



IDC410

A course on Image Processing and Machine Learning

(Lecture 23)

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Graphical Neural Network



GNN Lectures adapted from following References

1. Youtube Lectures given by Petar Velickovic on YouTube:

<https://www.youtube.com/watch?v=uF53xsT7mjc&t=1350s>

<https://www.youtube.com/watch?v=8owQBFAHw7E&list=PPSV>

<https://www.youtube.com/watch?v=uF53xsT7mjc&list=PPSV&t=728s>

2. Other Youtube Videos

<https://www.youtube.com/watch?v=fOctJB4kVIM&list=PPSV>

<https://www.youtube.com/watch?v=ABCGCf8cJOE&list=PPSV>

<https://www.youtube.com/watch?v=0YLZXjMHA-8&list=PPSV>

<https://www.youtube.com/watch?v=2KRAOZIULzw&list=PPSV>

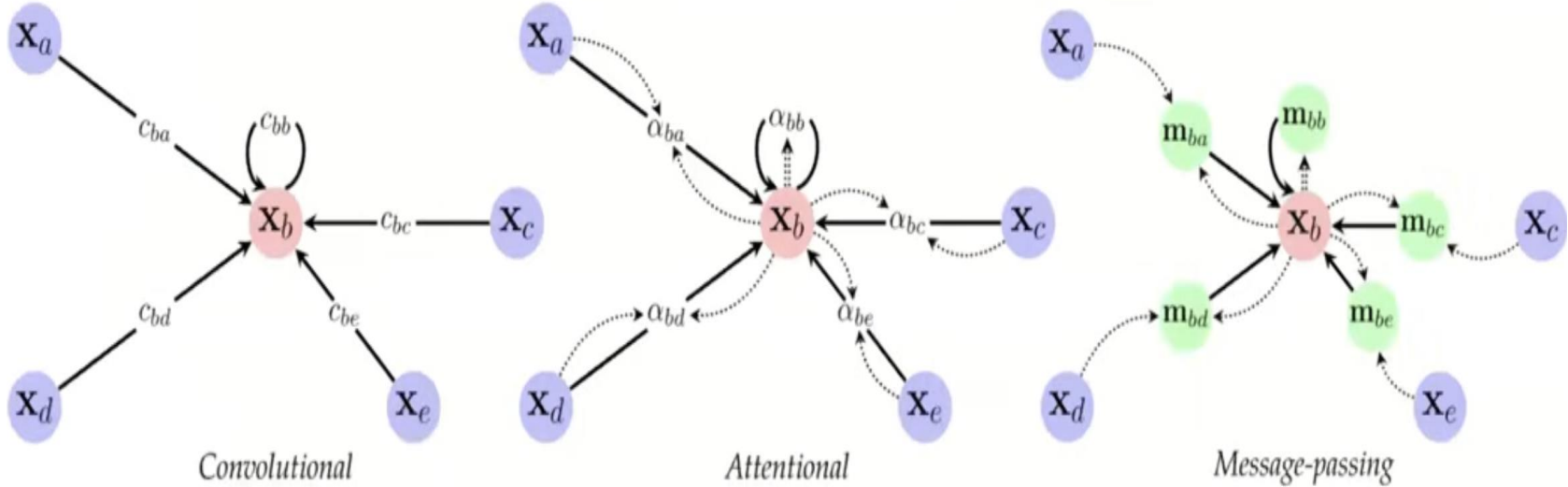
<https://www.youtube.com/watch?v=wJQQFUcHO5U&list=PPSV>

