

Automated PCB Disassembler



Background

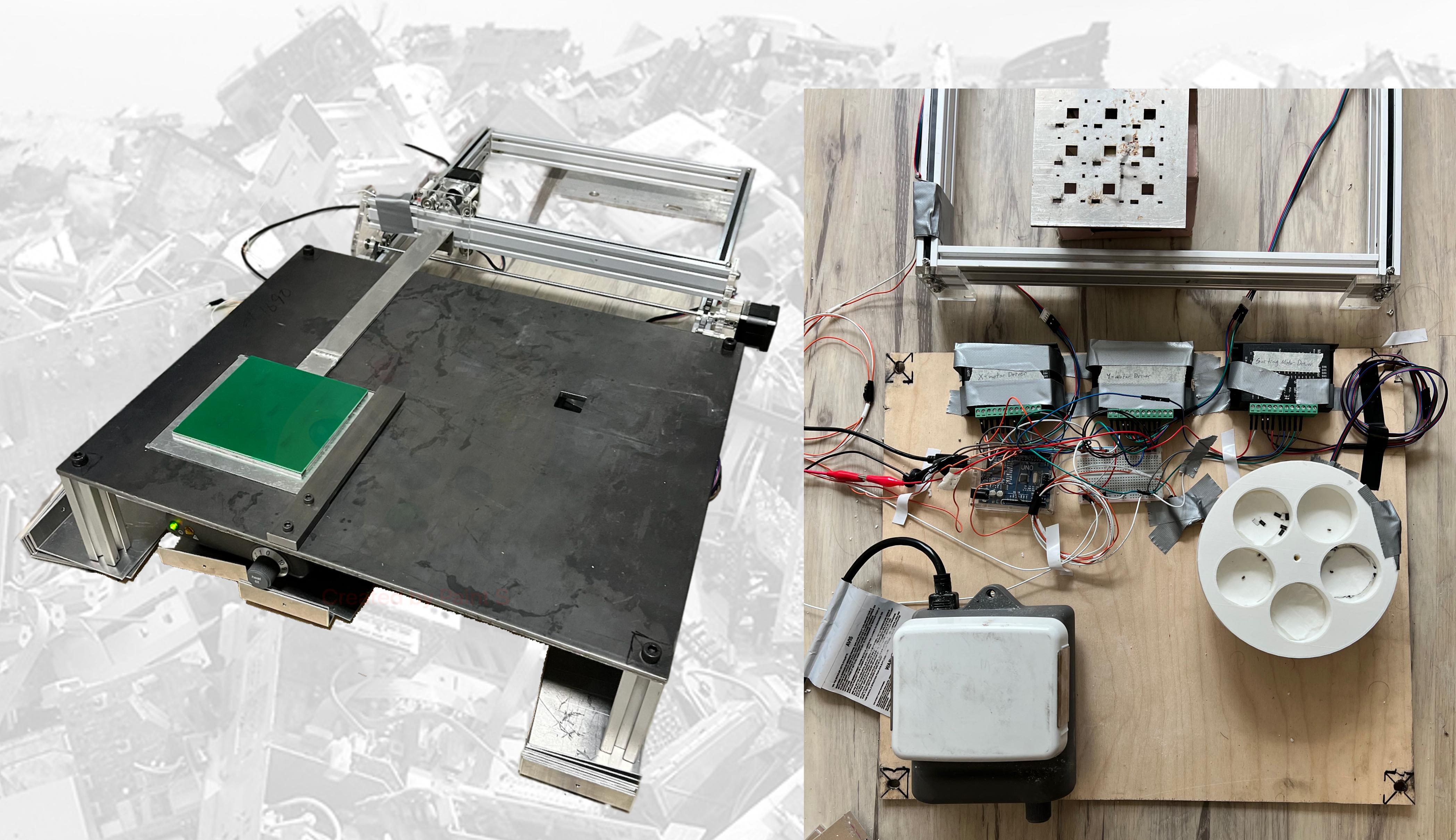
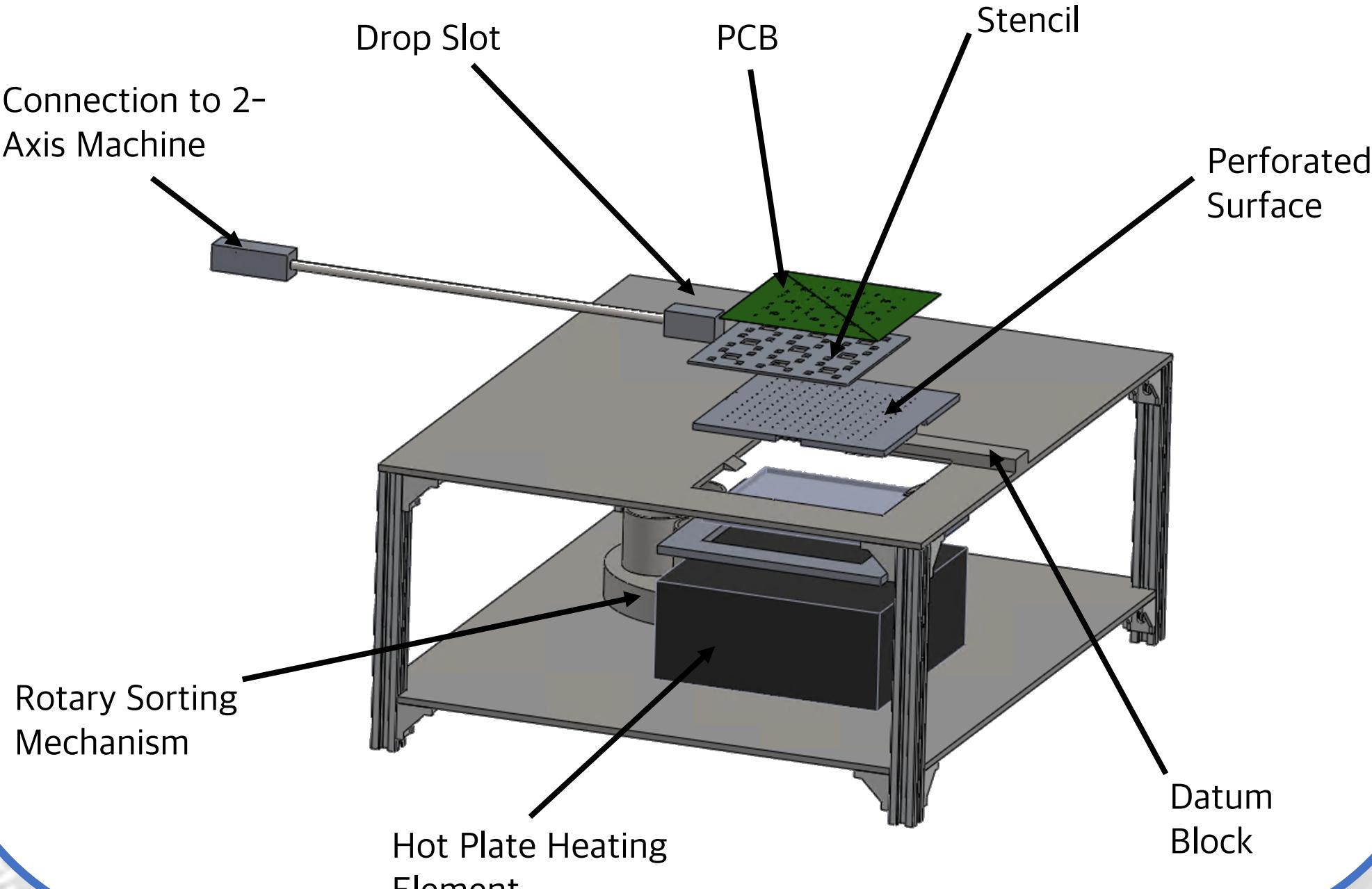
- The world produced 53.6 million tonnes of e-waste in 2020 yet only 17.4% of this was recycled
- Many PCBs end up directly in landfills due to costs and time associated with disassembling
 - Issue has a two-fold impact, contributes to the growing amount of e-waste
 - Also results in components continuing to be manufactured even though many could be directly re-used if properly desoldered

