Who: Team

Team Name	JK (just kidding, but are we tho?)
Team Members	Kona Ogawa, Jess Soo Hoo
Repository Link	https://github.com/psb-2019-2020-s1-autonomous-robotics/jk02.git

What: Description (what is the goal?)

Goal (what is this to accomplish?)	Our goal is to have the robot sense human walking by and stop, move forward, backward, left, and right.
Use case(s) (how do you use it?)	

How / Why: Other Documentation List

Design	
Code	
Trade Offs (why?)	