

Solving optimization problems

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Basics...

Linear optimization

```
using JuMP, HiGHS
m = Model(optimizer_with_attributes(HiGHS.Optimizer))
@variable(m, x1 >= 0)
@variable(m, x2 >= 0)
@objective(m, Min, 50x1 + 70x2)
@constraint(m, 200x1 + 2000x2 >= 9000)
@constraint(m, 100x1 + 30x2 >= 300)
@constraint(m, 9x1 + 11x2 >= 60)
optimize!(m)
JuMP.value.([x1, x2])
```

Note – how to type indexes in Julia

- `julia> x`
- `julia> x_`
- `julia> x_1`
- `julia> x_1<TAB>`
- `julia> x1`

... and Integer programming

```
using JuMP, HiGHS
m = Model(optimizer_with_attributes(HiGHS.Optimizer))
@variable(m, x1 >= 0, Int)
@variable(m, x2 >= 0)
@objective(m, Min, 50x1 + 70x2)
@constraint(m, 200x1 + 2000x2 >= 9000)
@constraint(m, 100x1 + 30x2 >= 300)
@constraint(m, 9x1 + 11x2 >= 60)
optimize!(m)
```

How it works - metaprogramming

```
julia> code = Meta.parse("x=5")  
:(x = 5)
```

```
julia> dump(code)  
Expr  
  head: Symbol =  
  args: Array{Any}((2,))  
    1: Symbol x  
    2: Int64 5
```

```
julia> eval(code)  
5
```

```
julia> x  
5
```

Macros – hello world...

```
macro sayhello(name)
    return :( println("Hello, ", $name) )
end
```

```
julia> macroexpand(Main,:(@sayhello("aa")))
:((Main.println)("Hello, ", "aa"))
```

```
julia> @sayhello "world!"
Hello, world!
```

Macro @variable

```
julia> @macroexpand @variable(m, x₁ >= 0)
quote
  (JuMP.validmodel)(m, :m)
  begin
    #1###361 = begin
      let
        #1###361 = (JuMP.constructvariable!)(m, getfield(JuMP, Symbol("#_error#107")){Tuple{Symbol,Expr}}{(:m, :(x₁ >= 0))}, 0,
        Inf, :Default, (JuMP.string)(:x₁), NaN)
        #1###361
      end
    end
    (JuMP.registervar)(m, :x₁, #1###361)
    x₁ = #1###361
  end
end
```


Some of JuMP Solvers (over 40 as of today)

Solver	Julia Package	License	LP	SOCP	MILP	NLP	MINLP	SDP
<u>Artelys Knitro</u>	<u>KNITRO.jl</u>	Comm.				X	X	
<u>BARON</u>	<u>BARON.jl</u>	Comm.				X	X	
<u>Bonmin</u>	<u>AmpNLWriter.jl</u>	EPL	X		X	X	X	
	<u>CoinOptServices.jl</u>							
<u>Cbc</u>	<u>Cbc.jl</u>	EPL			X			
<u>Clp</u>	<u>Clp.jl</u>	EPL	X					
<u>Couenne</u>	<u>AmpNLWriter.jl</u>	EPL	X		X	X	X	
	<u>CoinOptServices.jl</u>							
<u>CPLEX</u>	<u>CPLEX.jl</u>	Comm.	X	X	X			
<u>ECOS</u>	<u>ECOS.jl</u>	GPL	X	X				
<u>FICO Xpress</u>	<u>Xpress.jl</u>	Comm.	X	X	X			
<u>HiGHS</u>	<u>HiGHSMathProgInterfac e</u>	GPL	X		X			
<u>Gurobi</u>	<u>Gurobi.jl</u>	Comm.	X	X	X			
<u>Ipopt</u>	<u>Ipopt.jl</u>	EPL	X			X		
<u>MOSEK</u>	<u>Mosek.jl</u>	Comm.	X	X	X	X		X
<u>NLopt</u>	<u>NLopt.jl</u>	LGPL				X		
<u>QSOQ</u>	<u>QSOQ.jl</u>	MIT	X	X				X

JuMP

Transportation of good among
branches

Use case scenario

The Subway restaurant chain in Las Vegas has a total of 118 restaurants in different parts of the city.

18 restaurants have adjacent huge product warehouses that keep ingredients cool and fresh, moreover fresh vegetables are delivered only to those warehouses (rather than to every restaurant) daily at 3am.

