



**FACULTAD
DE INGENIERIA**

Universidad de Buenos Aires

Procesamiento de señales, fundamentos

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Maestría en sistemas embebidos MSE2020

Universidad de Buenos Aires

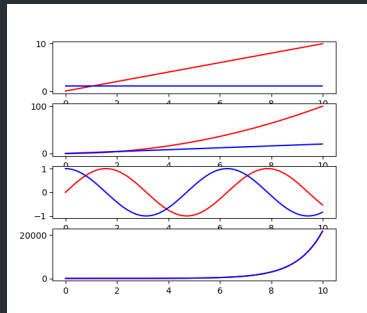
Clase 2 - Euler | Fourier

Ing. Pablo Slavkin



2.7182818284590450907955982984276488423347473144

- $f(t) = t$
- $f(t) = t^2$
- $f(t) = \sin(t)$
- $f'(t) = 1$
- $f'(t) = 2 * t$
- $f'(t) = \cos(t)$



La derivada es igual a la funcion

$$f(t) = e^t \implies f'(t) = e^t$$
$$f(t) = e^{kt} \implies f'(t) = k e^{kt}$$

$$e^{j2\pi t}$$

Euler

Pero que pasa con e^{jt} ?

La derivada es igual a la funcion

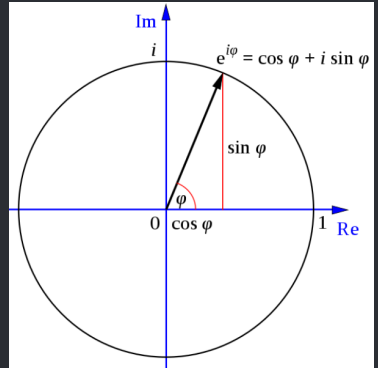
$$f(t) = e^{jt} \implies f'(t) = je^{jt}$$

$$e^{jt} = \cos(t) + j \sin(t)$$

$$e^{j\pi} = -1$$

$$e^{j\frac{\pi}{2}} = i$$

$$e^{j\frac{3\pi}{2}} = -i$$



$e^{j2\pi t}$ $e^{j2\pi t}$ animado

```
import numpy as np
import matplotlib.pyplot as plt
from matplotlib.animation import FuncAnimation

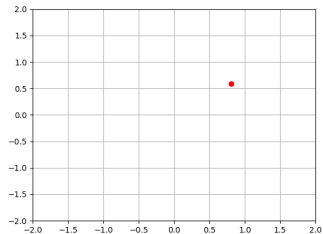
fig = plt.figure()
fs = 10
N = 10

circleAxe = fig.add_subplot(1,1,1)
circleLn, = plt.plot([],[],'ro')
circleAxe.grid(True)
circleAxe.set_xlim(-2,2)
circleAxe.set_ylim(-2,2)
circleFrec = 1

circle = lambda c,f,n: c*np.exp(-1j*2*np.pi*f*n*1/fs)

def update(n):
    circleLn.set_data(np.real(circle(1,circleFrec,n)),
                     np.imag(circle(1,circleFrec,n)))
    return circleLn,

ani=FuncAnimation(fig,update,N,interval=100 ,blit=False,repeat=True)
plt.show()
```



