

SDS 385: Stat Models for Big Data

Lecture 6: Support Vector Machines

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Support Vector Machines

• Given training data $(x_i, y_i)_{i=1}^n \in \mathbb{R}^p \times \{-1, 1\}$, we want to minimize:

$$\min_{w} \frac{w^T w}{2} + C \sum_{i} \max(0, 1 - y_i w^T x_i)$$

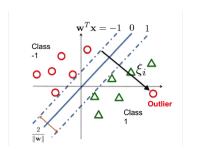


Figure 1: Courtesy Cho-Jui Hsieh's class

SGD for SVM

• Define:

$$f(w) = \frac{1}{n} \sum_{i} \left(\underbrace{\frac{w^{T}w}{2} + nC \max(0, 1 - y_{i}w^{T}x_{i})}_{f_{i}(w)} \right)$$

- For t = 1...
 - Pick j uniformly at random.
 - Compute $\nabla f_j(w)$
 - Update $w = w \eta_t \nabla f_j(w)$

SGD for SVM

- In this case, the hinge loss is not differentiable.
- A subgradient of the hinge loss $\max(0, 1 y_i w^T x_i)$

$$\begin{cases} -y_{i}x_{i} & \text{if } 1 - y_{i}w^{T}x_{i} > 0\\ 0 & \text{if } 1 - y_{i}w^{T}x_{i} < 0\\ 0 & \text{if } 1 - y_{i}w^{T}x_{i} = 0 \end{cases}$$

SGD for SVM

- For t = 1...
 - Pick *j* uniformly at random.
 - If $y_j w^T x_j < 1$
 - $w_{t+1} = w_t(1 \eta_t) + \eta_t Cny_i x_i$
 - Else update $w_{t+1} = w_t(1 \eta_t)$
 - If you store w as a scalar vector pair $w=\gamma v$, then just updating γ leads to O(1) computation.
- This is in "Pegasos: primal estimated subgradient solver for SVM", ICML 2007, Shalev-Schwartz et al.

Remember the primal problem?

$$\min_{w,\xi} \frac{w^{T}w}{2} + C \sum_{i} \xi_{i}$$
s.t. $y_{i} w^{T} x_{i} - 1 + \xi_{i} \ge 0, \xi_{i} \ge 0, i = 1, ..., n$

Add lagrange multipliers:

$$\min_{\substack{w,\xi \ \alpha \ge 0, \beta \ge 0}} \max_{\substack{d \ge 0, \beta \ge 0}} \frac{w^T w}{2} + C \sum_{i} \xi_i - \sum_{i} \alpha_i (y_i w^T x_i - 1) - \sum_{i} \beta_i \xi_i$$
s.t. $y_i w^T x_i - 1 + \xi_i \ge 0, \xi_i \ge 0, i = 1, ..., n$

 Under Slater's condition, exchanging min and max does not change the optimal solution.

Dual

• The dual is:

$$\max_{\alpha \ge 0, \beta \ge 0} \min_{w, \xi} \frac{w^T w}{2} + C \sum_{i} \xi_{i} - \sum_{i} \alpha_{i} (y_{i} w^T x_{i} - 1) - \sum_{i} \beta_{i} \xi_{i}$$
s.t. $y_{i} w^T x_{i} - 1 + \xi_{i} \ge 0, \xi_{i} \ge 0, i = 1, ..., n$

• Differentiate w.r.t w.

$$w^* = \sum_i \alpha_i^* y_i x_i$$

• Differentiate w.r.t ξ_i .

$$C = \alpha_i + \beta_i$$

• Substituting

$$\max_{0 \leq \alpha \leq C} -\frac{1}{2} \sum_{ij} \alpha_i \alpha_j y_i y_j {x_i}^T x_j + \sum_i \alpha_i$$

SVM: the dual problem

• The dual of SVM is given by:

$$\min_{\alpha} \frac{1}{2} \alpha^{T} Q \alpha - \sum_{i} \alpha_{i}$$

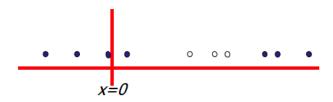
$$s.t.\alpha_{i} \in [0, C]$$

Where $Q_{ij} = y_i y_j x_i^T x_j$.

