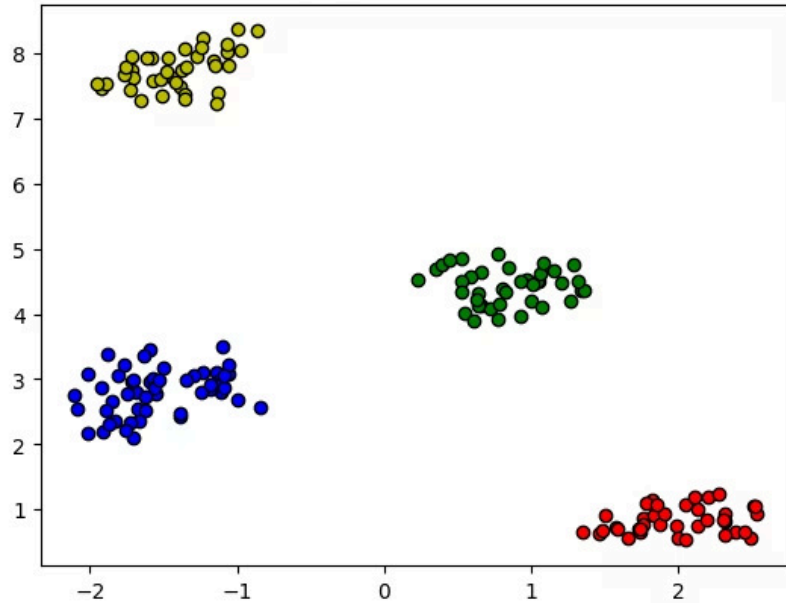


number of clusters: 4



# Clustering: K-Means and DBSCAN

NDL Lab 5 - 11/9/2025

# Attendance: "Clustering"



# Eboard Applications



# What is Clustering?

## Unsupervised Grouping

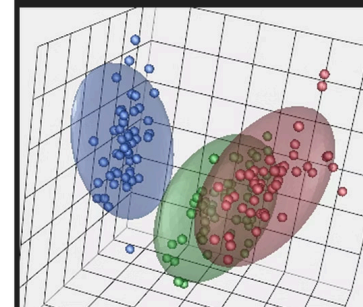
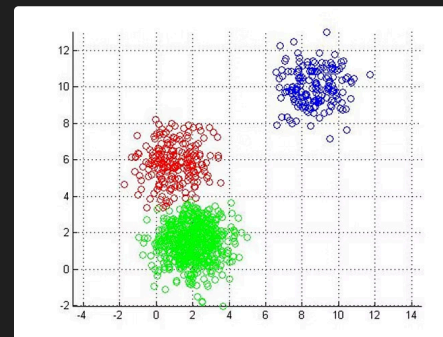
Clustering is an unsupervised learning technique used to group similar data points together based on inherent patterns.

## Key Applications

It is fundamental for pattern discovery, effective data segmentation, and identifying anomalies or outliers within a dataset.

## Real-World Impact

- Customer Segmentation
- Image Recognition & Compression
- Bioinformatics (Gene analysis)

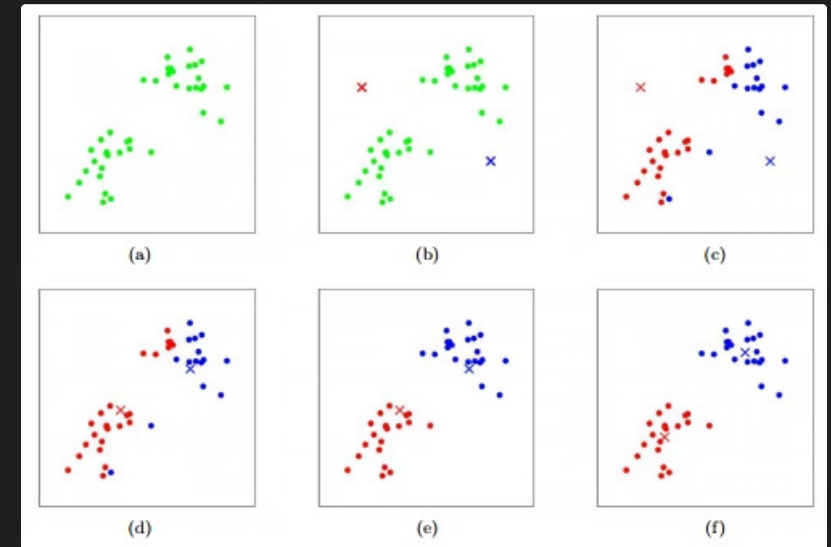


# Introducing K-Means Clustering

K-Means is one of the simplest and most popular partition-based clustering algorithms. It aims to partition **N** observations into **K** distinct, non-overlapping clusters.