$e^{j2\pi t}$ $e^{j2\pi t} \gamma \sin(t)$ animados independientemente

```

import numpy as np
import matplotlib.pyplot as plt
from matplotlib.animation import FuncAnimation

#-----
fig = plt.figure()
fs = 50
N = 50
#-----
circleAxe = fig.add_subplot(2,2,1)
circleLn, = plt.plot([],[],'r-')
circleAxe.grid(True)
circleAxe.set_xlim(-2,2)
circleAxe.set_ylim(-2,2)
circleFreq = 1
circleData=[]
circle = lambda c,f,n: c*np.exp(-1j*2*np.pi*f*n*1/fs)
#-----
signalAxe = fig.add_subplot(2,2,2)
signalLn, = plt.plot([],[],'b-')
signalAxe.grid(True)
signalAxe.set_xlim(0,N/fs)
signalAxe.set_ylim(-1,1)
signalFreq = 2
signalData=[]
signal = lambda f,n: np.cos(2*np.pi*f*n*1/fs)
#-----
tData=[]

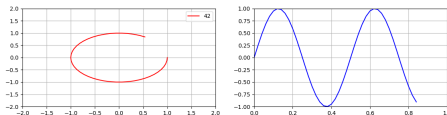
def init():
    return circleLn,

def update(n):
    global circleData,signalData,tData
    circleData.append(circle(1,circleFreq,n))
    circleLn.set_data(np.real(circleData),
                     np.imag(circleData))
    signalData.append(signal(signalFreq,n))
    tData.append(n/fs)
    signalLn.set_data(tData,signalData)

    if n==N-1:
        circleData=[]
        signalData=[]
        tData=[]
        circleLn.set_label(n)
        circleAxe.legend()
        return circleLn,circleAxe,signalLn

ani=FuncAnimation(fig,update,N,init,interval=10 ,blit=True,repeat=
    )
plt.show()

```



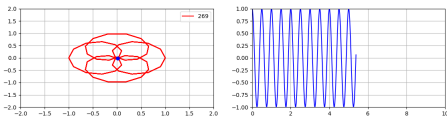
$e^{j2\pi t}$ $e^{j2\pi t}$ modulado por $\sin(t)$ y centro de masas

```

import numpy as np
import matplotlib.pyplot as plt
from matplotlib.animation import FuncAnimation

#-----
fig = plt.figure()
fs = 50
N = 500
#-----
circleAxe = fig.add_subplot(2,2,1)
circleIn.promLn = plt.plot([],[],'r-',[],[],'bo')
circleAxe.grid(True)
circleAxe.set_xlim(-2,2)
circleAxe.set_ylim(-2,2)
circleFreq = 3
circleData = []
prom = 0
circle = lambda c,f,n: c*np.exp(-1j*2*np.pi*f*n*1/fs)
#-----
signalAxe = fig.add_subplot(2,2,2)
signalLn = plt.plot([],[],'b-',)
signalAxe.grid(True)
signalAxe.set_xlim(0,N/fs)
signalAxe.set_ylim(-1,1)
signalFreq = 2
signalData = []
signal = lambda f,n: np.cos(2*np.pi*f*n*1/fs)
#-----
tData = []
def init():
    return circleIn,
def update(n):
    global circleData,signalData,tData,promData
    circleData.append(circle(1,circleFreq,n)*signal(signalFreq,n))
    prom=np.average(circleData)
    promLn.set_data(np.real(prom),
                    np.imag(prom))
    circleLn.set_data(np.real(circleData),
                     np.imag(circleData))
    signalData.append(signal(signalFreq,n))
    tData.append(n/fs)
    signalLn.set_data(tData,signalData)
    if n==N-1:
        circleData = []
        signalData = []
        tData = []
        prom = 0
        circleLn.set_label(n)
        circleAxe.legend()
    return circleIn,circleAxe,signalLn,promLn
ani=FuncAnimation(fig,update,N,init,interval=10 ,blit=True,repeat=True)
plt.show()

