Modeling changes to the functional composition of North American mammal diveristy

multi-level dynamics of a regional species pool

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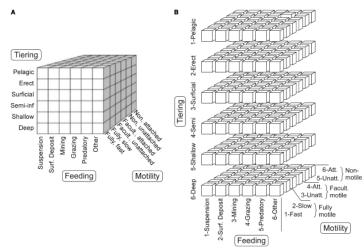


Question

When and why are certain ecologies or functional groups enriched or depleted in a species pool?

- relative abundance as function of
 - species traits
 - environmental context

Eco-cube and functional groups



TEXT-FIG. 1. Ecospace as defined by the three axes of tiering, motility level and feeding strategy. A, the ecospace cube with categories on each axis labelled. B, the ecospace cube 'exploded', showing 216 'bins' or modes of life specified by the combination of the categories on each ecospace axis.

(Bambach et al., 2007, Palaeontology)

Species pool concept

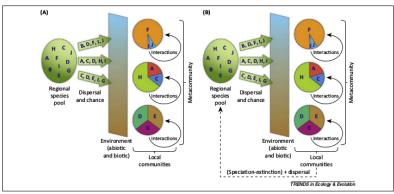


Figure 1. Two models of community assembly, (A) Local communities comprise a subset of species from the regional species pool that have passed through environmental filters. There is no feedback from the metacommunity (collection of local communities) to the regional species pool. Adapted from [5], (B) Local communities are assembled as in (A), but speciation adds new species to the pool, extinction removes others, and dispersal allows the persistence of species that might otherwise go extinct.

(Mittelbach and Schemske, 2015, TREE)

Structured, multi-level data in biology

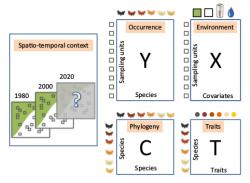
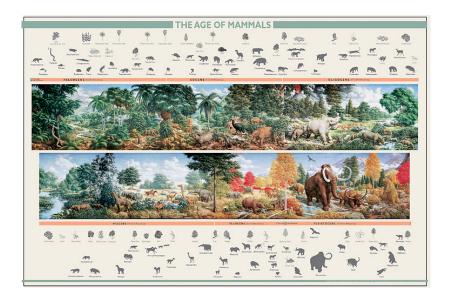


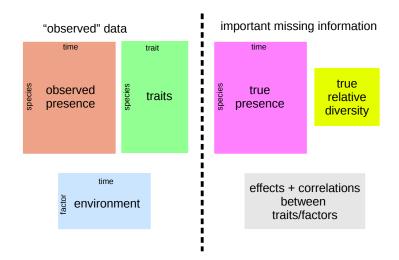
Figure 3 Data typically collected in community ecology. The occurrence data (denoted as the Y matrix) includes the occurrences of the species recorded in a set of temporal and/or spatial sampling units. The environmental data (denoted as the X matrix) consists of the environmental covariates measured over the sampling units. The traits data (denoted as the T matrix) consists of a set of traits measured for the species present in the Y matrix. To account for the phylogenetic dependencies among the species, we can include a fourth matrix consisting of the phylogenetic correlations among the species (denoted as the C matrix). The spatiotemporal context includes location and time information about the samples.

(Ovaskainen et al. 2017 Ecology Letters)

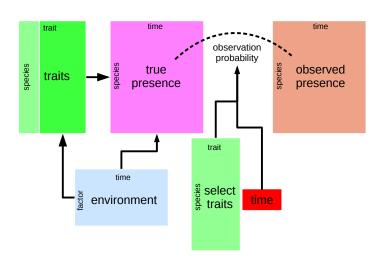
Cenozoic mammals of North America



Conceptualizing the question and data



Conceptualizing the analysis



Hidden Markov Model with absorbing state

Jolly-Seber CMR/Restricted occupancy model

$$egin{aligned} y_{i,t} &\sim \mathsf{Bernoulli}ig(z_{i,t}p_{i,t}ig) \ z_{i,t=1} &\sim \mathsf{Bernoulli}ig(\phi_{i,t=1}ig) \ z_{i,t} &\sim \mathsf{Bernoulli}\left(z_{i,t-1}\pi_{i,t} + \sum_{x=1}^t (1-z_{i,x})\phi_{i,t}
ight) \end{aligned}$$

y observed state; z estimated state.

p observation; ϕ origination; π survival.

i in N; t in T.

Modeling the probabilities; individual-level

Multi-level logistic regression

$$p_{i,t} \sim \operatorname{logit}^{-1}(b_t + e_{j[i]} + \beta^p \operatorname{mass}_i)$$
 $\phi_{i,t} \sim \operatorname{logit}^{-1}(f_{j[i],t}^{\phi} + o_{k[i]}^{\phi} + \beta^{\phi} \operatorname{mass}_i)$
 $\pi_{i,t} \sim \operatorname{logit}^{-1}(f_{j[i],t}^{\pi} + o_{k[i]}^{\pi} + \beta^{\pi} \operatorname{mass}_i)$

observation: b_t time-varying intercept; $e_{j[i]}$ functional group eff; β^p mass eff.

origination: $f^{\phi}_{j[i],t}$ time/FG-varying intercept; $o^{\phi}_{j[i]}$ order eff; β^{ϕ} mass eff.

survival: $f_{i[i],t}^{\pi}$ time/FG-varying intercept; $o_{i[i]}^{\pi}$ order eff; β^{π} mass eff.

