## featurization\_activity

July 18, 2019

```
In [0]: %matplotlib inline
       import warnings
       warnings.filterwarnings("ignore")
        import pandas as pd
        import seaborn as sns
        import matplotlib.pyplot as plt
        import numpy as np
       from sklearn.model_selection import train_test_split
        import math as m
In [0]: from google.colab import drive
       drive.mount('/content/gdrive')
Drive already mounted at /content/gdrive; to attempt to forcibly remount, call drive.mount("/c
In [0]: dataset_url = '/content/gdrive/My Drive/case_studies/UT_Data_Complex/smartphoneatpocker
       data = pd.read_csv(dataset_url)
       data.head
Out[0]: <bound method NDFrame.head of
                                                            -3.1327 -10.188
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                1.390000e+12 -5.924900 -10.9780
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```
[1169999 rows x 14 columns]>
In [0]: my_columns = ["timestamp", "acc_X", "acc_Y", "acc_Z", "linearacc_X", "linearacc_Y", "linearacc_Y"
        data.columns = my_columns
        print (data)
                                     acc_Y
             timestamp
                            acc X
                                             . . .
                                                  mag Y mag Z
                                                                  labels
0
         1.390000e+12 -5.924900 -10.9780
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         1.390000e+12 -3.963500 -15.5680
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1169997 1.430000e+12 5.843100
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1169998 1.430000e+12 5.802300 -2.0567
                                         ... -1.14 46.50
                                                             11123
[1169999 rows x 14 columns]
In [0]: print (data.columns)
Index(['timestamp', 'acc_X', 'acc_Y', 'acc_Z', 'linearacc_X', 'linearacc_Y',
       'linearacc_Z', 'gyro_X', 'gyro_Y', 'gyro_Z', 'mag_X', 'mag_Y', 'mag_Z',
       'labels'],
     dtype='object')
In [0]: data["labels"].value_counts()
Out[0]: 11122
                90000
        11123
                90000
        11120
                90000
        11121
                90000
                90000
        11114
        11115
                90000
        11112
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        11113
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        11118
       11119
                90000
        11116
                90000
       11117
                90000
       11111
                89999
       Name: labels, dtype: int64
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```
In [0]: data = data.drop(["timestamp"],axis = 1)
        \#X = data.iloc[:,1:14]
        #y = data.iloc[1:,13:14]
        #print(X.columns)
        print(data.columns)
        y_activity = data["labels"].map({11111: 'walk',
            11112: 'stand',
           11113: 'jog',
           11114: 'sit',
           11115: 'bike',
           11116: 'upstairs',
           11117: 'downstairs',
           11118: 'type',
           11119: 'write',
           11120: 'coffee',
           11121: 'talk',
           11122: 'smoke',
            11123: 'eat',})
        data['Activity_Name'] = y_activity
        #print(data)
Index(['acc_X', 'acc_Y', 'acc_Z', 'linearacc_X', 'linearacc_Y', 'linearacc_Z',
       'gyro_X', 'gyro_Y', 'gyro_Z', 'mag_X', 'mag_Y', 'mag_Z', 'labels'],
      dtype='object')
In [0]: df = data
In [0]: df.head()
Out[0]:
             acc_X acc_Y
                              acc_Z linearacc_X ... mag_Y mag_Z labels Activity_Name
        0 -5.924900 -10.978 1.00790
                                          -5.3538 ...
                                                        42.60 15.78
                                                                       11111
                                                                                       walk
        1 -6.960000 -12.136 0.28603
                                          -5.4353 ... 42.60 16.74
                                                                       11111
                                                                                       walk
        2 -3.963500 -15.568 -3.37780
                                          -2.3250 ... 42.36 17.34
                                                                       11111
                                                                                       walk
        3 -0.054481 -15.677 -4.44020
                                          1.2882 ... 42.06 18.36
                                                                       11111
                                                                                       walk
        4 0.354130 -13.048 -2.57420
                                          1.5373 ... 42.06 19.02
                                                                       11111
                                                                                       walk
        [5 rows x 14 columns]
In [0]: df = df.reset_index()
In [0]: #end indices of run of values in 'Activity_Name' column
        df.loc[df.groupby(['Activity_Name'])['index'].idxmax()]['labels']
Out[0]: 449998
                   11115
        899998
                   11120
        629998
                  11117
        1169998
                  11123
        269998
                  11113
```

```
359998
                   11114
                   11122
        1079998
        179998
                   11112
        989998
                   11121
        719998
                   11118
                   11116
        539998
        89998
                   11111
        809998
                   11119
        Name: labels, dtype: int64
In [0]: print(df[0:89999]['Activity Name'].value counts())
        print(df[89999:179999]['Activity Name'].value counts())
        print(df[179999:269999]['Activity_Name'].value_counts())
        print(df[269999:359999]['Activity_Name'].value_counts())
        print(df[359999:449999]['Activity_Name'].value_counts())
        print(df[449999:539999]['Activity_Name'].value_counts())
        print(df[539999:629999]['Activity_Name'].value_counts())
        print(df[629999:719999]['Activity_Name'].value_counts())
        print(df[719999:809999]['Activity_Name'].value_counts())
        print(df[809999:899999]['Activity_Name'].value_counts())
        print(df[899999:989999]['Activity_Name'].value_counts())
        print(df[989999:1079999]['Activity_Name'].value_counts())
        print(df[1079999:1700000]['Activity Name'].value counts())
walk
        89999
Name: Activity_Name, dtype: int64
         90000
stand
Name: Activity_Name, dtype: int64
       90000
jog
Name: Activity_Name, dtype: int64
sit
       90000
Name: Activity_Name, dtype: int64
bike
        90000
Name: Activity_Name, dtype: int64
            90000
upstairs
Name: Activity_Name, dtype: int64
             90000
downstairs
Name: Activity_Name, dtype: int64
type
        90000
Name: Activity_Name, dtype: int64
write
         90000
Name: Activity_Name, dtype: int64
          90000
coffee
Name: Activity_Name, dtype: int64
talk
        90000
Name: Activity_Name, dtype: int64
smoke
         90000
Name: Activity_Name, dtype: int64
```

```
eat 90000
Name: Activity_Name, dtype: int64
```

