

Death and taxa: time invariant differences in species duration

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Abstract

1 Introduction

Extinction is one of most important components of diversification, second only to speciation. Why species go extinct at different rates remains one of the most fundamental questions in paleobiology (Jablonski, 2005, Kitchell et al., 1986, Payne and Finnegan, 2007, Quental and Marshall, 2013, Raup, 1991, 1994, Simpson, 1944, Van Valen, 1973, Wagner and Estabrook, 2014). Determining which and how biological traits influence extinction risk is vital for understanding the differential diversification of life during the Phanerozoic and making predictions about species' vulnerability to anthropogenic impacts. Yet investigations into the factors that affect extinction rate have proved inconclusive and often contradictory results. Additionally, Van Valen (1973) proposed the Law of Constant Extinction which states that the instantaneous rate of extinction for a taxon is independent of it's age, which is the basis for the Red Queen Hypothesis and is a cornerstone of quantitative paleobiology.

The fossil record of North American mammals is well resolved and represents an ideal data set for modeling long term evolutionary patterns (Alroy, 1996, 1998, 2009, Alroy et al., 2000, Blois and Hadly, 2009, Marcot, 2014, Quental and Marshall, 2013, Simpson, 1944, Tomiya, 2013). Here I take a Bayesian hierarchical survival model approach for understanding the effects of organismal and species traits, time of origination, and shared evolutionary history on species duration while also allowing for potentially time-dependent extinction. This is a direct extension of the more traditional dynamic and cohort survival analyses from paleontology (Baumiller, 1993, Foote, 1988, Raup, 1975, 1978, Sepkoski, 1975, Simpson, 1944, Van Valen, 1973, 1979).

Background extinction, or extinction occurring not at a mass extinction, is considered to involve many potential factors influencing the instantaneous extinction risk of any given species (Harnik et al., 2013, Jablonski, 1986, Kitchell et al., 1986, Nürnberg and Aberhan, 2013, Payne and Finnegan, 2007, Wang, 2003). Factors such as geographic range have well known effects on survival (Jablonski, 1987, Payne and Finnegan, 2007) because the effect size is large and thus easy to identify for a given sample size. The relationship between extinction risk and other traits, specifically organismal ones, is less well known because the effect size is most likely much smaller which makes inference difficult.

The approach taken here focuses on identifying time invariance effects of these traits on the expected duration of a species. Time invariant effect means that when comparing taxa over a long time period there is a consistent effect that is generalizable over the entire period of interest. While the strength of that effect may vary over time, overall there is a consistent expected effect of that trait of interest. In many ways, this was the point of Alroy et al. (2000): there was no consistent, time invariant response to climate change. While it is almost certain that selection pressures vary with time, consistent effects reveal fundamental differences in fitness or responses to selection.

The organismal and species traits studied here are biogeographic occupancy, body mass, and both dietary and locomotor categories. This is a mixture of well established factors that potentially influencing extinction risk (i.e. occupancy and body mass) and less well understood ones (i.e. dietary and locomotor categories). Dietary category is of particular interest as it has been shown to influence diversification rate (Price et al., 2012) though because of the limitations of many phylogenetic comparative methods it is unknown if this is due to differences in speciation, extinction, or both (Rabosky, 2010).

2 Methods

2.1 Species information

Fossil occurrence information was downloaded from the Paleobiology Database (PBDB; <http://paleodb.org/>). Occurrence, taxonomic, stratigraphic, and biological information was downloaded for all North American mammals. This data set was filtered so that only occurrences identified to the species level, excluding all “sp.”-s. All aquatic and volant taxa were also excluded. Additionally, all occurrences without latitude and longitude information were excluded.

Species dietary and locomotor category assignments were done using the assignments in initial the PBDB which were then reassigned into coarser categories (Table 1). This was done to improve interpretability, increase sample size per category, and make these results comparable to previous studies (Jernvall and Fortelius, 2004, Price et al., 2012).

Table 1: Species trait assignments in this study are a coarser version of the information available in the PBDB. Information was coarsened to improve per category sample size and uniformity and followed this table.

This study		PBDB categories
Diet	Carnivore	Carnivore
	Herbivore	Browser, folivore, granivore, grazer, herbivore.
	Insectivore	Insectivore.
	Omnivore	Frugivore, omnivore.
Locomotor	Arboreal	Arboreal.
	Ground dwelling	Fossorial, ground dwelling, semifossorial, saltatorial.
	Scansorial	Scansorial.

Fossil occurrences were assigned to 2 My bins ranging through the entire Cenozoic. Taxon duration was measured as the number of bins from the first bin of occurrence to the last bin of occurrence, inclusive.

Species body size estimates were sourced from a large selection of primary literature and compilations, principally the PBDB, PanTHERIA (Jones et al., 2009), the Neogene Old World Mammal database (Now; <http://www.helsinki.fi/science/now/>), and other large scale data collection efforts (Brook and Bowman, 2004, Freudenthal and Martín-suárez, 2013, McKenna, 2011, Raia et al., 2012, Smith et al., 2004). In many cases, species body mass was estimated from anatomical dimensions such as tooth size. These estimates were made using a variety of published regression equations. See Appendix: Data for a complete list of individual sources and equations.

2.1.1 Bioprovince occupancy

For each 2 My time bin, a bipartite biogeographic network was created between species occurrences and spatial units. Spatial units were defined as 2x2 latitude–longitude grid cells from an azimuthal equal-area map projection. In these bipartite networks, taxa can only be linked to localities and *vice versa*. Taxa are not linked to each other, nor are localities linked. Emergent bioprovinces within the biogeographic occurrence network were identified using the map equation (Rosvall and Bergstrom, 2008, Rosvall et al., 2009). A bioprovince is a set of species–locality connections that are more interconnected within the group than without. This was done for each bin’s biogeographic network using the **igraph** package for R (Csardi and Nepusz, 2006, R Core Team, 2014). The relative number of bioprovinces occupied per time bin was then determined for each species.

