

What's in a good representation?

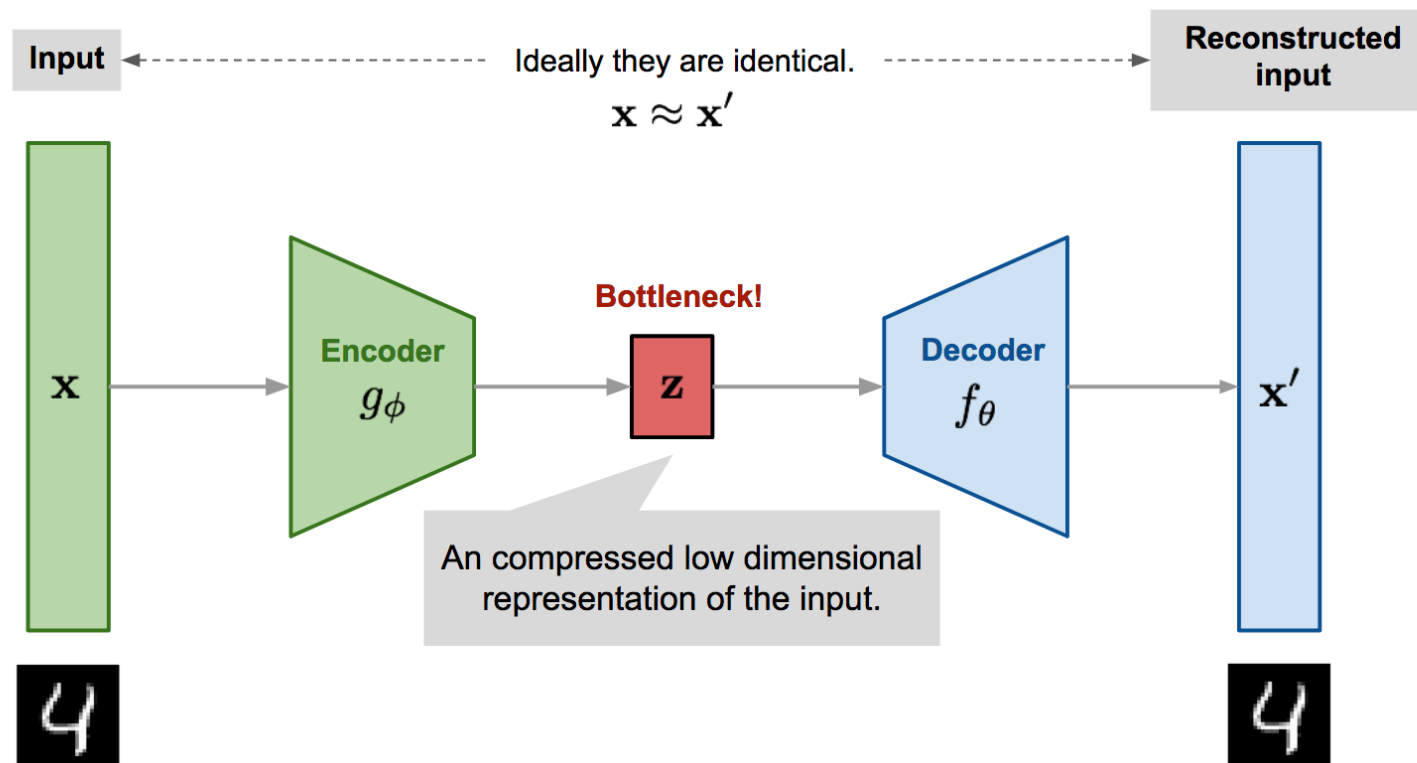
John Tan Chong Min

Aim

- Find a way to encode a suitable representation to perform decision making
- Such representation can also be how we store memories for use in the future

Autoencoders: Representation via Reconstruction

- Prioritises output clarity – may not disentangle well in latent space



Do you need to predict everything? (Recap)

- Some things in input space are not important to understand for your goals



Transformers: Representation via Prediction

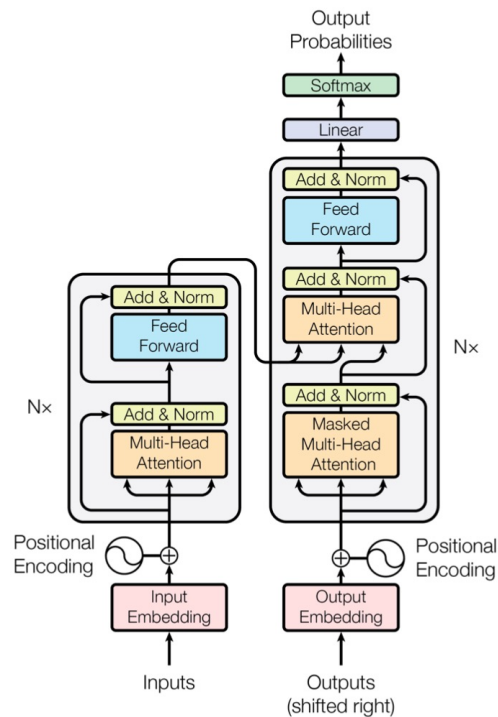
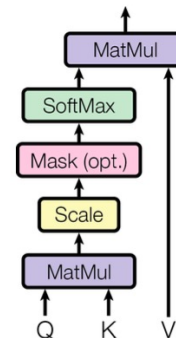


