

Procesamiento de señales, fundamentos

Maestría en sistemas embebidos
Universidad de Buenos Aires
MSE 5Co2020

Clase 4 - Euler | Fourier - IDFT

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Síntesis

Como reconstruyo la señal en el tiempo



```
import numpy as np
import matplotlib.pyplot as plt
from matplotlib.animation import FuncAnimation

#-----
fig = plt.figure()
fs = 100
N = 100
#-----
circleAxe = fig.add_subplot(2,2,1)
circleLn,massLn, = plt.plot([],[],'r-',[],[],'bo')
circleAxe.grid(True)
circleAxe.set_xlim(-1,1)
circleAxe.set_ylim(-1,1)
circleFreq = np.arange(-fs/2,fs/2,fs/N)
circleLn.set_label(circleFreq[0])
circleLg=circleAxe.legend()
circleData = []
mass = 0
freqIter = 0
def circle(f,n):
    return np.exp(-1j*2*np.pi*f*n*1/fs)
def circleInv(f,n,c):
    return c*np.exp(-1j*2*np.pi*f*n*1/fs)
#-----
signalAxe = fig.add_subplot(2,2,2)
signalLn, = plt.plot([],[],'b-')
signalAxe.grid(True)
signalAxe.set_xlim(0,N/fs)
signalAxe.set_ylim(-1,1)
signalFreq = 2
signalData=[]
def signal(f,n):
    return np.sin(2*np.pi*f*n*1/fs)
```

```
    return np.sin(2*np.pi*f*n*1/fs)
#-----
promAxe = fig.add_subplot(2,2,3)
promRLn,promILn, = plt.plot([],[],'g-o',[],[],'y-o')
promAxe.grid(True)
promAxe.set_xlim(-fs/2,fs/2)
promAxe.set_ylim(-1,1)
promData=np.zeros(N,dtype=complex)
#-----
inversaAxe = fig.add_subplot(2,2,4)
inversaLn, = plt.plot([],[],'m-o')
inversaAxe.grid(True)
inversaAxe.set_xlim(-1,1)
inversaAxe.set_ylim(-1,1)
inversaData = []
#-----
tData=np.arange(0,N/fs,1/fs)
def init():
    return circleLn,circleLg,signalLn,massLn,promRLn,promILn,inversaLn
def updateF(n):
    global promData,fData,inversaData,freqIter
    if aniT.repeat==True:
        return inversaLn,
        inversaData=[0]
        for f in range(N):
            inversaData.append(inversaData[-1]+circleInv(circleFreq[f],freqIter,promData[f]))
        inversaLn.set_data(np.imag(inversaData),np.real(inversaData))
        freqIter+=1
    if freqIter==N:
        freqIter=0
    return inversaLn,
```

Síntesis

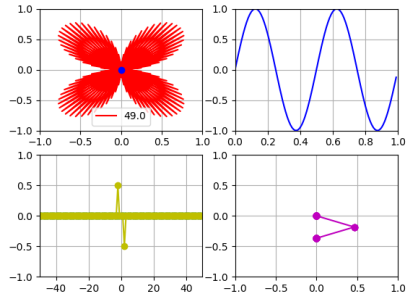
Como reconstruyo la señal en el tiempo



```
def updateT(nn):
    global circleData, signalData, promData, frecIter, circleFrec, circleLg
    circleData = []
    signalData = []
    for n in range(N):
        circleData.append(circle(circleFrec[frecIter], n)*signal(signalFrec, n))
        mass=np.average(circleData)
        signalData.append(signal(signalFrec, n))
        promData[frecIter]=mass
    massLn.set_data(np.real(mass),
                    np.imag(mass))
    circleLn.set_data(np.real(circleData),
                     np.imag(circleData))
    signalLn.set_data(tData[:n+1], signalData)
    promRLn.set_data(circleFrec[:frecIter+1], np.real(promData[:frecIter+1]))
    promILn.set_data(circleFrec[:frecIter+1], np.imag(promData[:frecIter+1]))
    circleLn.set_label(circleFrec[frecIter])
    circleLg=circleAxe.legend()

    if frecIter == N-1:
        aniT.repeat=False
    else:
        frecIter+=1
    return circleLn, circleLg, signalLn, massLn, promRLn, promILn,

aniT=FuncAnimation(fig, updateT, N, init, interval=10 ,blit=True, repeat=True)
aniF=FuncAnimation(fig, updateF, N, init, interval=30 ,blit=True, repeat=True)
plt.show()
```