Objective

Design and build a machine or process that can desolder a used PCB in order to remove and sort as many microelectronic components as possible. These components include but are not limited to resistors, capacitors, inductors, transistors and ICs.

Implementation

- Desolders components using a laboratory-grade hot plate
- Heat is transferred indirectly through a custom stencil that is in contact with the PCB
- Entire stencil is actuated to wedge the components off the PCB using a datum block
- Stencil is then actuated to a drop slot in the platform with a rotary bin mechanism below
- Limit switches are used to centre 2-axis machine and rotary sorting mechanism
- Controlled by an Arduino Mega

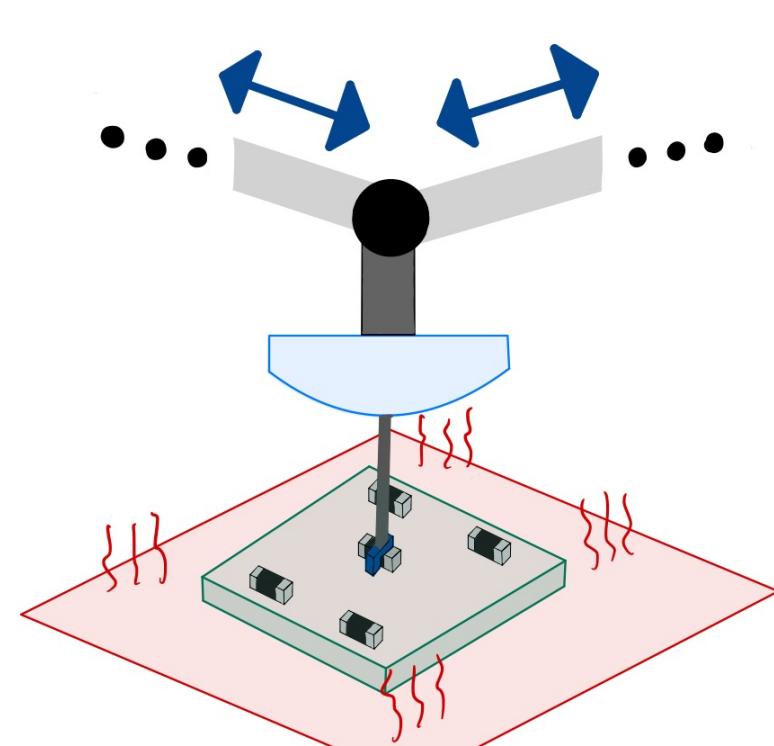