Figure 1: The Transformer - model architecture.

Scaled Dot-Product Attention



Multi-Head Attention

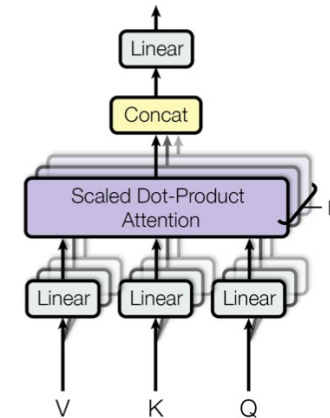


Figure 2: (left) Scaled Dot-Product Attention. (right) Multi-Head Attention consists of several attention layers running in parallel.

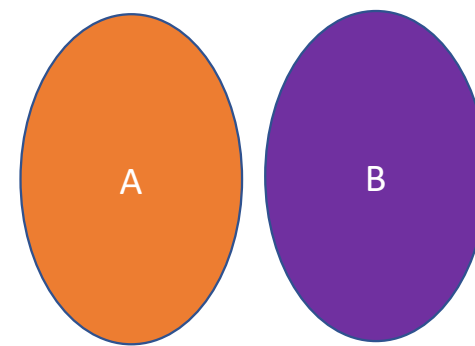
$$\text{Attention}(Q, K, V) = \text{softmax}\left(\frac{QK^T}{\sqrt{d_k}}\right)V$$

Taken from: Attention is all you need. Vaswani et al. (2017)

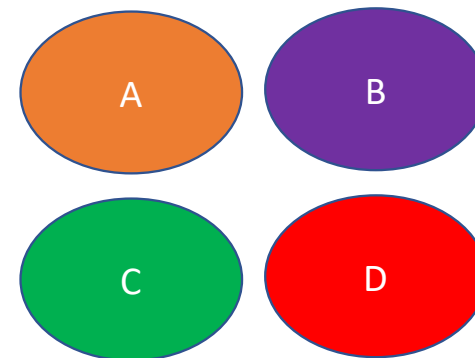
Large Self-Supervised Learning

- Self-supervised learning helps to learn better manifolds across large data
- Can work zero-shot on a new sample