Síntesis, Transformada inversa discreta de Fourier

IDFT

$$x_n = \frac{1}{N} \sum_{k=0}^{N-1} X_k e^{\frac{2\pi i}{N} kn} \quad n = 0, \dots, N-1.$$



Señales complejas como entrada?

```
import numpy as np
import matplotlib.pyplot as plt
from matplotlib.animation import FuncAnimation

#-----
fig = plt.figure()
fs = 100
N = 100
#-----
circleAxe = fig.add_subplot(2,2,1)
circleLn,massLn, = plt.plot([],[],'r-',[],[],'bo')
circleAxe.grid(True)
circleAxe.set_xlim(-1,1)
circleAxe.set_ylim(-1,1)
circleFrec = np.arange(-fs/2,fs/2,fs/N)
circleLn.set_label(circleFrec[0])
circleLg=circleAxe.legend()
circleData = []
mass = 0
frecIter = 0
def circle(f,n):
    return np.exp(-1j*2*np.pi*f*n*1/fs)
def circleInv(f,n,c):
    return c*np.exp(-1j*2*np.pi*f*n*1/fs)
#-----
signalAxe = fig.add_subplot(2,2,2)
signalRLn,signalILn = plt.plot([],[],'b-',[],[],'r-')
signalAxe.grid(True)
signalAxe.set_xlim(0,N/fs)
signalAxe.set_ylim(-1,1)
signalFrec = 2
signalData=[]
def signal(f,n):
    return np.sin(2*np.pi*f*n*1/fs)+0.4j*np.sin(2*np.pi*f*n*1/fs)
```

```
        return np.sin(2*np.pi*f*n*1/fs)+0.4j*np.sin(2*np.pi*f*n*1/fs)
#-----
promAxe = fig.add_subplot(2,2,3)
promRLn,promILn, = plt.plot([],[],'g-o',[],[],'y-o')
promAxe.grid(True)
promAxe.set_xlim(-fs/2,fs/2)
promAxe.set_ylim(-1,1)
promData=np.zeros(N,dtype=complex)
#-----
inversaAxe = fig.add_subplot(2,2,4)
inversaLn,penLn,penRLn,penILn = plt.plot([],[],'m-o',[],[],'k-',[],[],'b-',[],[],'r-')
inversaAxe.grid(True)
inversaAxe.set_xlim(-1,1)
inversaAxe.set_ylim(-1,1)
inversaData,penData= [],[]
#-----
tData=np.arange(0,N/fs,1/fs)
def init():
    return circleLn,circleLg,signalRLn,signalILn,massLn,promRLn,promILn,inversaLn,penLn,penRLn,
def updateF(n):
    global promData,fData,vectorData,frecIter,penData
    if aniT.repeat==True:
        return inversaLn,
        vectorData=[0]
    for f in range(N):
        vectorData.append(vectorData[-1]+circleInv(circleFrec[f],frecIter,promData[f]))
    inversaLn.set_data(np.imag(vectorData),np.real(vectorData))
    penData.insert(0,vectorData[-1])
    traceData=penData[0:N//2]
    t=np.linspace(0,1,len(traceData))
    penRLn.set_data(t,np.real(traceData))
    penILn.set_data(np.imag(traceData),t)
```