2.1.2 Semi-formal supertree

Because there exists no phylogenetic hypothesis of all Cenozoic fossils mammals from North America, it was necessary to construct a semi-formal supertree. This was done by combining taxonomic information for all the observed species and a few published phylogenies.

The taxonomic information from the PBDB served as the basis for additional revision. The taxonomy of many species was updated using the Encyclopedia of Life (<http://eol.org/>), which collects and collates taxonomic information in a single database. This was done programatically using the `taxize` package for R (Scott Chamberlain and Eduard Szocs, 2013). This was additionally correct using various published phylogenies and taxonomies of fossil mammals (Janis et al., 1998, 2008, Raia et al., 2012), producing a tree that was a series of nested polytomies.

Polytomies were resolved in order of species first appearance. The resulting tree was then time scaled using the `paleotree` package via the “minimum branch length” approach with a minimum length of 0.1 My (Bapst, 2012). The minimum length is necessary to avoid zero-length branches which cause the phylogenetic covariance matrix not be positive definite, which is an important convenience for computation (see below). While other time scaling approaches are possible (Bapst, 2013, Hedman, 2010) this method was chosen for it’s simplicity and not requiring additional information about diversification rates which are of interest in this study.

2.2 Survival model

The statistical model described here was the final model at the end of a continuous model development framework where the sampling and prior distributions were iteratively modified to best reflect theory, knowledge of the data, the inclusion of important covariates, and to fit the data. This follows the approach described in Gelman and Hill (2007) and Gelman et al. (2013). A survival model was fit in a Bayesian context where species duration were assumed to be drawn from a Weibull distribution (Eq. 1) with shape α and scale σ parameters.

$$\begin{aligned} p(y_i|\alpha, \sigma) &= \text{Weibull}(y_i|\alpha, \sigma) \\ &= \frac{\alpha}{\sigma} \left(\frac{y_i}{\sigma}\right)^{\alpha-1} \exp\left(-\left(\frac{y_i}{\sigma}\right)^\alpha\right) \end{aligned} \quad (1)$$

Following standard practice in survival analysis (Klein and Moeschberger, 2003), α was assumed constant and was given a weakly informative half-Cauchy prior. σ was reparameterized as an exponentiated regression model (Eq. 2). Note, the inclusion of α in the denominator of the exponentiated term is a standard parameterization for survival models using a Weibull distribution (Klein and Moeschberger, 2003).

$$\sigma = \exp \left(\frac{-(h_i + \eta_{j[i]} + \sum \beta^T \mathbf{X}_i)}{\alpha} \right) \quad (2)$$

K species level covariates were included as a $n \times K$ matrix, \mathbf{X} . The covariates of interest included the logit of mean relative occupancy and the logarithm of body size (g). The discrete covariate index variables dietary and locomotor category were transformed into $n \times (k - 1)$ matrices where each column is an indicator variable (0/1) for that species's category, k being the number of categories of the index variable. Only $k - 1$ indicator variables are necessary as the intercept takes on the remaining value. Finally, a vector of 1-s were included in the matrix \mathbf{X} whose corresponding β coefficient is the intercept, making K equal eight.

β is a vector of regression coefficients, where each element was given a unique, weakly informative Normally distributed prior. These priors were chosen because it is expected that the effect size of each variable on duration will be small, as is generally the case with binary covariates.

Regression coefficients are not directly comparable without first standardizing the input variables to have equal standard deviations. This linear transform greatly improves the interpretability of the coefficients as expected change in mean duration given a difference of one standard deviation in the covariate (Schielzeth, 2010). However, because the expected standard deviation for a binary variable is 0.5, in order to make comparisons between the binary and continuous variables, the continuous inputs were divided by twice their standard deviation (Gelman, 2008). The above model was fit with both unstandardized and standardized inputs for illustrative purposes.

2.2.1 Hierarchical effects

The two hierarchical effects of interest in this study are origination cohort and shared evolutionary history, or phylogeny. Hierarchical modeling can be considered an intermediate between complete and no pooling (Gelman and Hill, 2007), where complete pooling is when the differences between groups are ignored while no pooling is where different groups are analyzed separately. By allowing for partial pooling, we are modeling a compromise between these two extremes which allows for better inference. This is done by having all of the groups sharing the same prior with the scale parameter estimated from the data, which then acts as an indicator of the amount of pooling. A scale of 0 and ∞ indicate complete and no pooling, respectively. Hierarchical modeling is analogous to mixed-effects modeling (Gelman and Hill, 2007).