Manifold of having only 2 classes

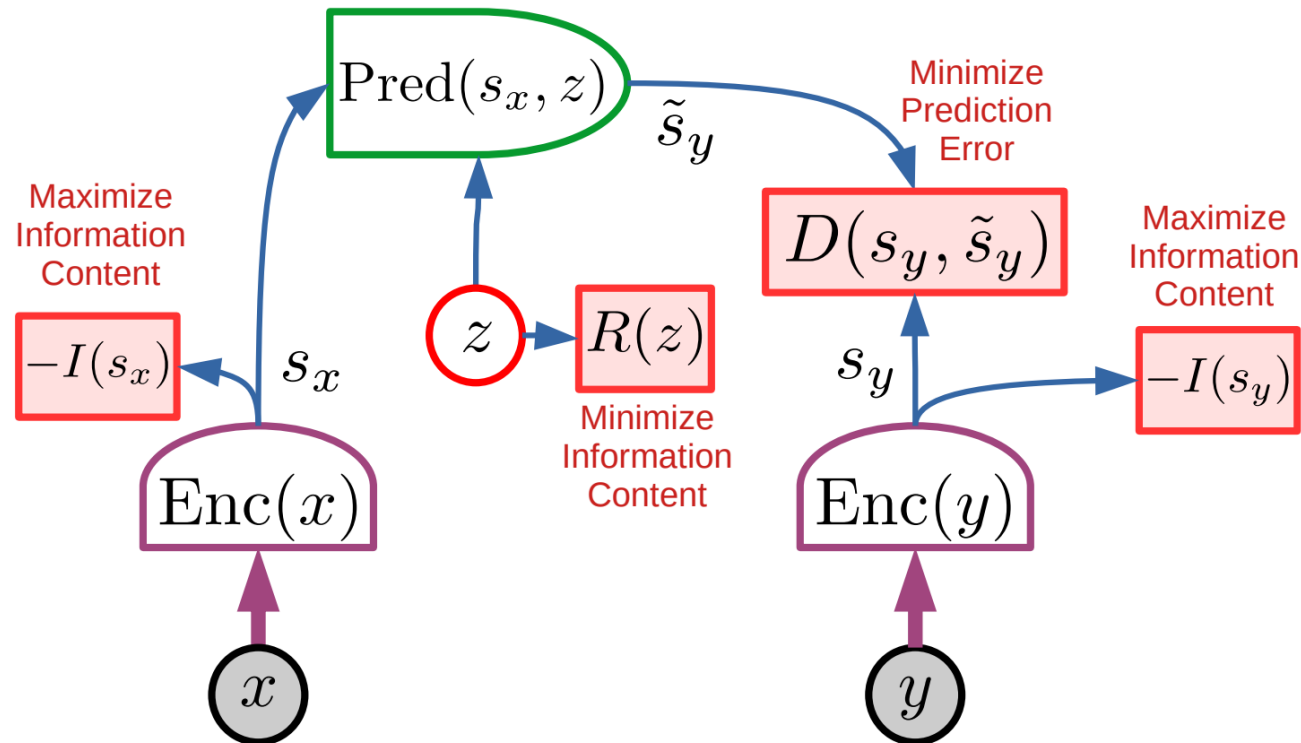


Manifold of having 4 classes



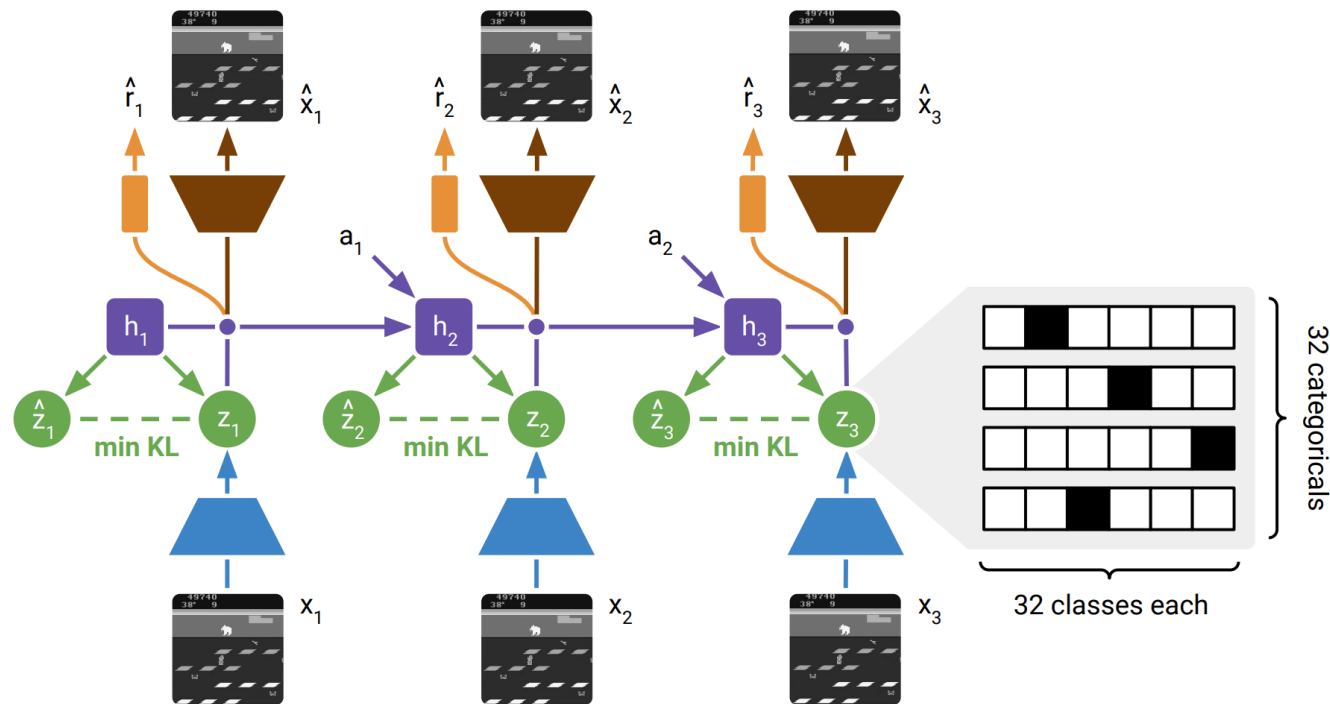
JEPA - Only use whatever is necessary to predict