3. Notes:

<https://distill.pub/2021/gnn-intro/>

<https://distill.pub/2021/understanding-gnns/>

Embedding Algorithms

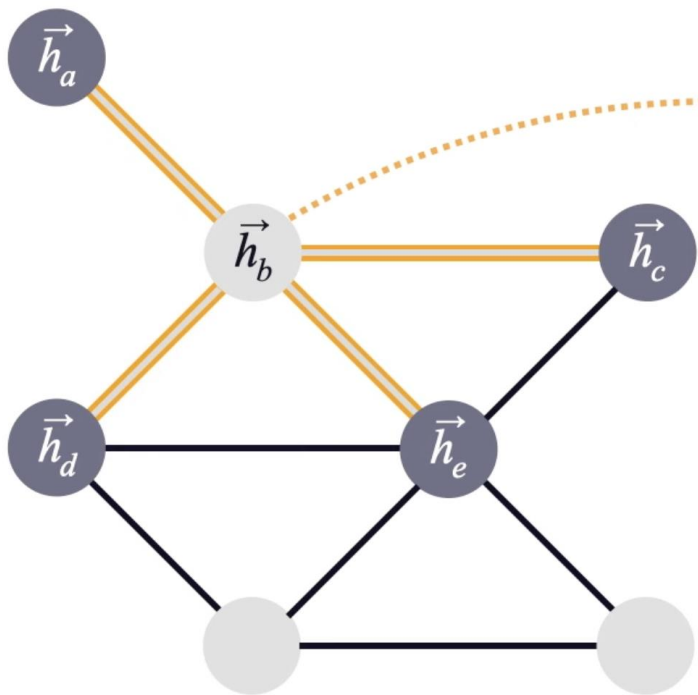


$$\mathbf{h}_i = \phi \left(\mathbf{x}_i, \bigoplus_{j \in \mathcal{N}_i} c_{ij} \psi(\mathbf{x}_j) \right)$$

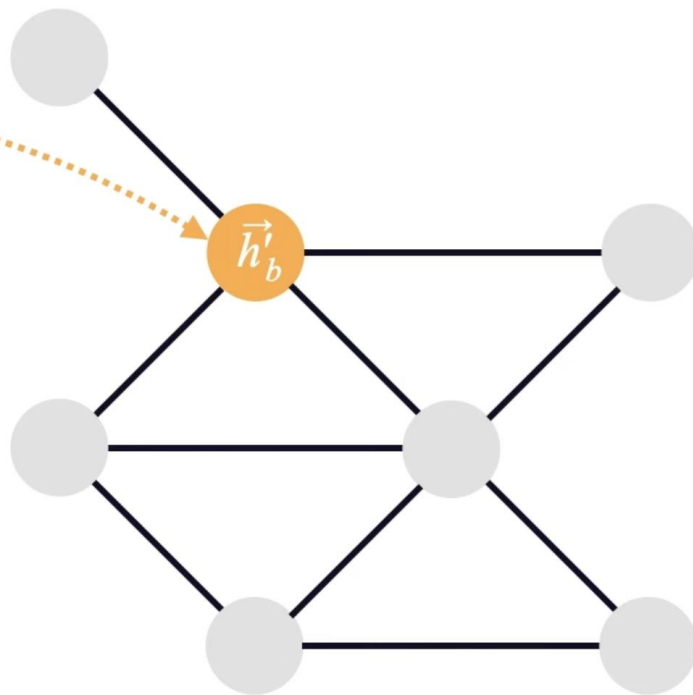
$$\mathbf{h}_i = \phi \left(\mathbf{x}_i, \bigoplus_{j \in \mathcal{N}_i} a(\mathbf{x}_i, \mathbf{x}_j) \psi(\mathbf{x}_j) \right)$$

$$\mathbf{h}_i = \phi \left(\mathbf{x}_i, \bigoplus_{j \in \mathcal{N}_i} \psi(\mathbf{x}_i, \mathbf{x}_j) \right)$$