Señales complejas como entrada?



```

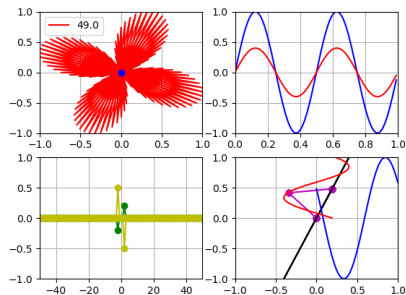
penILn.set_data(np.imag(traceData),t)
penLn.set_data(np.imag(penData),np.real(penData))
frecIter+=1
if frecIter==N:
    frecIter=0
return inversaLn,penLn,penILn,penRLn,

def updateT(nn):
    global circleData,signalData,promData,frecIter,circleFrec,circleLg
    circleData = []
    signalData = []
    for n in range(N):
        circleData.append(circle(circleFrec[frecIter],n)*signal(signalFrec,n))
        mass=np.average(circleData)
        signalData.append(signal(signalFrec,n))
        promData[frecIter]=mass
    massLn.set_data(np.real(mass),
                    np.imag(mass))
    circleLn.set_data(np.real(circleData),
                     np.imag(circleData))
    signalRLn.set_data(tData[:n+1],np.real(signalData))
    signalILn.set_data(tData[:n+1],np.imag(signalData))
    promRLn.set_data(circleFrec[:frecIter+1],np.real(promData[:frecIter+1]))
    promILn.set_data(circleFrec[:frecIter+1],np.imag(promData[:frecIter+1]))
    circleLn.set_label(circleFrec[frecIter])
    circleLg=circleAxe.legend()

    if frecIter == N-1:
        aniT.repeat=False
    else:
        frecIter+=1
    return circleLn,circleLg,signalRLn,signalILn,massLn,promRLn,promILn,

aniT=FuncAnimation(fig,updateT,N,init,interval=10 ,blit=True,repeat=True)
aniF=FuncAnimation(fig,updateF,N,init,interval=30 ,blit=True,repeat=True)
plt.show()

```





```
import numpy as np
import matplotlib.pyplot as plt
from matplotlib.animation import FuncAnimation

#-----
fig = plt.figure()
fs = 100
N = 100
#-----
conejo=np.load("conejo.npy")[:,1]
N=len(conejo)
def signal(f,n):
    return conejo[n]
#-----
circleAxe = fig.add_subplot(2,2,1)
circleLn,massLn = plt.plot([],[],'r-',[],[],'bo')
circleAxe.grid(True)
circleAxe.set_xlim(-1,1)
circleAxe.set_ylim(-1,1)
circleFrec = np.arange(-fs/2,fs/2,fs/N)
circleLn.set_label(circleFrec[0])
circleLg=circleAxe.legend()
circleData = []
mass = 0
frecIter = 0
def circle(f,n):
    return np.exp(-1j*2*np.pi*f*n*1/fs)
def circleInv(f,n,c):
    return c*np.exp(-1j*2*np.pi*f*n*1/fs)
#-----
signalAxe = fig.add_subplot(2,2,2)
signalRLn,signalILn = plt.plot([],[],'b-',[],[],'r-')
signalAxe.grid(True)
signalAxe.set_xlim(0,N/fs)
```

```
signalAxe.set_xlim(0,N/fs)
signalAxe.set_ylim(-1,1)
signalFrec = 2
signalData=[]
#def signal(f,n):
#    return np.sin(2*np.pi*f*n*1/fs)+0.4j*np.sin(2*np.pi*f*n*1/fs)
#-----
promAxe = fig.add_subplot(2,2,3)
promRLn,promILn = plt.plot([],[],'g-o',[],[],'y-o')
promAxe.grid(True)
promAxe.set_xlim(-fs/2,fs/2)
promAxe.set_ylim(-1,1)
promData=np.zeros(N,dtype=complex)
#-----
inversaAxe = fig.add_subplot(2,2,4)
inversaLn,penLn,penRLn,penILn = plt.plot([],[],'m-o',[],[],'k-',[],[],'b-',[],[],'r-')
inversaAxe.grid(True)
inversaAxe.set_xlim(-1,1)
inversaAxe.set_ylim(-1,1)
inversaData,penData= [],[]
#-----
tData=np.arange(0,N/fs,1/fs)
def init():
    return circleLn,circleLg,signalRLn,signalILn,massLn,promRLn,promILn,inversaLn,penILn,penRLn,
def updateF(n):
    global promData,fData,vectorData,frecIter,penData
    if aniT.repeat==True:
        return inversaLn,
        vectorData=[0]
    for f in range(N):
        vectorData.append(vectorData[-1]+circleInv[circleFrec[f],frecIter,promData[f]])
        inversaLn.set_data(np.imag(vectorData),np.real(vectorData))
```