Process Flow



Design Alternatives

Lower Heating Element + Mechanical Gripper



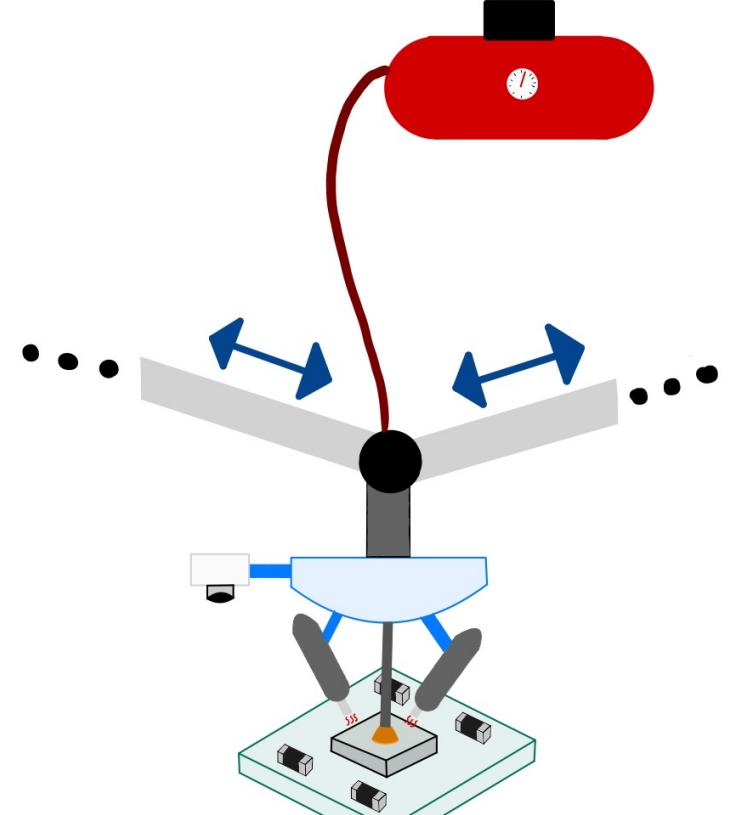
Benefits

- Batch desoldering

Drawbacks

- Part picking time
- Direct heating may damage PCB

Heat Guns + Pneumatic Suction + Machine Vision



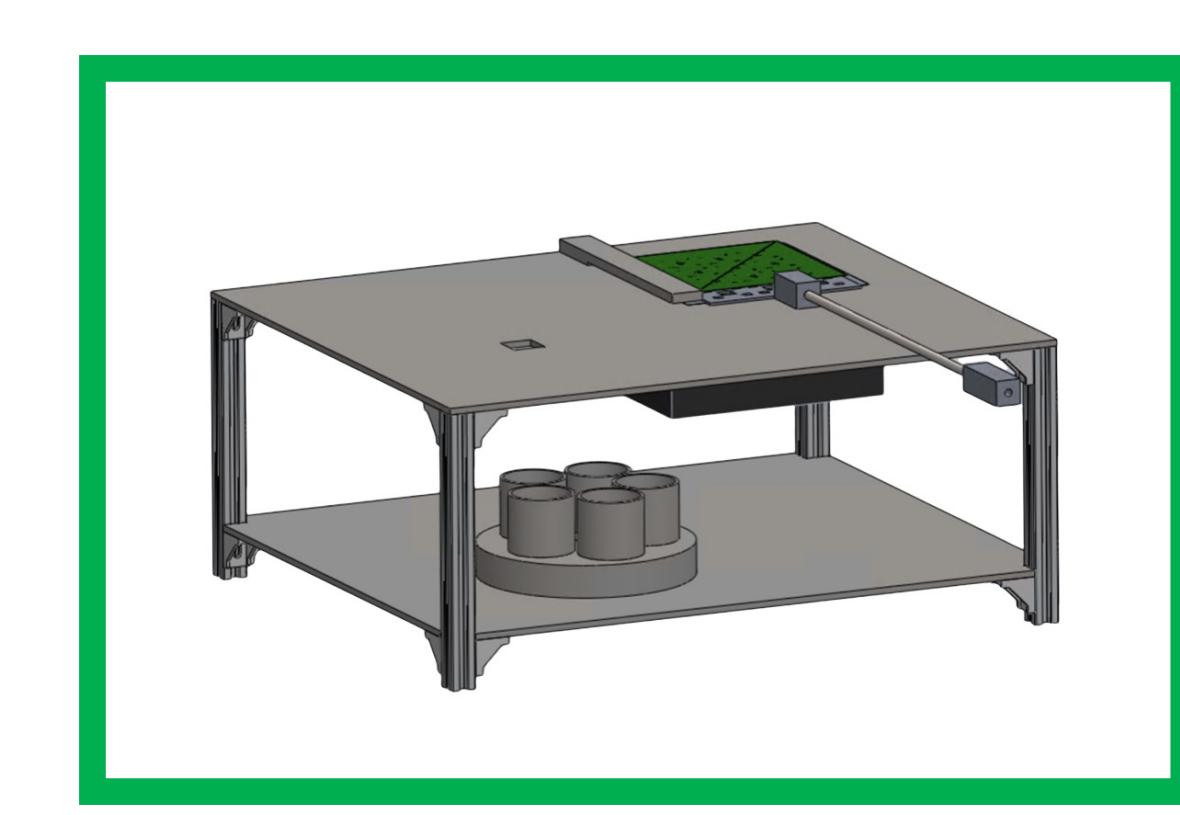
Benefits

- Board compatibility

Drawbacks

- Machine vision reliability
- Power draw due to lossy heat guns + compressor

PCB-Specific Heated Stencil + Drop Slot



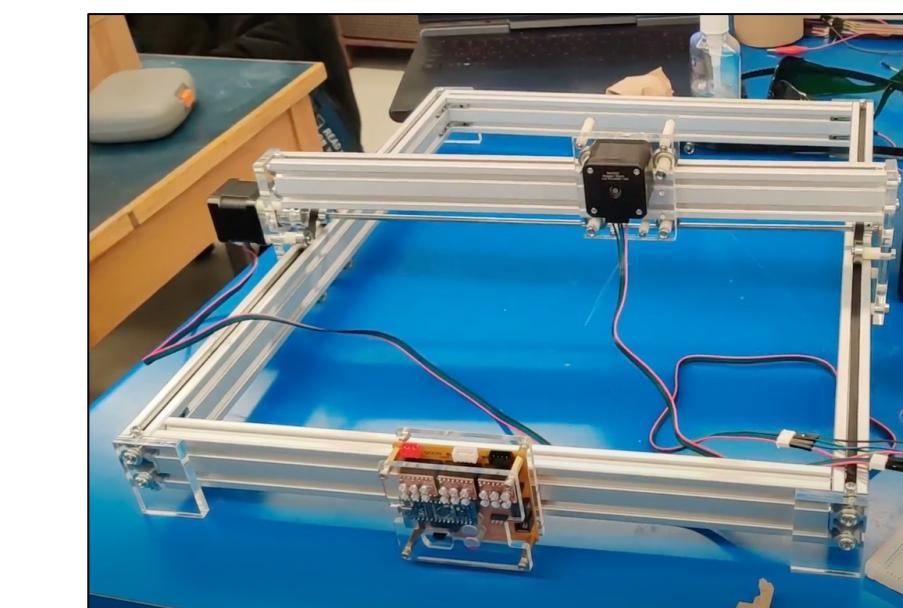
Benefits

- Batch desoldering

Drawbacks

- Lowest device cost
- Different stencils for different PCBs

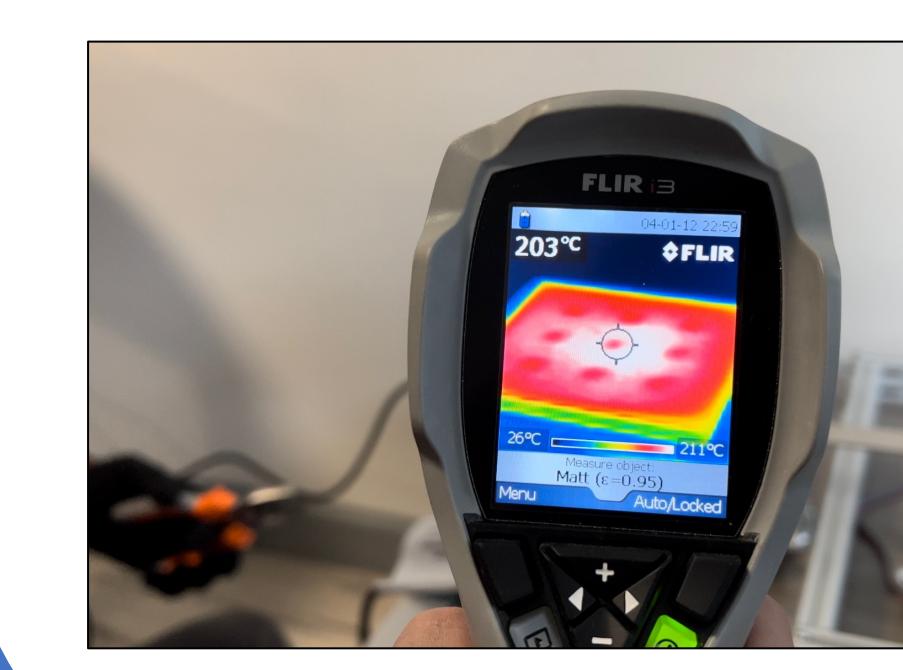
Challenges



Uneven actuation along the two-axis machine
 Counter-measured by upgrading stepper motor drivers



Insufficient contact with the heating element
 Fixed with shims to correct levelling



Heat loss to main platform
 Mitigated using a slotted seating mechanism to minimize contact area

Results

Objective	Target	Result
Constraints	Target	Met?
Ease of development	N/A	✓
Component weight	<5 g	[0.010 g, 0.0513 g]
Size of components	[1.25 mm x 2 mm, 6.3 mm x 3.2 mm]	[1.25 mm x 2 mm, 6.3 mm x 3.2 mm]
Minimize time to remove components	10 minutes	7 minutes
Maximize sorting accuracy	100%	>80%
Minimize peak power usage	1250 W	350 W
Minimize required human intervention	N/A	✓
Attainable heating element temperature	400°C	550°C

Acknowledgements

Prof. Andrew Kennings
 Prof. Behrad Khamesee
 Prof. Rodolfo Pellizzoni