Convolutional GNN \rightarrow GCN



$$\vec{h}'_i = g(\vec{h}_a, \vec{h}_b, \vec{h}_c, \dots)$$



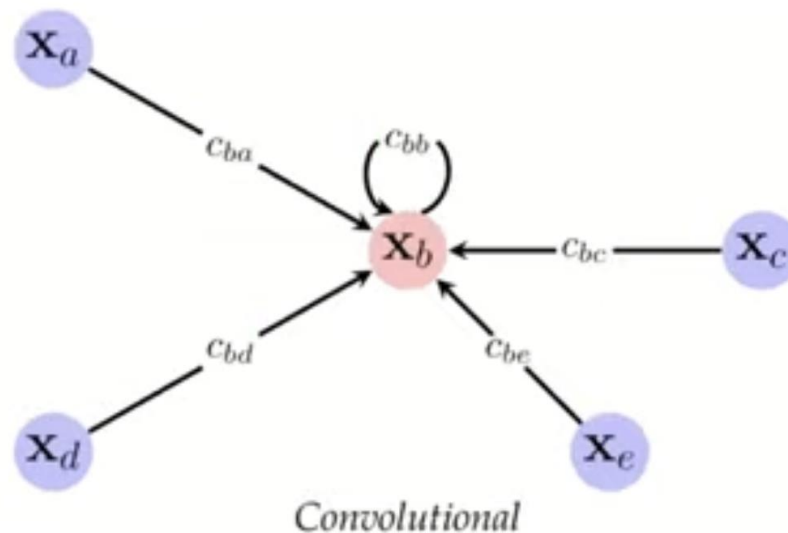
$$(a, b, c, \dots \in N_i)$$

Convolutional GNN → GCN

- Features of neighbours aggregated with fixed weights, c_{ij}

$$\mathbf{h}_i = \phi \left(\mathbf{x}_i, \bigoplus_{j \in \mathcal{N}_i} c_{ij} \psi(\mathbf{x}_j) \right)$$

- Usually, the weights depend directly on **A**.
 - ChebyNet (Defferrard *et al.*, NeurIPS'16)
 - GCN (Kipf & Welling, ICLR'17)
 - SGC (Wu *et al.*, ICML'19)
- Useful for **homophilous** graphs and **scaling up**
 - When edges encode *label similarity*



Homophily is a graph property describing the tendency of edges to connect similar nodes; the opposite is called **heterophily**.

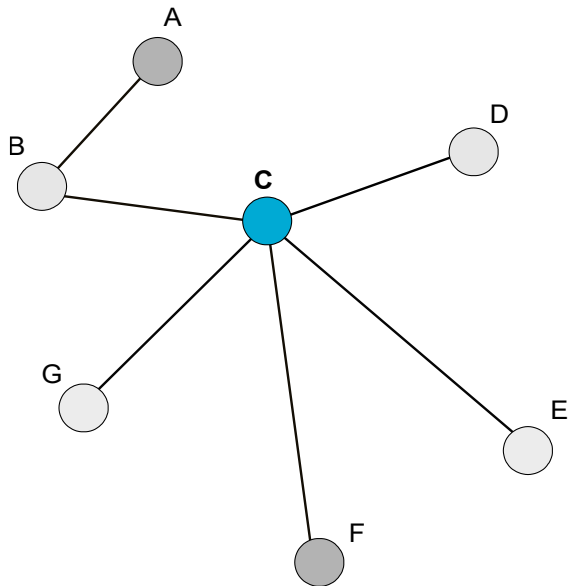
GCN: Polynomial Filters on Graphs

- For a given Graph G , Adjacency matrix A (matrix elements either 0 or 1), the degree of a *node* v can be obtained as:

$$D_v = \sum_u A_{uv}$$

- where, A_{uv} denotes the entry in the row corresponding v to and the column corresponding to u in the adjacency matrix
- Then, the *Laplacian* L of graph G with n nodes is given by a $n \times n$ matrix as:
 - $L = D - A$,
 - The name, *Laplacian of graph* if from being the discrete analog of the Laplacian operator from calculus.
- Note: D and A are matrices of size $n \times n$

GCN: Polynomial Filters on Graphs



Undirected Input Graph G

	A	B	C	D	E	F	G
A	1	-1					
B	-1	2	-1				
C		-1	5	-1	-1	-1	-1
D			-1	1			
E			-1		1		
F			-1			1	
G			-1				1

Laplacian of Input Graph G

GCN: Polynomial Filters on Graphs

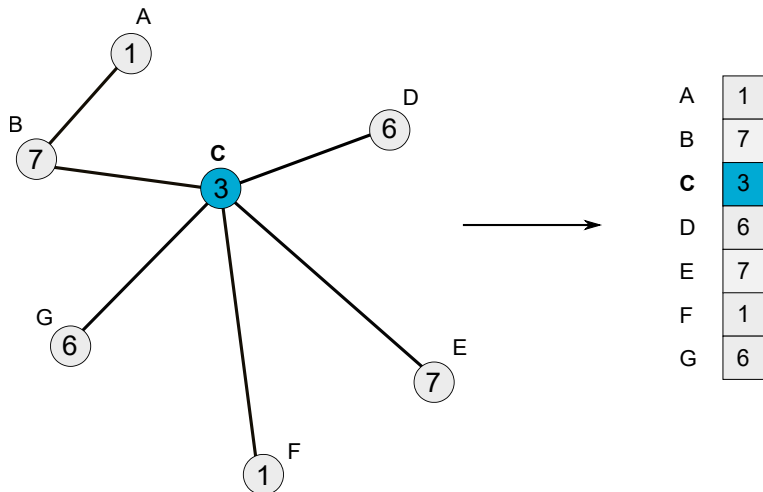
- We can build polynomials of order d of graph Laplacian the form:

$$p_w(L) = w_0 I_n + w_1 L + w_2 L^2 + w_3 L^3 + \dots + w_d L^d = \sum_{i=0}^d w_i L^i$$

