

Aim:

To write a program for region based segmentation.

Algorithm:

1.Import necessary libraries such as numpy, matplotlib.pyplot, skimage, and scipy.ndimage.

2.Load and Pre-process Image:

Load the sample rocket image using `data.rocket()`. Convert the RGB image to grayscale using `rgb2gray()`.

3.Edge Detection:

Apply the Canny edge detection algorithm to the grayscale image using `canny()`.

4.Region Filling:

Fill the regions enclosed by edges using `binary_fill_holes()` from `scipy.ndimage`.

5.Elevation Map Computation:

Compute the elevation map of the grayscale image using the Sobel filter with `filters.sobel()`.

6.Marker Creation for Watershed Segmentation:

Create markers for the watershed algorithm. Markers are created based on pixel intensity values:

Mark pixels with intensity less than 30/255 as 1.

Mark pixels with intensity greater than 150/255 as 2.

7.Watershed Segmentation:

Perform watershed segmentation using the elevation map and the created markers with `segmentation.watershed()`.

8.Hole Filling in Segmented Image:

Fill holes in the segmented image using `binary_fill_holes()` from `scipy.ndimage`. Label the filled regions using `nd.label()`.

### 9.Overlay Segmented Labels on Original Image:

Overlay the labeled segments on the original grayscale image using `label2rgb()`.

### 10.Visualization:

Create a figure with two subplots. The first subplot shows the original grayscale image. The second subplot shows the original image with labeled regions in different colors.

Program Code:

```
import numpy as np
import matplotlib.pyplot as plt
from skimage import data, segmentation, color, filters
from skimage.color import rgb2gray
from skimage.feature import canny
import scipy.ndimage as nd
```

```
plt.rcParams["figure.figsize"] = (12, 8)
```

```
# Load the rocket image and convert to grayscale
```

```
rocket = data.rocket()
```

```
rocket_gray = rgb2gray(rocket)
```

```
# Plot the original image
```

```
plt.figure()
```

```
plt.imshow(rocket_gray, cmap='gray')
```

```
plt.title('Original Image')
```

```
plt.axis('off')
```

```
plt.show()
```

```
# Canny edge detector
```

```
edges = canny(rocket_gray)
```

```
plt.figure()
```

```
plt.imshow(edges, cmap='gray', interpolation='gaussian')  
plt.title('Canny Detector')  
plt.axis('off')  
plt.show()
```

```
# Fill holes in the edges  
fill_im = nd.binary_fill_holes(edges)  
plt.figure()  
plt.imshow(fill_im, cmap='gray')  
plt.title('Region Filling')  
plt.axis('off')  
plt.show()
```

```
# Create an elevation map using the Sobel filter  
elevation_map = filters.sobel(rocket_gray)  
plt.figure()  
plt.imshow(elevation_map, cmap='gray')  
plt.title('Elevation Map')  
plt.axis('off')  
plt.show()
```

```
# Define markers for watershed  
markers = np.zeros_like(rocket_gray, dtype=np.int32)  
markers[rocket_gray < 0.4] = 1  
markers[rocket_gray > 0.6] = 2  
  
plt.figure()  
plt.imshow(markers, cmap='gray')  
plt.title('Markers')  
plt.axis('off')  
plt.show()
```

```
# Apply watershed segmentation
segmentation_result = segmentation.watershed(elevation_map, markers)

plt.figure()
plt.imshow(segmentation_result, cmap='gray')
plt.title('Watershed Segmentation')
plt.axis('off')
plt.show()

# Fill holes in the segmentation result
segmentation_filled = nd.binary_fill_holes(segmentation_result - 1)
label_rock, _ = nd.label(segmentation_filled)

# Create a label overlay
image_label_overlay = color.label2rgb(label_rock, image=rocket_gray, bg_label=0)

# Display the contour overlay and label overlay
fig, (ax1, ax2) = plt.subplots(1, 2, figsize=(24, 16), sharey=True)
ax1.imshow(rocket_gray, cmap='gray')
ax1.contour(segmentation_filled, [0.5], linewidths=1.8, colors='w')
ax1.set_title('Contour Overlay')
ax2.imshow(image_label_overlay)
ax2.set_title('Label Overlay')
plt.show()
```