- **The Goal:** Minimize the variance within each cluster, ensuring high intra-cluster similarity.
- **The Process:** It follows an iterative refinement approach: assign data points to the nearest centroid, then update the centroid position. This repeats until cluster assignments stabilize.

K-Means is intuitive and highly scalable for massive datasets with a clear structure.



# How K-Means Works: Step-by-Step

The K-Means algorithm systematically refines cluster definitions through iteration until convergence is reached.

1

## Define K

Choose the number of clusters (K) that the data must be partitioned into.

2

## Initialize Centroids

Randomly select K initial centroids, representing the center of each cluster.

3

## Assign Points

Assign every data point to its closest centroid, typically using Euclidean distance.

4

## Recalculate Centroids

Compute the mean of all points assigned to a cluster; this new mean becomes the updated centroid.

5

## Repeat

Continue the assignment and recalculation steps until the centroids no longer move significantly (convergence).

# K-Means: Strengths and Limitations

## Strengths



### Speed & Efficiency

Fast and computationally efficient, making it excellent for very large datasets.



### Simplicity

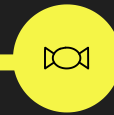
Easy to understand and implement, with results that are straightforward to interpret.

## Limitations



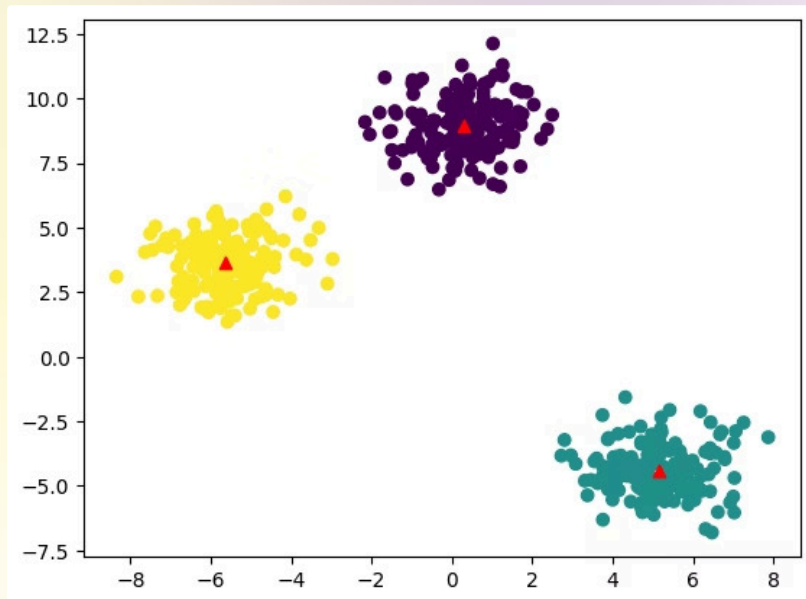
### Parameter Sensitivity

Dependent on number of clusters and initial positions of centroids



### Shape Assumption

Performs poorly when clusters are not spherical, unevenly sized, or have varying densities or outliers

