Fast Spatial Gaussian Process Maximum Likelihood Estimation via Skeletonization Factorizations



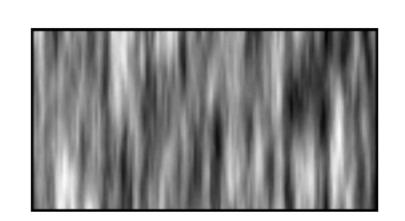
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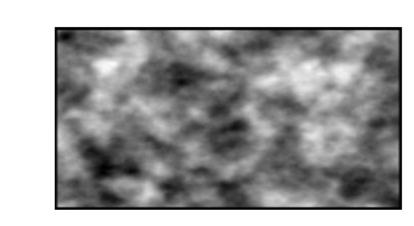
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Introduction

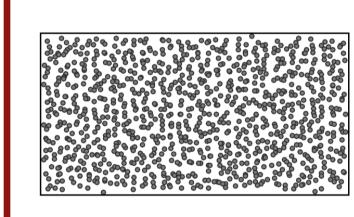
- Gaussian processes (Kriging) used frequently to model spatial fields in 2D.
- For data sets with many observations, limited by $O(N^3)$ cost of working with large kernelized covariance matrices.
- Using hierarchical matrix structure, we show a fast way to compute maximum likelihood estimates for parameterized kernels.

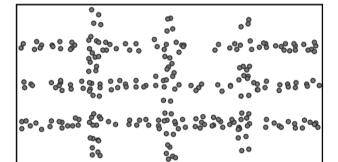


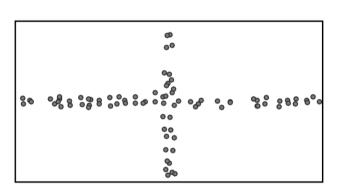


$$k_M(x, y; \theta) = (1 + \sqrt{3}||x - y||_{\theta}) \exp(-\sqrt{3}||x - y||_{\theta}) + \sigma^2 I$$

Numerical Results







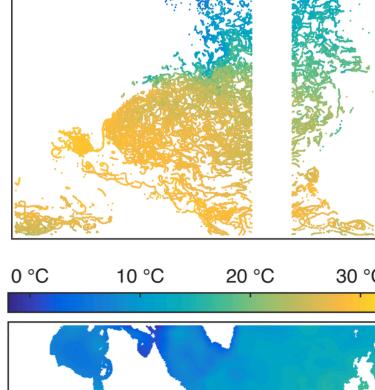


Given: observation vector $z \in \mathbb{R}^n$, parameter vector $\theta \in \mathbb{R}^p$, peel tolerance ϵ_{peel} , factorization tolerance $\epsilon_{\text{fact}} < \epsilon_{\text{peel}}$ and covariance kernel family $k(\cdot, \cdot; \theta)$

- 1: // Factor Σ with hierarchial factorization
- 2: $F \leftarrow \text{Recursive skeletonization factorization of } \Sigma \text{ with tolerance } \epsilon_{\text{fact}}$
- 3: // Use fast hierarchical solve and log-determinant
- 4: $\hat{\ell}(\theta) \leftarrow -\frac{1}{2}z^T F^{-1}z \frac{1}{2}\log|F| \frac{1}{2}\log 2\pi \approx \ell(\theta)$
- 5: **for** i = 1, ..., p **do**
- 6: // Factor Σ_i with hierarchical factorization
- $F_i \leftarrow \text{Recursive skeletonization factorization of } \Sigma_i \text{ with tolerance } \epsilon_{\text{fact}}$
- 3: // Compute trace of $\Sigma^{-1}\Sigma_i$ with peeling algorithm
- $t_i \leftarrow \text{Trace of peeled operator } \frac{1}{2}(F^{-1}F_i + F_iF^{-1}) \text{ via peeling algorithm with tolerance } \epsilon_{\text{peel}}$
- 10: // Use fast hierarchical apply and solve 11: $\hat{g}_i \leftarrow \frac{1}{2}z^TF^{-1}F_iF^{-1}z - \frac{1}{2}t_i \approx g_i$
- 11: $g_i \leftarrow \frac{1}{2}z$ T T_iT . 12: **end for**
- Output: $\hat{\ell}(\theta)$ and \hat{g}

