \frac{a \cos \theta}{1 + \sin \theta}, -\frac{b \cos \theta}{1 + \sin \theta} \right)$

**M1A1**

The midpoint of ST is therefore  $\left( \frac{1}{2} \left( \frac{a \cos \theta}{1 - \sin \theta} + \frac{a \cos \theta}{1 + \sin \theta} \right), \frac{1}{2} \left( \frac{b \cos \theta}{1 - \sin \theta} - \frac{b \cos \theta}{1 + \sin \theta} \right) \right)$

**M1**

$$\frac{1}{2} \left( \frac{a \cos \theta}{1 - \sin \theta} + \frac{a \cos \theta}{1 + \sin \theta} \right) = \frac{1}{2} a \cos \theta \frac{1 + \sin \theta + 1 - \sin \theta}{(1 - \sin \theta)(1 + \sin \theta)} = a \sec \theta$$



$$\frac{1}{2} \left( \frac{b \cos \theta}{1 - \sin \theta} - \frac{b \cos \theta}{1 + \sin \theta} \right) = \frac{1}{2} b \cos \theta \frac{1 + \sin \theta - 1 + \sin \theta}{(1 - \sin \theta)(1 + \sin \theta)} = b \tan \theta$$

**M1**

which means it is P. **A1 (7)**

(ii) As the tangents at P and Q are perpendicular,

$$\frac{b}{a \sin \theta} \times \frac{b}{a \sin \varphi} = -1$$

**B1**

(This is possible because  $a > b$ )

That is

$$a^2 \sin \theta \sin \varphi + b^2 = 0$$

The intersection of the tangents is given by the solution of

$$bx - ay \sin \theta = ab \cos \theta$$

$$bx - ay \sin \varphi = ab \cos \varphi$$

Thus

$$x = a \frac{(\sin \varphi \cos \theta - \sin \theta \cos \varphi)}{(\sin \varphi - \sin \theta)}$$

**M1**

and

$$y = b \frac{(\cos \theta - \cos \varphi)}{(\sin \varphi - \sin \theta)}$$

$$x^2 = \left[ a \frac{(\sin \varphi \cos \theta - \sin \theta \cos \varphi)}{(\sin \varphi - \sin \theta)} \right]^2$$

**A1**

$$y^2 = -a^2 \sin \theta \sin \varphi \left[ \frac{(\cos \theta - \cos \varphi)}{(\sin \varphi - \sin \theta)} \right]^2$$

**A1**

Note  $\sin \theta \sin \varphi = -\frac{b^2}{a^2} < 0$  so  $\sin \varphi \neq \sin \theta$  and so  $\sin \varphi - \sin \theta \neq 0$  **E1**

So

$$\begin{aligned} x^2 + y^2 &= \frac{a^2}{(\sin \varphi - \sin \theta)^2} [(\sin \varphi \cos \theta - \sin \theta \cos \varphi)^2 - \sin \theta \sin \varphi (\cos \theta - \cos \varphi)^2] \\ &= \frac{a^2}{(\sin \varphi - \sin \theta)^2} [\sin^2 \varphi \cos^2 \theta + \sin^2 \theta \cos^2 \varphi - \sin \theta \sin \varphi \cos^2 \theta - \sin \theta \sin \varphi \cos^2 \varphi] \end{aligned}$$

**M1**

$$\begin{aligned}
&= \frac{a^2}{(\sin \varphi - \sin \theta)^2} [\sin^2 \varphi (1 - \sin^2 \theta) + \sin^2 \theta (1 - \sin^2 \varphi) - 2 \sin \varphi \sin \theta + 2 \sin \varphi \sin \theta - \\
&\sin \theta \sin \varphi \cos^2 \theta - \sin \theta \sin \varphi \cos^2 \varphi] \quad \text{M1} \\
&= \frac{a^2}{(\sin \varphi - \sin \theta)^2} [(\sin \varphi - \sin \theta)^2 + \sin \varphi \sin \theta (2 - 2 \sin \varphi \sin \theta - \cos^2 \theta - \cos^2 \varphi)] \\
&= \frac{a^2}{(\sin \varphi - \sin \theta)^2} [(\sin \varphi - \sin \theta)^2 + \sin \varphi \sin \theta (\sin^2 \varphi - 2 \sin \varphi \sin \theta + \sin^2 \theta)] \\
&= a^2 + a^2 \sin \theta \sin \varphi = a^2 - b^2
\end{aligned}$$

as required.

**M1A1\* (9)**

5. (i)

$$(k+1)(A_{k+1} - G_{k+1}) - k(A_k - G_k) \geq 0$$

$$\Leftrightarrow (a_1 + a_2 + \dots + a_k + a_{k+1}) - (k+1)G_{k+1} - (a_1 + a_2 + \dots + a_k) + kG_k \geq 0 \quad \text{M1}$$

$$\Leftrightarrow a_{k+1} + kG_k \geq (k+1)G_{k+1}$$

$$\Leftrightarrow \frac{a_{k+1}}{G_k} + k \geq (k+1) \frac{G_{k+1}}{G_k} \quad \text{as } G_k > 0 \quad \text{M1 E1}$$

$$\frac{G_{k+1}}{G_k} = \frac{(G_k^k a_{k+1})^{1/k+1}}{G_k} = \left( \frac{a_{k+1}}{G_k} \right)^{1/k+1} = \lambda_k \quad \text{B1}$$