Subway has signed a contract with a transportation agency and is billed by the multiple of the weight of transported goods and the distance.

Knowing the amount of available stock at each warehouse and the expected demand at each restaurant (measured in kg), the company needs to decide how the goods should be distributed among warehouses.

Transportation problem statement

- Variables

- x_{ij} – number of units transported for i -th supplier to j -th requester
- c_{ij} – unit transportation cost between i -th supplier to j -th requester

- Cost function C

$$C = \sum_{i=1}^m \sum_{j=1}^n c_{ij} x_{ij}$$

- Constraints:

suppliers have maximum capacity S_i

$$\sum_{j=1}^n x_{ij} \leq S_i$$

demand D_j must be met

$$\sum_{i=1}^m x_{ij} \geq D_j$$

Implementation in JuMP

```
m = Model(optimizer_with_attributes(HiGHS.Optimizer));
@variable(m, x[i=1:S, j=1:D])
@objective(m, Min, sum( x[i, j]*distance_mx[i, j] for i=1:S, j=1:D))
@constraint(m, x .>= 0)
for j=1:D
    @constraint(m, sum( x[i, j] for i=1:S) >= demand[j] )
end
for i=1:S
    @constraint(m, sum( x[i, j] for j=1:D) <= supply[i] )
end
optimize!(m)
termination_status(m)
```

JuMP

Travelling salesman problem

Use case scenario

The Subway restaurant chain in Las Vegas has a total of 118 restaurants in different parts of the city.

Company's manager plans to visit all restaurants during a single day.

What is the optimal order that restaurants should be visited?

Traveling salesman problem (TSP)

- Variables:

- c_{ft} – cost of travel from “ f ” to “ t ”
- x_{ft} – binary variable indicating 1 when agent travels from “ f ” to “ t ”

$$\text{Min} \sum_{f=1}^N \sum_{t=1}^N c_{ft} x_{ft}$$

TSP

$$\text{Min} \sum_{f=1}^N \sum_{t=1}^N c_{ft} x_{ft}$$

Each city visited once

$$\sum_{t=1}^N x_{ft} = 1 \quad \forall f \in \{1, \dots, N\}$$

$$\sum_{f=1}^N x_{ft} = 1 \quad \forall t \in \{1, \dots, N\}$$

City cannot visit itself

$$x_{ff} = 0 \quad \forall f \in \{1, \dots, N\}$$

Avoid two-city cycles

$$x_{ft} + x_{tf} \leq 1 \quad \forall f, t \in \{1, \dots, N\}$$

Other cycles:

/dynamically add a constraint whenever a cycle occurs/

Variables:

- c_{ft} – cost of travel from “ f ” to “ t ”
- x_{ft} – binary variable indicating 1 when agent travels from “ f ” to “ t ”

For more details see: <http://opensourc.es/blog/mip-tsp>

JuMP implementation

```
m = Model(optimizer_with_attributes(HiGHS.Optimizer));
@variable(m, x[f=1:N, t=1:N], Bin)
@objective(m, Min, sum( x[i, j]*distance_mx[i,j] for i=1:N,j=1:N))
@constraint(m, notself[i=1:N], x[i, i] == 0)
@constraint(m, oneout[i=1:N], sum(x[i, 1:N]) == 1)
@constraint(m, onein[j=1:N], sum(x[1:N, j]) == 1)
for f=1:N, t=1:N
    @constraint(m, x[f, t]+x[t, f] <= 1)
end
```

Getting a cycle

```
function getcycle(m, N)
    x_val = getvalue(x)
    cycle_idx = Vector{Int}()
    push!(cycle_idx, 1)
    while true
        v, idx = findmax(x_val[cycle_idx[end], 1:N])
        if idx == cycle_idx[1]
            break
        else
            push!(cycle_idx, idx)
        end
    end
    cycle_idx
end
```

Adding a constraint...

```
function solved(m, cycle_idx, N)
    println("cycle_idx: ", cycle_idx)
    println("Length: ", length(cycle_idx))
    if length(cycle_idx) < N
        cc = @constraint(m, sum(x[cycle_idx,cycle_idx])
            <= length(cycle_idx)-1)
        println("added a constraint")
        return false
    end
    return true
end
```

