

# Volume 3: Graph Algorithms & Advanced Data Structures

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### **BFS, DFS, Dijkstra, Union-Find, Topological Sort**

**Target:** Infosys L3 Specialist Programmer

**Edition:** 2025

**Focus:** Graph problems constitute 15-20% of coding round

### **Preface**

Graph problems test **algorithmic maturity**—the ability to model real-world scenarios as graphs and apply appropriate traversal/search strategies.

Infosys L3 expects:

- Clean BFS/DFS templates (codable in <5 minutes)
- Shortest path algorithms (Dijkstra for weighted graphs)
- Cycle detection in directed/undirected graphs
- Topological sorting for dependency resolution

**Pattern Recognition:** 80% of graph problems use BFS or DFS as foundation.

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## Chapter 1: Graph Representations

### 1.1 Adjacency List vs Adjacency Matrix

Aspect	Adjacency List	Adjacency Matrix
<b>Space</b>	$O(V + E)$	$O(V^2)$
<b>Check Edge</b>	$O(\text{degree})$	$O(1)$
<b>Iterate Neighbors</b>	$O(\text{degree})$	$O(V)$
<b>Best For</b>	Sparse graphs ( $E \ll V^2$ )	Dense graphs, quick edge lookup

**Sparse Graph** (social network):  $E \approx V$

**Dense Graph** (complete graph):  $E \approx V^2$

**Infosys Standard:** Use adjacency list (most graphs are sparse).

### 1.2 C++ Implementation

**Adjacency List:**

```
#include <vector>
#include <list>
using namespace std;

// Unweighted graph
vector<vector<int>> graph(n); // n vertices
graph[u].push_back(v); // Edge u → v

// Weighted graph
vector<vector<pair<int, int>>> graph(n);
graph[u].push_back({v, weight}); // Edge u → v with weight
```

**Adjacency Matrix:**

```
vector<vector<int>> graph(n, vector<int>(n, 0));
graph[u][v] = 1; // Edge u → v

// Weighted:
graph[u][v] = weight;
```

### 1.3 Python Implementation

```
from collections import defaultdict

# Adjacency list<a></a>
graph = defaultdict(list)
graph[u].append(v)

# Weighted<a></a>
graph = defaultdict(list)
graph[u].append((v, weight))
```

## Chapter 2: Breadth-First Search (BFS)

### 2.1 Concept

BFS explores level-by-level (like ripples in water).

Applications:

- Shortest path in **unweighted graph**
- Level-order traversal of tree
- Connected components
- Bipartite graph check

Time:  $O(V + E)$ , Space:  $O(V)$

### 2.2 Template (C++)

```
#include <queue>
#include <vector>;
using namespace std;

void bfs(vector<vector<int>> &graph, int start) {
    int n = graph.size();
    vector<bool> visited(n, false);
    queue<int> q;

    q.push(start);
    visited[start] = true;

    while (!q.empty()) {
        int u = q.front();
        q.pop();

        // Process u
        cout << u << " ";

        for (int v : graph[u]) {
            if (!visited[v]) {
                visited[v] = true;
                q.push(v);
            }
        }
    }
}
```

## 2.3 Shortest Path in Unweighted Graph

**Problem:** Find shortest distance from source to all vertices.

**Solution:**

```
vector<int> shortestPath(vector<vector<int>>& graph, int start) {
    int n = graph.size();
    vector<int> dist(n, -1); // -1 = unreachable
    queue<int> q;

    q.push(start);
    dist[start] = 0;

    while (!q.empty()) {
        int u = q.front();
        q.pop();

        for (int v : graph[u]) {
            if (dist[v] == -1) { // Not visited
                dist[v] = dist[u] + 1;
                q.push(v);
            }
        }
    }
    return dist;
}
```

**Example:**

```
Graph: 0 → 1 → 2
      ↓   ↓
      3 → 4 ← 5

Start = 0
dist = [0, 1, 2, 1, 2, 3]
```

## 2.4 Python Template

```
from collections import deque

def bfs(graph, start):
    visited = set()
    queue = deque([start])
    visited.add(start)

    while queue:
        u = queue.popleft()
        print(u, end=' ')

        for v in graph[u]:
            if v not in visited:
                visited.add(v)
                queue.append(v)
```

## 2.5 Problem: Number of Islands (Infosys Medium)

**Statement:** Given 2D grid of '1's (land) and '0's (water), count islands.

**Input:**

```
[  
    ["1", "1", "0", "0", "0"],  
    ["1", "1", "0", "0", "0"],  
    ["0", "0", "1", "0", "0"],  
    ["0", "0", "0", "1", "1"]  
]
```