So

$$\frac{a_{k+1}}{G_k} + k \geq (k+1) \frac{G_{k+1}}{G_k} \Leftrightarrow \lambda_k^{k+1} + k \geq (k+1)\lambda_k$$

$$\Leftrightarrow \lambda_k^{k+1} - (k+1)\lambda_k + k \geq 0 \quad \text{as required.} \quad \text{M1A1 (6)}$$

$$(ii) \quad f(x) = x^{k+1} - (k+1)x + k$$

$$\text{So } f'(x) = (k+1)x^k - (k+1) = (k+1)(x^k - 1) \text{ and } f''(x) = (k+1)kx^{k-1} \quad \text{M1M1}$$

Thus, if  $x$  is positive, there is a single stationary point for  $x = 1$  and it is a minimum. **E1**

$$f(1) = 0$$

$$\text{and so } f(x) = x^{k+1} - (k+1)x + k \geq 0 \quad \text{E1* (4)}$$

$$(iii) (a) \text{ Assume } A_k \geq G_k \text{ for some particular } k \quad \text{B1}$$

$$\text{then by (ii), the condition for (i) is met and so } A_{k+1} - G_{k+1} \geq \frac{k}{k+1}(A_k - G_k) \quad \text{E1}$$

$$\text{and thus } A_{k+1} \geq G_{k+1}$$

$$A_1 = a_1 \text{ and } G_1 = a_1 \text{ and so } A_1 \geq G_1 \text{ (in fact } A_1 = G_1) \quad \text{B1}$$

$$\text{Thus, by the principle of mathematical induction, } A_n \geq G_n \text{ for all } n \quad \text{B1 (4)}$$

$$(b) \text{ If } A_k = G_k \text{ for some } k, \text{ then as } A_n \geq G_n \text{ for all } n, A_{k-1} \geq G_{k-1} \quad \text{E1}$$

$$\text{and by (i) and (ii) } A_{k-1} = G_{k-1} \text{ and}$$

$$\left( \frac{a_k}{G_{k-1}} \right)^{1/k} = 1 \quad \text{E1}$$

$$\text{in which case } a_k = G_{k-1}. \quad \text{B1}$$

But as  $A_n = G_n$ ,  $A_k = G_k$  and  $a_k = G_{k-1}$  for all  $k$ , for  $k = 1$  to  $n$  **E1**

But,  $A_1 = G_1 = a_1$  **B1** and so  $a_2 = G_1 = a_1$  and thus  $A_2 = G_2 = a_1$  and  $a_3 = G_2 = a_1$  and so on up to  $A_n = G_n = a_1$

Hence  $a_1 = a_2 = a_3 = \dots = a_n$  **E1 (6)**

6. (i)

$\overrightarrow{AQ}$  is parallel to  $\overrightarrow{AC}$

So  $q - a = \lambda(c - a)$  where  $\lambda$  is real.

Therefore  $\frac{q-a}{c-a} = \lambda$  which is real as required. **E1 (1)**

Hence,

$$\frac{q-a}{c-a} = \left(\frac{q-a}{c-a}\right)^*$$

**M1**

$$\left(\frac{q-a}{c-a}\right)^* = \frac{(q-a)^*}{(c-a)^*} = \frac{q^* - a^*}{c^* - a^*}$$

**M1**

So as

$$\frac{q-a}{c-a} = \frac{q^* - a^*}{c^* - a^*}$$

$$(c-a)(q^* - a^*) = (c^* - a^*)(q-a)$$

**A1\* (3)**

$$(c-a)\left(q^* - \frac{1}{a}\right) = \left(\frac{1}{c} - \frac{1}{a}\right)(q-a)$$

**M1**

Multiplying by  $ac$ ,

$$(c-a)(acq^* - c) = -(c-a)(q-a)$$

**M1**

Thus

$$acq^* - c = -(q-a)$$

as  $c - a \neq 0$

**E1**

and so

$$q + acq^* = a + c$$

**A1\* (4)**

(ii) Q lies on AC, so from (i)

$$q + acq^* = a + c$$

Also Q lies on BD, so similarly

$$q + bdq^* = b + d$$

**M1**

Subtracting  $(ac - bd)q^* = (a + c) - (b + d)$

**M1\***

Multiplying the AC equation by  $bd$  and the BD one by  $ac$  and subtracting,

$$(ac - bd)q = ac(b + d) - bd(a + c)$$

**M1**

So adding these two equations

$$(ac - bd)(q + q^*) = ac(b + d) - bd(a + c) + (a + c) - (b + d)$$

**M1**

Rearranging

$$(ac - bd)(q + q^*) = (a - b)(1 + cd) + (c - d)(1 + ab)$$

as required.