```



$e^{j2\pi t}$ del centro de masas de vuelta a $\sin(t)$



```
import numpy as np
import matplotlib.pyplot as plt
from matplotlib.animation import FuncAnimation
```

```
circles2 = fig.add_subplot(2,2,1)
circles2.plot([1,2], [1,2], 'r-', [1,2], 'bo')
circles2.grid(True)
circles2.set_xlabel(-3,2)
circles2.set_ylabel(-3,2)
```

```
circlefreq =
circledata = []
prom      = 0
freqiter  = 0
circle    = lambda c,f,u: c*np.exp(-1j*2*np.pi*f*u+1j/fu)
circleinv = lambda c,f,u: c*np.exp(1j*2*np.pi*f*u+1j/fu)
```

```

signalAse = fsg.ase.subplot(2,2,3)
signalAis = plt.plot([],[],'b-')
figureAse.grid(True)
signalAse.set_xlim(0,N/4f)
signalAse.set_ylim(-1,1)
signalFrac = 2
signalData=[]
signal = lambda f, n: mp.nis(2*np.pi*f*n*(1/f)+n*0.5*np.
    cos(2*np.pi*f))

```

```
fourierKee = fig.add_subplot(2,2,1)
fourierin_ = plt.plot([],[],'g-o')
fourierKee.grid(True)
fourierKee.set_xlim(0,4)
fourierKee.set_ylim(0,5)
fourierData=[]
```

```

InvertAxline = fig.add_subplot(2,2,4)
InvertAxline, vectorA = plt.gcf().add_subplot(2,2,4), 'a-o', [], [], 'b-o'
InvertAxline.grid(True)
InvertAxline.set_xlim(-1,1)
InvertAxline.set_ylim(-1,1)
InvertBdata = []
vectorBdata = []
#-----
rbdata=[]

```

```

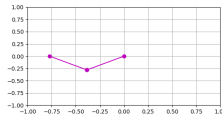
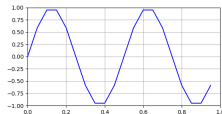
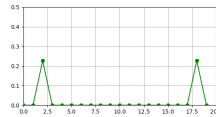
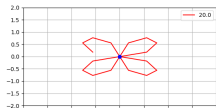
data={}

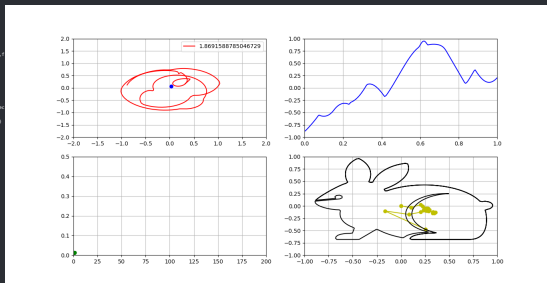
def init():
    return circula,
    def update(n):
        global fourdata,thre,vestdata
        if not fourdata:
            return
        vestdata={}
        for i in range(n):
            fourdata[i]=fourdata[i]+(4*4,n,i)
            vestdata.update({fourdata[i]:signal(signalfreq,n,i)})
        invertdata={}
        return invertdata,
    global circula,captdata,thre,probata,fractur,circfreq
    fourdata={}
    circula.append(circul(circulfreq,n))
    signal(signalfreq,n)
    probata.set timing,realprobata,
    np.imagprobata,
    circula.set timing,realcircdata,
    np.imag(circdata),
    signaldata.update(signal(signalfreq,n))
    thre.append(n/4)
    signals.set data,thre,signaldata

if n==0:
    circula = {}
    thredata = {}
    signals = {}
    fourdata = {}
    fourdata.append(probata)
    fourdata.append(circfreq)
    fourdata.set data(thre,probata,fourdata[""])
    probata=fracture=0
    fractur=0
    self.reset=False
    circifreq=fractur*f4
    circula.set limit(circifreq)
    circula.append(n)
    return circula,circula,signal,probata,fourdata

def funcupdate(n):
    if update,n_i,limit,interval==All-True,
    return funcupdate(n),update,n_i,limit-interval-100,All-True,
    reset=True

```





Bibliografia

Libros, links y otro material

- [1] Steven W. Smith. *The Scientist and Engineer's Guide to Digital Signal Processing*. Second Edition, 1999.
- [2] *Interactive Mathematics Site Info*.
- [3] Grant Sanderson <https://youtu.be/spUNpyF58BY>