Iterating over the model

```
while true
    status = solve(m)
    println(status)
    cycle_idx = getcycle(m, N)
    if solved(m, cycle_idx, N)
        break;
    end
end
```

Gurobi.jl

- Commercial software
- Free for academic use
- Integrates with JuMP via Gurobi.jl
- Supports JuMP Lazy constraints (<http://www.juliaopt.org/JuMP.jl/0.18/callbacks.html>)

Gurobi callbacks

```
function getcycle(cb, N)
    x_val = callback_value.(Ref(cb), x)
    getcycle(x_val)
end
function callbackhandle(cb)
    cycle_idx = getcycle(cb, N)
    println("Callback! N= $N cycle_idx: ", cycle_idx)
    println("Length: ", length(cycle_idx))
    if length(cycle_idx) < N
        con = @build_constraint(sum(x[cycle_idx,cycle_idx]) <= length(cycle_idx)-1)
        MOI.submit(m, MOI.LazyConstraint(cb), con)
        println("added a lazy constraint")
    end
end
MOI.set(m, MOI.LazyConstraintCallback(), callbackhandle)
```

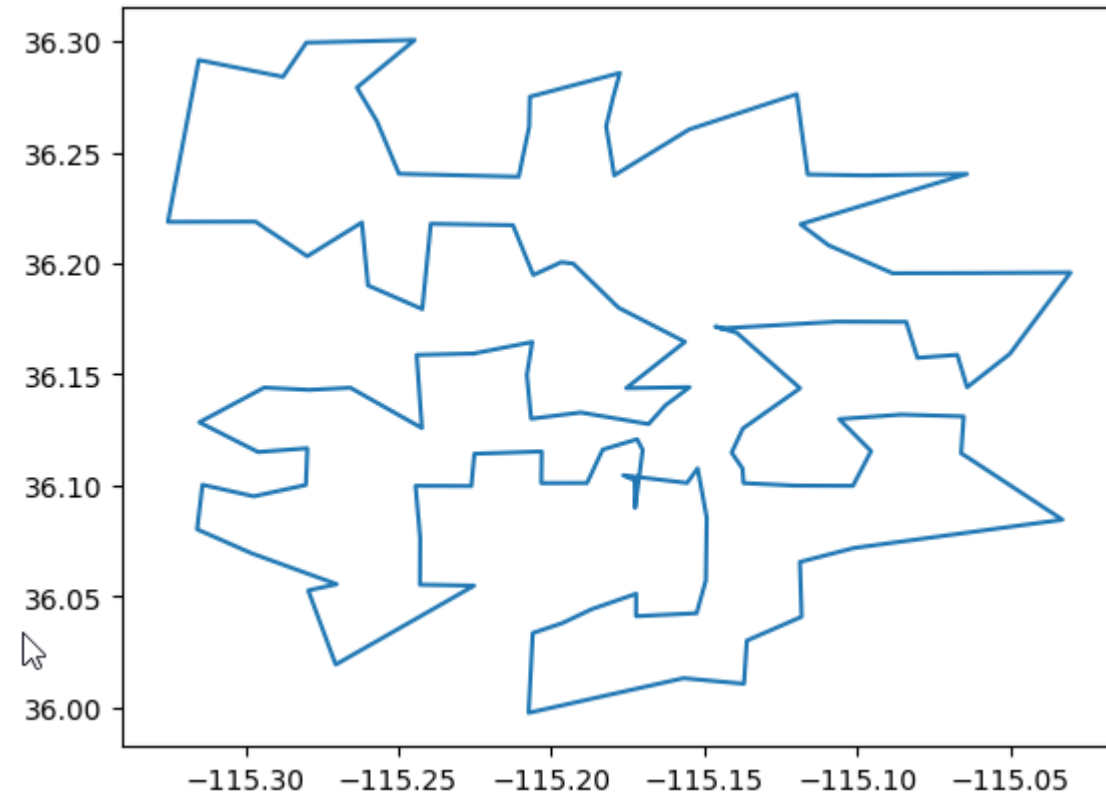
TravelingSalesmanHeuristics.jl

using TravelingSalesmanHeuristics

```
sol = TravelingSalesmanHeuristics.solve_tsp(  
distance_mx, quality_factor = 100)
```

More info:

<http://evanfields.github.io/TravelingSalesmanHeuristics.jl/latest/heuristics.html>