- Polynomial of this form can be represented by its vector of coefficients:
 - $w \rightarrow [w_0, w_1, w_2, \dots, w_d]$
 - Note that for every vector w ; $p_w(L)$ is an $n \times n$ matrix, just like L
- These polynomials can be thought of as the equivalent of *filters* in CNNs, and the coefficients w as the weights of the *filters*
- Having constructed the feature vector x , we can define its convolution with a polynomial filter p_w as: $x' = p_w(L) x$

GCN: Polynomial Filters on Graphs

- Let us consider the case where, nodes have one-dimensional features: each of the x_v for $v \in V$ is just a single real number. The same ideas hold when each of the x_v are higher-dimensional vectors, as well
- Using the previously chosen ordering of the nodes, we can stack all of the node features x_v to get a vector $x \in \mathbb{R}_n$



GCN: Polynomial Filters on Graphs

- To understand how the coefficients w affect the convolution, let us begin with the *simplest* polynomial: when $w_0=1$ and all of the other coefficients are 0. In this case, x' is just x

$$x'_v = p_w(L)x_v = \sum_{i=0}^d w_i L^i x_v = w_0 I_n x_v = x_v$$

- Consider a polynomial of *order 1* with $w_1=1$ and all other coefficients 0:
 - Note: Features at each node v are combined with the features of its immediate neighbours $u \in N(v)$

$$\begin{aligned} x'_v &= p_w(L)x_v = \sum_{i=0}^d w_i L^i x_v = w_1 L^1 x_v = (Lx)_v = L_v x \\ &= \sum_{u \in G} (D_{vu} - A_{vu}) x_u = D_v x_v - \sum_{u \in N(v)} x_u \end{aligned}$$

GCN: Polynomial Filters on Graphs

- Hops: Refers to the *minimum # of edges* a node is away from another node in a graph. A *1-hop* neighbour is directly connected to a node, a *2-hop* neighbour is connected to a *immediate* neighbour of the node, and so on. GNNs often *aggregates or convolutes* information from nodes within a certain *# of hops*, shaping the node's representation based on its local neighbourhood.
- *# of hops* used in polynomial filter in graph convolution is equivalent to the *size of convolutional filter in CNN*
- How does the degree *d* of the polynomial influence the behaviour of the convolution?
- If *# of hops* between two nodes is *k*, then it can be shown that,

$$L_{uv}^i = 0 \quad \text{for all} \quad i > k$$



GCN: Polynomial Filters on Graphs

- This implies, when we convolve x with $p_w(L)$ of degree d then to get x' :

$$x'_v = (p_w(L)x)_v = (p_w(L))_v x = \sum_{i=0}^d w_i L^i x = \sum_{i=0}^d w_i \sum_{u \in G} L^i_{uv} x_u = \sum_{i=0}^d w_i \sum_{\substack{u \in G, \\ \text{dist}_G(u,v) \leq i}} L^i_{uv} x_u$$

- Effectively, the convolution at node v occurs only with nodes u which are not more than i hops away. Thus, these polynomial filters are localized. The degree of the localization is governed completely by d