- Prediction is done in latent space



World Modelling

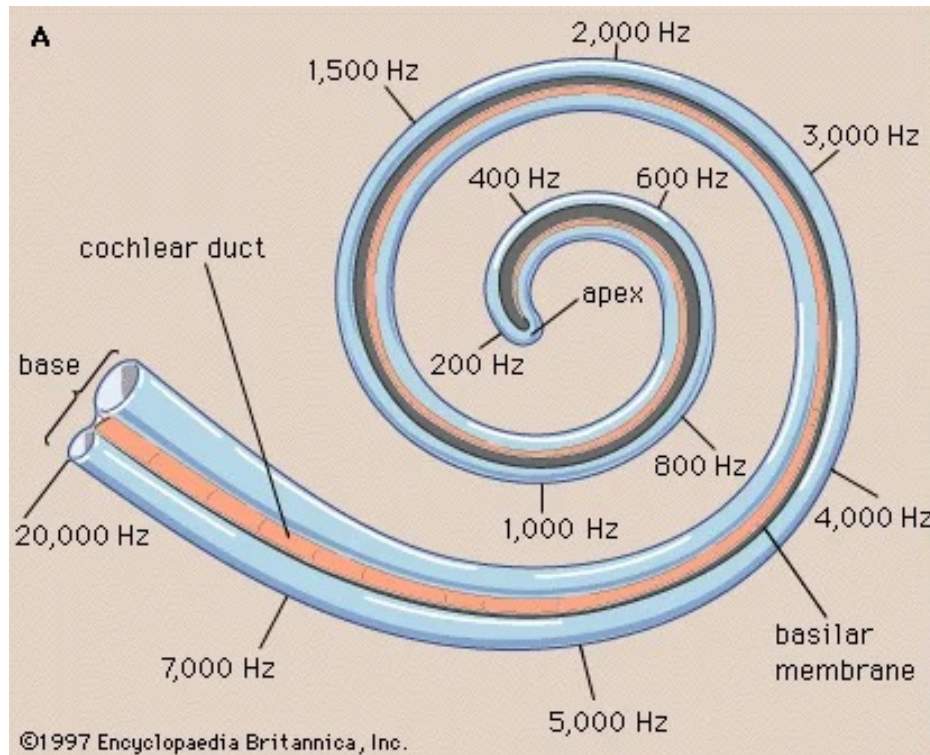
- Use hidden representations for prediction
- Latent space is **discrete** using latent space of categorical variables



Mastering Atari with Discrete World Models. Hafner et al. 2022.

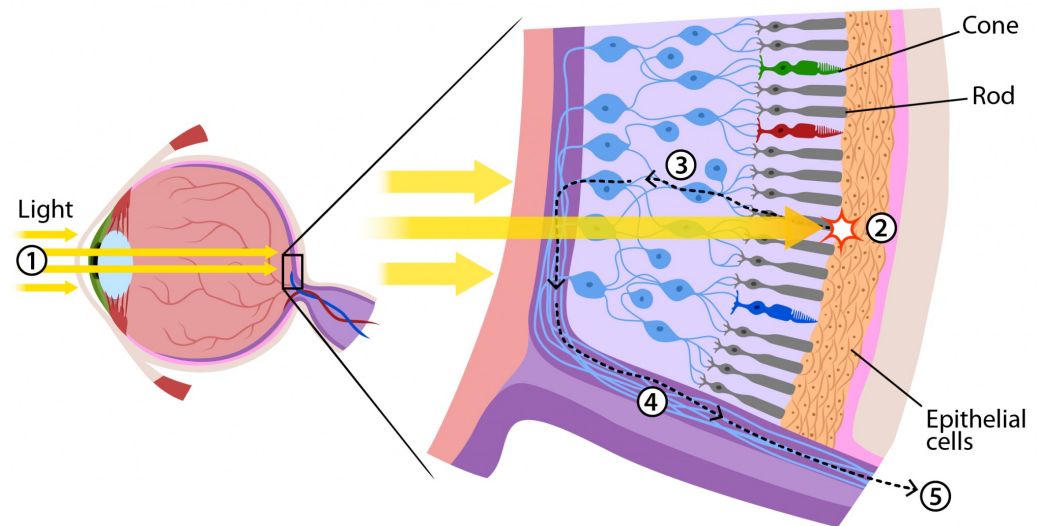
Natural Fixed Biases: Faster learning by constraints