**Output:** 3

**Approach:** BFS from each unvisited '1', mark all connected '1's.

**C++ Solution:**

```
int numIslands(vector<vector<char>>& grid) {  
    if (grid.empty()) return 0;  
  
    int m = grid.size(), n = grid[0].size();  
    int count = 0;  
  
    auto bfs = [&](int i, int j) {  
        queue<pair<int, int>> q;  
        q.push({i, j});  
        grid[i][j] = '0'; // Mark visited  
  
        int dirs[4][2] = {{-1, 0}, {1, 0}, {0, -1}, {0, 1}};  
  
        while (!q.empty()) {  
            auto [x, y] = q.front();  
            q.pop();  
  
            for (auto& d : dirs) {  
                int nx = x + d[0], ny = y + d[1];  
                if (nx >= 0 && nx < m && ny >= 0 && ny < n && grid[nx][ny] == '1') {  
                    grid[nx][ny] = '0';  
                    q.push({nx, ny});  
                }  
            }  
        }  
    };  
  
    for (int i = 0; i < m; i++) {  
        for (int j = 0; j < n; j++) {  
            if (grid[i][j] == '1') {  
                bfs(i, j);  
                count++;  
            }  
        }  
    }  
    return count;  
}
```

**Complexity:**  $O(m \times n)$

## Chapter 3: Depth-First Search (DFS)

### 3.1 Concept

DFS explores as deep as possible before backtracking.

Applications:

- Cycle detection
- Topological sort
- Connected components
- Path finding (not necessarily shortest)

Time:  $O(V + E)$ , Space:  $O(V)$  for recursion stack

### 3.2 Template (Recursive)

```
void dfs(vector<vector<int>>& graph, int u, vector<bool>& visited) {
    visited[u] = true;

    // Process u
    cout << u << " ";

    for (int v : graph[u]) {
        if (!visited[v]) {
            dfs(graph, v, visited);
        }
    }
}

// Wrapper
void dfsGraph(vector<vector<int>>& graph, int start) {
    int n = graph.size();
    vector<bool> visited(n, false);
    dfs(graph, start, visited);
}
```

### 3.3 Template (Iterative with Stack)

```
void dfsIterative(vector<vector<int>>& graph, int start) {
    int n = graph.size();
    vector<bool> visited(n, false);
    stack<int> st;

    st.push(start);

    while (!st.empty()) {
        int u = st.top();
        st.pop();

        if (visited[u]) continue;
        visited[u] = true;

        cout << u << " ";

        for (int v : graph[u]) {
            if (!visited[v]) {
                st.push(v);
            }
        }
    }
}
```

```

        }
    }
}

```

### 3.4 Cycle Detection (Undirected Graph)

**Approach:** DFS with parent tracking. If we visit a neighbor that's:

- Not parent → Cycle exists
- Not visited → Continue DFS

```

bool hasCycleDFS(vector<vector<int>>& graph, int u,
                  int parent, vector<bool>& visited) {
    visited[u] = true;

    for (int v : graph[u]) {
        if (!visited[v]) {
            if (hasCycleDFS(graph, v, u, visited))
                return true;
        } else if (v != parent) {
            return true; // Cycle found
        }
    }
    return false;
}

bool hasCycle(vector<vector<int>>& graph) {
    int n = graph.size();
    vector<bool> visited(n, false);

    for (int i = 0; i < n; i++) {
        if (!visited[i]) {
            if (hasCycleDFS(graph, i, -1, visited))
                return true;
        }
    }
    return false;
}

```

### 3.5 Cycle Detection (Directed Graph)

**Approach:** Use color scheme:

- White (0): Not visited
- Gray (1): In current DFS path
- Black (2): Completely processed

Cycle exists if we encounter **Gray node** (back edge).

```

bool hasCycleDFS(vector<vector<int>>& graph, int u,
                  vector<int>& color) {
    color[u] = 1; // Gray (in path)

    for (int v : graph[u]) {
        if (color[v] == 1) return true; // Back edge
        if (color[v] == 0 && hasCycleDFS(graph, v, color))
            return true;
    }
}

```

```

        color[u] = 2; // Black (done)
        return false;
    }

bool hasCycleDirected(vector<vector<int>> &graph) {
    int n = graph.size();
    vector<int> color(n, 0); // White

    for (int i = 0; i < n; i++) {
        if (color[i] == 0) {
            if (hasCycleDFS(graph, i, color))
                return true;
        }
    }
    return false;
}