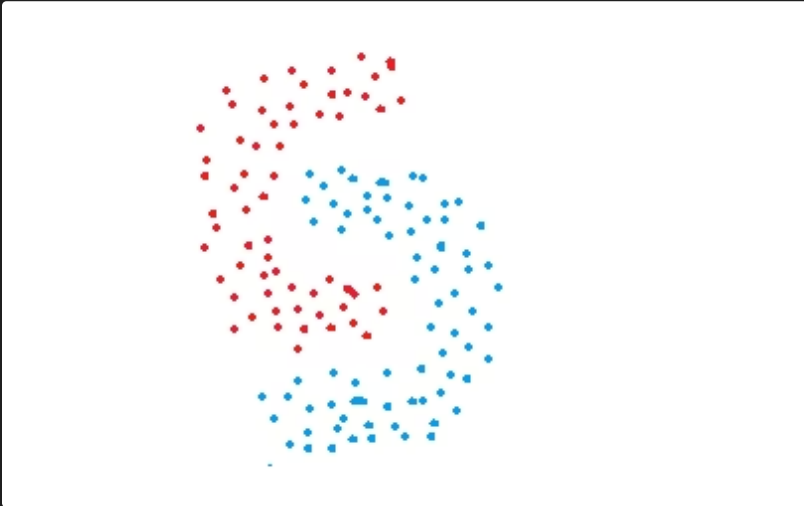


# Colab





# Introducing DBSCAN: Density-Based Clustering



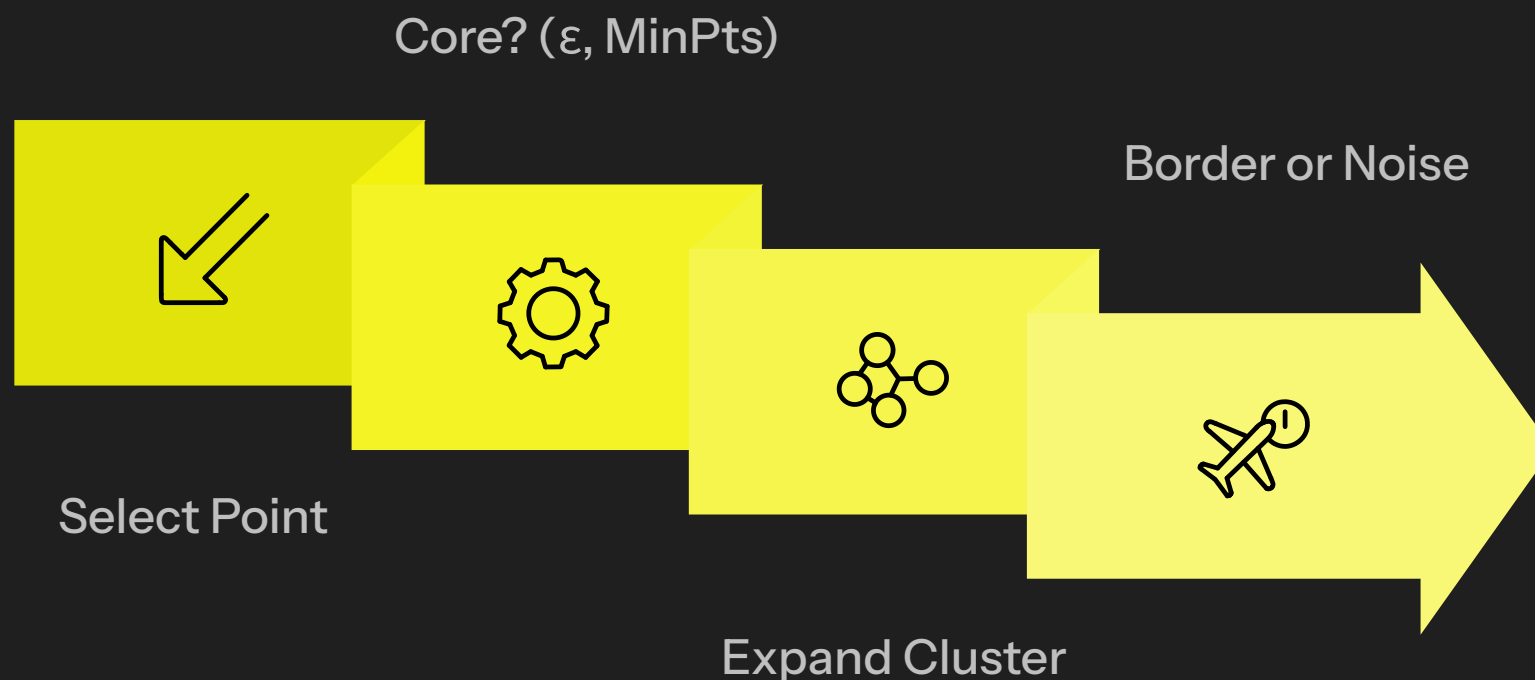
DBSCAN (Density-Based Spatial Clustering of Applications with Noise) approaches clustering from a different perspective, focusing on the density of data points.

It identifies clusters as areas of high density, separated by areas of low density, allowing it to discover clusters of **arbitrary shape**.

- Groups points based on what other points they are close to
- Automatically separates points into **Core**, **Border**, and **Noise** (outliers).
- Excels where K-Means fails: recognizing non-spherical clusters and explicitly handling noise.

# How DBSCAN Works: Step-by-Step

DBSCAN builds clusters by iteratively connecting neighboring points.



## Core Point

A point with at least **MinPts** neighbors (other points) within the distance  $\epsilon$  (epsilon).