Origination cohort is defined as the group of species which originated during the same 2 My temporal bin. The most recent temporal bin, 0-2 Mya, was excluded, leaving 32 different cohorts. The effect of origination cohort j was modeled with each group being a sample from a common cohort effect, η , which was considered Normally distributed with mean 0, and standard deviation σ_c . The value of σ_c was then estimated from the data itself, corresponding

to the amount of pooling in the individual estimates of η_j . This approach is a conceptual unification between dynamic and cohort survival analysis in paleontology (Baumiller, 1993, Foote, 1988, Raup, 1975, 1978, Van Valen, 1979), with σ_c acting as a measure of relative importance of these two end members.

$$\begin{aligned}\eta_j &\sim \mathcal{N}(0, \sigma_c) \\ \sigma_c &\sim \text{halfCauchy}(0, 2.5)\end{aligned}$$

The choice of prior for σ_c follows Gelman (2006)

The impact of shared evolutionary history, or phylogeny, was modeling as an individual effect where each observation, i , is distributed as a multivariate normal, h , where the covariance matrix was assumed known up to a constant variance, σ_p^2 (Housworth et al., 2004, Lynch, 1991). More fully, this is written

$$\begin{aligned}h &\sim \text{Multi}\mathcal{N}(0, \Sigma) \\ \Sigma &= \sigma_p^2 \mathbf{V}_{phy} \\ \sigma_p &\sim \text{halfCauchy}(0, 2.5),\end{aligned}$$

with \mathbf{V}_{phy} being the phylogenetic covariance matrix defined as an $n \times n$ matrix where the diagonal elements are the distance from root to tip, in branch length, for each observation and the off-diagonal elements are the amount of shared history, measured in branch length, between observations i and j . σ_p was given a weakly informative half-Cauchy hyperprior.

Both η and h were centered at 0 so that these effects can be interpreted as differences from the mean of the observed.

2.2.2 Censored observations

An important part of survival analysis is the inclusion of “censored” observations (Ibrahim et al., 2001, Klein and Moeschberger, 2003) or observations where the failure time has not been observed. The most common censored observation is right censored, where the point of extinction had not yet been observed in the period of study. In this case, this means taxa that are still extant. Left censored observations, on the other hand, correspond to observations that went extinct any time between 0 and some known point. In this study, taxa occurring in only a single time bin were left censored. Because of the minimum resolution of the record, we cannot observe if these taxa went extinct in less than that single bin or not.

To model censored data, there are a few functions which must first be defined following Klein and Moeschberger (2003). The survival function, $S(t)$, for a Weibull model is

$$S(t|\alpha, \sigma) = \exp \left(- \left(\frac{t}{\sigma} \right)^\alpha \right), \quad (3)$$

where σ is defined as above (Eq. 2). $S(t)$ is the probability that an observation will survive longer than a give time, t . The likelihood of uncensored observations is evaluated as as normal using Equation 1 while right censored observations are evaluated at $S(t)$ and left censored observations are evaluated at $1 - S(t)$. Note, $1 - S(t)$ is equivalent to the cummulative density function and $S(t)$ is equivalent to the complementary cummulative density function (Gelman et al., 2013).

Fully, the likelihood for both uncensored and both right and left censored observations is written

$$L \propto \prod_{i \in C} \text{Weibull}(y_i|\alpha, \sigma) \prod_{j \in R} S(y_j|\alpha, \sigma) \prod_{k \in L} (1 - S(y_k|\alpha, \sigma)),$$

where C is the set of uncensored observations, R is the set of right censored observations, and L is the set of left censored observations.

A summary of the entire model, save for calculations for censored observations, along with the exact priors for every estimated parameter is presented in Figure 1.

2.2.3 Estimation

Parameter posteriors were approximated using a Markov-chain Monte Carlo (MCMC) routine implemented in the Stan programming language (Stan Development Team, 2014). Stan implements a Hamiltonian Monte Carlo using a No-U-Turn sampler (Hoffman and Gelman, 2011). Posterior approximation was done using four parallel MCMC chains. Chain convergence was evaluated using the scale reduction factor, \hat{R} . Values of \hat{R} close to 1, or less than or equal to 1.1, indicate approximate convergence. Convergence means that the chains are approximately stationary and the samples are well mixed (Gelman et al., 2013).

Both models with and without phylogenetic effects were estimated. Because inverting a large matrix is a memory intense procedure and because the phylogenetic covariance matrix is only assumed known up to a constant, every iteration of the MCMC would involve solving a very large matrix which is not ideal. In order to speed up the MCMC routine, this aspect of the model had to be reparameterized for efficiency purposes. Because of the size of the covariance matrix a custom multivariate sampler was used (see Appendix: Code).

For the model without phylogenetic effect the four MCMC chains ran for 1000 steps, with the first 500 used as warm-up and the last 500 as samples from the posterior. Because of the added complexity of estimating the phylogenetic effect, instead all four chains were run 20000 steps thinned to every twentieth sample split evenly between warm-up and sampling.