**A1\* (5)**

(iii) P lies on AB, so from (i)

$$p + abp^* = a + b$$

**M1**

But as  $p$  is real,  $p = p^*$ , and so

$$p + abp = a + b$$

**M1\***

That is

$$p(1 + ab) = a + b$$

Similarly, as P lies on CD

$$p(1 + cd) = c + d$$

**M1**

Multiplying the final result of (ii) by  $p$  we have

$$(ac - bd)p(q + q^*) = (a - b)p(1 + cd) + (c - d)p(1 + ab)$$

**M1**

Thus

$$(ac - bd)p(q + q^*) = (a - b)(c + d) + (c - d)(a + b)$$

**M1**

So, simplifying

$$(ac - bd)p(q + q^*) = 2ac - 2bd = 2(ac - bd)$$

And as  $ac - bd \neq 0$ ,  $p(q + q^*) = 2$

**E1 A1\* (7)**

7. (i)

$$\frac{(\cot \theta + i)^{2n+1} - (\cot \theta - i)^{2n+1}}{2i} = \frac{(\cos \theta + i \sin \theta)^{2n+1} - (\cos \theta - i \sin \theta)^{2n+1}}{2i \sin^{2n+1} \theta}$$

**M1**

$$= \frac{(\cos(2n+1)\theta + i \sin(2n+1)\theta) - (\cos(2n+1)\theta - i \sin(2n+1)\theta)}{2i \sin^{2n+1} \theta}$$

**M1**

$$= \frac{2i \sin(2n+1)\theta}{2i \sin^{2n+1} \theta} = \frac{\sin(2n+1)\theta}{\sin^{2n+1} \theta}$$

**A1\* (3)**

Let  $y = \cot \theta$ , then

$$\frac{(y+i)^{2n+1} - (y-i)^{2n+1}}{2i}$$

**M1**

$$= \frac{(y^{2n+1} + \binom{2n+1}{1}y^{2n}i + \binom{2n+1}{2}y^{2n-1}i^2 + \dots) - (y^{2n+1} - \binom{2n+1}{1}y^{2n}i + \binom{2n+1}{2}y^{2n-1}i^2 - \dots)}{2i}$$

**M1**

$$= \binom{2n+1}{1}y^{2n} - \binom{2n+1}{3}y^{2n-2} + \dots + (i)^{2n}$$

**M1**

So if  $(2n+1)\theta = m\pi$  where  $m = 1, 2, \dots, n$ ,  $\sin \theta \neq 0$  and  $\sin(2n+1)\theta = 0$

**E1**

So

$$\binom{2n+1}{1}\cot^{2n} \theta - \binom{2n+1}{3}\cot^{2n-2} \theta + \dots + (-1)^n = 0$$

Thus if  $x = \cot^2 \theta$ ,  $\binom{2n+1}{1}x^n - \binom{2n+1}{3}x^{n-1} + \dots + (-1)^n = 0$  which gives the required result.

**A1\* (5)**

(ii)

$$\sum_{m=1}^n \cot^2 \left( \frac{m\pi}{2n+1} \right)$$

is the sum of the roots of the equation in part (i), and so is equal to

**M1**

$$\frac{\binom{2n+1}{3}}{\binom{2n+1}{1}} = \frac{(2n+1)!}{(2n-2)!3!} \times \frac{(2n)!1!}{(2n+1)!} = \frac{(2n)!}{(2n-2)!3!} = \frac{2n \times (2n-1)}{3 \times 2} = \frac{n(2n-1)}{3}$$

**A1**

**A1\* (3)**

(iii) As  $0 < \sin \theta < \theta < \tan \theta$ ,  $\frac{1}{\sin \theta} > \frac{1}{\theta} > \frac{1}{\tan \theta}$  as these are all positive, and

$$\frac{1}{\sin^2 \theta} > \frac{1}{\theta^2} > \frac{1}{\tan^2 \theta}$$

**M1**

Thus

$$\csc^2 \theta > \frac{1}{\theta^2} > \cot^2 \theta$$

**M1**

That is

$$1 + \cot^2 \theta > \frac{1}{\theta^2} > \cot^2 \theta$$

**M1**

or as required

$$\cot^2 \theta < \frac{1}{\theta^2} < 1 + \cot^2 \theta$$

$$\sum_{m=1}^n \cot^2 \left( \frac{m\pi}{2n+1} \right) < \sum_{m=1}^n \left( \frac{2n+1}{m\pi} \right)^2 < \sum_{m=1}^n \left( 1 + \cot^2 \left( \frac{m\pi}{2n+1} \right) \right)$$

**M1**

$$\frac{n(2n-1)}{3} < \left( \frac{2n+1}{\pi} \right)^2 \sum_{m=1}^n \frac{1}{m^2} < n + \frac{n(2n-1)}{3}$$

**M1**

$$\frac{n(2n-1)}{3(2n+1)^2} \times \pi^2 < \sum_{m=1}^n \frac{1}{m^2} < \frac{n(2n+2)}{3(2n+1)^2} \times \pi^2$$

**M1**

Letting  $n \rightarrow \infty$ ,

$$\frac{n(2n-1)}{3(2n+1)^2} \times \pi^2 \rightarrow \frac{\pi^2}{6}$$

**M1**

and

$$\frac{n(2n+2)}{3(2n+1)^2} \times \pi^2 \rightarrow \frac{\pi^2}{6}$$

**M1**

and so

$$\sum_{m=1}^{\infty} \frac{1}{m^2} = \frac{\pi^2}{6}$$

**A1\* (9)**



8. (i)

$$\sum_{n=1}^{\infty} \int_{y=n}^{n+1} \frac{f(y)}{y(1+y)} dy = \int_1^{\infty} \frac{f(y)}{y(1+y)} dy$$