• so we can see from the above table there is no overlap between activities

```
In [0]: df.head()
Out [0]:
           index
                              acc_Y
                                                   mag_Y mag_Z
                                                                  labels Activity_Name
                     acc_X
                                       acc_Z
                                              . . .
        0
               0 -5.924900 -10.978 1.00790
                                              . . .
                                                    42.60
                                                           15.78
                                                                   11111
                                                                                    walk
               1 -6.960000 -12.136 0.28603
                                              . . .
        1
                                                   42.60 16.74
                                                                   11111
                                                                                    walk
               2 -3.963500 -15.568 -3.37780
                                                   42.36 17.34
                                                                                    walk
                                                                   11111
        3
               3 -0.054481 -15.677 -4.44020
                                                   42.06 18.36
                                                                   11111
                                                                                    walk
               4 0.354130 -13.048 -2.57420
                                                   42.06 19.02
                                                                   11111
                                                                                    walk
        [5 rows x 15 columns]
```

- 10 healthy participants aged 25-35 Seven activities were performed by all ten participants which are walking, jogging, biking, walking upstairs, walking downstairs, sitting and standing.
- These activities were performed for 3 min by each participant
- Seven out of these ten participants performed eating, typing, writing, drinking coffee and giving a talk.
- These activities were performed for 5–6 min. Smoking was performed by six out of these ten participants, where each of them smoked one cigarette. Only six participants were smokers among the ten participants.
- We used 30 min of data for each activity with an equal amount of data from each participant. This resulted in a dataset of 390 (13 Œ 30) min.

```
11111: 'walk',
11112: 'stand',
11113: 'jog',
11114: 'sit',
11115: 'bike',
11116: 'upstairs',
11117: 'downstairs',
11118: 'type',
11119: 'write',
11120: 'coffee',
11121: 'talk',
11122: 'smoke',
11123: 'eat'
```