JuMP

Non-Linear Programming

Simple scenario

Estimate parameters of a quadratic form

$$y(\mathbf{x}_i) = \mathbf{x}_i^T \begin{bmatrix} a & b/2 \\ b/2 & c \end{bmatrix} \mathbf{x}_i, \text{ where } \mathbf{x}_i = \begin{bmatrix} x_i^1 \\ x_i^2 \end{bmatrix}$$

for a vector of observed values \mathbf{y} to minimize the observed error function

$$\sum_{i=1}^N (y(\mathbf{x}_i) - y_i)^2$$

Nonlinear optimization Julia

```
m = Model(optimizer_with_attributes(Ipopt.Optimizer));

@variable(m, aa[1:2,1:2])

function errs(aa)
    sum((y .- (x * aa) ) .* x * [1;1]) .^ 2)
end

@objective(m, Min, errs(aa))

optimize!(m)
```

Use case scenario

(source: Hart et al, Pyomo-optimization modeling in python, 2017)

Simulate dynamics of disease outbreak in a small community of 300 individuals (e.g. children at school)

Three possible states of a patient:

- susceptible (S)
- infected (I)
- recovered (R)

Infection spread model :

- N – population size
- α, β – model parameters

$$I_i = \frac{\beta I_{i-1}^\alpha S_{i-1}}{N}$$

$$S_i = S_{i-1} - I_i$$

Optimization problem for finding parameters α and β

S - susceptible

I - infected

N – population size

α, β – model parameters

SI - time indices $\{1, 2, 3, \dots\}$

C_i - known input (the actual
number of infected patients)

$$\min \sum_{i \in SI} (\varepsilon_i^I)^2$$

$$I_i = \frac{\beta I_{i-1}^\alpha S_{i-1}}{N} \quad \forall i \in SI \setminus \{1\}$$

$$S_i = S_{i-1} - I_i \quad \forall i \in SI \setminus \{1\}$$

$$C_i = I_i + \varepsilon_i^I$$

$$0 \leq I_i, S_i \leq N$$

$$0.5 \leq \beta \leq 70$$

$$0.5 \leq \alpha \leq 1.5$$

Model implementation in JuMP

- Input data (disease dynamics)

```
obs_cases = vcat(1,2,4,8,15,27,44,58,55,32,12,3,1,zeros(13))
```

Full model specification in JuMP

```
m = Model(optimizer_with_attributes(Ipopt.Optimizer));
@variable(m, 0.5 <= α <= 1.5)
@variable(m, 0.05 <= β <= 70)
@variable(m, 0 <= I_[1:SI_max] <= N)
@variable(m, 0 <= S[1:SI_max] <= N)
@variable(m, ε[1:SI_max])
@constraint(m, ε .== I_ .- obs_cases )
@constraint(m, I_[1] == 1)
for i=2:SI_max
    @NLconstraint(m, I_[i] == β*(I_[i-1]^α)*S[i-1]/N)
end
@constraint(m, S[1] == N)
for i=2:SI_max
    @constraint(m, S[i] == S[i-1]-I_[i])
end
@NLobjective(m, Min, sum(ε[i]^2 for i in 1:SI_max))
```

JuMP

Non-Linear Programming
for estimation of model parameters

Simple scenario

Estimate parameters of a quadratic form

$$y(\mathbf{x}_i) = \mathbf{x}_i^T \begin{bmatrix} a & b/2 \\ b/2 & c \end{bmatrix} \mathbf{x}_i, \text{ where } \mathbf{x}_i = \begin{bmatrix} x_i^1 \\ x_i^2 \end{bmatrix}$$

for a vector of observed values \mathbf{y} to minimize the observed error function

$$\sum_{i=1}^N (y(\mathbf{x}_i) - y_i)^2$$

Nonlinear optimization Julia

```
m = Model(optimizer_with_attributes(Ipopt.Optimizer));

@variable(m, aa[1:2,1:2])

function errs(aa)
    sum((y .- (x * aa) ) .* x * [1;1]) .^ 2)
end

@objective(m, Min, errs(aa))

optimize!(m)
```