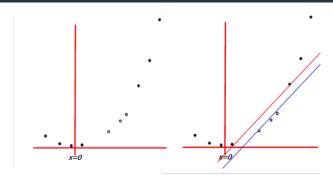
• The primal solution can be written in terms of the dual solution as:

$$w^* = \sum_i y_i \alpha_i^* x_i$$

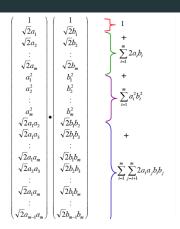
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- How do we use an SVM here?
- What if we use more than one dimensions?
- Say $z = (x, x^2)$



- So using a different mapping to a higher dimensional space helped.
- So if I want to map my features to a quadratic space, I will have coefficients: (1, x₁, x₂,...,x₁²,x₂²,...,x₁x₂,x₁x₃...,)
- So a total of $O(p^2)$ terms. If it is a cubic, then $O(p^3)$ terms. Wow! storage increases exponentially with the dimensionality.



- But this dot product is the same as $(a^T b + 1)^2$!
- Same for cubic maps. So instead of doing $O(p^k)$ computation to compute a dot product in degree k polynomial, you can compute it in O(p) time!

- But, how do you predict the class of a new example?
 - You would need to compute $w^T \phi(x)$, where $\phi(x)$ is the high dimensional mapping.
 - This is proportional to the length of $\phi(x)$
 - But remember the form of w?
 - $\mathbf{w}^T \phi(\mathbf{x}) = \sum_i \alpha_i y_i \phi(\mathbf{x}_i)^T \phi(\mathbf{x}) = \sum_i \alpha_i y_i K(\mathbf{x}_i, \mathbf{x})$

Stochastic Dual coordinate ascent

- For t = 1...
 - Compute

$$\delta^* = \arg\min_{0 < \alpha_i + \delta < C} f(\alpha + \delta e_i)$$

- Update $\alpha_i = \alpha_i + \delta^*$
- Update $w = w + \delta^* y_i x_i$ (time complexity $O(nnz(x_i))$
- After convergence this gives $w^* = \sum_i \alpha_i^* y_i x_i$

Stochastic Dual coordinate ascent

Consider the one variable problem:

$$f(\alpha + \delta e_i) = \frac{1}{2} (\alpha + \delta e_i)^T Q(\alpha + \delta e_i) - \sum_i \alpha_i - \delta$$
$$= \frac{1}{2} \alpha^T Q \alpha + \delta \alpha^T Q e_i + \delta^2 \frac{Q_{ii}}{2} - \sum_i \alpha_i - \delta$$

• Set the gradient to zero:

$$(Q\alpha)_i + Q_{ii}\delta^* - 1 = 0 \rightarrow \delta^* = \frac{1 - (Q\alpha)_i}{Q_{ii}}$$

• But we have the constraint $0 \le \alpha_i + \delta \le C$, so we have:

$$\alpha_{i} + \delta^{*} = \begin{cases} \alpha_{i} + \frac{1 - (Q\alpha)_{i}}{Q_{ii}} & \text{If } \alpha_{i} + \delta \in [0, C] \\ 0 & \text{If } \alpha_{i} + \delta < 0 \\ C & \text{If } \alpha_{i} + \delta > C \end{cases}$$

Fast computation

- Main computational bottleneck $Q\alpha$
- Write $Q = \underbrace{\operatorname{diag}(y)X}_{R} \underbrace{X^{T} \operatorname{diag}(y)}_{RT}$
- Note that:

$$(Q\alpha)_i = R_i \underbrace{R^T_{\alpha}}_{w} = y_i x_i^T w$$

- If you maintain w through the steps, computational complexity becomes O(nnz(x_i))
- After each $\alpha_i \leftarrow \alpha_i + \delta^* e_i$ update, you have:

$$w \leftarrow w + \delta^* Qe_i = w + \delta^* Q(:,i)$$

Acknowledgment

Cho-Jui Hsieh's class notes at UC Davis. Andrew Moore's notes on SVM.