# Artificial Intelligence II Homework 3

## Comments & Model Performance results on Questions 1 & 2

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#### **Basic Execution flow**

- 1. Before creating the train & validation sets, we read the .csv files the usual way (with pd.read\_csv), to check if all the samples have the expected format without missing values, and get the number of samples in the validation set (which will be needed later).
- 2. We create the Train and Validation sets, using TabularDataset objects:
- We preprocess each tweet with customPreprocessor and tokenize it using nltk.TweetVectorizer.
- We will access the two sets in batches, using BucketIterator objects. We initialize the validation set BucketIterator with batch\_size equal to the validation set size, so essentially we access the set in "batch mode" (one batch for the whole set).
- 3. We create the embeddings matrix, where we store the **GloVe** vector for each word in the train set vocabulary.
- 4. We initialize the Model. Hyperparameters such as number of epochs, batch size, learning rate, number & size of layers, Dropout probability etc. can be modified on code cell #5.

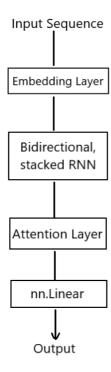
  We use CrossEntropyLoss and the Adam optimizer.
- 5. We train the model: We use numpy arrays to store several performance stats during training, such as Loss and F1 score on Train and Validation set after each epoch.

  During each epoch:
  - For each batch given by the train set BucketIterator:
    - We make predictions on this batch
    - Extract the predicted labels & calculate the accuracy
    - Calculate & store the batch Loss
    - Perform backpropagation
  - o After going through all the batches, we calculate the total Loss and the F1 score for the Train set
  - We make predictions on the Validation set
  - Calculate & store the Validation set Loss
  - We extract the predicted labels, calculate the accuracy and store the F1 score
- 6. Displaying performance results: After the end of training we display:
  - The Confusion Matrices of the final model predictions on the Train and Validation sets.
  - The F1 Learning Curves for both sets, to demonstrate the performance of the model after each epoch of the training phase.
  - The F1, Precision and Recall scores for the final model on both sets.
     We use the corresponding scikit-learn routines for calculating the scores. We use average='micro' for F1 score and average='macro' for Precision & Recall scores.

- Training phase Loss curves for both sets.
- The ROC Curves for the Validation set predictions.
  We mirror the usage of roc\_curve from scikit-learn for multiple classes, as demonstrated here.
  To create the curves, we apply the softmax function to the NN output vector, to convert it to possibility values that add-up to 1, and use the softmax output to create the curves.
  roc\_curve applies generated possibility thresholds to create the curves, therefore if we provided it with just the predicted labels, it would only apply 3 thresholds to each result, which is insufficient to create useful ROC curves.

## Model types used during development

• Models 1, 2 have the following architecture:

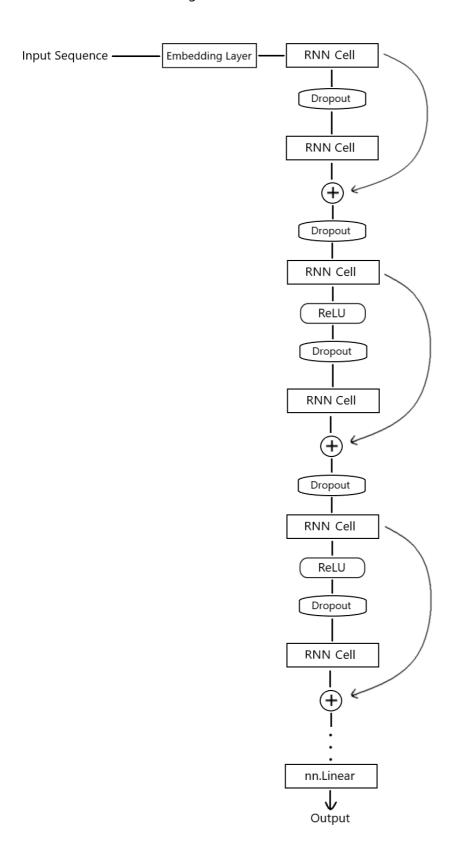


(Model 2 does not use attention layer, but other than that the structure is the same.

Model 1 is the chosen model, and can be used with or without attention layer. See the next sections for the performance comaprison.)

- We use bidirectional, stacked RNN, without skip connections.
- If desired (optionally in Model 1), we can pass the RNN output through an Attention Layer, to help the model focus in critical parts of each tweet and prevent the vanishing gradient in faraway hidden states.
- Finally, we add a Linear layer to output a vector of the desired size.