- Sound: frequency in cilia

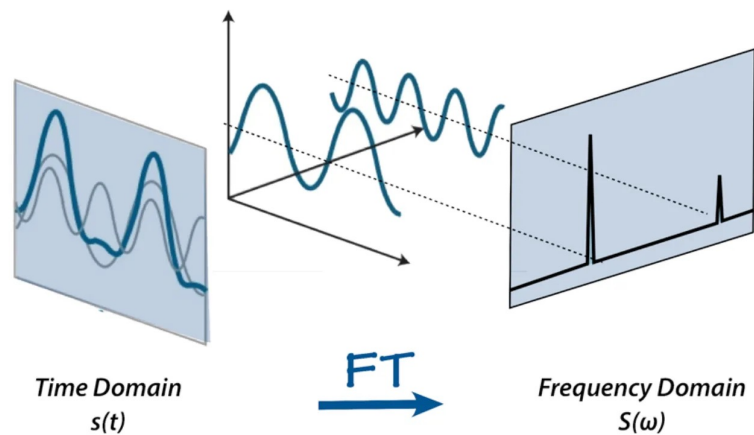


- Vision:

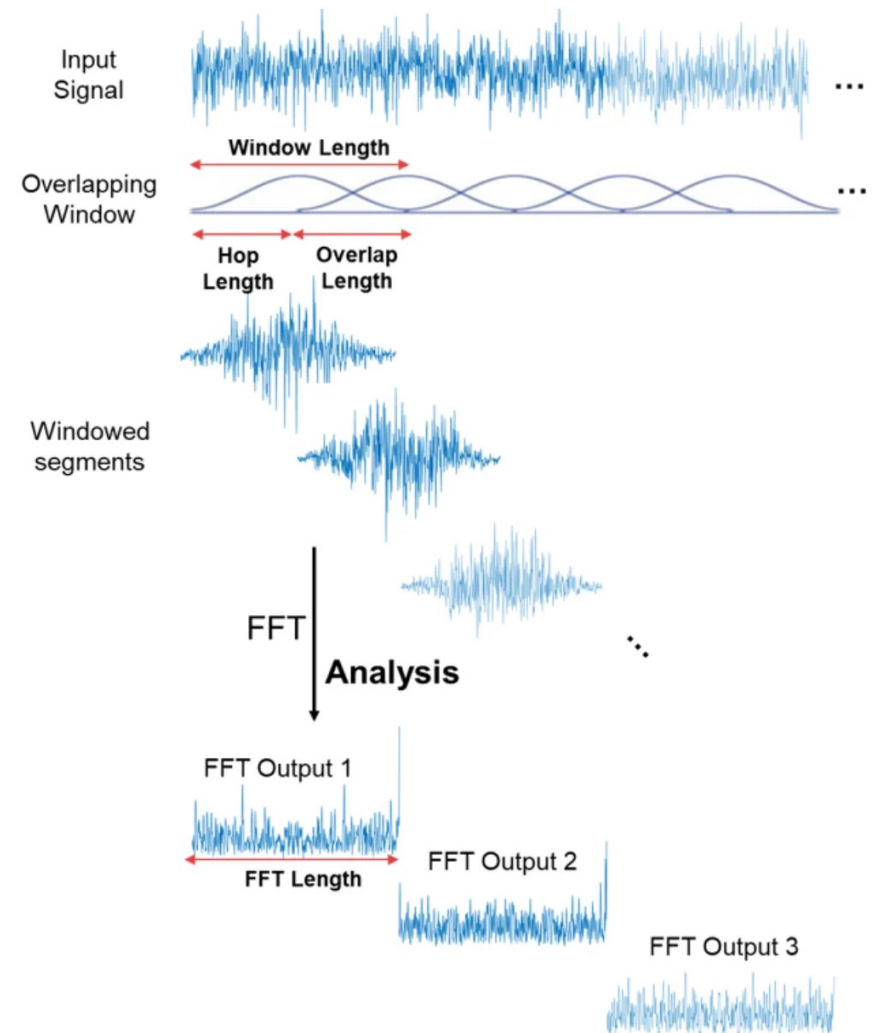
- Local patches
- Cones for Red, Green, Blue
- Rods for Black and White



Audio – Freq Modelling



Audio signal converted into frequencies



Use overlapping window to model waveform over time

Images taken from: <https://medium.com/analytics-vidhya/understanding-the-mel-spectrogram-fca2afa2ce53>

Vision – Pixel Proximity

Vertical edge detection

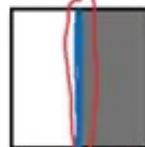
$$\begin{array}{|c|c|c|c|c|c|} \hline 10 & 10 & 10 & 0 & 0 & 0 \\ \hline 10 & 10 & 10 & 0 & 0 & 0 \\ \hline 10 & 10 & 10 & 0 & 0 & 0 \\ \hline 10 & 10 & 10 & 0 & 0 & 0 \\ \hline 10 & 10 & 10 & 0 & 0 & 0 \\ \hline 10 & 10 & 10 & 0 & 0 & 0 \\ \hline \end{array} \quad * \quad \begin{array}{|c|c|c|} \hline 1 & 0 & -1 \\ \hline 1 & 0 & -1 \\ \hline 1 & 0 & -1 \\ \hline \end{array} \quad = \quad \begin{array}{|c|c|c|c|} \hline 0 & 30 & 30 & 0 \\ \hline 0 & 30 & 30 & 0 \\ \hline 0 & 30 & 30 & 0 \\ \hline 0 & 30 & 30 & 0 \\ \hline \end{array}$$