#### 0.1 Featurization

- The TYPE\_ACCELERATION measures the acceleration force in 'meters per second' that is applied to a device on all three physical axes (x, y, and z), including the force of gravity.
- The TYPE\_LINEAR\_ACCELERATION measures the acceleration force in 'meters per second' that is applied to a device on all three physical axes (x, y, and z), excluding the force of gravity.

```
In [0]: def mag(a, b, c):
          return m.sqrt(a**2 + b**2 + c**2)
In [0]: mag(-5.924900, -10.978, 1.00790)
Out[0]: 12.515461893993365
0.2 Finding Start Indices of an activity
In [0]: df.loc[df.groupby(['Activity_Name'])['index'].idxmax()]['labels']
Out[0]: 449998
                   11115
        899998
                   11120
        629998
                   11117
        1169998
                   11123
        269998
                   11113
        359998
                   11114
        1079998
                   11122
        179998
                   11112
        989998
                   11121
        719998
                   11118
        539998
                   11116
        89998
                   11111
        809998
                   11119
        Name: labels, dtype: int64
   Calculating linear velocity
In [0]: def calVectX(sind) :
          t = 0.02
          comp = []
          for k in sind :
            comp.append(0)
            if k == 0 :
              for i in range(k, k+89999-1):
                comp.append(comp[i] + laccx[i]*t)
            else :
              for i in range(k, k+89999):
                comp.append(comp[i] + laccx[i]*t)
          return comp
        def calVectY(sind) :
```

```
comp = []
          for k in sind :
            comp.append(0)
            if k == 0:
              for i in range(k, k+89999-1):
                comp.append(comp[i] + laccy[i]*t)
            else :
              for i in range(k, k+89999):
                comp.append(comp[i] + laccy[i]*t)
          return comp
        def calVectZ(sind) :
          t = 0.02
          comp = []
          for k in sind :
            comp.append(0)
            if k == 0 :
              for i in range(k, k+89999-1):
                comp.append(comp[i] + laccz[i]*t)
            else :
              for i in range(k, k+89999):
                comp.append(comp[i] + laccz[i]*t)
          return comp
In [0]: laccx = df['linearacc_X'].values.tolist()
        laccy = df['linearacc_Y'].values.tolist()
        laccz = df['linearacc_Z'].values.tolist()
In [0]: sind = [0, 89999, 179999, 269999, 359999, 449999, 539999, 629999, 719999, 809999, 89999
In [0]: xcom = calVectX(sind)
        xcom[89999:179998] = df['linearacc_X'][89999:179998]*0.02
        xcom[269999:359998] = df['linearacc_X'][269999:359998]*0.02
```

t = 0.02

```
xcom[629999:719998] = df['linearacc_X'][629999:719998]*0.02
        xcom[719999:809998] = df['linearacc_X'][719999:809998]*0.02
        xcom[809999:899998] = df['linearacc_X'][809999:899998]*0.02
        xcom[899999:989998] = df['linearacc_X'][899999:989998]*0.02
        xcom[1079999:1169998] = df['linearacc X'][1079999:1169998]*0.02
In [0]: ycom = calVectY(sind)
        ycom[89999:179998] = df['linearacc_Y'][89999:179998]*0.02
        ycom[269999:359998] = df['linearacc_Y'][269999:359998]*0.02
        ycom[629999:719998] = df['linearacc_Y'][629999:719998]*0.02
        ycom[719999:809998] = df['linearacc_Y'][719999:809998]*0.02
        ycom[809999:899998] = df['linearacc_Y'][809999:899998]*0.02
        ycom[899999:989998] = df['linearacc_Y'][899999:989998]*0.02
        ycom[1079999:1169998] = df['linearacc_Y'][1079999:1169998]*0.02
In [0]: zcom = calVectZ(sind)
        zcom[89999:179998] = df['linearacc Z'][89999:179998]*0.02
        zcom[269999:359998] = df['linearacc_Z'][269999:359998]*0.02
        zcom[629999:719998] = df['linearacc_Z'][629999:719998]*0.02
        zcom[719999:809998] = df['linearacc_Z'][719999:809998]*0.02
        zcom[809999:899998] = df['linearacc_Z'][809999:899998]*0.02
        zcom[899999:989998] = df['linearacc_Z'][899999:989998]*0.02
        zcom[1079999:1169998] = df['linearacc Z'][1079999:1169998]*0.02
In [0]: df['velx'] = xcom
        df['vely'] = ycom
        df['velz'] = zcom
In [0]: df.head()
Out [0]:
           index
                     \mathtt{acc}_{\mathtt{X}}
                             acc_Y
                                      acc_Z ... Activity_Name
                                                                      velx
                                                                                vely
                                                                                           velz
        0
               0 -5.924900 -10.978 1.00790
                                                            walk 0.000000 0.000000
                                                                                      0.000000
        1
               1 -6.960000 -12.136 0.28603
                                                            walk -0.107076 -0.024436
                                                                                       0.036420
               2 -3.963500 -15.568 -3.37780
                                                            walk -0.215782 -0.073720
                                                                                       0.053232
               3 -0.054481 -15.677 -4.44020
                                                            walk -0.262282 -0.192286
                                                                                      0.000644
               4 0.354130 -13.048 -2.57420
                                                            walk -0.236518 -0.313222 -0.062654
        [5 rows x 18 columns]
0.4 Calculating distance travelled
```

```
In [0]: def calVectDistX(sind) :
           t = 0.02
           \Gamma = \alpha mos
           for k in sind :
```

```
comp.append(0)
    if k == 0 :
      for i in range(k, k+89999-1):
        comp.append(comp[i]*t + 0.5*laccx[i]*(t**2))
    else :
      for i in range(k, k+89999):
        comp.append(comp[i]*t + 0.5*laccx[i]*(t**2))
  return comp
def calVectDistY(sind) :
  t = 0.02
  comp = []
  for k in sind :
    comp.append(0)
    if k == 0 :
      for i in range(k, k+89999-1):
        comp.append(comp[i]*t + 0.5*laccy[i]*(t**2))
    else :
      for i in range(k, k+89999):
        comp.append(comp[i]*t + 0.5*laccy[i]*(t**2))
  return comp
def calVectDistZ(sind) :
  t = 0.02
  comp = []
  for k in sind :
    comp.append(0)
    if k == 0:
      for i in range(k, k+89999-1):
        comp.append(comp[i]*t + 0.5*laccz[i]*(t**2))
    else :
      for i in range(k, k+89999):
        comp.append(comp[i]*t + 0.5*laccz[i]*(t**2))
```