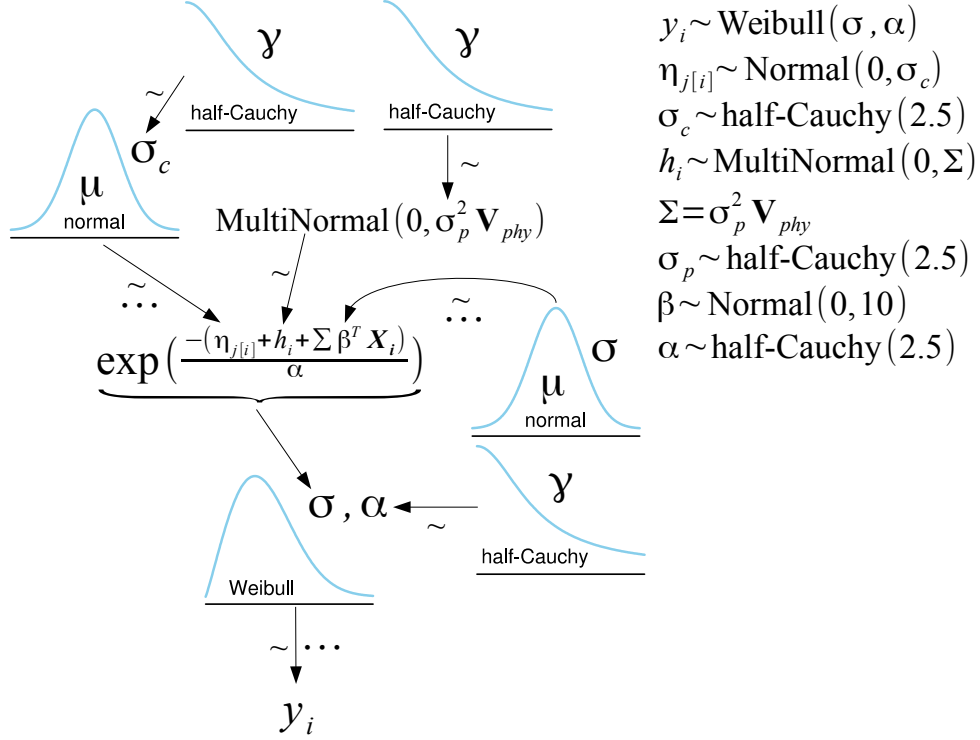


Figure 1: Graphical depiction of full survival model, save censoring, used here. Exact values for the hyperparameters are presented to the right. The observed duration of the i th observation is indicated towards the bottom left as y_i , which is assumed to follow a Weibull distribution.

2.3 Posterior predictive checks

The most basic assessment of model fit is that simulated data generated using the fitted model should be similar to the observed. This is the idea behind posterior predictive checks. Using the predictors from each of the observed durations, and randomly drawn parameter estimates from their marginal posteriors, a simulated data set y^{rep} was generated. This process repeated 1000 times and the distribution of y^{rep} was compared with the observed y (Gelman et al., 2013). This was done both graphically and numerically.

An example posterior predictive check used in this study is a graphical comparison of the Kaplan-Meier (K-M) survival curve estimated from the observed data with the survival curves from 1000 simulations. K-M survival curves are non-parametric estimates of the function $S(t)$ or the probability of a species going extinct given that it has lived to time t (Klein and Moeschberger, 2003). Other posterior predictive checks included comparison of the mean and quantiles of the observed durations to the distributions of the same quantities from the simulations, and inspection of the deviance residuals, defined below.

In ordinary linear regression, the residuals are defined as $r = y - y_{est}$. For hierarchical models, this definition is inadequate. For survival analysis, the equivalent values are deviance residuals. To define how deviance residuals are calculated, we first define the cumulative hazard function (Klein and Moeschberger, 2003). Given $S(t)$ (Eq. 3), we define the cumulative hazard function as

$$\Lambda(t) = -\log(S(t)).$$

Next, we define martingale residuals, m , which are defined in relation to the inclusion vector I

$$m_i = I_i - \Lambda(t_i).$$

I is as a vector of length n , where $I_i = 1$ means the observation is completely observed and $I_i = 0$ means the observation is censored.

Martingale residuals have a mean of 0 and ranges between 1 and $-\infty$ and can be viewed as the difference between the observed number of deaths between 0 and t_i and the expected number of deaths based on the model. However, martingale residuals are difficult to interpret, can be asymmetrically distributed, and are not equivalent to standard residuals.

The solution to this is to use the deviance residuals, D . This is defined as a function of martingale residuals and takes the form

$$D_i = \text{sign}(m_i) \sqrt{-2[m_i + I_i \log(I_i - m_i)]}.$$

2.4 Variance partitioning

There are three different variance components in this model (Fig. 1): sample σ_y^2 , cohort σ_c^2 , and phylogenetic σ_p^2 . The sample variance, σ_y^2 , is similar to the residual variance from a

normal linear regression. Partitioning the variance between these sources allows the relative amount of unexplained variance of the sample to be compared. However, the model used here (Eq. 1) does not include an estimate of overall variance, as the errors are not normally distributed. The partitioning of the variance between these three components was instead approximated via a simulation approach modified from Goldstein et al. (2002).

The procedure is as follows:

1. Simulate w (50,000) values of η ; $\eta \sim \mathcal{N}(0, \sigma_c)$.
2. For a given value of $\beta^T \mathbf{X}$, calculate σ^{c*} (Eq. 2) for all w simulations, holding h constant at 0.
3. Calculate v_c , the Weibull variance (Eq. 4) of each element of σ^{c*} with α drawn from the posterior estimate.
4. Simulate w values of h ; $h \sim \mathcal{N}(0, \sigma_p)$
5. For a given value of $\beta^T \mathbf{X}$, calculate σ^{p*} (Eq. 2) for all w simulations, holding η constant at 0.
6. Calculate v_p , the Weibull variance (Eq. 4) of each element of σ^{p*} with α drawn from the posterior estimate.
7. $\sigma_{y*}^2 = \frac{1}{2} \left(\left(\frac{1}{w} \sum_i^w v_{pi} \right) + \left(\frac{1}{w} \sum_j^w v_{cj} \right) \right)$
8. $\sigma_{c*}^2 = \text{var}(v_c)$ and $\sigma_{p*}^2 = \text{var}(v_p)$

The simulated values of h were drawn from a univariate normal distribution because each simulated value is in isolation, so there is no concern of phylogenetic autocorrelation. The chosen value for $\beta^T \mathbf{X}$ was a draw from the posterior estimate of the intercept. Because input variables were standardized prior to model fitting, the intercept corresponds to the estimated effect on survival of the sample mean.

Weibull variance is calculated as

$$\text{var}(x) = \sigma^2 \left(\Gamma \left(1 + \frac{2}{\alpha} \right) - \left(\Gamma \left(1 + \frac{1}{\alpha} \right) \right)^2 \right), \quad (4)$$

where Γ is the gamma function.

The variance partitioning coefficients are then calculated $VPC_{phylo} = \frac{\sigma_{p*}^2}{\sigma_{y*}^2 + \sigma_{c*}^2 + \sigma_{p*}^2}$ and similar for the other variance components.