```

## Chapter 4: Shortest Path (Dijkstra)

### 4.1 Concept

**Dijkstra's Algorithm:** Shortest path in **weighted graph with non-negative weights**.

**Greedy Strategy:** Always expand nearest unvisited node.

**Time:**  $O((V + E) \log V)$  with priority queue

**Space:**  $O(V)$

### 4.2 Template (C++)

```

#include <queue>;
#include <vector>;
using namespace std;

vector<int> dijkstra(vector<vector<pair<int, int>> &graph,
                      int start) {
    int n = graph.size();
    vector<int> dist(n, INT_MAX);

    // Min-heap: {distance, node}
    priority_queue<pair<int, int>, vector<pair<int, int>>, greater<int> pq;

    dist[start] = 0;
    pq.push({0, start});

    while (!pq.empty()) {
        auto [d, u] = pq.top();
        pq.pop();

        if (d > dist[u]) continue; // Outdated entry

        for (auto [v, w] : graph[u]) {
            if (dist[u] + w < dist[v]) {
                dist[v] = dist[u] + w;
                pq.push({dist[v], v});
            }
        }
    }
}

```

```

    return dist;
}

```

### 4.3 Python Template

```

import heapq

def dijkstra(graph, start):
    n = len(graph)
    dist = [float('inf')] * n
    dist[start] = 0

    pq = [(0, start)]  # (distance, node)

    while pq:
        d, u = heapq.heappop(pq)

        if d > dist[u]:
            continue

        for v, w in graph[u]:
            if dist[u] + w < dist[v]:
                dist[v] = dist[u] + w
                heapq.heappush(pq, (dist[v], v))

    return dist

```

### 4.4 Problem: Network Delay Time (Infosys Medium)

**Statement:** Given network of n nodes, edges with travel times, find minimum time for signal to reach all nodes from source k.

**Input:** times = [[2,1,1], [2,3,1], [3,4,1]], n = 4, k = 2

**Output:** 2 (max distance from source)

**Solution:** Dijkstra + find maximum distance.

```

int networkDelayTime(vector<vector<int>>& times, int n, int k) {
    vector<vector<pair<int, int>> graph(n + 1);

    for (auto& t : times) {
        graph[t[0]].push_back({t[1], t[2]});
    }

    vector<int> dist = dijkstra(graph, k);

    int maxDist = 0;
    for (int i = 1; i <= n; i++) {
        if (dist[i] == INT_MAX) return -1; // Unreachable
        maxDist = max(maxDist, dist[i]);
    }
    return maxDist;
}

```

## Chapter 5: Topological Sort

### 5.1 Concept

**Topological Order:** Linear ordering of vertices in DAG (Directed Acyclic Graph) where for every edge  $u \rightarrow v$ ,  $u$  comes before  $v$ .

**Applications:**

- Task scheduling with dependencies
- Course prerequisites
- Build systems (Makefile)

**Algorithm:** DFS with post-order traversal (reverse finish times).

### 5.2 Template (DFS-Based)

```
void topSortDFS(vector<vector<int>>& graph, int u,
                 vector<bool>& visited, stack<int>& st) {
    visited[u] = true;

    for (int v : graph[u]) {
        if (!visited[v]) {
            topSortDFS(graph, v, visited, st);
        }
    }

    st.push(u); // Add after all descendants
}

vector<int> topologicalSort(vector<vector<int>>& graph) {
    int n = graph.size();
    vector<bool> visited(n, false);
    stack<int> st;

    for (int i = 0; i < n; i++) {
        if (!visited[i]) {
            topSortDFS(graph, i, visited, st);
        }
    }

    vector<int> result;
    while (!st.empty()) {
        result.push_back(st.top());
        st.pop();
    }
    return result;
}
```

### 5.3 Kahn's Algorithm (BFS-Based)

**Approach:** Remove nodes with in-degree 0 repeatedly.

```
vector<int> topologicalSortKahn(vector<vector<int>>& graph) {
    int n = graph.size();
    vector<int> inDegree(n, 0);

    for (int u = 0; u < n; u++) {
        for (int v : graph[u]) {
            inDegree[v]++;
        }
    }
```

```

        inDegree[v]++;
    }

}

queue<int> q;
for (int i = 0; i < n; i++) {
    if (inDegree[i] == 0) q.push(i);
}

vector<int> result;
while (!q.empty()) {
    int u = q.front();
    q.pop();
    result.push_back(u);

    for (int v : graph[u]) {
        inDegree[v]--;
        if (inDegree[v] == 0) q.push(v);
    }
}

// If result.size() < n, cycle exists
return result;
}

```

## 5.4 Problem: Course Schedule (Infosys Medium)

**Statement:** Given numCourses and prerequisites (course pairs), determine if all courses can be finished.

**Input:** numCourses = 2, prerequisites = [[1,0]]

**Output:** true (take course 0, then 1)

**Input:** numCourses = 2, prerequisites = [[1,0], [0,1]]

**Output:** false (cycle: 0 → 1 → 0)

**Solution:** Check if topological sort produces all courses.

```

bool canFinish(int numCourses, vector<vector<int>> &prerequisites) {
    vector<vector<int>> graph(numCourses);

    for (auto& p : prerequisites) {
        graph[p[1]].push_back(p[0]); // p[1] → p[0]
    }

    vector<int> sorted = topologicalSortKahn(graph);
    return sorted.size() == numCourses;
}

