The University of Connecticut Dept. of ECE

Spring 2021 KRP

<u>Problem Set # 5</u> (Due April 6, 2021).

- 1. Problem 11.16, Theodoridis, Page 589.
- 2. Suppose we have N data points $\{\underline{x}_i: i=1,2,...,N\}$. We want to find the smallest enclosing sphere for the transformed feature samples $\{\underline{\Phi}(\underline{x}_i): i=1,2,...,N\}$ by solving the following optimization problem:

$$\begin{aligned} & \underset{r>0,\underline{c}}{\min} \, r^2 \\ & \text{subject to } [\underline{\Phi}(\underline{x}_i) - \underline{c}]^T [\underline{\Phi}(\underline{x}_i) - \underline{c}] \leq r^2 \, \forall i = 1, 2, ..., N \end{aligned}$$

Show that the optimal solution satisfies $\underline{c} = \sum_{i=1}^N \alpha_i \underline{\Phi}(\underline{x}_i)$ where $\{\alpha_i\}$ are the solution to the dual optimization problem:

$$\max_{\underline{\alpha}} \sum_{i=1}^{N} \alpha_{i} K(\underline{x}_{i}, \underline{x}_{i}) - \sum_{i=1}^{N} \sum_{j=1}^{N} \alpha_{i} \alpha_{j} K(\underline{x}_{i}, \underline{x}_{j})$$
subject to: $\underline{\alpha} \ge \underline{0}$ and $\sum_{i=1}^{N} \alpha_{i} = 1$.

Compute r.

- 3. Problem 11.8, Theodoridis, Page 588.
- 4. In this problem, we use the back-propagation algorithm to solve a difficult nonlinear prediction problem and compare its performance with that of the LMS algorithm. Consider the time series modeled by

$$y(n) = w(n) + \beta w(n-1)w(n-2)$$

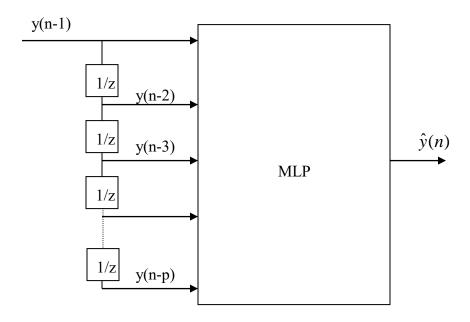
The time series has zero mean, and is uncorrelated and therefore has a white spectrum. However, the time series sample are not independent of each other, and therefore a higher-order predictor can be constructed. The variance of the model output is:

$$\sigma_v^2 = \sigma_w^2 (1 + \beta^2 \sigma_w^2)$$

where σ_w^2 is the white-noise input variance set to unity and $\beta = \frac{1}{2}$. With these values $\sigma_y^2 = 1.25$.

(a) Construct a MLP with an input layer of 6 nodes, a hidden layer of 16 neurons, and a single output neuron. Fig. 1 shows the network architecture of MLP used as a predictor, where a tapped delay line is used to feed the input layer of the network. The hidden neurons use logistic nonlinearities, whereas the output neuron operates as a linear combiner. The network is trained with the heavy-ball back propagation

- algorithm with the following parameters: learning-rate parameter η =0.001, momentum constant μ =0.9, Total number of samples processed = 100,000, Number of samples per epoch =1,000, Total number of epochs = 100. Compute the learning curve of the nonlinear predictor, with the variance of the predictor plotted as a function of the number of training epochs.
- (b) Repeat the experiment using the LMS algorithm designed to perform a linear prediction on an input of 6 samples. The learning rate of the LMS algorithm is set at 0.9.



The results should reveal that initially the back-propagation algorithm and the LMS algorithm follow a similar path, and then the back-propagation algorithm continues to improve, finally producing a prediction variance close to the ideal value. Use MATLAB NN toolbox, if necessary.