GCN: ChbNetPolynomial Filters on Graphs

- Chebnet uses the polynomial of the forma:

$$p_w(L) = \sum_{i=0}^d w_i T_i(\bar{L})$$

- where, T_i is the degree- i Chebyshev polynomial of the first kind ($T_i(\cos\theta) = \cos(i\theta)$) and \bar{L} is the *normalized* Laplacian defined using the largest eigenvalue of L as:

$$\bar{L} = \frac{2L}{\lambda_{\max}(L)} - I_n$$

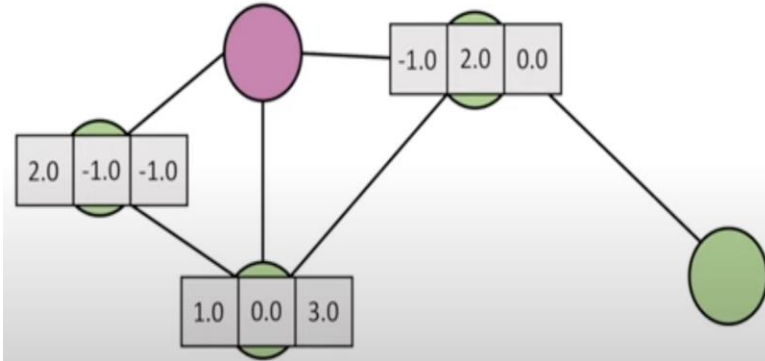
- \bar{L} always have eigenvalues between $[-1,1]$ whereas the eigenvalues for un-normalised L can be >1 may cause divergences at higher order of L
- Use of Chebyshev polynomials has certain properties that makes interpolation more numerically stable.



GCN: Embedding Computation

- GNN is built by stacking ChebNet (or any polynomial filter) layers one after the other with non-linearities, much like a standard CNN.
- $h^{(0)}=x$ is an original feature
- Then iterate, for $k=1, 2, 3, \dots$ up to K : Compute the *matrix* $p^{(k)}$ as the polynomial filter defined by the filter weights $w^{(k)}$ evaluated at L : $p^{(k)} = p_{w^{(k)}}(L)$
- Multiply $p^{(k)}$ with $h^{(k-1)}$, a standard matrix-vector multiplication operation: $g^{(k)} = p^{(k)} \times h^{(k-1)}$
- Now apply an activation function σ and introduce non-linearity to get the next level learned features $h^{(k)}$: $h^{(k)} = \sigma(g^{(k)})$
- Note that these networks uses the same filter weights across different nodes, exactly mimicking weight-sharing in CNNs

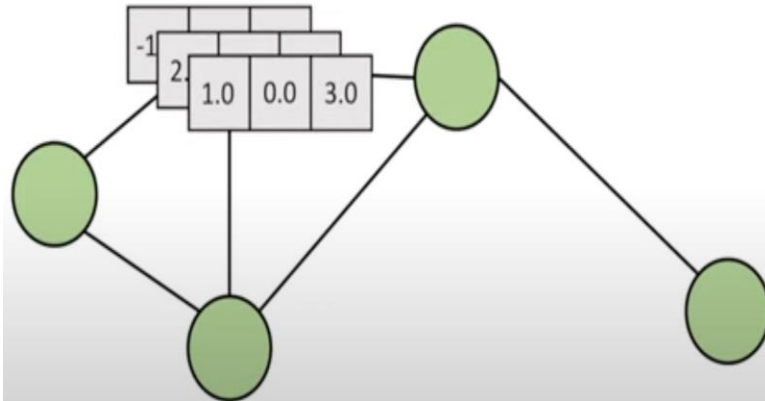
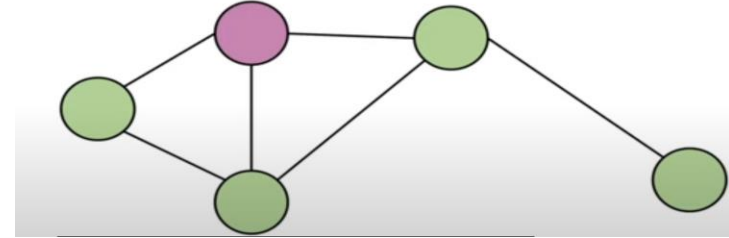
GNN Example: Predictions with Message Passing



Average(

2.0	1.0	1.0
1.0	0.0	3.0

)