I used ratios of the variances and variance partitioning coefficients (VPC) to measure the amount of partial pooling. The former, when compared to the sample size of the hierarchical effect such as the number of cohorts, is an estimate of the relative amount of pooling, while the latter is a measure of the relative importance of the different variance components (Gelman and Hill, 2007). Phylogenetic heritability, h_p^2 (Housworth et al., 2004), is effectively

identical to the VPC of the phylogenetic effect. Additionally, because phylogenetic effect was estimated using a principally taxonomy based tree the estimates derived here can be considered minimum estimates of the tree effect.

3 Results

Table 2: Summaries 1000 samples drawn from the marginal posteriors for the principle parameters of interest. Because of variable standardization, the intercept can be interpreted as the estimate for the mean observed species. As such, the other values are expected effects of trait values expressed as deviation from the mean. The categorical variables are binary index variables where an observation is of that category or not. \hat{R} values of less than 1.1 indicate chain convergence for the posterior samples.

	mean	sd	2.5%	25%	50%	75%	97.5%	\hat{R}
alpha	1.31	0.03	1.25	1.29	1.31	1.34	1.38	1.01
intercept	-0.82	0.18	-1.17	-0.94	-0.82	-0.70	-0.48	1.00
ground dwelling	-0.12	0.12	-0.34	-0.20	-0.12	-0.04	0.12	1.00
scansorial	-0.13	0.13	-0.38	-0.22	-0.13	-0.05	0.12	1.00
herbivore	0.11	0.12	-0.13	0.03	0.12	0.19	0.35	1.00
insectivore	0.09	0.13	-0.17	0.00	0.09	0.19	0.36	1.00
omnivore	-0.12	0.13	-0.37	-0.20	-0.12	-0.04	0.14	1.00
logit(occupancy)	-0.66	0.08	-0.81	-0.71	-0.65	-0.60	-0.50	1.00
log(size)	-0.05	0.05	-0.15	-0.08	-0.05	-0.01	0.05	1.00
sd cohort	0.33	0.07	0.22	0.29	0.33	0.37	0.48	1.00
sd phylogeny	0.21	0.10	0.07	0.14	0.19	0.26	0.46	1.05

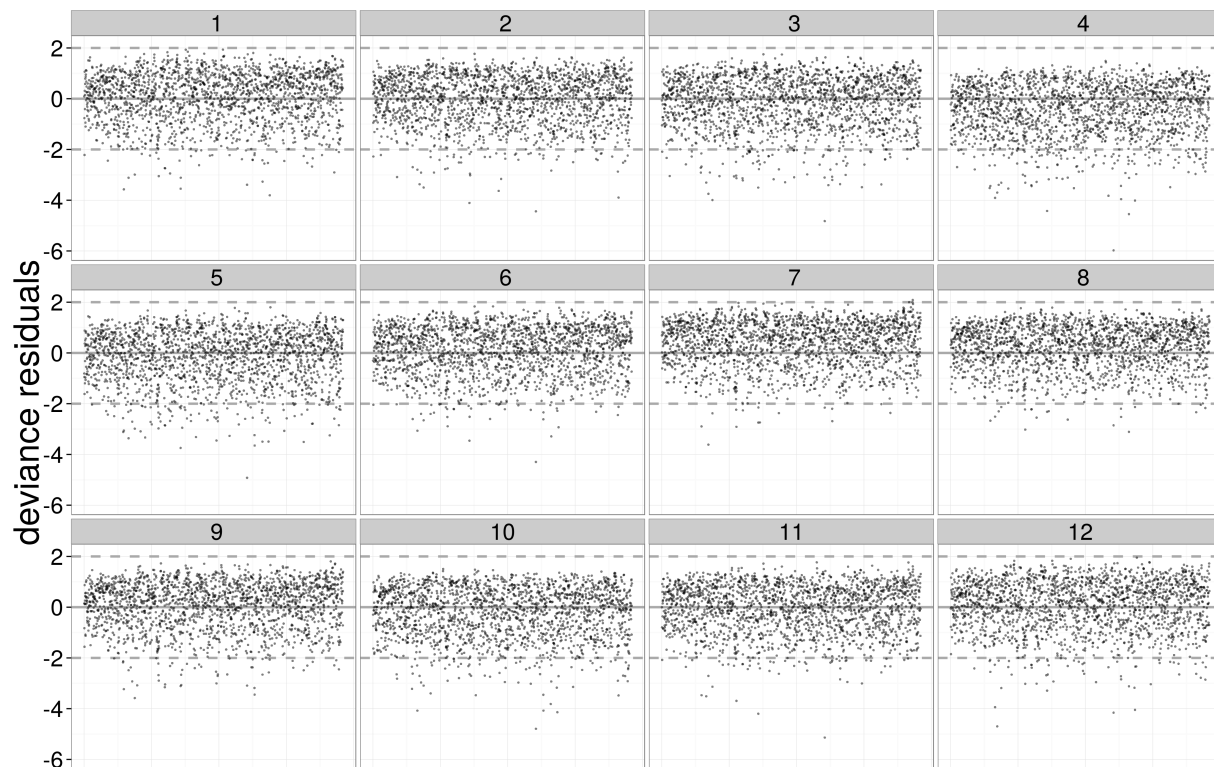


Figure 2: Deviance residuals from the fitted survival model. Each graph depicts the residuals from single draws from the posteriors distributions of all estimated parameters. Positive values indicate an under estimate of the observed duration, while negative values indicate an over estimate of the observed duration. Twelve difference examples are provided here to indicate the lack of individual observation based biases.