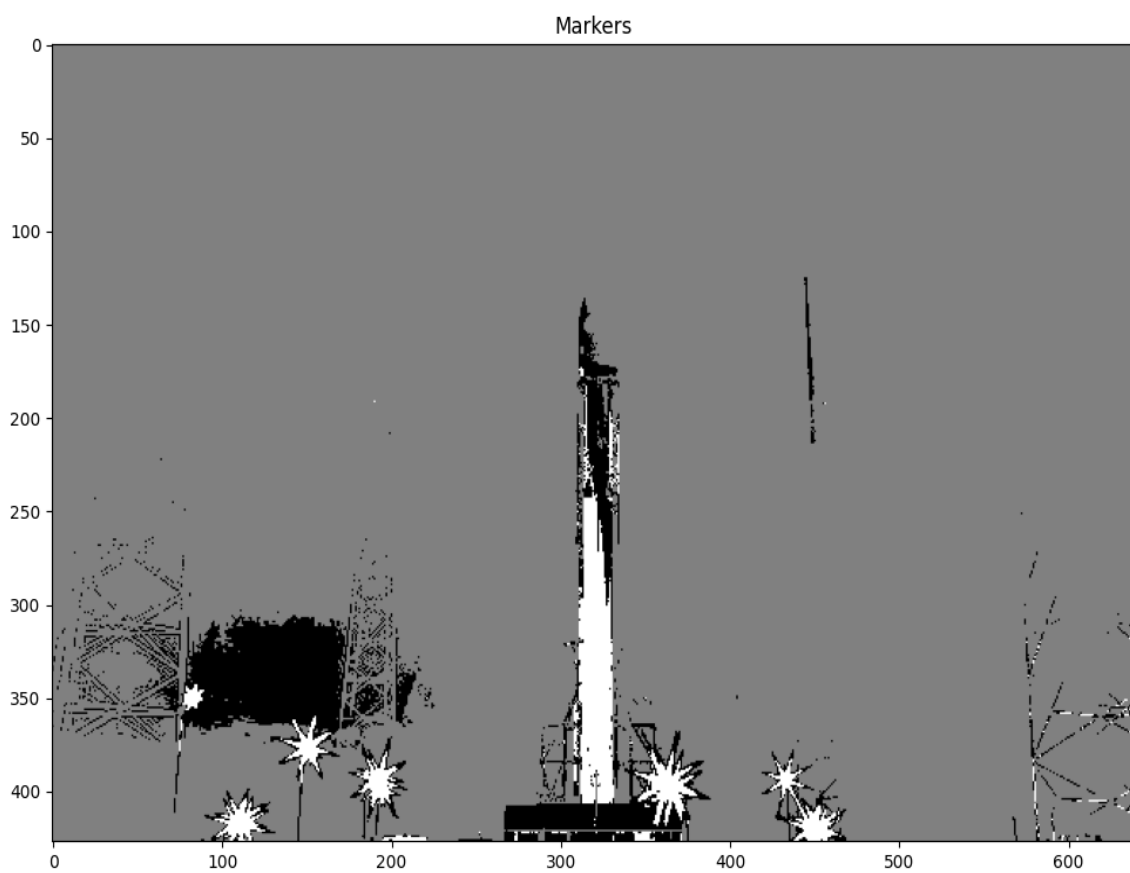
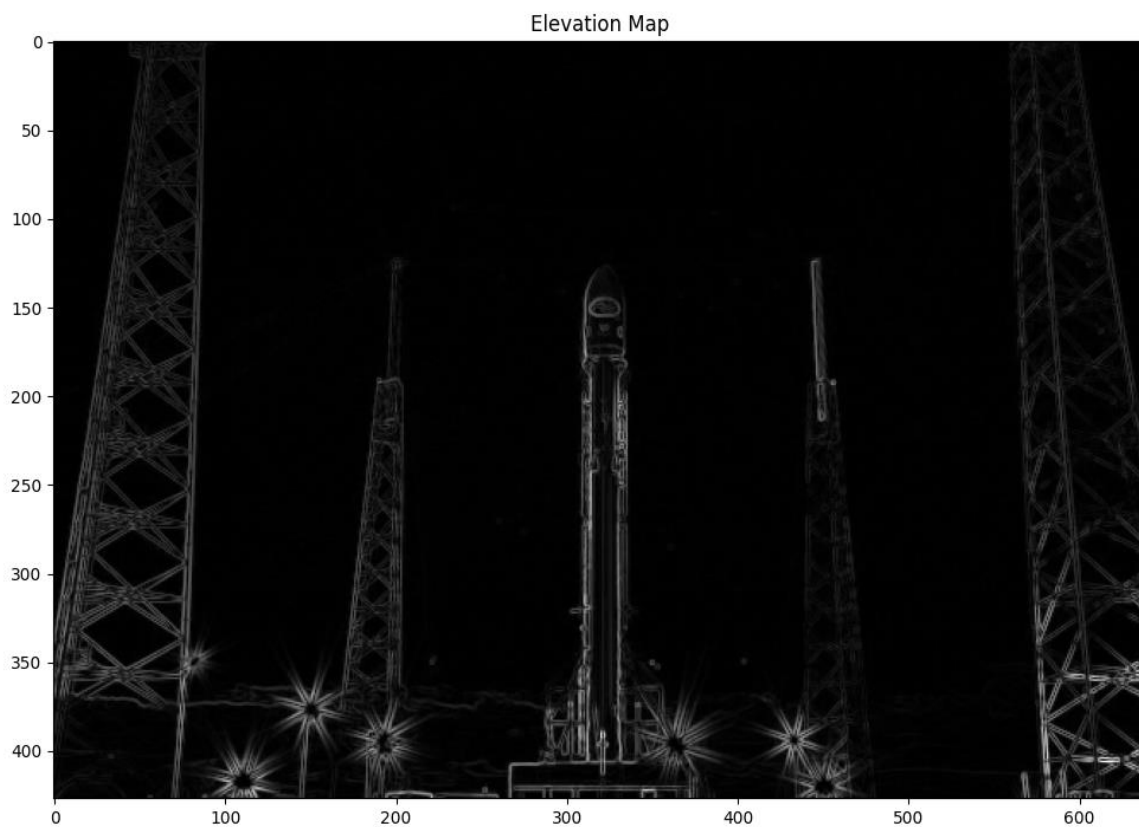
Output:

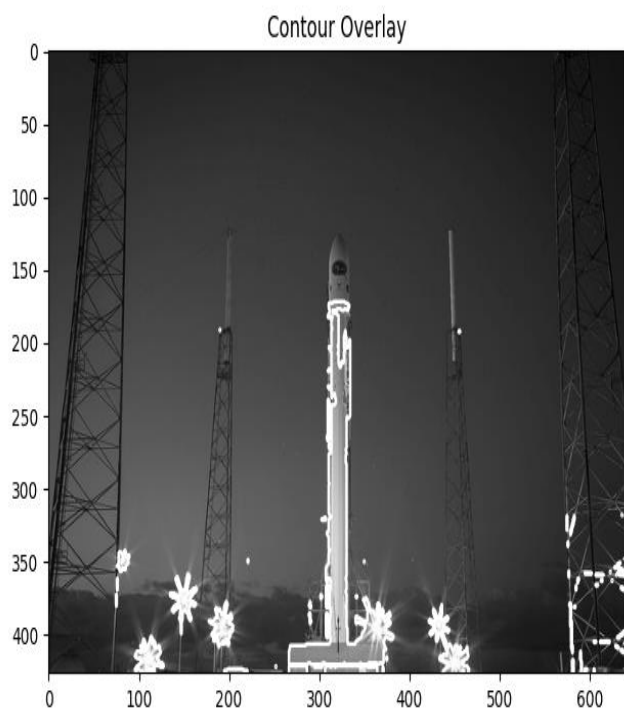
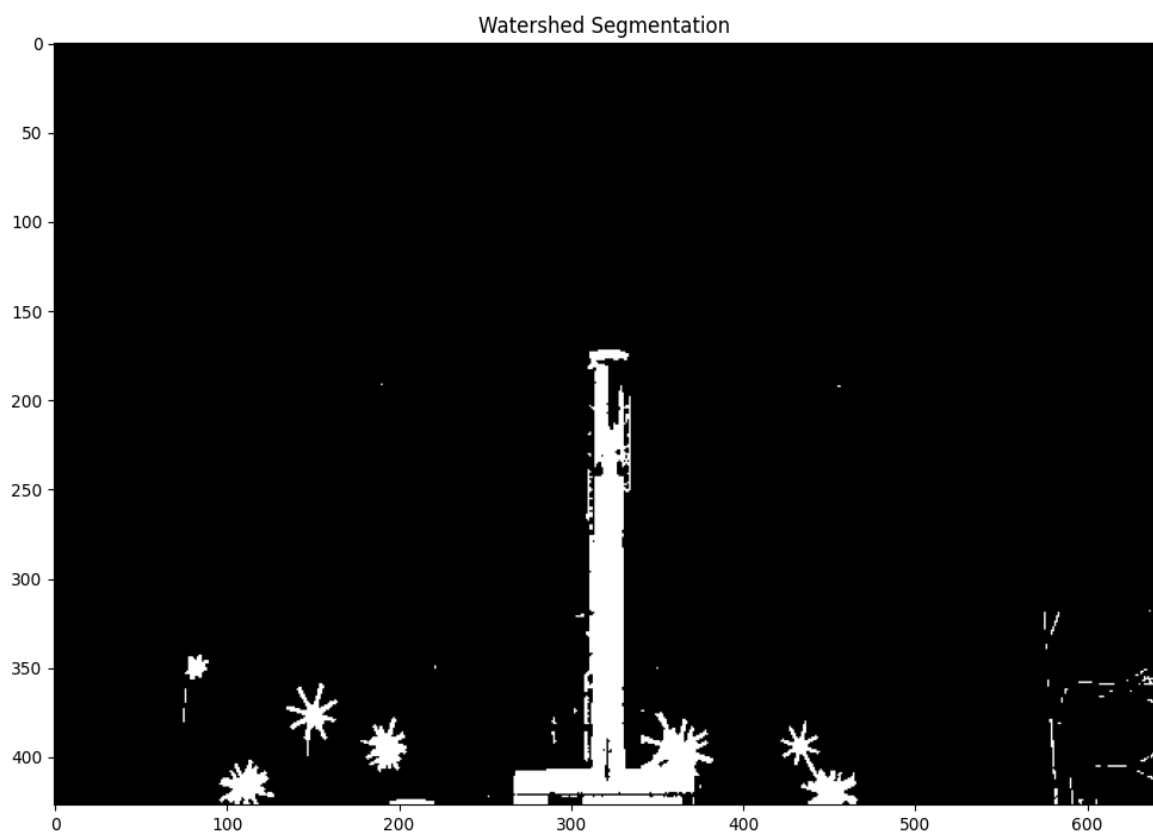
Original Image



Canny detector







Result:

Hence, the region based segmentation of an image has been successfully executed.