#### return comp

```
In [0]: xcom = calVectDistX(sind)
        xcom[89999:179998] = 0.5*df['linearacc X'][89999:179998]*(0.02**2)
        xcom[269999:359998] = 0.5*df['linearacc X'][269999:359998]*(0.02**2)
        xcom[629999:719998] = 0.5*df['linearacc_X'][629999:719998]*(0.02**2)
        xcom[71999:809998] = 0.5*df['linearacc X'][71999:809998]*(0.02**2)
        xcom[809999:899998] = 0.5*df['linearacc_X'][809999:899998]*(0.02**2)
        xcom[899999:989998] = 0.5*df['linearacc X'][899999:989998]*(0.02**2)
        xcom[1079999:1169998] = 0.5*df['linearacc X'][1079999:1169998]*(0.02**2)
In [0]: ycom = calVectDistY(sind)
        vcom[89999:179998] = 0.5*df['linearacc Y'][89999:179998]*(0.02**2)
        ycom[269999:359998] = 0.5*df['linearacc_Y'][269999:359998]*(0.02**2)
        vcom[629999:719998] = 0.5*df['linearacc Y'][629999:719998]*(0.02**2)
        ycom[719999:809998] = 0.5*df['linearacc_Y'][719999:809998]*(0.02**2)
        ycom[809999:899998] = 0.5*df['linearacc_Y'][809999:899998]*(0.02**2)
        ycom[899999:989998] = 0.5*df['linearacc_Y'][899999:989998]*(0.02**2)
        ycom[1079999:1169998] = 0.5*df['linearacc_Y'][1079999:1169998]*(0.02**2)
In [0]: zcom = calVectDistZ(sind)
        zcom[89999:179998] = 0.5*df['linearacc Z'][89999:179998]*(0.02**2)
        zcom[269999:359998] = 0.5*df['linearacc Z'][269999:359998]*(0.02**2)
        zcom[629999:719998] = 0.5*df['linearacc Z'][629999:719998]*(0.02**2)
        zcom[719999:809998] = 0.5*df['linearacc_Z'][719999:809998]*(0.02**2)
        zcom[809999:899998] = 0.5*df['linearacc_Z'][809999:899998]*(0.02**2)
        zcom[899999:989998] = 0.5*df['linearacc_Z'][899999:989998]*(0.02**2)
        zcom[1079999:1169998] = 0.5*df['linearacc Z'][1079999:1169998]*(0.02**2)
In [0]: df['distx'] = xcom
        df['disty'] = ycom
        df['distz'] = zcom
In [0]: df.head()
Out [0]:
           index
                     \mathtt{acc}_{\mathtt{X}}
                             acc_Y
                                      acc_Z ...
                                                      velz
                                                               distx
                                                                         disty
                                                                                   distz
               0
        1
               1 -6.960000 -12.136 0.28603 ...
                                                  0.036420 -0.001071 -0.000244
               2 -3.963500 -15.568 -3.37780 ...
                                                 0.053232 -0.001108 -0.000498  0.000175
               3 -0.054481 -15.677 -4.44020 ...
                                                  0.000644 -0.000487 -0.001196 -0.000522
               4 \quad 0.354130 \quad -13.048 \quad -2.57420 \quad \dots \quad -0.062654 \quad 0.000248 \quad -0.001233 \quad -0.000643
        [5 rows x 21 columns]
```

