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/******
 * Includes
#include "mpi.h"
#include <stdio.h>
#include <stdlib.h>
* Defines
#define PARTICLES 1000000
/******
 * Data Structures
 *******
typedef struct
     float x, y, z, w;
} vec4D;
/*****
* Global Variables
 ********
// particle position and velocity
vec4D pos[PARTICLES];
vec4D vel[PARTICLES];
// current force being applied to the particles
vec4D force;
// inverse mass of the particles
float inv_mass[PARTICLES];
// step in time
float dt = 0.01f;
double temperature;
/*******
* Main Execution
 ********
int main( int argc, char *argv[] )
   int i, j, k;
   int numprocs, myid;
   float time;
   float dt_inv_mass;
   double mytemp = 0.0;
   int end_of_time = 0;
   double starttime, endtime;
   MPI_Init(&argc, &argv);
   // numprocs must evenly divide into 100
   MPI_Comm_size(MPI_COMM_WORLD, &numprocs);
   MPI_Comm_rank(MPI_COMM_WORLD, &myid);
   // No error or type checking is done!
   if (myid == 0)
     printf("I am 0\n");
     printf("Enter end of time: ");
scanf("%d", &end_of_time);
     printf("You entered: %d\n", end_of_time);
   starttime = MPI_Wtime();
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MPI_Bcast(&end_of_time, 1, MPI_INT, 0, MPI_COMM_WORLD);
// Initialize velocities with the random numbers between 0 and 1
for (i = myid; i < PARTICLES; i += numprocs)</pre>
   vel[i].x = drand48();
   vel[i].y = drand48();
   vel[i].z = drand48();
if (myid == 0)
   printf("Particle Velocities Initialized\n");
// Initialize mass
for (i = myid; i < PARTICLES; i += numprocs)</pre>
   inv_mass[i] = 1.0;
if (myid == 0)
   printf("Inv_Masses Initialized\n");
// Initialize the x, y, z force components of each particle with 0.01 \,
force.x = 0.01;
force.y = 0.01;
force.z = 0.01;
if (myid == 0)
   printf("Force Initialized\n");
// Initialize Positions
for (i = myid; i < 100; i += numprocs)</pre>
   for (j = myid; j < 100; j += numprocs)
      for (k = myid; k < 100; k += numprocs)
         pos[i*(100*100) + j*100 + k].x = i * 0.1;
         pos[i*(100*100) + j*100 + k].y = j * 0.1;
pos[i*(100*100) + j*100 + k].z = k * 0.1;
   }
}
if (myid == 0)
   printf("Particle Positions Initialized\n");
\ensuremath{//} For each step in time
for (time = 0; time < end_of_time; time += dt)</pre>
   mytemp = 0;
   //temperature = 0;
   // For each particle
   // each processor handles 1/4th the particles per timeslice
   for (i = myid; i < PARTICLES; i += numprocs)</pre>
      // Compute the new position and velocity
      // as acted upon by the force f.
     pos[i].x = vel[i].x * dt + pos[i].x;
      pos[i].y = vel[i].y * dt + pos[i].y;
      pos[i].z = vel[i].z * dt + pos[i].z;
      dt_inv_mass = dt * inv_mass[i];
     vel[i].x = dt_inv_mass * force.x + vel[i].x;
vel[i].y = dt_inv_mass * force.y + vel[i].y;
      vel[i].z = dt_inv_mass * force.z + vel[i].z;
```