IDFT

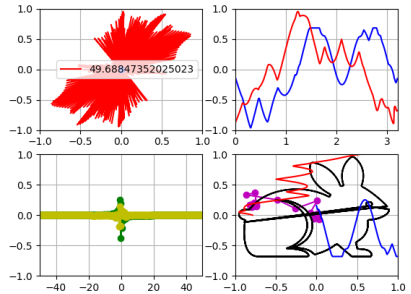
Un conejo como entrada?



```
inversaLn.set_data(np.imag(vectorData), np.real(vectorData))
penData.insert(0, vectorData[-1])
traceData=penData[0:N//2]
t=np.linspace(0,1,len(traceData))
penRLn.set_data(t, np.real(traceData))
penILn.set_data(np.imag(traceData), t)
penLn.set_data(np.imag(penData), np.real(penData))
frecIter+=1
if frecIter==N:
    frecIter=0
return inversaLn, penLn, penILn, penRLn,

def updateT(nn):
    global circleData, signalData, promData, frecIter, circleFrec, circleLg
    circleData = []
    signalData = []
    for n in range(N):
        circleData.append(circle(circleFrec[frecIter], n)*signal(signalFrec, n))
        mass=np.average(circleData)
        signalData.append(signal(signalFrec, n))
        promData[frecIter]=mass
        massLn.set_data(np.real(mass),
                        np.imag(mass))
        circleLn.set_data(np.real(circleData),
                          np.imag(circleData))
        signalRLn.set_data(tData[:n+1], np.real(signalData))
        signalILn.set_data(tData[:n+1], np.imag(signalData))
        promRLn.set_data(circleFrec[:frecIter+1], np.real(promData[:frecIter+1]))
        promILn.set_data(circleFrec[:frecIter+1], np.imag(promData[:frecIter+1]))
        circleLn.set_label(circleFrec[frecIter])
        circleLg=circleAxe.legend()

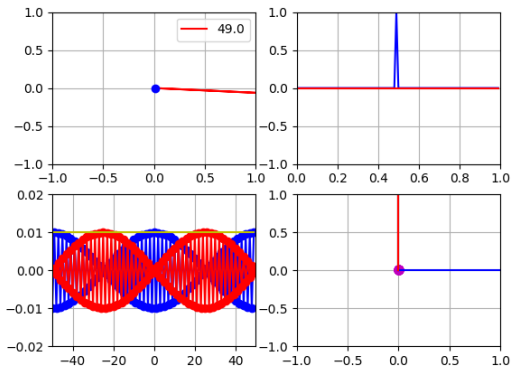
    if frecIter == N-1:
        aniT.repeat=False
    else:
        frecIter+=1
    return circleLn, circleLg, signalRLn, signalILn, massLn, promRLn, promILn,
aniT=FuncAnimation(fig, updateT, N, init, interval=10 ,blit=True, repeat=True)
aniF=FuncAnimation(fig, updateF, N, init, interval=30 ,blit=True, repeat=True)
plt.show()
```