6x6

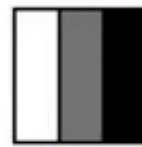
3x3

4x4

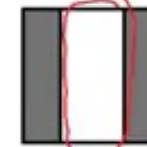
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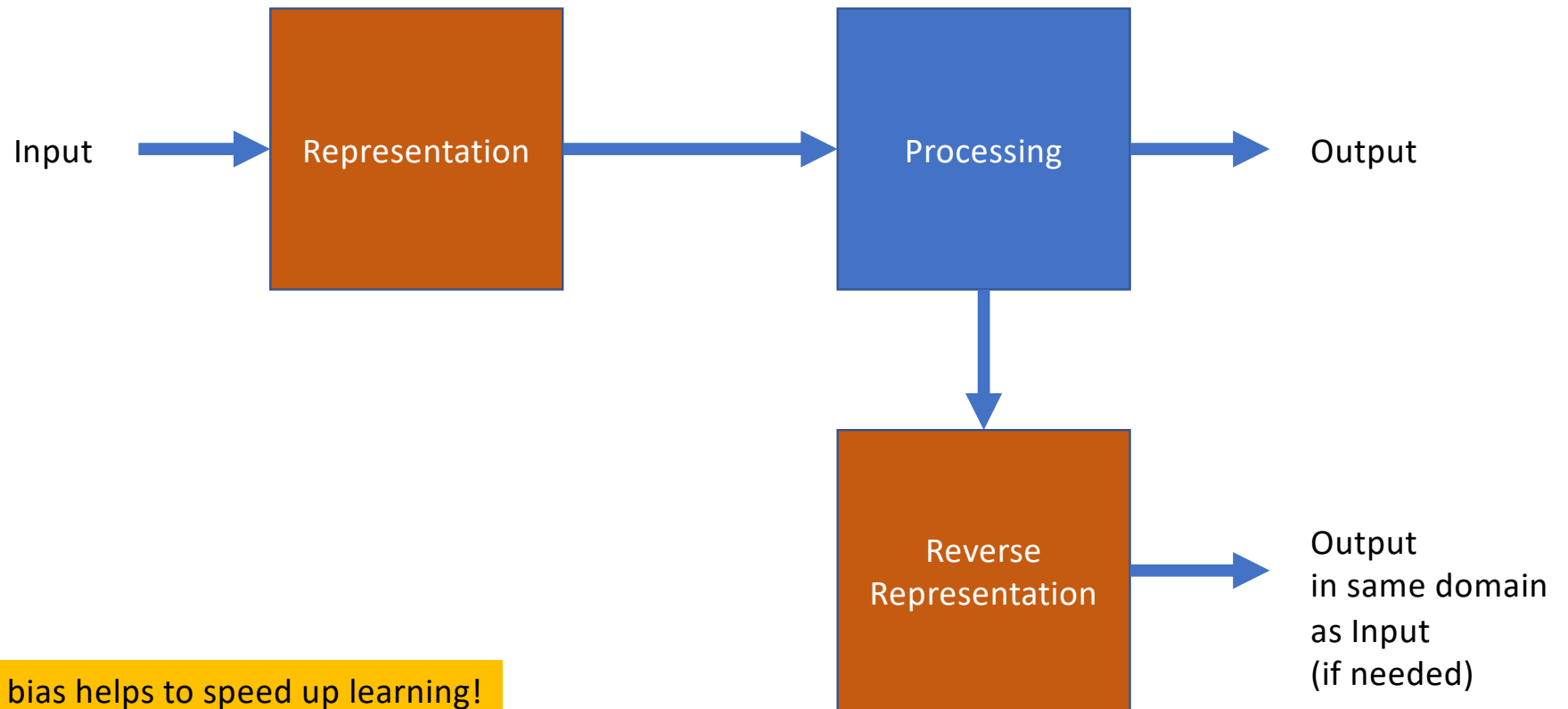


↑ ↑ ↑



Andrew Ng

Information Pipeline – Bias for Representation (Recap)