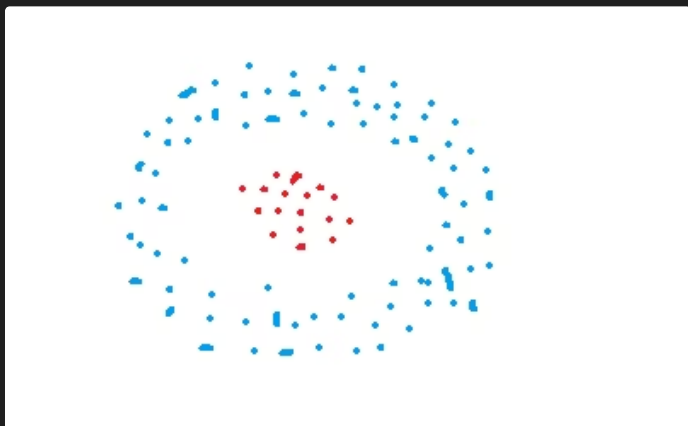
## Border Point

A point that is within  $\epsilon$  of a Core Point but has fewer than **MinPts** neighbors (not a Core Point)

## Noise Point

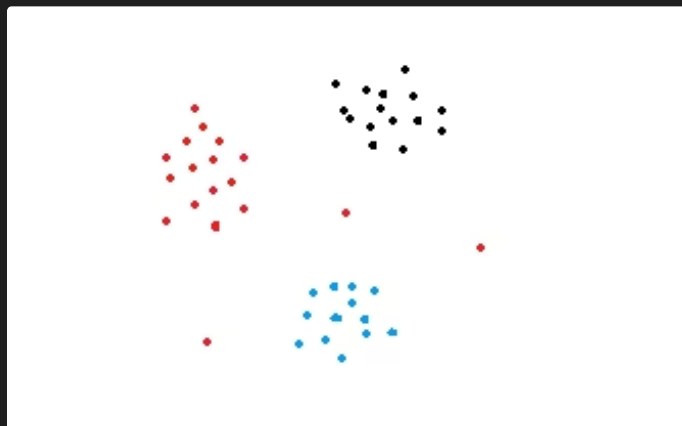
A point that is neither a Core Point nor a Border Point. These are considered outliers.

# DBSCAN: Strengths and Limitations



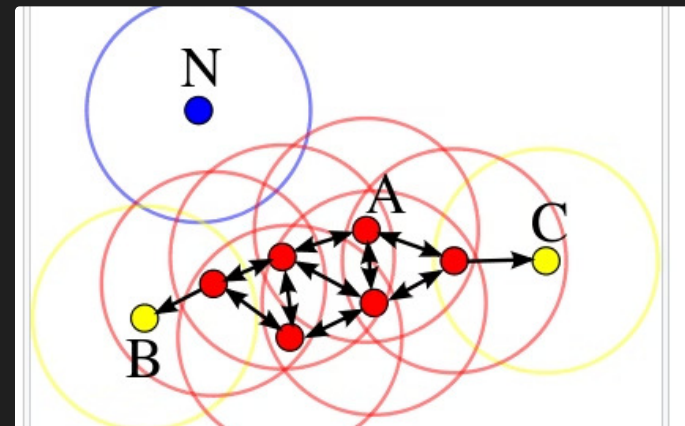
## Handles Complex Shapes

Its density-based approach allows it to identify clusters of arbitrary shapes



## Robust to Noise

Outliers are explicitly labeled as noise, minimizing their impact on the final clustering result.



## Parameter Sensitivity

Performance is highly dependent on setting the optimal values for  $\epsilon$  (radius) and **MinPts**.

# Choosing Between K-Means and DBSCAN

The choice of algorithm depends entirely on the nature and structure of your data.

## K-Means

1

Ideal for structured, clean data where cluster boundaries are well-defined.

- Clusters are **spherical** and balanced.
- You **know K** (number of clusters) beforehand.
- Focus is on scalability and speed.

2

## DBSCAN

Essential for data with natural gaps, complex shapes, or significant noise contamination.

- Clusters have **irregular shapes** or varying densities.
- You want to **identify noise**/outliers explicitly.
- The number of clusters is unknown or variable.

📌 Experimentation is key: Test both methods if your initial assumptions about the data structure are unclear.

# Summary & Takeaway

## Data Guides Choice

Cluster shape, density, and noise level are the primary factors determining which algorithm is superior.

## Practical Application

Explore implementations in scikit-learn (Python) to apply these concepts hands-on.



## Different Tools

K-Means optimizes for partition homogeneity; DBSCAN optimizes for density connectedness and noise detection.

## Complementary Insights

Use both methods to gain a comprehensive understanding of complex datasets.

Selecting the right clustering algorithm transforms raw data into meaningful segments for actionable insights.