4 Discussion

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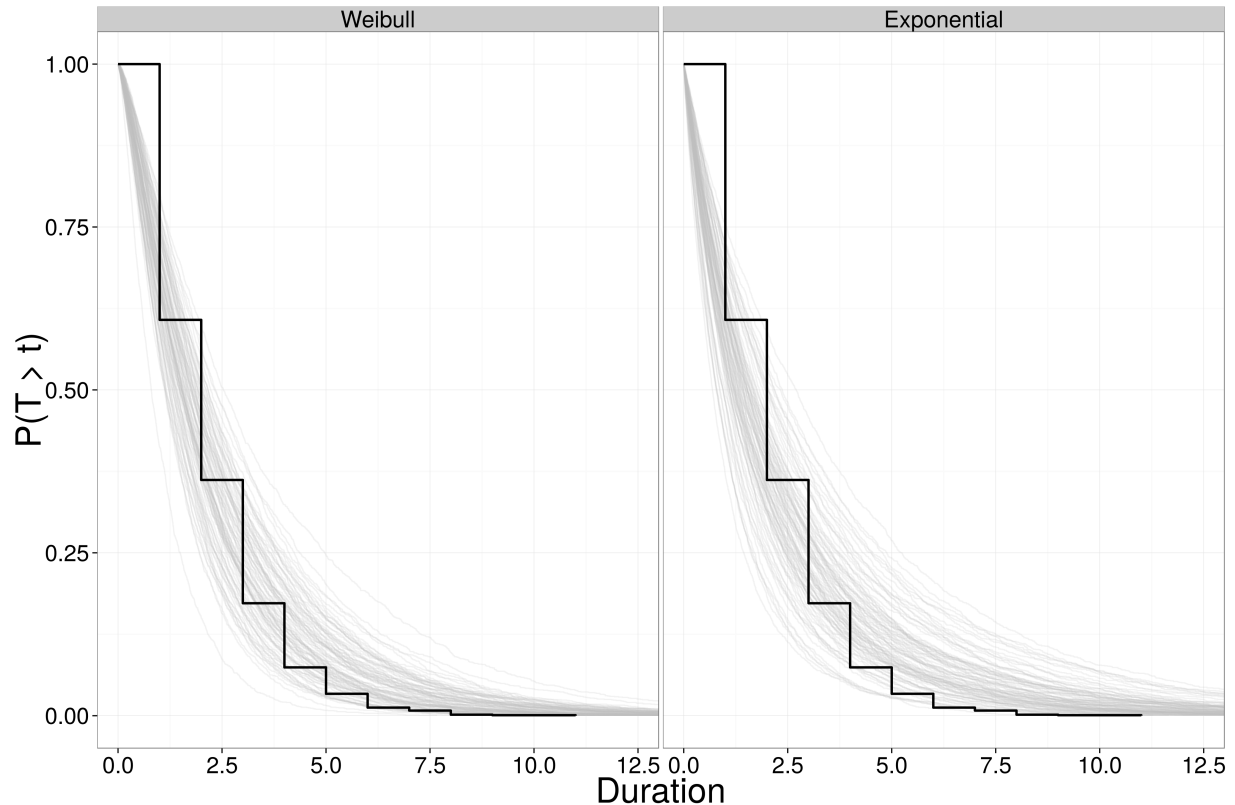


Figure 3: Comparison between K-M estimate of survival function (black) from the observed versus K-M estimates from 100 simulated data sets using the fitted model (dark grey). Simulated data sets were generated by drawing parameter values randomly from their estimated posteriors and using the observed covariate information to estimate durations for all the observed species. On the left are the results from the full survival model (Fig. 1), while on the right are the results from a simplified model where duration follows an exponential distribution and there is no phylogenetic effect.

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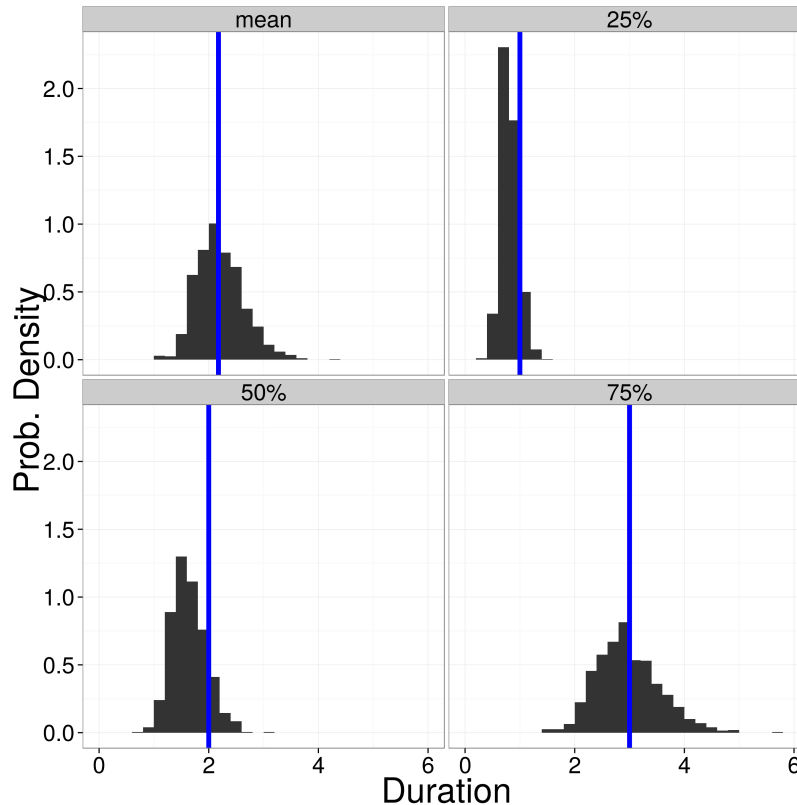


Figure 4: The results of additional posterior predictive checks for four summaries of the observed durations, as labeled. Blue vertical indicate the observed value. None of the observed are significantly different from the posterior predictive distributions.