Use case scenario

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S - susceptible

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N – population size

α, β – model parameters

SI - time indices $\{1, 2, 3, \dots\}$

C_i - known input (the actual
number of infected patients)

$$\min \sum_{i \in SI} (\varepsilon_i^I)^2$$

$$I_i = \frac{\beta I_{i-1}^\alpha S_{i-1}}{N} \quad \forall i \in SI \setminus \{1\}$$

$$S_i = S_{i-1} - I_i \quad \forall i \in SI \setminus \{1\}$$

$$C_i = I_i + \varepsilon_i^I$$

$$0 \leq I_i, S_i \leq N$$

$$0.5 \leq \beta \leq 70$$

$$0.5 \leq \alpha \leq 1.5$$

Model implementation in JuMP

- Input data (disease dynamics)

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obs_cases = vcat(1,2,4,8,15,27,44,58,55,32,12,3,1,zeros(13))
```

Full model specification in JuMP

```
m = Model(optimizer_with_attributes(Ipopt.Optimizer));
@variable(m, 0.5 <= α <= 1.5)
@variable(m, 0.05 <= β <= 70)
@variable(m, 0 <= I_[1:SI_max] <= N)
@variable(m, 0 <= S[1:SI_max] <= N)
@variable(m, ε[1:SI_max])
@constraint(m, ε .== I_ .- obs_cases )
@constraint(m, I_[1] == 1)
for i=2:SI_max
    @NLconstraint(m, I_[i] == β*(I_[i-1]^α)*S[i-1]/N)
end
@constraint(m, S[1] == N)
for i=2:SI_max
    @constraint(m, S[i] == S[i-1]-I_[i])
end
@NLobjective(m, Min, sum(ε[i]^2 for i in 1:SI_max))
```

JuMP

Multi-criteria optimization
for stock portfolio optimization

[additional material]

Stock portfolio optimization

- Estimate the weights vector

$$\vec{x} = [x_1 \ x_2 \ \cdots \ x_n]^T$$

where x_i represents the share of asset i in a portfolio: $\vec{1}^T \vec{x} = 1$

- maximize the expected return $x_p = \bar{p}^T \vec{x} = \sum_{i=1}^n x_i p_i$
- minimize the risk

for the variance-covariance
matrix:

$$\sigma_p^2 = \vec{x}^T V \vec{x} = \sum_{i=1}^n \sum_{j=1}^n x_i x_j \sigma_{i,j}$$

$$V = \begin{pmatrix} \sigma_{11} & \cdots & \sigma_{1n} \\ \vdots & \ddots & \vdots \\ \sigma_{n1} & \cdots & \sigma_{nn} \end{pmatrix}$$

Possible approaches

- Maximize the expected return, disregarding risk
- Minimize the expected risk, disregarding return
- Maximize the return for a given level of risk
- Minimize the risk for a given level of return
- **Maximize the risk AND minimize the return**
 ➔ multi-criteria optimization

Stock price data

- Top 10 Fortune 500 companies
- 3 years
- Daily opening and closing prices
- Expected return
 - average daily rate of return (for simplicity calculated as a difference between opening and closing price)
- Risk
 - calculate variance-covariance matrix for daily returns

Julia implementation – data processing

```
prices = CSV.read("10_stocks_3yr.csv", allowmissing=:none)
prices.rateOfRet =
    (prices.close-prices.open) ./ prices.open
dates = unstack(prices, :date, :Name, :rateOfRet)
const avg_rets = colwise(mean, dates[2:end])
const cov_mx = cov(Matrix(dates[2:end]))
```

Julia MultiJuMP model

```
m = multi_model(Ipopt.Optimizer)
@variable(m, 0 <= x[i=1:10] <= 1)
@constraint(m, sum(x) == 1)
@variable(m, risk)
@constraint(m, risk == x'*cov_mx*x)
@variable(m, rets)
@constraint(m, rets == avg_rets' * x)
@NLexpression(m, f_risk, risk)
@NLexpression(m, f_rets, rets)
```

Solving the model

```
iv1 = fill(0.1, 10) # Initial guess
obj1 = SingleObjective(f_risk, sense = MOI.MIN_SENSE,
                       iv = Dict{String,Any}("x[$i]" => iv1[i] for i in 1:length(iv1)))
obj2 = SingleObjective(f_rets, sense = MOI.MAX_SENSE)
md = get_multidata(m)
md.objectives = [obj1, obj2]
md.pointsperdim = 20

optimize!(m, method = NBI(false))
```

Plotting the Pareto-frontier

`Plots.pyplot()`

`Plots.plot(md)`