**M1**

Making a change of variable,  $y = x^{-1}$ ,  $\frac{dy}{dx} = -x^{-2}$

**M1**

so

$$\sum_{n=1}^{\infty} \int_{y=n}^{n+1} \frac{f(y)}{y(1+y)} dy = \int_1^{\infty} \frac{f(y)}{y(1+y)} dy = \int_1^0 \frac{f(x^{-1})}{x^{-1}(1+x^{-1})} \cdot -x^{-2} dx$$

**M1**

$$= \int_1^0 \frac{-f(x^{-1})}{(x+1)} \cdot dx = \int_0^1 \frac{f(x^{-1})}{(1+x)} \cdot dx = I$$

**A1\* (4)**

$$I = \sum_{n=1}^{\infty} \int_{y=n}^{n+1} \frac{f(y)}{y(1+y)} dy = \sum_{n=1}^{\infty} \int_{y=n}^{n+1} \frac{f(y)}{y} - \frac{f(y)}{1+y} dy$$

**M1**

$$= \sum_{n=1}^{\infty} \int_{x=n-1}^n \frac{f(x+1)}{x+1} dx - \sum_{n=1}^{\infty} \int_{y=n}^{n+1} \frac{f(y)}{1+y} dy$$

**M1**

$$= \sum_{n=1}^{\infty} \int_{x=n-1}^n \frac{f(x)}{x+1} dx - \sum_{n=1}^{\infty} \int_{y=n}^{n+1} \frac{f(y)}{1+y} dy$$

**M1**

$$= \int_{x=0}^{\infty} \frac{f(x)}{x+1} dx - \int_{x=1}^{\infty} \frac{f(x)}{x+1} dx$$

**M1**

$$= \int_{x=0}^1 \frac{f(x)}{1+x} dx$$

as required.

**A1\* (5)**

(ii) From (i)

$$\int_{x=0}^1 \frac{\{x^{-1}\}}{x+1} dx = \int_{x=0}^1 \frac{\{x\}}{x+1} dx$$

**M1**

$$= \int_{x=0}^1 \frac{x}{x+1} dx = \int_{x=0}^1 1 - \frac{1}{x+1} dx = [x - \ln(x+1)]_0^1 = 1 - \ln 2$$

**M1**

**M1**

**A1 (4)**

$$\int_{x=0}^1 \frac{\{2x^{-1}\}}{x+1} dx$$

$$\{2(x+1)\} = \{2x+2\} = \{2x\}$$

**E1**

and so we can once again use the result from part (i), and thus

$$\int_{x=0}^1 \frac{\{2x^{-1}\}}{x+1} dx = \int_{x=0}^1 \frac{\{2x\}}{x+1} dx = \int_{x=0}^{\frac{1}{2}} \frac{2x}{x+1} dx + \int_{x=\frac{1}{2}}^1 \frac{2x-1}{x+1} dx$$

**M1**

**M1A1**

$$= 2[x - \ln(x+1)]_0^{\frac{1}{2}} + [2x - 3\ln(x+1)]_{\frac{1}{2}}^1$$

**dM1**

$$= 1 - 2\ln\frac{3}{2} + 2 - 3\ln 2 - 1 + 3\ln\frac{3}{2}$$

$$= 2 + \ln\frac{3}{16} = 2 - \ln\frac{16}{3}$$

**M1A1 (7)**

9. (i) NELI for the n-1 th collision between P and Q gives

$$v_{n-1} - u_{n-1} = e(v_{n-2} + u_{n-2})$$

**M1**

and conserving momentum

$$kmv_{n-1} + mu_{n-1} = mu_{n-2} - kmv_{n-2}$$

**M1**

which simplifies to

$$kv_{n-1} + u_{n-1} = u_{n-2} - kv_{n-2}$$

Eliminating  $v_{n-2}$  between the two equations by multiplying the first by  $k$  and the second by  $e$  and adding gives

**M1**

$$k(1 + e)v_{n-1} + (e - k)u_{n-1} = e(1 + k)u_{n-2}$$

**A1**

Similarly, the nth collision gives

$$v_n - u_n = e(v_{n-1} + u_{n-1})$$

and

$$kv_n + u_n = u_{n-1} - kv_{n-1}$$

**M1**

Eliminating  $v_n$  between these two equations by multiplying the first by  $k$  and subtracting from the second

**M1**

$$(1 + k)u_n = (1 - ke)u_{n-1} - k(1 + e)v_{n-1} \quad (**)$$

**A1**

Adding the left hand side of the equation from the n-1 th collision to the right hand side of that just obtained (and vice versa)

$$(1 + k)u_n + e(1 + k)u_{n-2} = (1 - ke)u_{n-1} + (e - k)u_{n-1}$$

**M1**

Thus

$$(1 + k)u_n + e(1 + k)u_{n-2} = (1 + e - k - ke)u_{n-1} = (1 - k)(1 + e)u_{n-1}$$

**M1**

Giving

$$(1 + k)u_n - (1 - k)(1 + e)u_{n-1} + e(1 + k)u_{n-2} = 0$$

**A1\* (10)**

(ii) The first impact gives using (\*\*)

$$\left(1 + \frac{1}{34}\right)u_1 = \left(1 - \frac{1}{34} \times \frac{1}{2}\right)u_0 - \frac{1}{34}\left(1 + \frac{1}{2}\right)v_0$$

