

# Problem Set 0

①

1) a)  $f(x) = \frac{1}{2} x^T A x + b^T x$  ; calc.  $\nabla f(x)$  when  
A is symmetric (i.e.  $A^T = A$ )

$\nabla f(x) \Rightarrow$  in this case is called  
"Gradient of the Quadratic  
Form."

Solution from lectures:

Assuming we know

①  $x^T A x = \text{Tr}(x^T A x)$

②  $\nabla_x \text{tr}(x^T A x) = A x + A^T x$

③  $A^T = A \rightarrow (A + A^T)x = 2Ax$

$$\nabla_x \left( \frac{1}{2} x^T A x \right) = \frac{1}{2} \times 2 A x = A x$$

Now,  $\frac{\partial (x^T y)}{\partial x_i} = y$

$$\therefore \frac{\partial (b^T x)}{\partial x_i} = \frac{\partial (x^T b)}{\partial x_i} = b$$

$$\therefore \nabla f(x) = A x + b$$

Otherwise:

$$\frac{\partial A^T x}{\partial x} = \frac{\partial x^T A}{\partial x} = A^T ; \quad \frac{\partial x}{\partial x} = I$$

Identity matrix

$$\begin{aligned} \frac{df(g(x), h(x))}{dx} &= g^T(x) \frac{\partial h(x)}{\partial x} + h^T(x) \frac{\partial g(x)}{\partial x} \\ &= x^T \frac{\partial A x}{\partial x} + (A x)^T \frac{\partial x}{\partial x} \\ &= x^T A + x^T A^T I \\ &= x^T (A + A^T) \end{aligned}$$

$$\nabla f = \left( \frac{df}{dx} \right)^T = \left( x^T (A + A^T) \right)^T = (A^T + A)x$$

b)  $f(x) = g(h(x))$        $g: \mathbb{R} \rightarrow \mathbb{R}$   
 $h: \mathbb{R}^n \rightarrow \mathbb{R}$

$$\begin{aligned} \frac{\partial g(h(x))}{\partial x_i} &= \frac{\partial g(h(x))}{\partial h(x)} \cdot \frac{\partial (h(x))}{\partial x_i} \\ &= g'(h(x)) \cdot \frac{\partial (h(x))}{\partial x_i} \\ &= g'(h(x)) \nabla h(x) \end{aligned}$$

$$\begin{aligned} \therefore \nabla f(x) &= \nabla g(h(x)) \\ &= g'(h(x)) \nabla h(x) \end{aligned}$$

c)  $f(x) = \frac{1}{2} x^T A x + b^T x$  ;  $A$  is symmetric  
 $b \in \mathbb{R}^n$  is a vector.  $\nabla^2 f(x)$ ? (find hessian)

$$\nabla^2 f(x) = \begin{bmatrix} \frac{\partial^2 f(x)}{\partial x_1^2} & \frac{\partial^2 f(x)}{\partial x_1 \partial x_2} & \dots & \frac{\partial^2 f(x)}{\partial x_1 \partial x_n} \\ \frac{\partial^2 f(x)}{\partial x_2 \partial x_1} & \frac{\partial^2 f(x)}{\partial x_2^2} & \dots & \frac{\partial^2 f(x)}{\partial x_2 \partial x_n} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial^2 f(x)}{\partial x_n \partial x_1} & \frac{\partial^2 f(x)}{\partial x_n \partial x_2} & \dots & \frac{\partial^2 f(x)}{\partial x_n^2} \end{bmatrix}$$

$$= \left[ \frac{\partial \nabla f(x)}{\partial x_1} \quad \frac{\partial \nabla f(x)}{\partial x_2} \quad \dots \quad \frac{\partial \nabla f(x)}{\partial x_n} \right] \quad (2)$$

we know  $\nabla f(x) = Ax + b$

$$= \left[ \frac{\partial (Ax + b)}{\partial x_1} \quad \frac{\partial (Ax + b)}{\partial x_2} \quad \dots \right]$$

$$= \begin{bmatrix} A_{11} & A_{12} & \dots & A_{1n} \\ A_{21} & A_{22} & \dots & A_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ A_{n1} & A_{n2} & \dots & A_{nn} \end{bmatrix} = A$$

d) i)  $f(x) = g(a^T x)$   $g: \mathbb{R} \rightarrow \mathbb{R}$  is differentiable  
 $a \in \mathbb{R}^n$  is a vector

$$= \frac{\partial g(a^T x)}{\partial (a^T x)} \cdot \frac{\partial (a^T x)}{\partial x_i}$$

$$= g'(a^T x) a$$

ii) We may generalize the hessian to

$$\frac{\partial^2 f}{\partial x_i \partial x_j}$$

$$\frac{\partial^2 (g(h(x)))}{\partial x_i \partial x_j} = \frac{\partial^2 g(h(x))}{\partial (h(x))^2} \frac{\partial (h(x))}{\partial x_i} \frac{\partial (h(x))}{\partial x_j}$$

$$= g'(h(x)) \frac{\partial h(x)}{\partial x_i} \frac{\partial h(x)}{\partial x_j}$$



Now  $\frac{\partial^2 g(a^T x)}{\partial x_i \partial x_j} = g''(a^T x) \frac{\partial (a^T x)}{\partial x_i} \frac{\partial (a^T x)}{\partial x_j}$

We know,  $\frac{\partial (a^T x)}{\partial x_i} = a_i$

$$\therefore g''(a^T x) \frac{\partial (a^T x)}{\partial x_i} \frac{\partial (a^T x)}{\partial x_j} = g''(a^T x) a_i a_j$$

$$\nabla^2 f(x) = \nabla^2 g(a^T x)$$

$$= g'' a^T x \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{bmatrix}$$

$$= g'' a^T x a a^T$$



2) a)  $z \in \mathbb{R}^n$  be an  $n$ -vector (3)  
 $A = z z^T$ ; prove  $A$  is positive semidefinite

$$A = z z^T$$

$$A^T = (z z^T)^T = z^T (z^T)^T = z^T z$$

if  $z$  is invertible then, take any  $x \in \mathbb{R}^n$   
$$x^T z z^T x = (z^T x)^T (z^T x) > 0$$
$$= (x^T z)^2 > 0$$

b) If  $n=1$ , the null space is a zero/null vector and its dimension is zero.

