

# OS Project Final Phase

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Note: Behavior of my OS (Firmware) and Application (Cartridge) is in README.txt

## API as System Calls Documentation

### **Name**

System Call(3) – To fetch the current register status of the game controller.

### **Parameters**

N/A

### **Return Value**

A character array of length 8 (a byte/8 bits), representing the current state/value of the register.

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### **Name**

System Call(6) – To set the background on a particular layer.

### **Signature with parameters**

void setBackground(int control\_index, uint16\_t x, uint16\_t y, uint8\_t z, uint8\_t palette\_index, int R, int G, int B, int ALPHA)

### **Return Value**

Return 0 if the operation is performed.

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### **Name**

System Call(8) – Draw a small sprite

### **Signature with parameters**

void setSmallSprite(int control\_index, uint16\_t x, uint16\_t y, uint8\_t w, uint8\_t h, uint8\_t z, uint8\_t palette\_index, int R, int G, int B, int ALPHA)

### **Return Value**

Return 0 if the operation is performed.

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**Name**

System Call(9) – Draw a large sprite

**Signature with parameters**

void setLargeSprite(int control\_index, uint16\_t x, uint16\_t y, uint8\_t w, uint8\_t h, uint8\_t palette\_index, int R, int G, int B, int ALPHA)

**Return Value**

Return 0 if the operation is performed.

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**Name**

System Call(7) – Display a message/text on the console.

**Signature with parameters**

void display\_text\_on\_console(char\* message\_to\_display, uint32\_t start\_index)

**Return Value**

Return 0 if the operation is performed successfully.

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**Name**

System Call(5) – Switch mode between TEXT MODE and GRAPHICS MODE

**Signature with parameters**

void switch\_mode(uint32\_t mode)

**Return Value**

Return 0 if the operation is performed successfully.

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**Name**

System Call(1) – To get the current timer ticks

**Parameters** - N/A

**Return Value**

Returns the current amount Timer Ticks (time units elapsed)

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**Name**

System Call(2) – To get the current MODE (Text or Graphics mode)

**Parameters** - N/A

**Return Value**

Returns the value of the MODE CONTROL REGISTER

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**Name**

System Call(4) – To fetch the status of the Interrupt pending register

**Parameters** - N/A

**Return Value**

Returns the value of the INTERRUPT PENDING REGISTER (before resolving the raised interrupt)

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