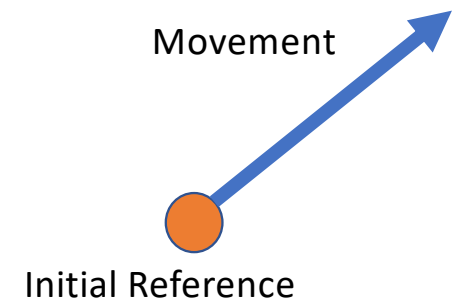
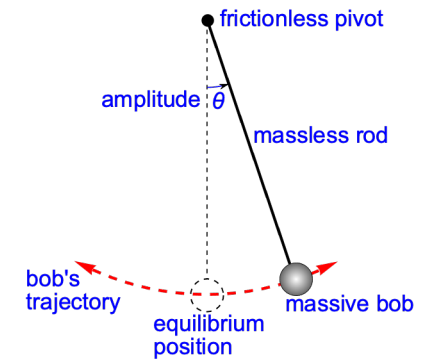
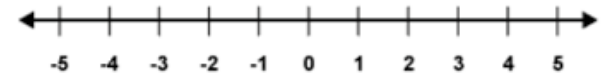
Vector Representation

Initial Reference + Movement

Could aid with generalization

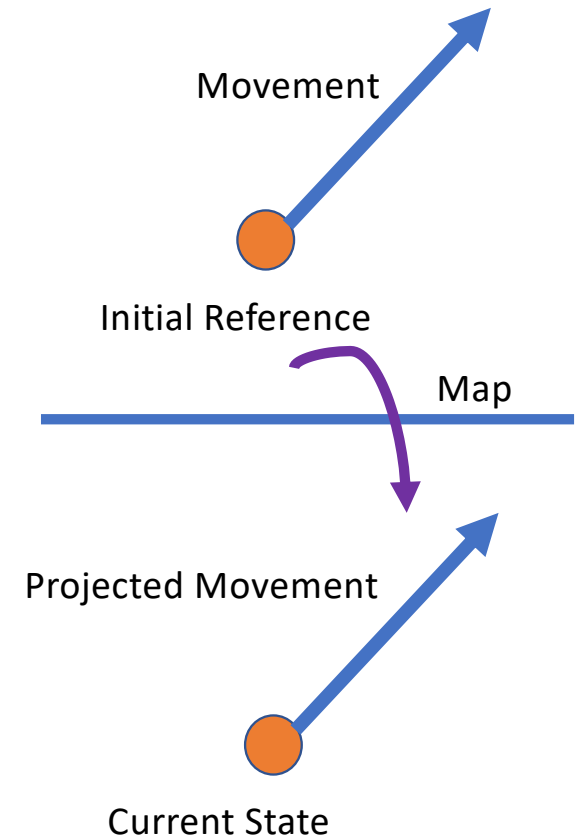
Vector Representation of memory (my view)

- Initial Reference + Movement
- Naturally represented by vectors
- Fits nicely with concepts
 - **Science:** Initial position/state of object + movement
 - **Movement:** Starting position + action
 - **Geography:** Start from one country and move to another
 - **History:** Starting time and moving up or down timeline
 - **Mathematics:** Starting number and moving up or down number line
 - **Reinforcement Learning:** Start state, action, end state



How we generalize from memory (my view)

- When we retrieve memories, the initial reference can be adjusted to suit the situation
- That way, the movement obtained can be applied to the new situation to get the desired outcome
- We can probably simulate various outcomes by retrieving from memory, applying the movement to current situation
- Current vectors don't disentangle between reference and movement – may be required for better memory referencing?