Modeling the probabilities; group-level

Multivariate regression of time/FG-varying intercept

$$f^{\phi} \sim \mathsf{MVN} egin{pmatrix} U\gamma_{j=1}^{\phi} \ dots &, \mathsf{diag}(au_{f^{\phi}})\Omega_{f^{\phi}}\mathsf{diag}(au_{f^{\phi}}) \end{pmatrix} \ f^{\pi} \sim \mathsf{MVN} egin{pmatrix} U\gamma_{j=1}^{\pi} \ dots &, \mathsf{diag}(au_{f^{\pi}})\Omega_{f^{\pi}}\mathsf{diag}(au_{f^{\pi}}) \end{pmatrix} \ U\gamma_{i=J}^{\pi} \end{pmatrix}$$

U matrix group-level covariates; γ^ϕ , γ^π vectors group-level reg coefs.

 Ω_{ϕ} , Ω_{π} corr matrix of FG by time; τ_{ϕ} , τ^{π} scale of FG by time.

Final details (priors, implementation)

- Random-walk priors for time-varying intercepts to control for auto-correlation.
- ▶ Priors predict very weak/no effects of mass on observation, origination, survival (e.g. $\mathcal{N}(0, 0.5)$).
- ▶ Priors predict very weak/no effect of group-level covariates on observation, origination, survival (e.g. $\mathcal{N}(0,0.5)$).
- Priors favor no correlation between functional groups over time (e.g. LKJ(2)).
- Programmed as marginalization problem b/c gradient based estimation.

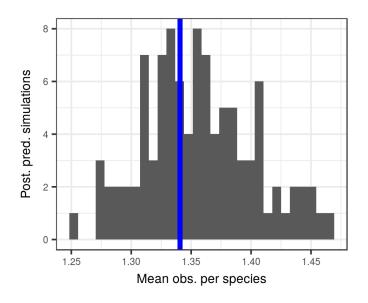
Parameter estimation and inference

Bayesian inference

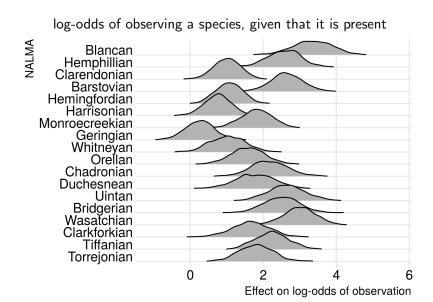
- intuitive and expressive
- regularization/partial pooling
- external information
- Automatic Differentiation Variational Inference (ADVI)
 - when full HMC/MCMC slow
 - approximate Bayesian inference assumes posterior is Gaussian
 - true Bayesian posterior



Model adequate? Posterior predictive check

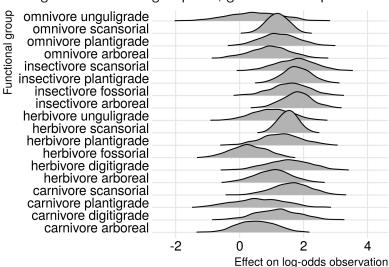


Observation; NALMA



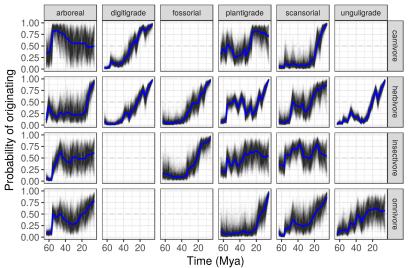
Observation; functional group

log-odds of observing a species, given that it is present



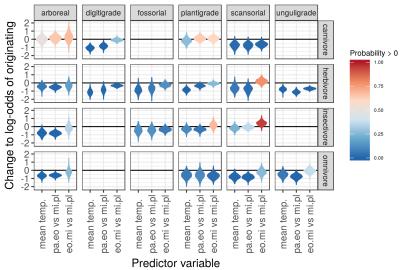
Origination; individual-level

probability of species originating, given it hasn't originated yet



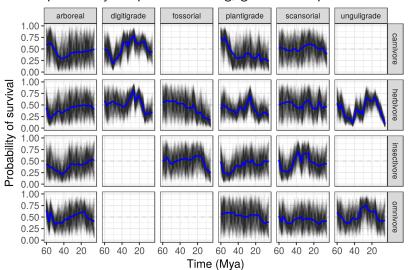
Origination; group-level

log-odds of species originating, given it hasn't originated yet



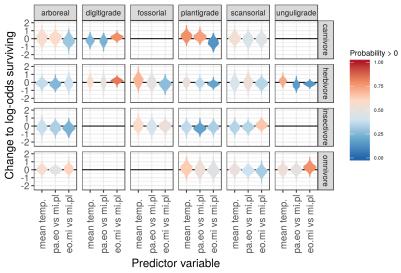
Survival; individual-level

probability of species surviving, given it was present

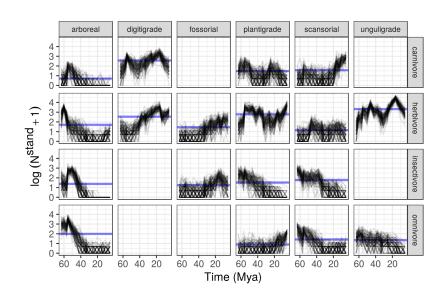


Survival; group-level

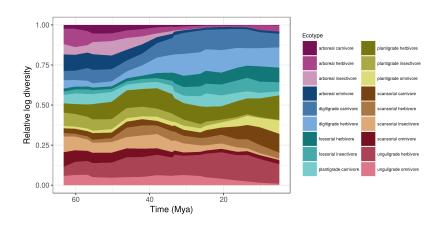




Standing diversity of functional groups through time



Relative diversity of functional groups through time



Changes to relative diversity between Neogene/Paleogene

- increase
 - digitigrade, plantigrade, unguligrade herbivores
 - fossorial functional groups
 - plantigrade omnivores
- decrease
 - near total loss of arboreal functional groups
 - plantigrade, scansorial insectivores
 - unguligrade omnivores

Conclusions

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