**M1**

Thus

$$70u_1 = 67u_0 - 3v_0$$

**A1**

Letting  $n = 0$

$$u_0 = A + B$$

**M1**

and letting  $n = 1$

$$A\left(\frac{7}{10}\right) + B\left(\frac{5}{7}\right) = u_1 = \frac{67u_0 - 3v_0}{70}$$

**M1**

So  $49A + 50B = 67u_0 - 3v_0$

Thus

$$A = -17u_0 + 3v_0$$

and

$$B = 18u_0 - 3v_0$$

**M1 A1 (6)**

Thus

$$u_n = (-17u_0 + 3v_0)\left(\frac{7}{10}\right)^n + (18u_0 - 3v_0)\left(\frac{5}{7}\right)^n$$

**M1**

$$= \left(\frac{5}{7}\right)^n \left[ (-17u_0 + 3v_0)\left(\frac{49}{50}\right)^n + (18u_0 - 3v_0) \right]$$

If  $v_0 > 6u_0$ ,  $(-17u_0 + 3v_0 > u_0)$  and  $18u_0 - 3v_0 < 0$

**M1**

For large  $n$ , the term  $\left(\frac{49}{50}\right)^n \rightarrow 0$

**E1**

$$u_n \rightarrow \left(\frac{5}{7}\right)^n (18u_0 - 3v_0) < 0$$

**E1\* (4)**

10. If G is the centre of mass of the combined disc and particle, then

$$(M + m) \times OG = M \times 0 + m \times a$$

**M1**

In equilibrium, G is vertically below A, so  $\sin \beta = \frac{OG}{OA} = \frac{m}{M+m}$

**A1 (2)**

Applying the cosine rule to triangle OAP,

$$AP^2 = a^2 + a^2 - 2a^2 \cos\left(\frac{\pi}{2} - \beta\right) = 2a^2(1 - \sin \beta)$$

**M1**

**M1**

Thus

$$\frac{AP}{a} = \sqrt{2(1 - \sin \beta)} = \sqrt{2\left(1 - \frac{m}{M+m}\right)} = \sqrt{\frac{2M}{M+m}}$$

**M1**

**A1\* (4)**

The kinetic energy of the disc about L is  $\frac{1}{2}I\dot{\theta}^2$  **B1** and the kinetic energy of the particle about L is  $\frac{1}{2}m(AP\dot{\theta})^2 = \frac{1}{2}m2a^2(1 - \sin \beta)\dot{\theta}^2 = (1 - \sin \beta)ma^2\dot{\theta}^2$

**B1**

**M1**

The potential energy of the system relative to the zero level of the point G in equilibrium is  $(M + m)gAG(1 - \cos \theta) = (M + m)ga \cos \beta(1 - \cos \theta)$

**B1**

**M1**

So, during the motion, conserving energy

$$\frac{1}{2}I\dot{\theta}^2 + (1 - \sin \beta)ma^2\dot{\theta}^2 + (M + m)ga \cos \beta(1 - \cos \theta)$$

Is constant.

**E1 (6)**

$$\frac{1}{2}I\dot{\theta}^2 + (1 - \sin \beta)ma^2\dot{\theta}^2 + (M + m)ga \cos \beta(1 - \cos \theta) = c$$

Differentiating with respect to time,

$$I\dot{\theta}\ddot{\theta} + 2(1 - \sin \beta)ma^2\dot{\theta}\ddot{\theta} + (M + m)ga \cos \beta \sin \theta \dot{\theta} = 0$$

**M1 A1**

Thus, as  $m = \frac{3}{2}M$ ,  $\sin \beta = \frac{m}{M+m} = \frac{3}{5}$  and  $\cos \beta = \frac{4}{5}$  ( $\cos \beta$  is positive as  $\beta$  is acute) **B1**

and because  $I = \frac{3}{2}Ma^2$ ,

$$\left(\frac{3}{2}Ma^2 + 2 \times \frac{2}{5} \times \frac{3}{2}Ma^2\right)\ddot{\theta} + \left(M + \frac{3}{2}M\right)ga \times \frac{4}{5} \sin \theta = 0$$

**M1**

For small oscillations,  $\sin \theta \approx \theta$ ,

**M1**

so

$$\frac{27}{10}a\ddot{\theta} + 2g\theta \approx 0$$

That is

$$\ddot{\theta} \approx -\frac{20}{27} \frac{g}{a} \theta$$

**A1**

and hence the period of small oscillations is

$$2\pi \sqrt{\frac{27a}{20g}} = 3\pi \sqrt{\frac{3a}{5g}}$$

**M1**

**A1\* (8)**

11. At a general moment in the motion, when the acute angle between the string and the upward vertical is  $\theta$ , and the speed of the particle is  $v$ , resolving towards O

$$T' + mg \cos \theta = m \frac{v^2}{b}$$

where  $T'$  is the tension in the string and  $m$  is the mass of the particle.