# 0.5 Calculating Magnitude of Velocity, Distance, accelerometer, linearacc, gyro, magnetometer

```
In [0]: df['mag_vel'] = df.apply(lambda row : mag(row['velx'], row['vely'], row['velz']), axis
        df['mag_dist'] = df.apply(lambda row : mag(row['distx'], row['disty'], row['distz']), ;
        df['mag_acc'] = df.apply(lambda row : mag(row['acc_Y'], row['acc_X'], row['acc_Z']), a
        df['mag_lacc'] = df.apply(lambda row : mag(row['linearacc_X'], row['linearacc_Y'], row
        df['mag_gyro'] = df.apply(lambda row : mag(row['gyro_X'], row['gyro_Y'], row['gyro_Z']
        df['mag_magnet'] = df.apply(lambda row : mag(row['mag_X'], row['mag_Y'], row['mag_Z'])
In [0]: df.head()
Out [0]:
           index
                     acc X
                             acc_Y
                                       acc_Z
                                                     mag_acc mag_lacc
                                                                                   mag_magnet
                                              . . .
                                                                         mag_gyro
               0 -5.924900 -10.978 1.00790
                                              . . .
                                                   12.515462 5.785500
                                                                         3.732066
                                                                                    50.098132
        1
               1 -6.960000 -12.136 0.28603
                                                   13.993066 6.026725 3.036441
                                                                                    50.283795
                                              . . .
               2 -3.963500 -15.568 -3.37780
                                                   16.415891 6.889420 3.109439
                                                                                    50.210107
        3
               3 -0.054481 -15.677 -4.44020
                                                   16.293762 6.945491 4.217099
                                                                                    50.222437
               4 0.354130 -13.048 -2.57420
                                                   13.304218 3.935439 2.937097
                                                                                    50.443231
        [5 rows x 27 columns]
In [0]: df.info()
<class 'pandas.core.frame.DataFrame'>
RangeIndex: 1169999 entries, 0 to 1169998
Data columns (total 27 columns):
index
                 1169999 non-null int64
                 1169999 non-null float64
\mathtt{acc}_{\mathtt{X}}
acc_Y
                 1169999 non-null float64
acc Z
                 1169999 non-null float64
                 1169999 non-null float64
linearacc_X
linearacc_Y
                 1169999 non-null float64
linearacc_Z
                 1169999 non-null float64
gyro_X
                 1169999 non-null float64
                 1169999 non-null float64
gyro_Y
gyro_Z
                 1169999 non-null float64
mag_X
                 1169999 non-null float64
mag_Y
                 1169999 non-null float64
                 1169999 non-null float64
mag_Z
labels
                 1169999 non-null int64
                 1169999 non-null object
Activity_Name
velx
                 1169999 non-null float64
                 1169999 non-null float64
vely
                 1169999 non-null float64
velz
distx
                 1169999 non-null float64
                 1169999 non-null float64
disty
distz
                 1169999 non-null float64
```