$\{0\}$  has dimension 0

A vector in itself has no dimension

A subspace has dimension

$\mathbb{R}^3$  has dimension 3 because we find it in a linearly independent set with 3 elements.

Subsets of  $\{0\}$  is empty set & whole set  
In whole set zero vector is linearly dependent  
(you can't find a zero linear combination with non-zero coefficients out of its elements), so only linearly independent set is empty set which has dimension 0.

c)  $A \in \mathbb{R}^{n \times n} \rightarrow$  positive semidefinite

$B \in \mathbb{R}^{m \times n} \rightarrow$  arbitrary where  $m, n \in \mathbb{N}$

is  $B A B^T$  a positive semidefinite? Yes

for  $x \in \mathbb{R}^m$  we can define  
a vector  $v = B^T x \in \mathbb{R}^n$

$$x^T (B A B^T) x = (B^T x)^T A (B^T x)$$



$$= v^T A v \geq 0$$

as this holds true for any vector  $v$ .  
( $v^T A v$ )

3) a)  $A \in \mathbb{R}^{n \times n}$  is diagonalizable i.e.  $A = T \Lambda T^{-1}$   
where  $T$  is an invertible  $T \in \mathbb{R}^{n \times n}$

$\Lambda = \text{diag}(\lambda_1, \lambda_2, \dots, \lambda_n)$  is diagonal

$t^{(i)}$  denote the cols of  $T$ ,  $T = [t^{(1)}, t^{(2)}, \dots, t^{(n)}]$   
 $t^{(i)} \in \mathbb{R}^n$

$$\text{Show } A t^{(i)} = \lambda_i t^{(i)}$$

so that eigen vector pairs of  $A$  are  
 $(t^{(i)}, \lambda_i)$

Proof: If  $T$  is invertible

$$T^{-1} A T = \Lambda \quad \& \quad A = T \Lambda T^{-1}$$

$$A = T \Lambda T^{-1}$$

$$A T = T \Lambda$$

$$A [t^{(1)} \ t^{(2)} \ \dots \ t^{(n)}] = [t^{(1)} \ t^{(2)} \ \dots \ t^{(n)}] \begin{bmatrix} \lambda_1 & 0 & 0 & 0 \\ 0 & \lambda_2 & 0 & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \lambda_n \end{bmatrix}$$

$$[A t^{(1)} \ A t^{(2)} \ \dots \ A t^{(n)}] = [\lambda_1 t^{(1)} \ \lambda_2 t^{(2)} \ \dots \ \lambda_n t^{(n)}]$$

$$A t^{(i)} = \lambda_i t^{(i)}$$

where  $\{(\lambda_i, t_i)\}_{i=1}^n$  are the eigenvalue  
- eigen vector pairs of  $A$ .

b)  $U \in \mathbb{R}^{n \times n}$  is orthogonal if  $U^T U = I$  (4)

Spectral Theorem

$A \in \mathbb{R}^{n \times n}$  is symmetric i.e.  $A = A^T$

then  $A$  is diagonalizable by a real orthogonal matrix

$\Lambda \in \mathbb{R}^{n \times n}$  is a diagonal matrix

$U \in \mathbb{R}^{n \times n}$  is orthogonal such that  $U^T A U = \Lambda$  or  $A = U \Lambda U^T$

&  $\lambda_i = \lambda_i(A)$  is the  $i$ th eigenvalue of  $A$

If  $U = [u^{(1)} \dots u^{(n)}]$  is orthogonal  $u^{(i)} \in \mathbb{R}^n$

&  $A = U \Lambda U^T$ , then  $u^{(i)}$  is eigenvector

of  $A$  &  $A u^{(i)} = \lambda_i u^{(i)}$ ,  $\Lambda = \text{diag}(\lambda_1, \dots, \lambda_n)$

(just like previous question)

$$A = U \Lambda U^T \quad \text{or} \quad U A U^T = \Lambda$$

$$A U = U \Lambda U^T U$$

$$A U = U \Lambda$$

$$A \begin{bmatrix} u^{(1)} & u^{(2)} & \dots & u^{(n)} \end{bmatrix} = \begin{bmatrix} u^{(1)} & u^{(2)} & \dots & u^{(n)} \end{bmatrix} \begin{bmatrix} \lambda_1 & \dots & 0 \\ 0 & \lambda_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \lambda_n \end{bmatrix}$$

$$\begin{bmatrix} A u^{(1)} & A u^{(2)} & \dots & A u^{(n)} \end{bmatrix} = \begin{bmatrix} \lambda_1 u^{(1)} & \lambda_2 u^{(2)} & \dots & \lambda_n u^{(n)} \end{bmatrix}$$

$$A u^{(i)} = \lambda_i u^{(i)}$$

$$c) \quad A t^{(i)} = \lambda_i t^{(i)}$$

$$(t^{(i)})^T A t^{(i)} = \lambda_i \|t^{(i)}\|_2$$

$$= \lambda_i \geq 0$$