Models 3, 4 use the following architecture:



- We use a stacked RNN, this time with skip connections. We apply a skip connection in every 2 layers (layers 1, 3, 5 etc. have a skip connection, and the output of layers 2, 4, 6 etc. is the destination of a skip connection). Skip connections are implemented simply using torch.add.
- Before providing input to any layer (except for the first one) we apply a Dropout layer to it.
- We apply a ReLU layer to the odd layer outputs, except for the first one.
- Finally, we add a Linear layer to output a vector of the desired size.

## Different models performance comparison

#### Notes on all models:

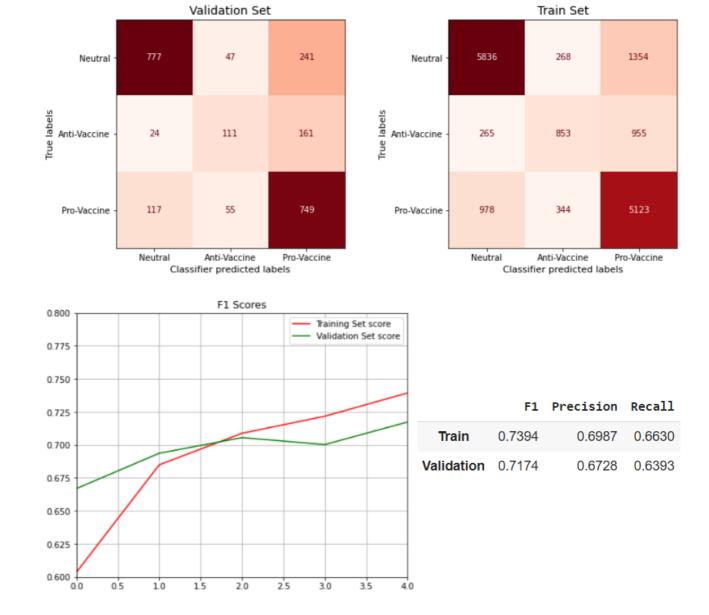
- The performance results displayed below have been produced without using GPU acceleration.
- When not using GPU, the results can be reproduced using SEED = 42.
- Unfortunately, GPU-accelerated model results could not be fully reproduced.
- The execution of each model using only CPU takes about 4-5 minutes. In case this is inconvenient, GPU can be enabled in code cell #6, but note that the results for all models will differ from the ones presented below.
- All models use the **GloVe** pre-trained word embeddings from glove.6B.100d.txt.
- 1. This is the preselected model in the interactive notebook. For this model, we use:

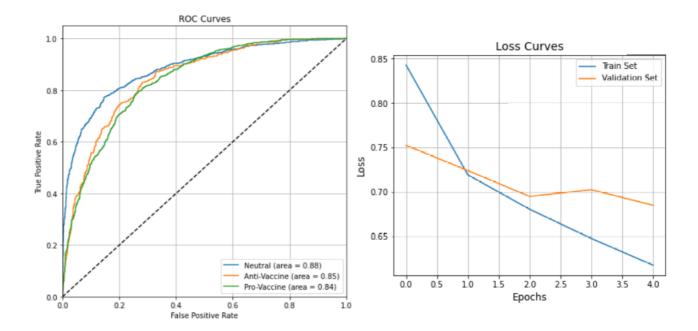
Learning rate: 0.005

Batch Size: 256# Epochs: 5

• RNN: Bidirectional, 4-layer **GRU**, with hidden\_size = 32

Dropout probability: 0.5



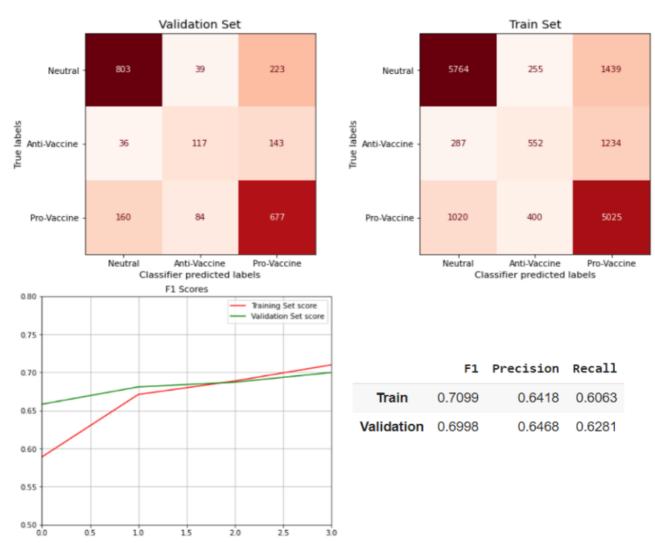


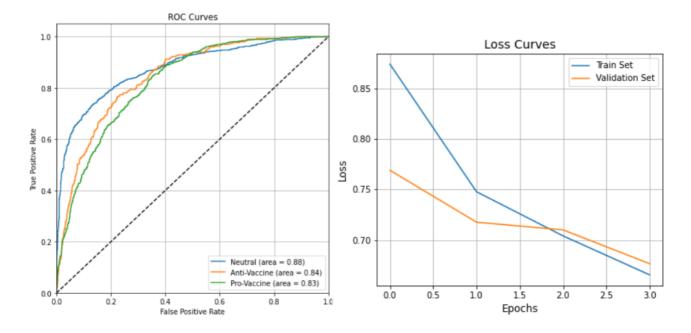
### 2. For this model, we use:

Learning rate: 0.005Batch Size: 128# Epochs: 4

• RNN: Bidirectional, 4-layer **LSTM**, with hidden\_size = 32

o Dropout probability: 0.5



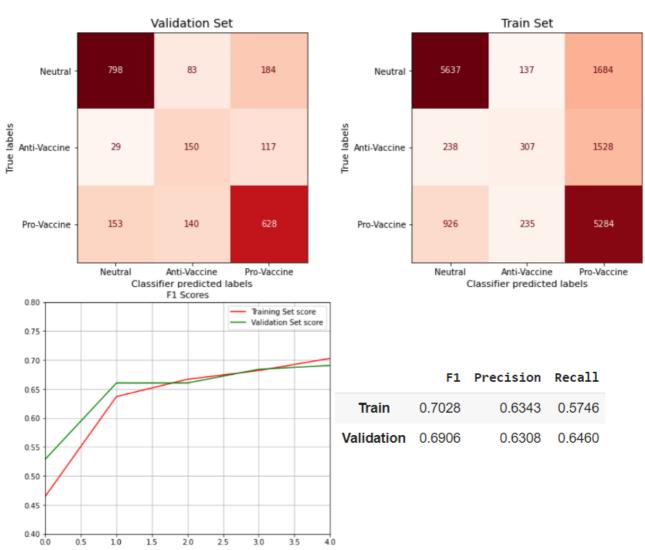


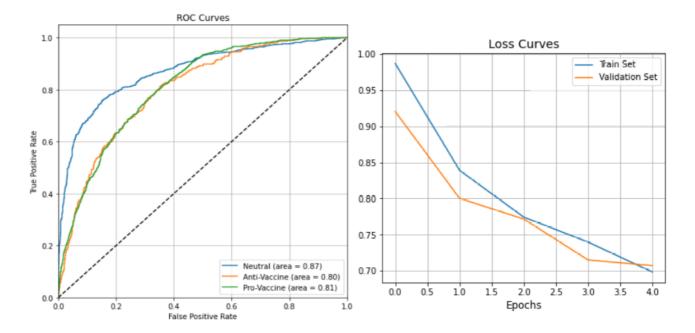
### 3. In this model, we use:

Learning rate: 0.005Batch Size: 128# Epochs: 5

• RNN: 6-layer **GRU**, with hidden\_size = 64 and skip connections

• Dropout probability: 0.5





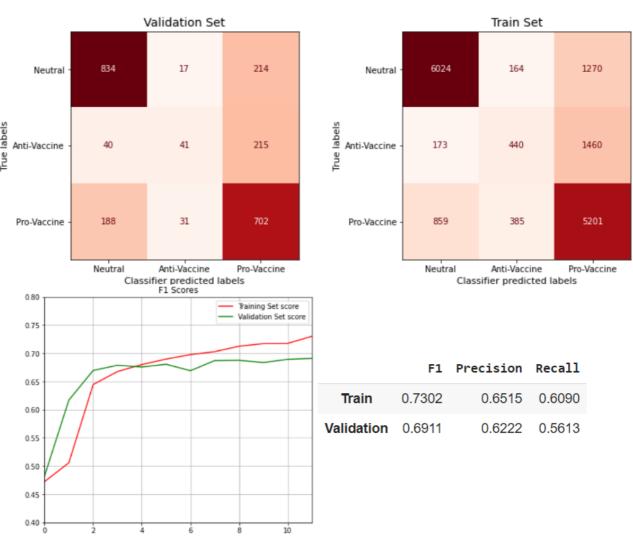
### 4. In the last model, we use:

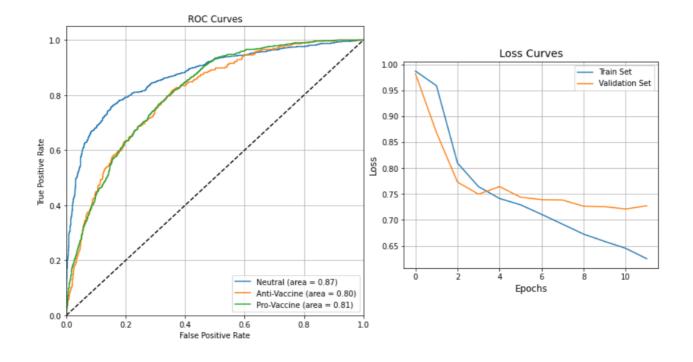
Learning rate: 0.0055Batch Size: 256

o # Epochs: 12

• RNN: 3-layer **LSTM**, with hidden\_size = 64 and skip connections

• Dropout probability: 0.5



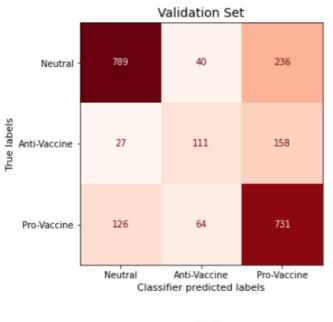


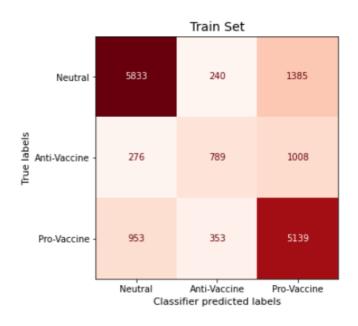
### Comments/Observations on the models and their develpoment

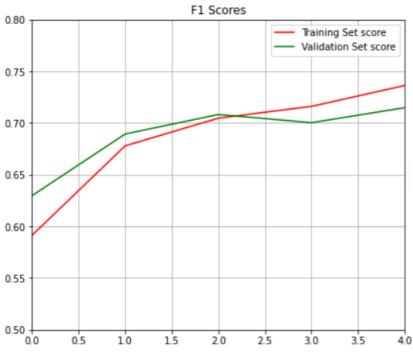
- We notice that bidirectional models tend to perform better. They learn more quickly (in terms of epochs) and perform better in each seperate class, which affects the **Precision** and especially the **Recall** score.
- Skip connections did not seem to have any significant effect in the model performance.
- GRU models achieved slightly better performance, possibly due to their simplicity, which prevents
  overfitting in comparison to LSTM's.
- Decreasing the Dropout probability and/or the batch size usually resulted in higher tendency for overfitting.
- Using **GloVe** embeddings with vector size = 100 appeared to be just about right. Higher vector size would cause significant overfitting in most cases.
- Just like in the previous 2 homeworks, we see much better performance on Neutral and Pro-Vaccine tweets in all models, since the vast amount of train set tweets are labeled as such.
- However, the ROC curves show that while the model may have trouble classifying Anti-Vaccine
  tweets correctly, the possibility assigned to this class when the prediction is wrong is not small. In other
  words, the model may be misclassifying the Anti-Vaccine tweets, but it is not very "confident" in
  these cases.

## Adding Attention Layer to Model 1

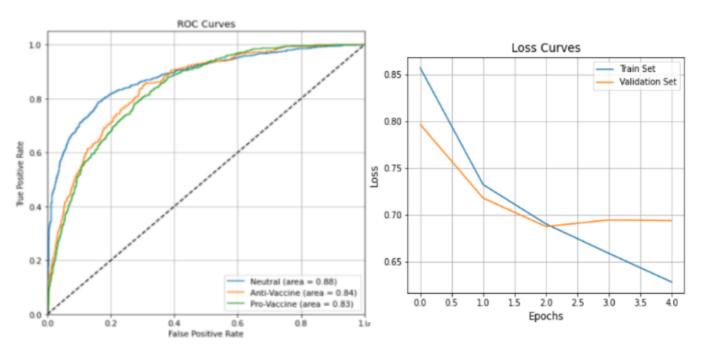
Adding the implemented Attention layer did not have any significant impact to the Model. Below are the performance results of Model 1, after adding Attention:





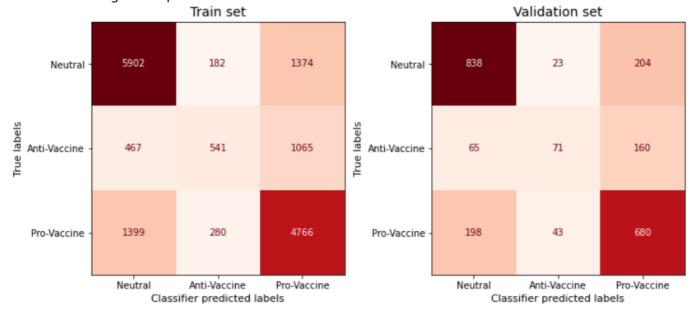


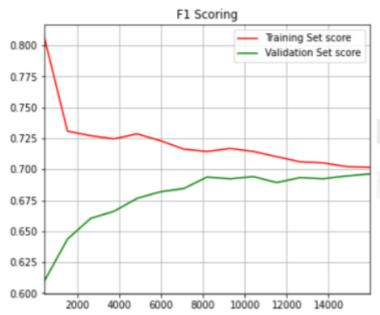
	F1	Precision	Recall
Train	0.7362	0.6931	0.6534
Validation	0.7147	0.6679	0.6365



# Comparison to HW1 Softmax Regression Model and HW2 Feed-Forward NN Model

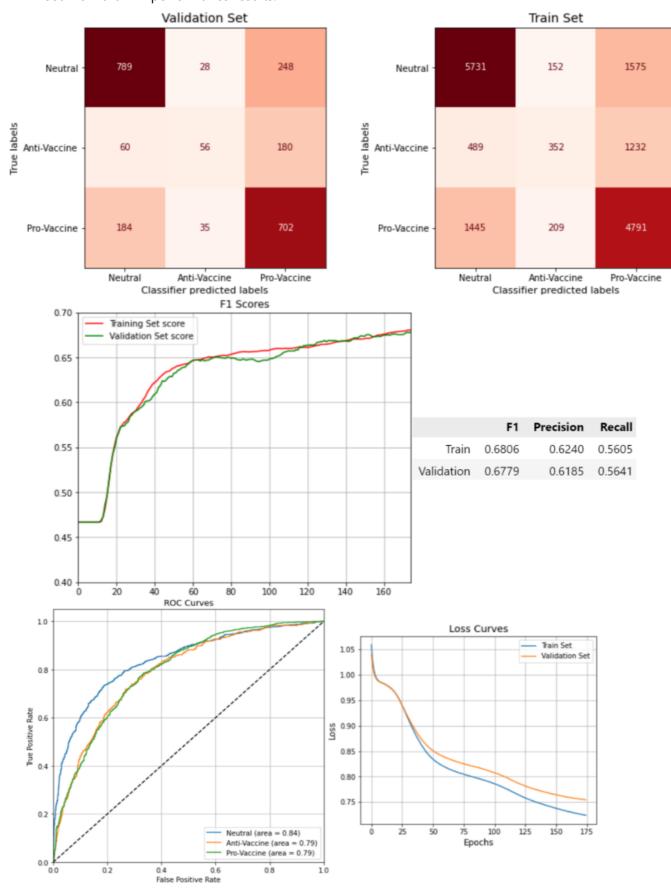
HW1 SoftMax Regression performance results:





	F1	Precision	Recall
Train	0.7016	0.6536	0.5973
Validation	0.6963	0.6436	0.5883

HW2 Feed-Forward NN performance results:



While the macro accuracy and the F1 score have not improved a lot, we notice many performance improvements in comparison to the previous Models:

• The RNN Model performs much better in Anti-Vaccine tweets. This has an impact on multiple metrics:

- The confusion matrix,
- The Precision and especially the Recall score,
- The ROC curves. The ROC Area for the Anti-Vaccine has risen to 0.85 (0.06 increase from 0.79 in the Feed-Forward Model)
- The loss value has been decreased below 0.70 (it was above 0.75 in the Feed-Forward NN).
- The RNN Model performs better in all seperate classes, as seen in the ROC Area scores.
- We can conclude that a bidirectional (or even a single-directional) RNN is a much more effective way to handle the word vectors (in comparison to the "naive" mean sentence vector used in HW2 Model), since it takes the word positions into account.

## Development

The notebook has been developed mostly in Google Colab, but also in WSL Ubuntu 20.04, using Visual Studio Code & Python 3.8.10.

It has been tested successfully in the Google Colab environment, using both CPU-only and GPU-accelerated runtime engines.