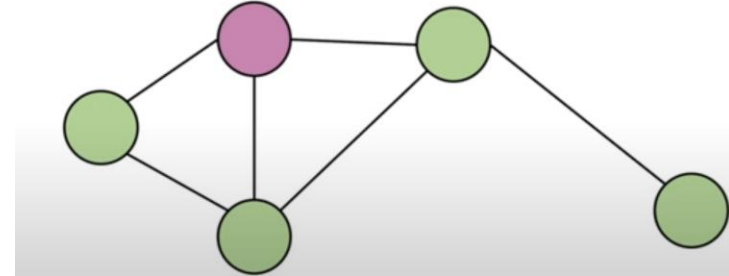


Average(

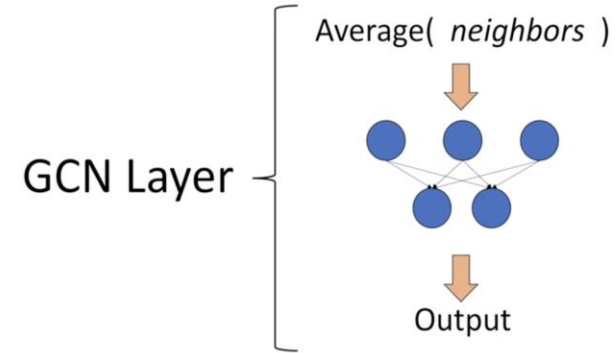
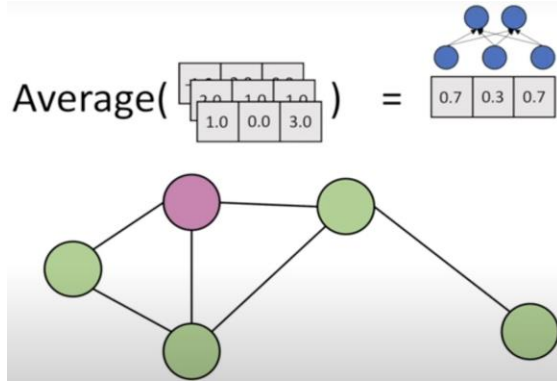
2.0	1.0	1.0
1.0	0.0	3.0

) =

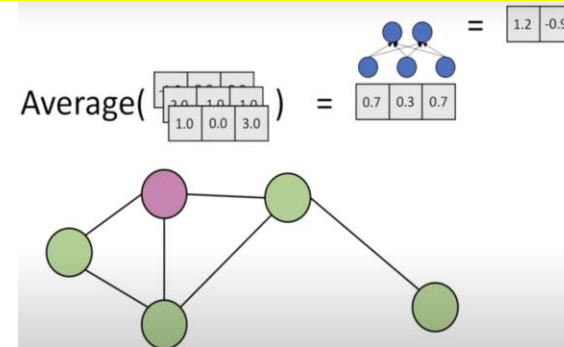
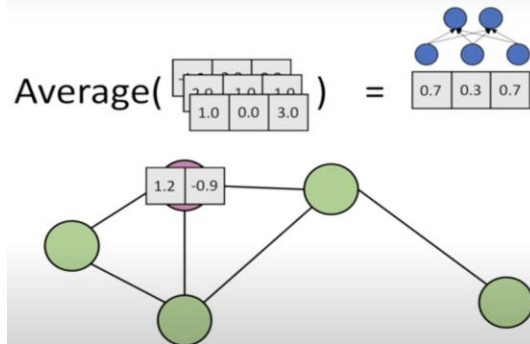
0.7	0.3	0.7
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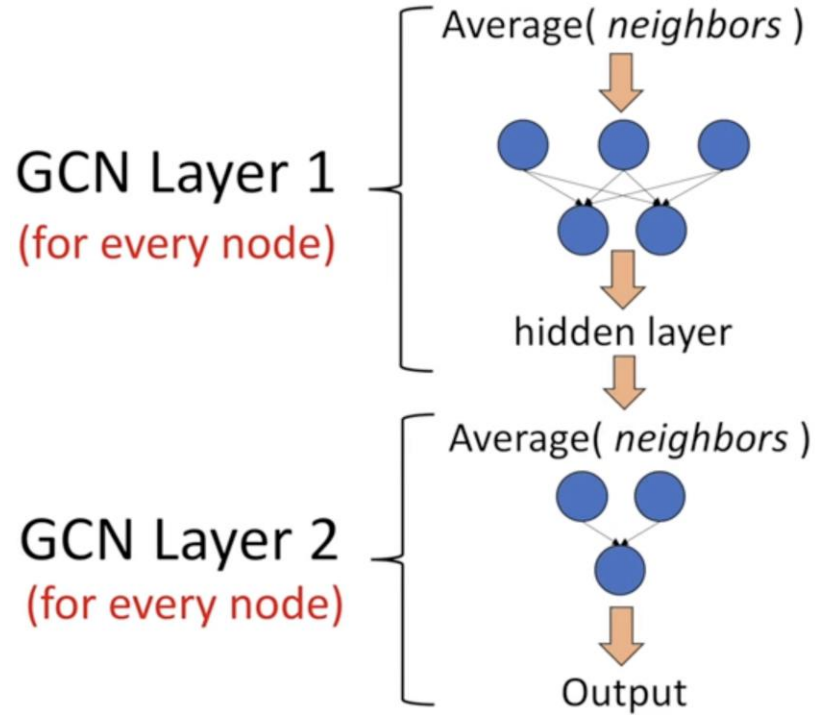
GNN Example: Predictions with Message Passing