10⁶ 10⁵ 10⁴ 10³ 10² 10²

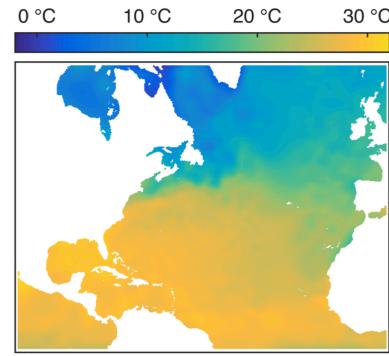




Top: runtime scaling for one iteration of maximum likelihood estimation with our method.

Number of observations

Right: Kriged estimates of sea-surface temperature in the Atlantic ocean using restricted maximum likelihood estimation on a subset of the ICOADS data set.



Basic Idea

Log-likelihood is

$$\ell(\theta) = -\frac{1}{2}z^T\Sigma^{-1}z - \frac{1}{2}\log|\Sigma| - \frac{n}{2}\log 2\pi$$
 with gradient

$$g_i = \frac{\partial \ell(\theta)}{\partial \theta_i} = \frac{1}{2} z^T \Sigma^{-1} \Sigma_i \Sigma^{-1} z - \frac{1}{2} \operatorname{Tr}(\Sigma^{-1} \Sigma_i)$$

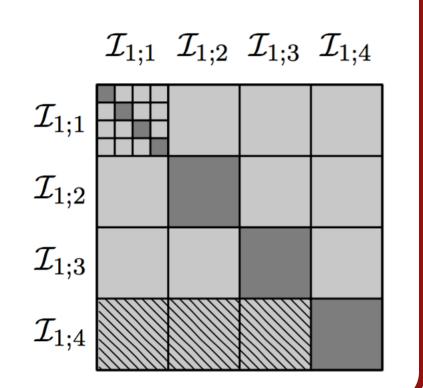
Use recursive skeletonization factorization to approximate

$$\Sigma pprox \left[\prod_{\ell=1}^L \left(\prod_{\mathcal{I} \in \mathscr{L}_\ell} L_{\mathcal{I}} U_{\mathcal{I}} \right) P_\ell \right] \tilde{\Sigma}_0 \left[\prod_{\ell=1}^L \left(\prod_{\mathcal{I} \in \mathscr{L}_\ell} L_{\mathcal{I}} U_{\mathcal{I}} \right) P_\ell \right]^T$$

Use black-box applies to construct
 H-matrix to "peel" trace term.

Rank r_ℓ of off-diagonal blocks of G at level ℓ	Time	Storage
$O(1) - O(\log n_\ell)$	$ ilde{O}(n)$	$ ilde{O}(n)$
$O(\sqrt{n}_\ell)$	$\tilde{O}\left(n^2 ight)$	$\tilde{O}(n^{3/2})$

$\Omega_{2;1}$ $\Omega_{2;2}$ $\Omega_{2;3}$ $\Omega_{2;4}$	2		``````````````````````````````````````	21	\vdots 2 \vdots 2 \vdots	•	0	0
		0 0 0	•	•	0	0	0	6
	0 0	0 0	.	L 1	;4	٥	0	e
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Key References

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Full references in paper (see http://arxiv.org/abs/1603.08057 or QR code)

Acknowledgments

V.M. is supported by a U.S. Department of Energy Computational Science Graduate Fellowship under grant number DE-FG02-97ER25308. A.D. is partially supported by a National Science Foundation Graduate Research Fellowship under grant number DGE-1147470 and a Simons Graduate Research Assistantship. K.H. is supported by a National Science Foundation Mathematical Sciences Postdoctoral Research Fellowship under grant number DMS-1203554. L.Y. is supported by the National Science Foundation under award DMS-1328230 and DMS-1521830 and the U.S. Department of Energy's Advanced Scientific Computing Research program under award DE-FC02-13ER26134/DE-SC0009409.