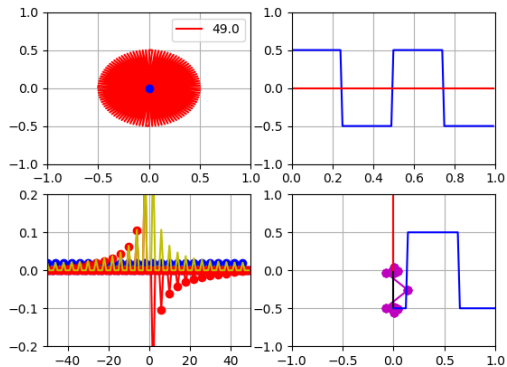
DFT<>IDFT

Transformadas relevantes

Delta



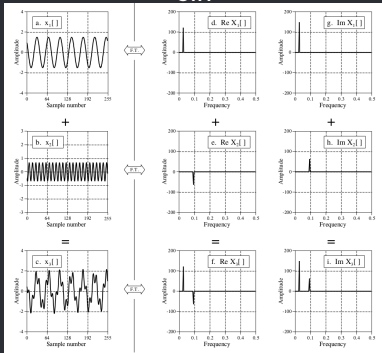
Cuadrada



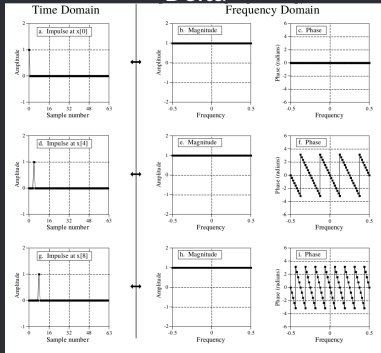
DFT<>IDFT

Transformadas relevantes

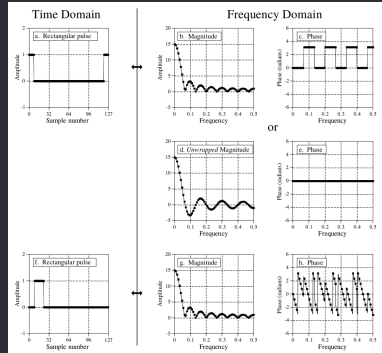
Sin



Delta



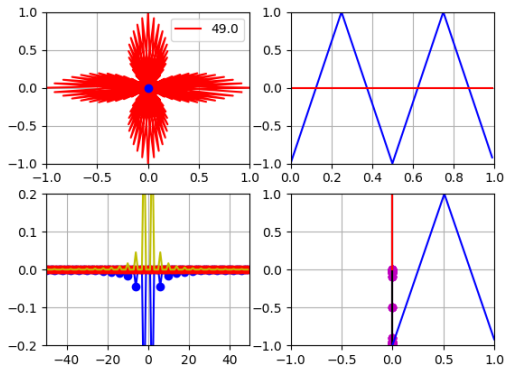
Cuadrada



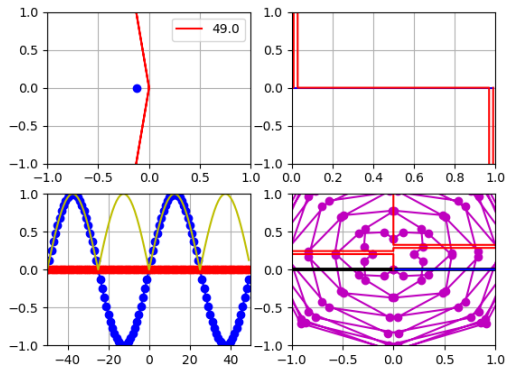
DFT<>IDFT

Transformadas relevantes

Triangular

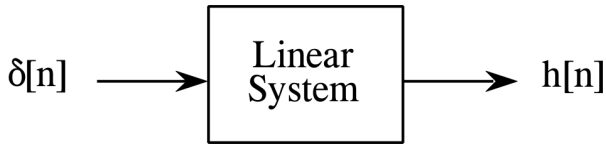
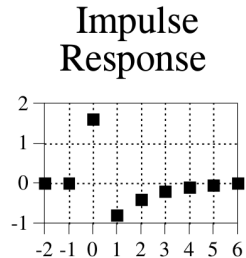
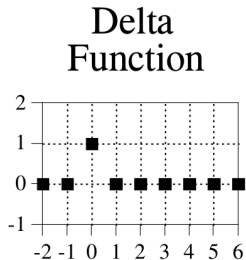