```

## Chapter 6: Union-Find (Disjoint Set)

### 6.1 Concept

**Union-Find:** Data structure for tracking disjoint sets with operations:

- **Find:** Which set does element belong to?
- **Union:** Merge two sets

**Applications:**

- Detect cycles in undirected graph
- Kruskal's MST algorithm
- Network connectivity

**Optimizations:**

- **Path Compression:** Flatten tree during Find
- **Union by Rank:** Attach smaller tree to larger

**Time:**  $O(\alpha(n))$  per operation ( $\alpha = \text{inverse Ackermann}$ , practically constant)

## 6.2 Template (C++)

```
class UnionFind {
private:
    vector<int> parent, rank;

public:
    UnionFind(int n) {
        parent.resize(n);
        rank.resize(n, 0);
        for (int i = 0; i < n; i++) {
            parent[i] = i;
        }
    }

    int find(int x) {
        if (parent[x] != x) {
            parent[x] = find(parent[x]); // Path compression
        }
        return parent[x];
    }

    bool unite(int x, int y) {
        int rootX = find(x);
        int rootY = find(y);

        if (rootX == rootY) return false; // Already connected

        // Union by rank
        if (rank[rootX] < rank[rootY]) {
            parent[rootX] = rootY;
        } else if (rank[rootX] > rank[rootY]) {
            parent[rootY] = rootX;
        } else {
            parent[rootY] = rootX;
            rank[rootX]++;
        }
        return true;
    }

    bool connected(int x, int y) {
        return find(x) == find(y);
    }
};
```

### 6.3 Problem: Number of Connected Components

**Statement:** Count connected components in undirected graph.

**Solution:** Union-Find, count remaining roots.

```
int countComponents(int n, vector<vector<int>> &edges) {
    UnionFind uf(n);

    for (auto& e : edges) {
        uf.unite(e[0], e[1]);
    }

    unordered_set<int> roots;
    for (int i = 0; i < n; i++) {
        roots.insert(uf.find(i));
    }

    return roots.size();
}
```

## Chapter 7: Advanced: Strongly Connected Components (SCC)

### 7.1 Concept

**SCC:** Maximal subgraph where every vertex is reachable from every other vertex.

**Algorithm:** Kosaraju's (two DFS passes)

1. DFS on original graph, record finish times
2. DFS on transposed graph in reverse finish order
3. Each DFS tree in step 2 is one SCC

**Time:**  $O(V + E)$

### 7.2 Template (Kosaraju's)

```
void dfs1(vector<vector<int>> &graph, int u,
          vector<bool> &visited, stack<int> &st) {
    visited[u] = true;
    for (int v : graph[u]) {
        if (!visited[v]) dfs1(graph, v, visited, st);
    }
    st.push(u);
}

void dfs2(vector<vector<int>> &graphT, int u,
          vector<bool> &visited, vector<int> &component) {
    visited[u] = true;
    component.push_back(u);
    for (int v : graphT[u]) {
        if (!visited[v]) dfs2(graphT, v, visited, component);
    }
}

vector<vector<int>> findSCCs(vector<vector<int>> &graph) {
    int n = graph.size();

    // Step 1: DFS and stack
```

```

vector<bool> visited(n, false);
stack<int> st;
for (int i = 0; i < n; i++) {
    if (!visited[i]) dfs1(graph, i, visited, st);
}

// Step 2: Transpose graph
vector<vector<int>> graphT(n);
for (int u = 0; u < n; u++) {
    for (int v : graph[u]) {
        graphT[v].push_back(u);
    }
}

// Step 3: DFS on transpose
fill(visited.begin(), visited.end(), false);
vector<vector<int>> sccs;

while (!st.empty()) {
    int u = st.top();
    st.pop();
    if (!visited[u]) {
        vector<int> component;
        dfs2(graphT, u, visited, component);
        sccs.push_back(component);
    }
}

return sccs;
}

```

## Practice Problem Set

### Easy (BFS/DFS Basics)

1. Clone Graph
2. Flood Fill
3. Max Area of Island
4. Surrounded Regions
5. Pacific Atlantic Water Flow

### Medium (Shortest Path, Topological Sort)

6. Course Schedule
7. Course Schedule II
8. Network Delay Time
9. Cheapest Flights Within K Stops
10. Minimum Height Trees

### Hard (Advanced)

11. Word Ladder
12. Alien Dictionary
13. Critical Connections in Network
14. Reconstruct Itinerary

## References

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