**M1**

So at the point when the string becomes slack,

$$g \cos \alpha = \frac{V^2}{b}$$

**M1**

i.e.  $V^2 = bg \cos \alpha$

**A1 (3)**

If  $x$  is the horizontal displacement of the particle from O at time  $t$ , and  $y$  the vertical. Then

$$x = b \sin \alpha - Vt \cos \alpha$$

**M1**

and

$$y = b \cos \alpha + Vt \sin \alpha - \frac{1}{2}gt^2$$

**M1**

The string is taut when  $x^2 + y^2 = b^2$

**M1**

So

$$(b \sin \alpha - VT \cos \alpha)^2 + \left(b \cos \alpha + VT \sin \alpha - \frac{1}{2}gT^2\right)^2 = b^2$$

**A1**

Thus

$$\begin{aligned} b^2 \sin^2 \alpha - 2b \sin \alpha VT \cos \alpha + V^2 T^2 \cos^2 \alpha \\ + b^2 \cos^2 \alpha + 2b \sin \alpha VT \cos \alpha + V^2 T^2 \sin^2 \alpha - bgT^2 \cos \alpha - gVT^3 \sin \alpha \\ + \frac{1}{4}g^2 T^4 = b^2 \end{aligned}$$

**M1**

So

$$V^2 T^2 - bgT^2 \cos \alpha - gVT^3 \sin \alpha + \frac{1}{4}g^2 T^4 = 0$$

But as  $V^2 = bg \cos \alpha$ ,

$$V^2 T^2 - V^2 T^2 - gVT^3 \sin \alpha + \frac{1}{4}g^2 T^4 = 0$$

**M1**

So

$$g^2 T^4 = 4gVT^3 \sin \alpha$$

and as  $T \neq 0$ ,

$$gT = 4V \sin \alpha$$

**A1\* (7)**

$$\dot{x} = -V \cos \alpha$$

**B1**

$$\dot{y} = V \sin \alpha - gt$$

**B1**

Thus

$$\tan \beta = \frac{V \sin \alpha - gT}{-V \cos \alpha} = \frac{V \sin \alpha - 4V \sin \alpha}{-V \cos \alpha} = 3 \tan \alpha$$

**M1 A1\* (4)**

The particle comes instantaneously to rest if and only if its motion is radial at the point of impact.

In other words,

$$\frac{y}{x} = \tan \beta$$

when  $t = T$ .

**M1**

Thus

$$x = b \sin \alpha - VT \cos \alpha = b \sin \alpha - V \frac{4V \sin \alpha}{g} \cos \alpha = b \sin \alpha - 4b \sin \alpha \cos^2 \alpha$$

**M1**

and

$$\begin{aligned} y &= b \cos \alpha + VT \sin \alpha - \frac{1}{2} g T^2 = b \cos \alpha + V \frac{4V \sin \alpha}{g} \sin \alpha - \frac{1}{2} g \left( \frac{4V \sin \alpha}{g} \right)^2 \\ &= b \cos \alpha + 4b \cos \alpha \sin^2 \alpha - 8b \cos \alpha \sin^2 \alpha = b \cos \alpha - 4b \cos \alpha \sin^2 \alpha \end{aligned}$$

**M1**

So

$$\tan \beta = 3 \tan \alpha = \frac{b \cos \alpha - 4b \cos \alpha \sin^2 \alpha}{b \sin \alpha - 4b \sin \alpha \cos^2 \alpha}$$

**M1**



Rewritten. this is

$$\frac{3 \sin \alpha}{\cos \alpha} = \frac{\cos \alpha (1 - 4 \sin^2 \alpha)}{\sin \alpha (1 - 4 \cos^2 \alpha)}$$

$$3 \sin^2 \alpha (1 - 4(1 - \sin^2 \alpha)) = (1 - \sin^2 \alpha)(1 - 4 \sin^2 \alpha)$$

**M1**

Thus

$$8(\sin^2 \alpha)^2 - 4 \sin^2 \alpha - 1 = 0$$

So

$$\sin^2 \alpha = \frac{4 \pm 4\sqrt{3}}{16} = \frac{1 \pm \sqrt{3}}{4}$$

However,  $\sin^2 \alpha > 0$ , so  $\sin^2 \alpha = \frac{1+\sqrt{3}}{4}$

**A1\* (6)**

12. (i)  $P(Y_k \leq y)$  is the probability that at least  $k$  numbers are less than or equal to  $y$  **E1**

The probability that exactly  $k$  are smaller than or equal to  $y$  is given by

$$\binom{n}{k} y^k (1-y)^{n-k}$$

**M1**

So

$$\begin{aligned} P(Y_k \leq y) &= \binom{n}{k} y^k (1-y)^{n-k} + \binom{n}{k+1} y^{k+1} (1-y)^{n-k-1} + \binom{n}{k+2} y^{k+2} (1-y)^{n-k-2} + \dots \binom{n}{n} y^n \\ &= \sum_{m=k}^n \binom{n}{m} y^m (1-y)^{n-m} \end{aligned}$$

as required.

**A1\* (3)**

(ii)

$$m \binom{n}{m} = \frac{m \times n!}{(n-m)! m!} = \frac{n!}{(n-m)! (m-1)!} = \frac{n \times (n-1)!}{((n-1) - (m-1))! (m-1)!} = n \binom{n-1}{m-1}$$

**B1**

**M1**

**A1\***

$$(n-m) \binom{n}{m} = \frac{(n-m) \times n!}{(n-m)! m!} = \frac{n!}{(n-m-1)! m!} = \frac{n \times (n-1)!}{((n-1) - m)! m!} = n \binom{n-1}{m}$$

