

SDS 385: Stat Models for Big Data

Lecture 5: Proximal methods

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Proximal methods

• You want to minimize functions of the form

$$f(x) = \underbrace{g(x)}_{convex, differentiable} + \underbrace{h(x)}_{convex, nonsmooth}$$

• If h was differentiable, we would use

$$x_{k+1} = x_k - \alpha \nabla f(x_k)$$

• Here we would use:

$$\begin{aligned} x_{k+1} &= \arg\min_{z} \frac{1}{2\alpha} \quad \underbrace{\left\|z - (x_t - \alpha \nabla f(x_t))\right\|^2}_{\text{Stay close to the gradient}} \quad + \quad \underbrace{h(z)}_{\text{minimize h}} \end{aligned}$$

1

Proximal mapping

• Define:

$$\operatorname{prox}_{\alpha}(x) = \arg\min_{z} \frac{1}{2\alpha} \|x - z\|^2 + h(z)$$

- Proximal GD:
 - Choose initial $x^{(0)}$
 - Repeat, for k = 1, 2, 3

$$x_{k+1} = \mathsf{prox}_{\alpha_k}(x_k - \alpha_k \nabla g(x_k))$$

But, we just turned one minimization into another. And both has h
which is the troublesome part.

Example: Lasso

$$f(\beta) = \frac{1}{2} ||y - X\beta||^2 + \lambda ||\beta||_1$$

• The proximal map is:

$$\begin{aligned} \operatorname{prox}_{\alpha}(\beta) &= \arg\min_{Z} \left(\frac{1}{2\alpha} \|\beta - z\|^2 + \lambda \|\beta\|_1 \right) \\ &= S_{\lambda\alpha}(\beta) \\ [\operatorname{prox}_{\alpha}(\beta)]_i &= \begin{cases} \beta_i - \lambda \alpha & \text{if } \beta_i > \lambda \alpha \\ 0 & \text{if } |\beta_i| \leq \lambda \alpha \\ \beta_i + \lambda \alpha & \text{if } \beta_i < -\lambda \alpha \end{cases} \end{aligned}$$

Lasso

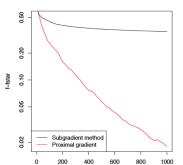
• In this case, the gradient is

$$\nabla g(\beta) = -X^{T}(y - X\beta)$$

• So the update step for Lasso becomes:

$$\beta_{k+1} = S_{\lambda\alpha} \left(\beta_k + \alpha X^T (y - X\beta) \right)$$

• This is the Iterative Soft Thresholding Algorithm.



Example: matrix completion

Given a matrix $Y \in \mathbb{R}^{m \times n}$ and observed entries $(i, j) \in \Omega$, you want to fill missing entries by solving:

$$\min_{B \in \mathbb{R}^{m \times n}} \frac{1}{2} \sum_{ij \in \Omega} (Y_{ij} - B_{ij})^2 + \lambda ||B||_*$$

• $||B||_*$ is the nuclear norm of B, defined as:

$$||B||_* = \sum_{i=1}^k \sigma_i(B),$$

where k is the rank of B and $\sigma_1(B) \ge \sigma_2(B) \dots$ are the singular values.

• Nuclear norm is a convex approximation of rank, think how you cannot easily minimize ℓ_0 norm, aka the number of nonzero entries, an instead minimize the ℓ_1 norm to induce sparsity in regression problems.

5

Proximal gradient

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$$[P_{\Omega}(B)]_{ij}=B_{ij}1((ij)\in\Omega)$$

• So the optimization can also be written as:

$$\min \frac{1}{2} \|P_{\Omega}(Y) - P_{\Omega}(B)\|_F^2 + \lambda \|B\|_*$$

- Gradient of smooth first part: $-(P_{\Omega}(Y) P_{\Omega}(B))$
- Prox function:

$$\operatorname{prox}_{\alpha}(B) = \arg\min_{Z \in \mathbb{R}^{m \times n}} \frac{1}{2\alpha} \|B - Z\|_F^2 + \lambda \|Z\|_*$$

Proximal GD

- We will show that $prox_{\alpha}(B) = S_{\alpha}(B)$, where
- $S_{\alpha}(B)$ is $U\Sigma_{\alpha}V^{T}$, where $B=U\Sigma V^{T}$ and

$$\Sigma_{\alpha}(i,i) = \max(\Sigma_{ii} - \lambda, 0)$$

- First, it is known that the subdifferential of the nuclear norm is given by: $\partial \|Z\|_* = \{UV^T + W : \|W\| \le 1, U^TW = 0, WV = 0\}$
- Now we will show that $0 \in S_{\alpha\lambda}(B) B + \lambda \alpha \partial ||S_{\alpha\lambda}(B)||_*$

Proximal GD

- Take U_0 , V_0 as the singular vectors corresponding to $\sigma_i > \lambda \alpha =: t$.
- Take the remaining singular vectors as U_\perp, V_\perp and the corresponding singular value matrix as Σ_\perp
- $S_t(B) B = -tU_0V_0^T U_{\perp}\Sigma_{\perp}V_{\perp}^T$
- $S_t(B) B + t(U_0V_0^T + W) = tW U_{\perp}\Sigma_{\perp}V_{\perp}^T$
- Taking $W = U_{\perp} \Sigma_{\perp} V_{\perp}^{T} / t$, we see that
 - $U^T W = 0$
 - *WV* = 0
 - $||W|| \le 1$

Proximal GD

- $B_{k+1} = S_{\lambda\alpha}(B + t(P_{\Omega}(Y) P_{\Omega}(B)))$
- This is called the Soft Impute algorithm.
 - Cai et al, "A Singular Value Thresholding Algorithm for Matrix Completion", 2010.
 - Mazumdar et al 2011, Spectral regularization algorithms for learning large incomplete matrices

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