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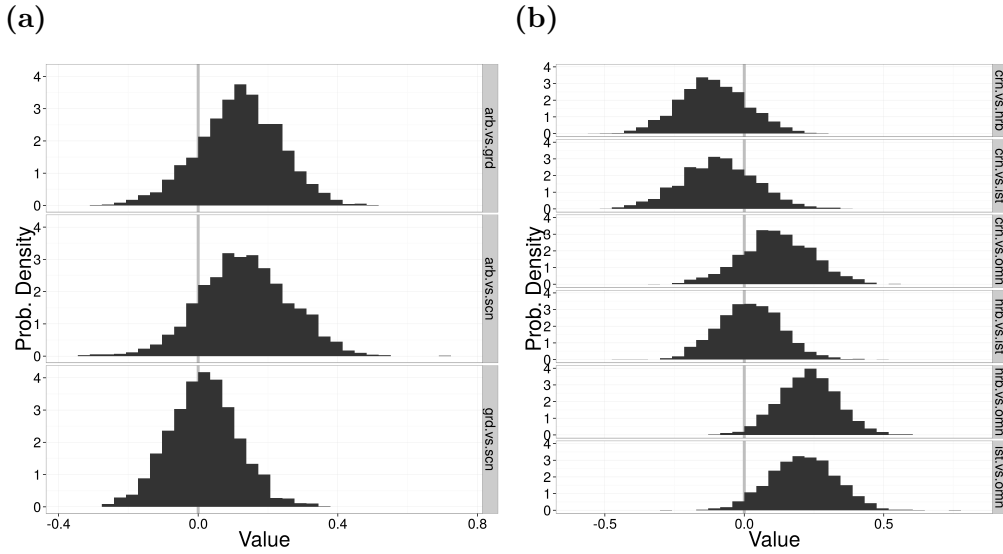


Figure 5: Pairwise differences in effect of the locomotor (a) and dietary categories (b) on expected duration from 1000 samples from the posterior distribution. Comparisons of locomotor categories, from top to bottom (a), are: arboreal versus ground dwelling, arboreal versus scansorial, and ground dwelling versus scansorial. For dietary category, from top to bottom (b): carnivore versus herbivore, carnivore versus insectivore, carnivore versus omnivore, herbivore versus insectivore, herbivore versus omnivore, and insectivore versus omnivore. Values to the left indicate that the first category is expected to have a greater duration than the second, while values to the right indicate that the first category is expected to have a shorter duration.

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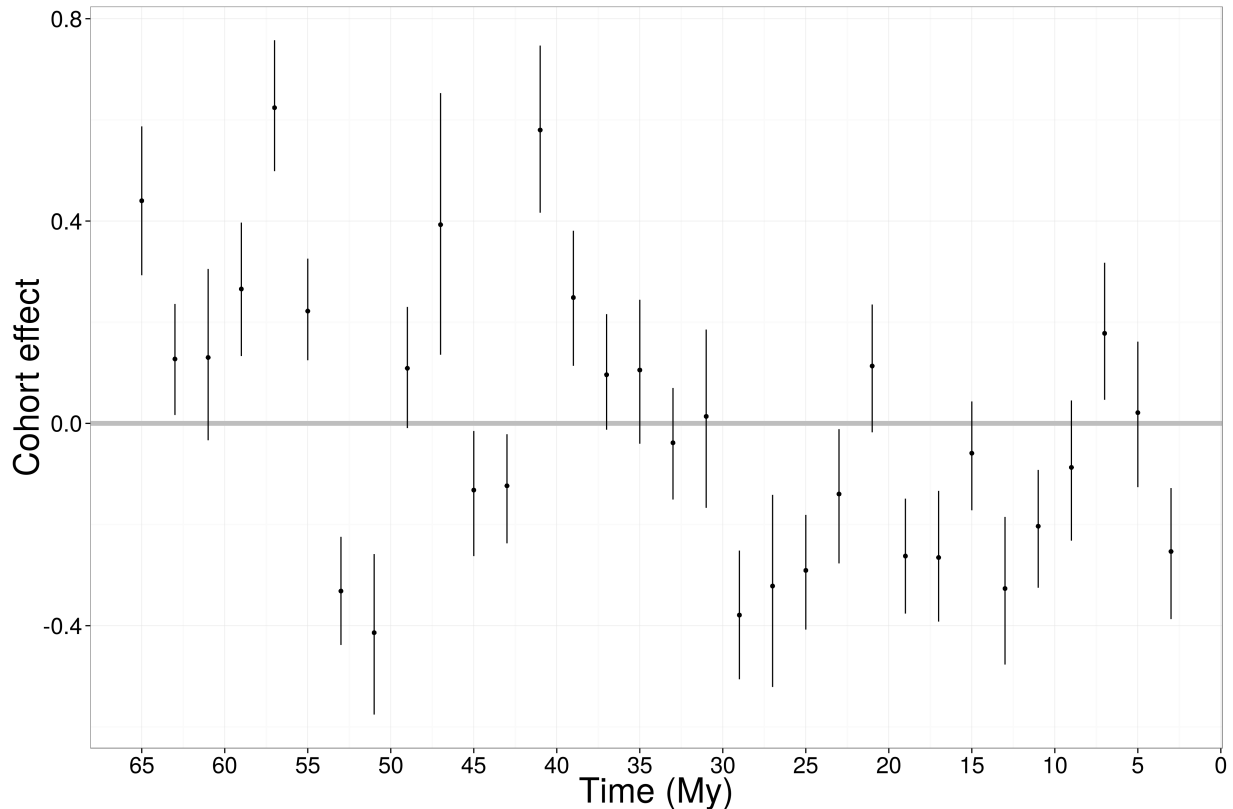


Figure 6: Summaries of estimated individual cohort effect posteriors. Depicted are medians and 80% credible intervals of the estimated posterior distributions. High values correspond to shorter species durations while lower values correspond to greater species durations compared to the mean duration. Lines are placed at the middle of the 2 My origination cohorts.