**M1**

**A1 (5)**

$$F(y) = \sum_{m=k}^n \binom{n}{m} y^m (1-y)^{n-m}$$

so

$$f(y) = \frac{d}{dy} \sum_{m=k}^n \binom{n}{m} y^m (1-y)^{n-m}$$

**M1**

$$= \sum_{m=k}^n m \binom{n}{m} y^{m-1} (1-y)^{n-m} + \sum_{m=k}^n -(n-m) \binom{n}{m} y^m (1-y)^{n-m-1}$$

**M1**

$$= \sum_{m=k}^n m \binom{n}{m} y^{m-1} (1-y)^{n-m} + \sum_{m=k}^{n-1} -(n-m) \binom{n}{m} y^m (1-y)^{n-m-1}$$

**M1**

$$= \sum_{m=k}^n n \binom{n-1}{m-1} y^{m-1} (1-y)^{n-m} + \sum_{m=k}^{n-1} -n \binom{n-1}{m} y^m (1-y)^{n-m-1}$$

**M1**

$$= \sum_{m=k}^n n \binom{n-1}{m-1} y^{m-1} (1-y)^{n-m} + \sum_{m=k+1}^n -n \binom{n-1}{m-1} y^{m-1} (1-y)^{n-m}$$

**M1**

$$= n \binom{n-1}{k-1} y^{k-1} (1-y)^{n-k}$$

as required.

**A1\* (6)**

Because  $f(y)$  is a probability density function,  $\int_0^1 f(y) dy = 1$

**E1**

Thus

$$\int_0^1 y^{k-1} (1-y)^{n-k} dy = \frac{1}{n \binom{n-1}{k-1}}$$

**B1 (2)**

(iii)

$$E(Y_k) = n \binom{n-1}{k-1} \int_0^1 y \times y^{k-1} (1-y)^{n-k} dy = n \binom{n-1}{k-1} \int_0^1 y^k (1-y)^{n-k} dy$$

**M1**

$$= n \binom{n-1}{k-1} \int_0^1 y^{k+1-1} (1-y)^{n+1-(k+1)} dy = n \binom{n-1}{k-1} \frac{1}{(n+1) \binom{n+1-1}{k+1-1}}$$

**M1**

**M1**

$$= n \binom{n-1}{k-1} \frac{1}{(n+1) \binom{n}{k}} = \frac{n(n-1)!}{(n-k)! (k-1)!} \frac{(n-k)! k!}{(n+1)n!} = \frac{k}{n+1}$$

**A1 (4)**

13.

$$G(t) = p_0 + p_1 t + p_2 t^2 + p_3 t^3 + \dots$$

$$G(1) = p_0 + p_1 + p_2 + p_3 + \dots$$

$$G(-1) = p_0 - p_1 + p_2 - p_3 + \dots$$

**M1**

$$G(1) + G(-1) = 2p_0 + 2p_2 + \dots = 2(p_0 + p_2 + p_4 + \dots) = 2P(X = 0 \text{ or } 2 \text{ or } 4 \dots)$$

**M1**

Thus

$$P(X = 0 \text{ or } 2 \text{ or } 4 \dots) = \frac{1}{2}(G(1) + G(-1))$$

as required.

**A1\* (3)**

$$P(X = r) = e^{-\lambda} \frac{\lambda^r}{r!}$$

$$G(t) = \sum_{r=0}^{\infty} t^r e^{-\lambda} \frac{\lambda^r}{r!} = e^{-\lambda} \sum_{r=0}^{\infty} \frac{(\lambda t)^r}{r!} = e^{-\lambda} e^{\lambda t} = e^{-\lambda(1-t)}$$

**M1**

**A1\* (2)**

(i)

$$\sum_{r=0}^{\infty} P(Y = r) = k P(X = 0 \text{ or } 2 \text{ or } 4 \dots) = k \times \frac{1}{2}(G(1) + G(-1))$$

**M1**

$$= \frac{k}{2}(1 + e^{-2\lambda}) = k \frac{e^{\lambda} + e^{-\lambda}}{2e^{\lambda}} = k \frac{\cosh \lambda}{e^{\lambda}}$$

As

$$\sum_{r=0}^{\infty} P(Y = r) = 1$$

$$k = \frac{e^{\lambda}}{\cosh \lambda}$$

**A1**

$$G_Y(t) = \sum_{r=0}^{\infty} P(Y = r) t^r = k \left( e^{-\lambda} + e^{-\lambda} \frac{\lambda^2}{2!} t^2 + e^{-\lambda} \frac{\lambda^4}{4!} t^4 + \dots \right)$$

**M1**

$$= k e^{-\lambda} \left( 1 + \frac{(\lambda t)^2}{2!} + \frac{(\lambda t)^4}{4!} + \dots \right)$$

$$= \frac{k e^{-\lambda}}{2} \left[ \left( 1 + \lambda t + \frac{(\lambda t)^2}{2!} + \frac{(\lambda t)^3}{3!} + \frac{(\lambda t)^4}{4!} + \dots \right) + \left( 1 - \lambda t + \frac{(\lambda t)^2}{2!} - \frac{(\lambda t)^3}{3!} + \frac{(\lambda t)^4}{4!} - \dots \right) \right]$$

$$= \frac{e^\lambda e^{-\lambda}}{\cosh \lambda} \frac{e^{\lambda t} + e^{-\lambda t}}{2} = \frac{\cosh \lambda t}{\cosh \lambda}$$

**M1** **A1\* (5)**

as required.