Conjugado



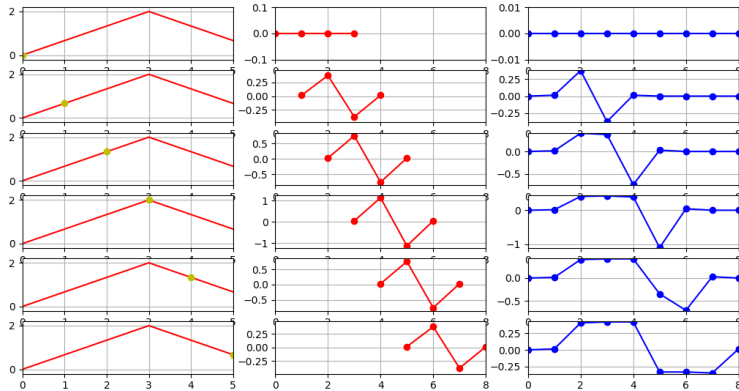
Funcion delta

Respuesta al impulso



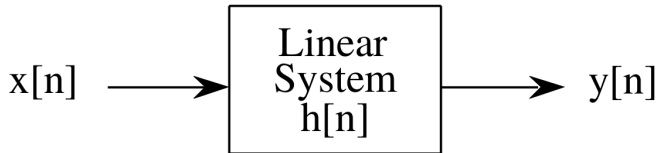
Convolucion

Descomposicion Delta



Funcion delta

Respuesta al impulso



$$x[n] * h[n] = y[n]$$

$$y[n] = x[n] * h[n] = \sum_{k=-\infty}^{\infty} x[k] \cdot h[n - k]$$

Convolucion

Respuesta al impulso

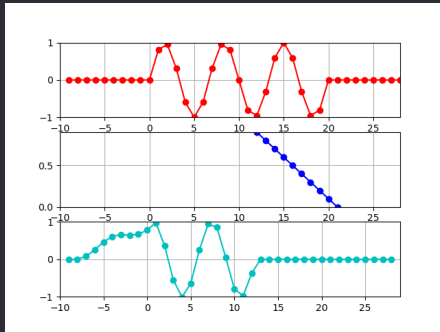
```
import numpy as np
import matplotlib.pyplot as plt
import matplotlib
from matplotlib.animation import FuncAnimation

#-----
fig = plt.figure()
fs = 20
N = 20
M=10
#-----
xFrec = 3
def x(f,n):
    return np.sin(2*np.pi*f*n*1/fs)
tData=np.arange(-(M-1),N+(M-1),1)
xData=np.zeros(N+2*(M-1))
xData[M-1:M-1+N]=x(xFrec,tData[M-1:M-1+N])
xAxis = fig.add_subplot(3,1,1)
xLn,xHighLn = plt.plot(tData,xData,'r-o',[],[],'y-
o')
xAxis.grid(True)
xAxis.set_xlim(-M,M+N-2)
xAxis.set_ylim(np.min(xData),np.max(xData))
#-----
hData=[0.1*n for n in range(M)]
hAxis = fig.add_subplot(3,1,2)
hLn, = plt.plot([],[],'b-o')
```

```
hAxis.grid(True)
hAxis.set_xlim(-M,M+N-2)
hAxis.set_ylim(np.min(hData),np.max(hData))
#-----
yAxis = fig.add_subplot(3,1,3)
yLn, = plt.plot([],[],'c-o')
yAxis.grid(True)
yAxis.set_xlim(-M,M+N-1)
yAxis.set_ylim(np.min(xData),np.max(xData))
yData=[]
#-----
def init():
    global yData
    yData=np.zeros(N+2*(M-1))
    return hLn,xLn,xHighLn,yLn,

def update(i):
    global yData
    t=np.linspace(-(M-1)+i,i,M,endpoint=True)
    yData[i]=np.sum(xData[i:i+M]*hData[::-1])
    xHighLn.set_data(t,xData[i:i+M])
    hLn.set_data(t,hData[::-1])
    yLn.set_data(tData,yData)
    return hLn,xLn,xHighLn,yLn,

ani=FuncAnimation(fig,update,M+N-1,init,interval
=1000 ,blit=True,repeat=True)
plt.show()
```