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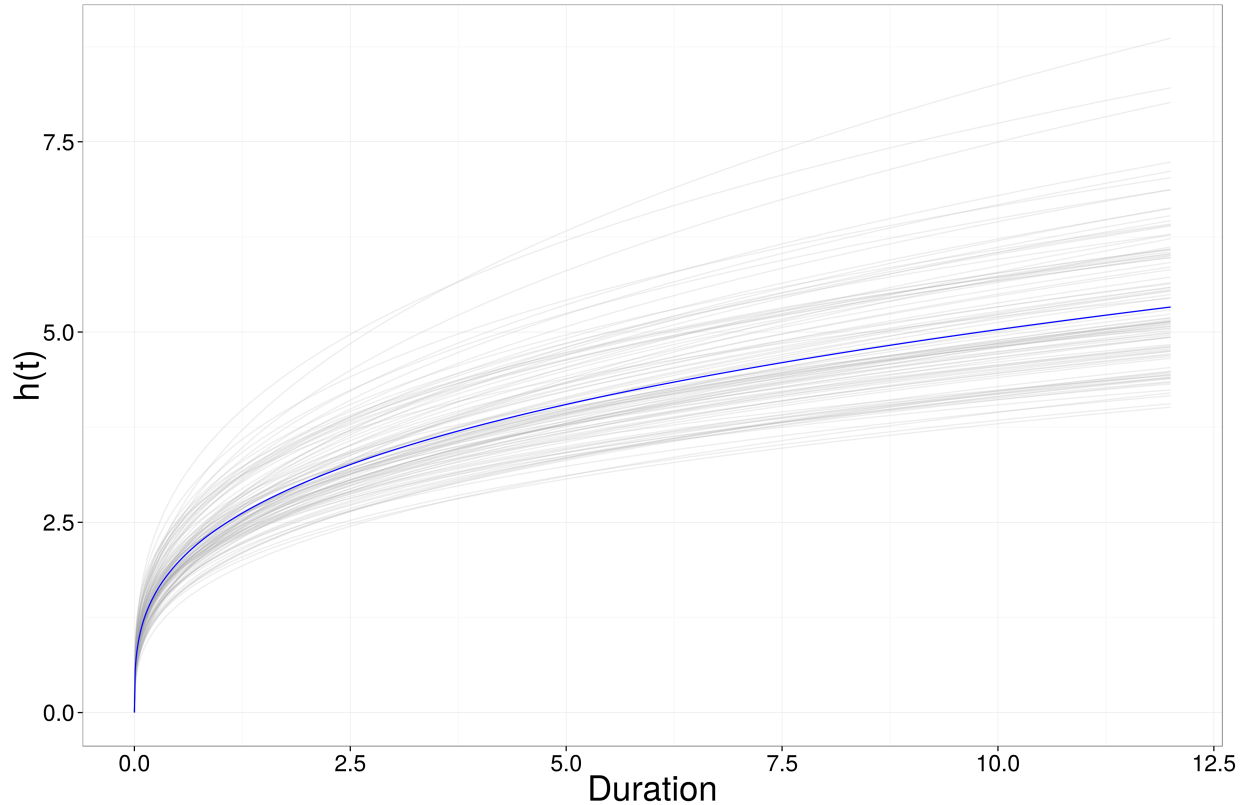


Figure 7: 100 estimates of the hazard function ($h(t)$) for the observed species mean (grey), along with the median estimated hazard function. $h(t)$ is an estimate of the number of extinctions that occur given an amount of time, t . Hazard functions were estimated from random draws from the estimated posterior distributions and evaluated with all covariate information set to 0, which corresponds to the expected duration of the mean species.

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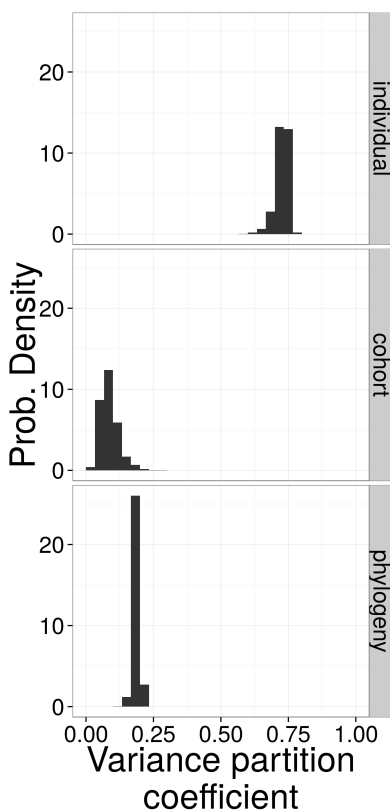


Figure 8: Estimates of the variance partitioning coefficients for the three different sources of variance: species, cohort, and phylogeny. Higher values correspond to greater contribution to total unexplained variance. Each of the estimates is a distribution of 1000 approximating simulations due to the model’s non-normality.

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