$$E(Y) = G'_Y(1)$$

$$G'_Y(t) = \frac{\lambda \sinh \lambda t}{\cosh \lambda}$$

**M1**

Thus

$$E(Y) = \frac{\lambda \sinh \lambda}{\cosh \lambda} = \lambda \tanh \lambda < \lambda$$

**M1** **A1\* (3)**

for  $\lambda > 0$

Alternatively,

$$E(Y) = \frac{\lambda \sinh \lambda}{\cosh \lambda} = \lambda \frac{e^\lambda - e^{-\lambda}}{e^\lambda + e^{-\lambda}} = \lambda \frac{1 - e^{-2\lambda}}{1 + e^{-2\lambda}} < \lambda$$

(ii)

$$G(t) = p_0 + p_1 t + p_2 t^2 + p_3 t^3 + \dots$$

$$G(1) = p_0 + p_1 + p_2 + p_3 + \dots$$

$$G(-1) = p_0 - p_1 + p_2 - p_3 + \dots$$

$$G(i) = p_0 + ip_1 - p_2 - ip_3 + \dots$$

$$G(-i) = p_0 - ip_1 - p_2 + ip_3 + \dots$$

$$G(1) + G(-1) + G(i) + G(-i) = 4p_0 + 4p_4 + \dots = 4P(X = 0 \text{ or } 4 \dots)$$

$$\sum_{r=0}^{\infty} P(Z = r) = c P(X = 0 \text{ or } 4 \dots) = c \times \frac{1}{4} (G(1) + G(-1) + G(i) + G(-i))$$

$$= \frac{c}{4} (1 + e^{-2\lambda} + e^{-\lambda(1-i)} + e^{-\lambda(1+i)})$$

$$= \frac{c}{4} (1 + e^{-2\lambda} + e^{-\lambda}(\cos \lambda + i \sin \lambda + \cos \lambda - i \sin \lambda))$$

$$= \frac{c}{4} \frac{(e^\lambda + e^{-\lambda} + 2 \cos \lambda)}{e^\lambda} = \frac{c(\cosh \lambda + \cos \lambda)}{2e^\lambda}$$

**M1**

As  $\sum_{r=0}^{\infty} P(Z = r) = 1$ ,  $c = \frac{2e^\lambda}{\cosh \lambda + \cos \lambda}$

**A1**

$$\begin{aligned}
G_Z(t) &= \sum_{r=0}^{\infty} P(Z=r) t^r = c \left( e^{-\lambda} + e^{-\lambda} \frac{\lambda^4}{4!} t^2 + e^{-\lambda} \frac{\lambda^8}{8!} t^8 + \dots \right) \\
&= c e^{-\lambda} \left( 1 + \frac{(\lambda t)^4}{4!} + \frac{(\lambda t)^8}{8!} + \dots \right) \\
&= \frac{c e^{-\lambda}}{4} \left[ \left( 1 + \lambda t + \frac{(\lambda t)^2}{2!} + \dots \right) + \left( 1 - \lambda t + \frac{(\lambda t)^2}{2!} - \dots \right) + \left( 1 + \lambda i t - \frac{(\lambda t)^2}{2!} + \dots \right) \right. \\
&\quad \left. + \left( 1 - \lambda i t - \frac{(\lambda t)^2}{2!} + \dots \right) \right] \\
&= \frac{c e^{-\lambda}}{4} (e^{\lambda t} + e^{-\lambda t} + e^{i \lambda t} + e^{-i \lambda t}) \\
&= \frac{c e^{-\lambda}}{2} (\cosh \lambda t + \cos \lambda t)
\end{aligned}$$

**M1**

As  $G_Z(1) = 1$ ,  $c = \frac{2e^{\lambda}}{\cosh \lambda + \cos \lambda}$

So

$$G_Z(t) = \frac{(\cosh \lambda t + \cos \lambda t)}{(\cosh \lambda + \cos \lambda)}$$

**A1ft**

$$G'_Z(t) = \frac{\lambda(\sinh \lambda t - \sin \lambda t)}{(\cosh \lambda + \cos \lambda)}$$

And thus

$$E(Z) = G'_Z(1) = \frac{\lambda(\sinh \lambda - \sin \lambda)}{(\cosh \lambda + \cos \lambda)}$$

**M1**

If  $\lambda = \frac{3\pi}{2}$ ,

**M1**

$$\begin{aligned}
E(Z) &= \frac{3\pi}{2} \frac{\left( \sinh \frac{3\pi}{2} + 1 \right)}{\cosh \frac{3\pi}{2}} \\
&= \frac{3\pi}{2} \times \frac{\frac{e^{\frac{3\pi}{2}} - e^{-\frac{3\pi}{2}}}{2} + 1}{\frac{e^{\frac{3\pi}{2}} + e^{-\frac{3\pi}{2}}}{2}} = \frac{3\pi}{2} \times \frac{\frac{e^{\frac{3\pi}{2}} + e^{-\frac{3\pi}{2}}}{2} + \left( 1 - e^{-\frac{3\pi}{2}} \right)}{\frac{e^{\frac{3\pi}{2}} + e^{-\frac{3\pi}{2}}}{2}}
\end{aligned}$$

As  $e^{-\frac{3\pi}{2}} < 1$ , in this case,  $E(Z) > \lambda$  and so no,  $E(Z)$  is not less than  $\lambda$  for all positive values of  $\lambda$

**A1 (7)**