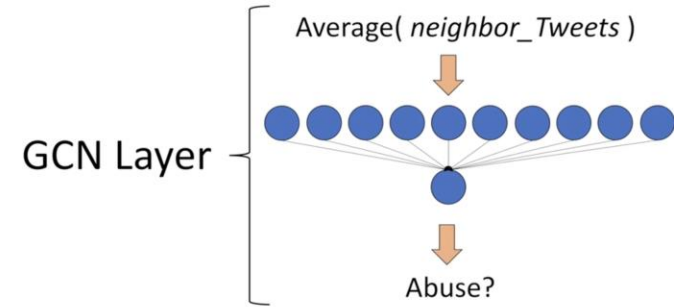
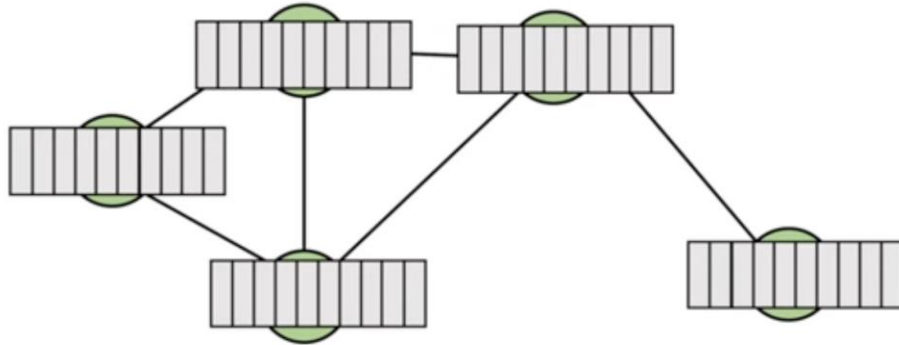
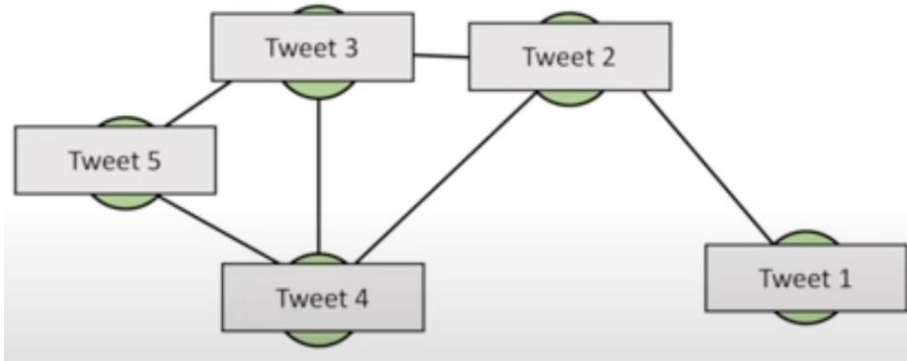
The dimensionality of each attribute is revised with the update function. The update function is generally a 1-layer MLP with a ReLU activation function and a layer norm for normalization of activations



GNN Example: Predictions with Message Passing



GNN Example: Predictions with Message Passing



$$h_i^{l+1} = \sigma \left(\sum_{j \in N_i} \frac{1}{c_{ij}} h_j^l W^l \right)$$

$$h_i^{l+1} = \sigma \left(W_0^l h_i^l + \sum_{r \in R} \sum_{j \in N_i^r} \frac{1}{c_{ir}} W_r^l h_j^l \right)$$

Super Adjacency Matrix

$$W_r^l = \bigoplus_{b=1}^B Q_{br}^l$$

