

Procesamiento de señales, fundamentos

Maestría en sistemas embebidos Universidad de Buenos Aires MSE 5Co2O2O

Clase 3 - Euler | Fourier

Ing. Pablo Slavkin slavkin.pablo@gmail.com wapp:011-62433453

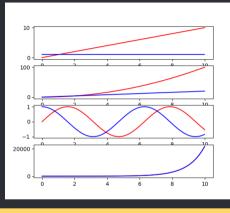




2.7182818284590450907955982984276488423347473144

- f(t) = t
- $f(t) = t^2$
- $f(t) = \sin(t)$

- f'(t) = 1
- f'(t) = 2 * t
- $f'(t) = \cos(t)$



La derivada es igual a la funcion

$$f(t) = e^t \implies f'(t) = e^t$$

 $f(t) = e^{kt} \implies f'(t) = ke^{kt}$

Euler

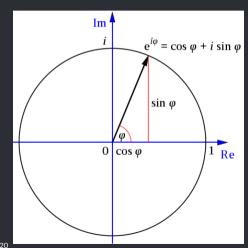
Pero que pasa con e^{jt}?

La derivada es igual a la funcion

$$f(t) = e^{jt} \implies f'(t) = je^{jt}$$

$$e^{jt} = \cos(t) + j\sin(t)$$

 $e^{j\pi} = -1$
 $e^{\frac{j\pi}{2}} = j$
 $e^{\frac{j3\pi}{2}} = -j$

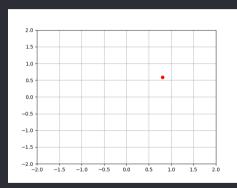




e^{j2πft} e^{j2πft} animado

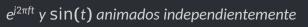


```
import numpy as np
import matplotlib.pvplot as plt
from matplotlib.animation import FuncAnimation
fig
          = plt.figure()
          = 10
          = 10
circleAxe = fig.add subplot(1.1.1)
circleLn, = plt.plot([],[],'ro')
circleAxe.grid(True)
circleAxe.set xlim(-2,2)
circleAxe.set vlim(-2,2)
circleFrec = 1
circle = lambda c.f.n: c*np.exp(-1i*2*np.pi*f*n*1/fs)
def update(n):
   circleLn.set data(np.real(circle(1,circleFrec,n)),
                     np.imag(circle(1,circleFrec,n)))
ani=FuncAnimation(fig,update,N,interval=1000 ,blit=False,repeat=True)
plt.show()
```



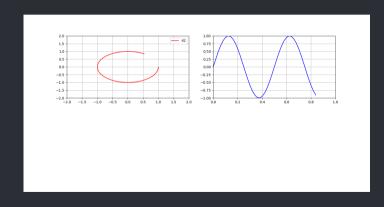


import numpy as np





```
from matplotlib.animation import FuncAnimation
circleAxe = fig.add subplot(2,2,1)
circleAxe.set vlim(-2.2)
legendLn = circleAxe.legend()
signalAxe = fig.add subplot(2.2.2)
signalAxe.set ylim(-1.1)
signal = lambda f.m: np.cos(2*np.pi*f*n*1/fs)
    alobal circleData signalData tData legendin
   circleData.append(circle(1.circleFrec.n))
   circleLn.set data(np.real(circleData).
    signalData append(signal(signalFrec.n))
    tData.append(n/fs)
    signalLn.set data(tData.signalData)
    legendLn=circleAxe.legend()
    return circlela signalla legendia
ani=FuncAnimation(fig undate N init interval=18 blit=True repeat=True)
nlt.show()
```

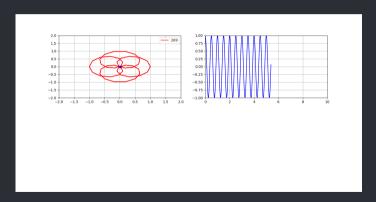






$e^{j2\pi ft}$ modulado por Sin(t) y centro de masas

```
import numpy as np
from matplotlib.animation import FuncAnimation
circlein,promin = plt.plot([],[],'r-',[],[],'bo')
circleAxe.grid(True)
circleAxe.set xlim(-2,2)
circleAxe.set ylim(-2.2)
circleFrec = 3
signalAxe = fig.add subplot(2.2.2)
signalAxe.grid(True)
signalAxe.set_ylim(-1,1)
signal = lambda f.n: np.cos(2*np.pi*f*n*1/fs)
   global circleData.signalData.tData.promData
   circleData_annend(circle(1.circleFrec.n)*signal(signalFrec.n))
   prom-np.average(circleData)
   promin.set data(np.real(prom).
    circleLn.set data(np.real(circleData).
    signalData.append(signal(signalFrec.n))
    signalLn.set data(tData,signalData)
   circleLo=circleAxe,legend()
    return circleLn.circleLo.signalLn.promLn
         Pablo Slavkin N, init, interval=18 ,blit=True, repeat=True)
```



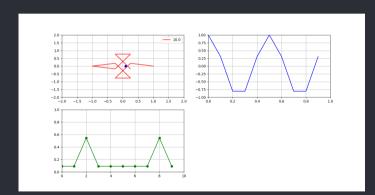
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$e^{j2\pi ft}$ modulado por sin(t) y centro de masas en f

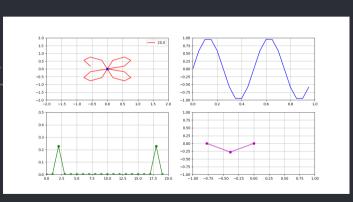
```
tBsta_append(n/fs)
rionalin set data(tBsta, signalData)
    thats + []
fourierData.appending.real(pros)
    fourseroute append
fbata append(circleFrec)
fourserie.set_data(fbata,fourserbata)
```





$e^{j2\pi ft}$ del centro de masas de vuelta a sin(t)



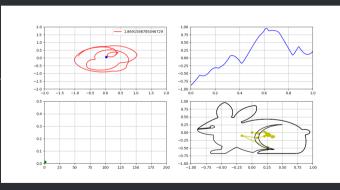




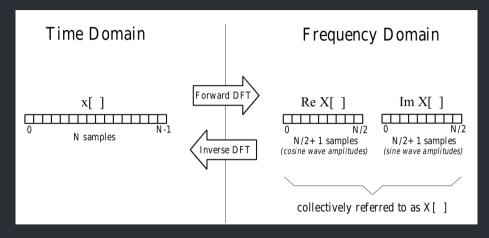
Señales complejas, conejo



```
prom-mp.sverage(circlebata)
op.imag(prum))
circlein_cot data(op.real(circlebata)
      fourierData_append(pros)
thats_append(circleFrec)
```







Bibliografia

Libros, links y otro material

- [1] ARM CMSIS DSP.
- [2] Steven W. Smith. The Scientist and Engineer's Guide to Digital Signal Processing. Second Edition, 1999.
- [3] Interactive Mathematics Site Info.
- [4] Grant Sanderson link
- [5] Interactive Mathematics Site Info. link