1169999 non-null float64

1169999 non-null float64

mag\_vel
mag\_dist

```
1169999 non-null float64
mag_acc
                 1169999 non-null float64
mag_lacc
mag_gyro
                 1169999 non-null float64
                 1169999 non-null float64
mag_magnet
dtypes: float64(24), int64(2), object(1)
memory usage: 241.0+ MB
0.6 Calculating Jerk
In [0]: accx = df['acc_X'].values.tolist()
        accy = df['acc_Y'].values.tolist()
        accz = df['acc_Z'].values.tolist()
In [0]: accx.append(0)
        accy.append(0)
        accz.append(0)
In [0]: sind = [0, 89999, 179999, 269999, 359999, 449999, 539999, 629999, 719999, 809999, 89999
In [0]: def calJerkX(sind) :
          t = 0.02
          comp = []
          for k in sind :
            if k == 0 :
              for i in range(k, k+89999):
                comp.append((accx[i+1] - accx[i])/t)
              comp[k+89999-1] = (-accx[k+89999-1])/0.02
              len(comp)
            else :
              for i in range(k, k+90000):
                {\tt comp.append((accx[i+1] - accx[i])/t)}
              comp[k+90000-1] = (-accx[k+90000-1])/0.02
          return comp
        def calJerkY(sind) :
          t = 0.02
          comp = []
          for k in sind :
```

```
if k == 0 :
              for i in range(k, k+89999):
                comp.append((accx[i+1] - accy[i])/t)
              comp[k+89999-1] = (-accy[k+89999-1])/0.02
              len(comp)
            else :
              for i in range(k, k+90000):
                comp.append((accx[i+1] - accy[i])/t)
              comp[k+90000-1] = (-accy[k+90000-1])/0.02
          return comp
        def calJerkZ(sind) :
          t = 0.02
          comp = []
          for k in sind :
            if k == 0:
              for i in range(k, k+89999):
                comp.append((accx[i+1] - accz[i])/t)
              comp[k+89999-1] = (-accz[k+89999-1])/0.02
              len(comp)
            else :
              for i in range(k, k+90000):
                comp.append((accx[i+1] - accz[i])/t)
              comp[k+90000-1] = (-accz[k+90000-1])/0.02
          return comp
In [0]: df['jerkx'] = calJerkX(sind)
        df['jerky'] = calJerkY(sind)
        df['jerkz'] = calJerkZ(sind)
In [0]: df.head()
```

```
Out[0]:
                                             jerkx
           index
                     acc_X
                             acc_Y ...
                                                        jerky
                                                                   jerkz
        0
               0 -5.924900 -10.978
                                    . . .
                                         -51.75500
                                                    200.90000 -398.39500
        1
               1 -6.960000 -12.136
                                         149.82500 408.62500 -212.47650
        2
               2 -3.963500 -15.568
                                         195.45095 775.67595 166.16595
        3
               3 -0.054481 -15.677
                                          20.43055
                                                    801.55650 239.71650
               4 0.354130 -13.048
                                         -28.60300 641.50350 117.81350
        [5 rows x 30 columns]
In [0]: df[269999:359999].head()
Out [0]:
                 index
                         acc_X acc_Y acc_Z ... mag_magnet jerkx
                                                                           jerky
                                                                                    jerkz
                269999 2.4380 -1.5800 -9.5342
                                                      56.781370 -5.445
                                                                        195.455
                                                                                  593.165
        269999
        270000
                270000 2.3291 -1.4438 -9.6704
                                                      56.578377 2.040
                                                                        190.685
                                                                                  602.015
        270001
                270001 2.3699 -1.3893 -9.5206
                                                      56.610119 -0.680
                                                                        187.280
                                                                                  593.845
                270002 2.3563 -1.3757 -9.5615
                                                      56.538723 -5.445
        270002
                                                . . .
                                                                        181.155
                                                                                  590.445
        270003 270003 2.2474 -1.4165 -9.5206
                                                . . .
                                                      56.478137 -2.725 180.470
                                                                                 585.675
        [5 rows x 30 columns]
In [0]: df['mag_jerk'] = df.apply(lambda row : mag(row['jerkx'], row['jerky'], row['jerkz']), ;
In [0]: df.info()
<class 'pandas.core.frame.DataFrame'>
RangeIndex: 1169999 entries, 0 to 1169998
Data columns (total 31 columns):
                 1169999 non-null int64
index
acc_X
                 1169999 non-null float64
acc Y
                 1169999 non-null float64
                 1169999 non-null float64
acc_Z
linearacc_X
                 1169999 non-null float64
linearacc_Y
                 1169999 non-null float64
linearacc_Z
                 1169999 non-null float64
                 1169999 non-null float64
gyro_X
gyro_Y
                 1169999 non-null float64
gyro_Z
                 1169999 non-null float64
mag_X
                 1169999 non-null float64
                 1169999 non-null float64
mag_Y
mag_Z
                 1169999 non-null float64
                 1169999 non-null int64
labels
Activity_Name
                 1169999 non-null object
                 1169999 non-null float64
velx
                 1169999 non-null float64
vely
velz
                 1169999 non-null float64
                 1169999 non-null float64
distx
disty
                 1169999 non-null float64
                 1169999 non-null float64
distz
                 1169999 non-null float64
mag_vel
```

```
mag_dist
                 1169999 non-null float64
                 1169999 non-null float64
mag_acc
                 1169999 non-null float64
mag_lacc
mag_gyro
                 1169999 non-null float64
                 1169999 non-null float64
mag_magnet
jerkx
                 1169999 non-null float64
jerky
                 1169999 non-null float64
                 1169999 non-null float64
jerkz
                 1169999 non-null float64
mag_jerk
dtypes: float64(28), int64(2), object(1)
memory usage: 276.7+ MB
```