Filtrado

Pasa bajos

```
import numpy as np
import matplotlib.pyplot as plt
import matplotlib
from matplotlib.animation import FuncAnimation

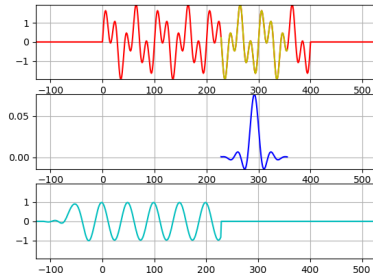
#-----
fig = plt.figure()
fs = 100
N = 400
fir=np.load("low_pass.npy").astype(float)
M=len(fir)
#fir=np.load("diferenciador.npy").astype(float)
#M=len(fir)
#-----
def x(f,n):
    return np.sin(2*np.pi*2*n*1/fs)+\
           np.sin(2*np.pi*5*n*1/fs)

xFreq = 3
tData=np.arange(-(M-1),N+(M-1),1)
xData=np.zeros(N+2*(M-1))
xData[M:M+N]=x(xFreq,tData[M:M+N])
hAxe = fig.add_subplot(3,1,1)
xLn,xHighLn = plt.plot(tData,xData,'r-',[],[],'y-'
)
hAxe.grid(True)
hAxe.set_xlim(-M,M+N-2)
hAxe.set_ylim(np.min(hData),np.max(hData))
#-----
hData=fir
```

```
hAxe = fig.add_subplot(3,1,2)
hLn, = plt.plot([],[],'b-')
hAxe.grid(True)
hAxe.set_xlim(-M,M+N-2)
hAxe.set_ylim(np.min(hData),np.max(hData))
#-----
yAxe = fig.add_subplot(3,1,3)
yLn, = plt.plot([],[],'c-')
yAxe.grid(True)
yAxe.set_xlim(-M,M+N-1)
yAxe.set_ylim(np.min(xData),np.max(xData))
yData=[]
#-----
def init():
    global yData
    yData=np.zeros(N+2*(M-1))
    return hLn,xLn,xHighLn,yLn,

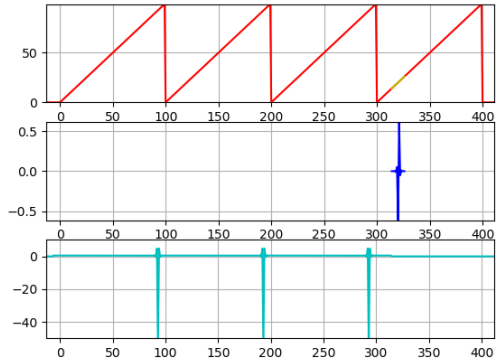
def update(i):
    global yData
    t=np.linspace(-(M-1)+i,i,M,endpoint=True)
    yData[i]=np.sum(xData[i:i+M]*hData[::-1])
    xHighLn.set_data(t,xData[i:i+M])
    hLn.set_data(t,hData[::-1])
    yLn.set_data(tData,yData)
    return hLn,xLn,xHighLn,yLn,

ani=FuncAnimation(fig,update,M+N-1,init,interval=10
,blit=True,repeat=True)
plt.get_current_fig_manager().window.showMaximized
()
plt.show()
```



Filtrado

diferenciador



Bibliografía

Libros, links y otro material

[1] ARM CMSIS DSP.

[link](#)

[2] Steven W. Smith. *The Scientist and Engineer's Guide to Digital Signal Processing*. Second Edition, 1999.

[3] *Interactive Mathematics Site Info*.

[4] Grant Sanderson

[link](#)

[5] *Interactive Mathematics Site Info*.

[link](#)