### 0.7 Calculating Gyro Jerk

```
In [0]: accx = df['gyro_X'].values.tolist()
        accy = df['gyro_Y'].values.tolist()
        accz = df['gyro_Z'].values.tolist()
In [0]: accx.append(0)
        accy.append(0)
        accz.append(0)
In [0]: def calGJerkX(sind) :
          t = 0.02
          comp = []
          for k in sind :
            if k == 0 :
              for i in range(k, k+89999):
                comp.append((accx[i+1] - accx[i])/t)
              comp[k+89999-1] = (-accx[k+89999-1])/0.02
              len(comp)
            else :
              for i in range(k, k+90000):
                comp.append((accx[i+1] - accx[i])/t)
              comp[k+90000-1] = (-accx[k+90000-1])/0.02
```

return comp

```
def calGJerkY(sind) :
  t = 0.02
  comp = []
  for k in sind :
    if k == 0 :
      for i in range(k, k+89999):
        comp.append((accx[i+1] - accy[i])/t)
      comp[k+89999-1] = (-accy[k+89999-1])/0.02
      len(comp)
    else :
      for i in range(k, k+90000):
        comp.append((accx[i+1] - accy[i])/t)
      comp[k+90000-1] = (-accy[k+90000-1])/0.02
  return comp
def calGJerkZ(sind) :
  t = 0.02
  comp = []
  for k in sind :
    if k == 0 :
      for i in range(k, k+89999):
        {\tt comp.append((accx[i+1] - accz[i])/t)}
      comp[k+89999-1] = (-accz[k+89999-1])/0.02
      len(comp)
    else :
      for i in range(k, k+90000):
        comp.append((accx[i+1] - accz[i])/t)
      comp[k+90000-1] = (-accz[k+90000-1])/0.02
  return comp
```

```
In [0]: df['gjerkx'] = calGJerkX(sind)
       df['gjerky'] = calGJerkY(sind)
       df['gjerkz'] = calGJerkZ(sind)
In [0]: df['mag_gjerk'] = df.apply(lambda row : mag(row['gjerkx'], row['gjerky'], row['gjerkz']
In [0]: df.head()
Out[0]:
          index
                    acc_X acc_Y
                                    acc_Z ... gjerkx
                                                          gjerky
                                                                    gjerkz
                                                                            mag_gjerk
       0
              0 -5.924900 -10.978 1.00790 ... 33.855 -115.4855 -119.7770
                                                                           169.792790
       1
              1 -6.960000 -12.136 0.28603
                                           ... 49.070 -81.6415 -68.4160
                                                                           117.277229
       2
              2 -3.963500 -15.568 -3.37780
                                           ... -38.225 -23.1500 -98.4860
                                                                           108.150660
              3 -0.054481 -15.677 -4.44020
                                           ... -0.155
                                                         16.9050 -92.4715
                                                                            94.004156
              4 0.354130 -13.048 -2.57420 ...
                                                36.500 -77.1685 -53.4515 100.718867
        [5 rows x 35 columns]
In [0]: new_df = df.drop(['index'], axis=1)
In [0]: new_df.head()
Out[0]:
             acc_X
                     acc_Y
                             acc_Z ...
                                           gjerky
                                                     gjerkz
                                                              mag_gjerk
       0 -5.924900 -10.978 1.00790
                                    ... -115.4855 -119.7770 169.792790
       1 -6.960000 -12.136 0.28603
                                    ... -81.6415 -68.4160 117.277229
                                     ... -23.1500
       2 -3.963500 -15.568 -3.37780
                                                   -98.4860 108.150660
       3 -0.054481 -15.677 -4.44020
                                    ... 16.9050
                                                   -92.4715
                                                              94.004156
                                    ... -77.1685 -53.4515 100.718867
       4 0.354130 -13.048 -2.57420
        [5 rows x 34 columns]
In [0]: new_df.to_csv('/content/gdrive/My Drive/case studies/UT Data_Complex/new_df.csv')
```