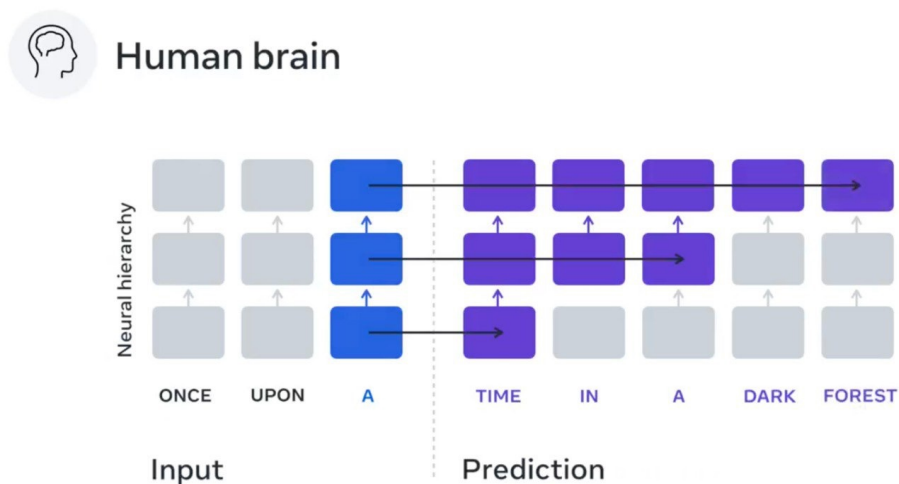
The next level

Hierarchical Prediction

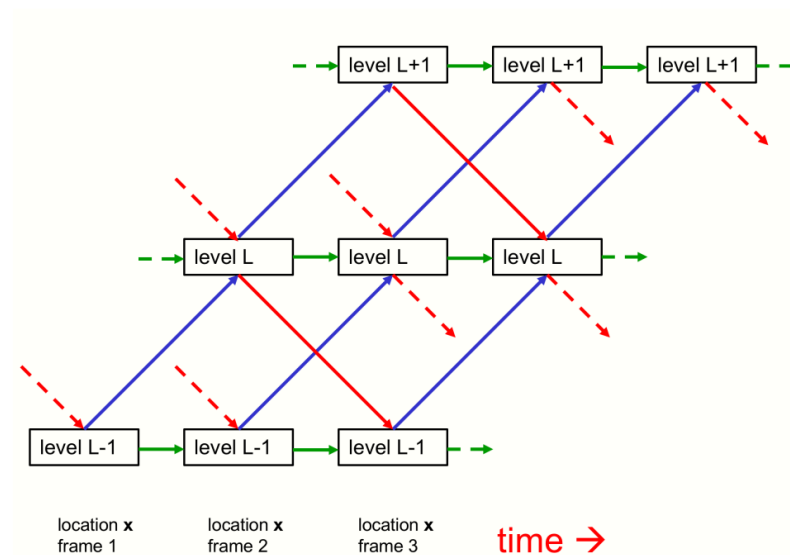
Top level forms basis for interpretation of the bottom

Hierarchical Prediction is the future

- Hierarchical prediction of more than just next token, but broader prediction at higher levels
- Higher level prediction can be more abstract and less detailed than lower levels



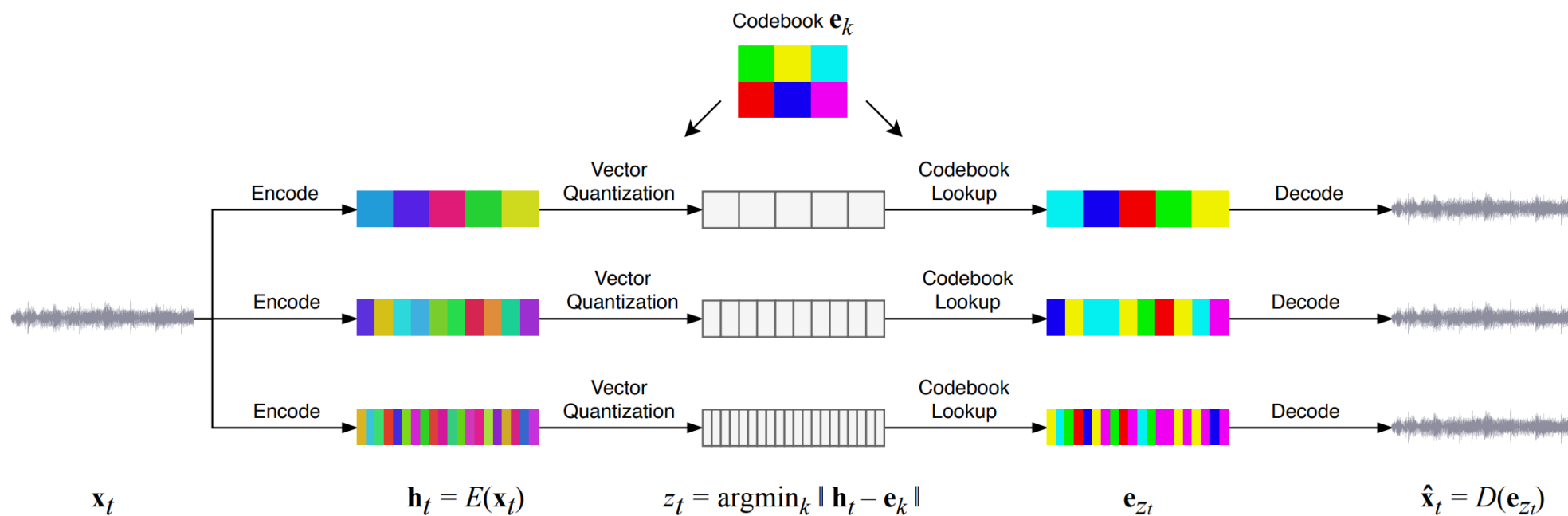
Evidence of a predictive coding hierarchy in the human brain listening to speech.
Caucheteux. 2022. Nature Human Behaviour.



How to represent part-whole hierarchies in a neural network. Hinton. 2021.

Hierarchical Prediction – Jukebox (OpenAI)

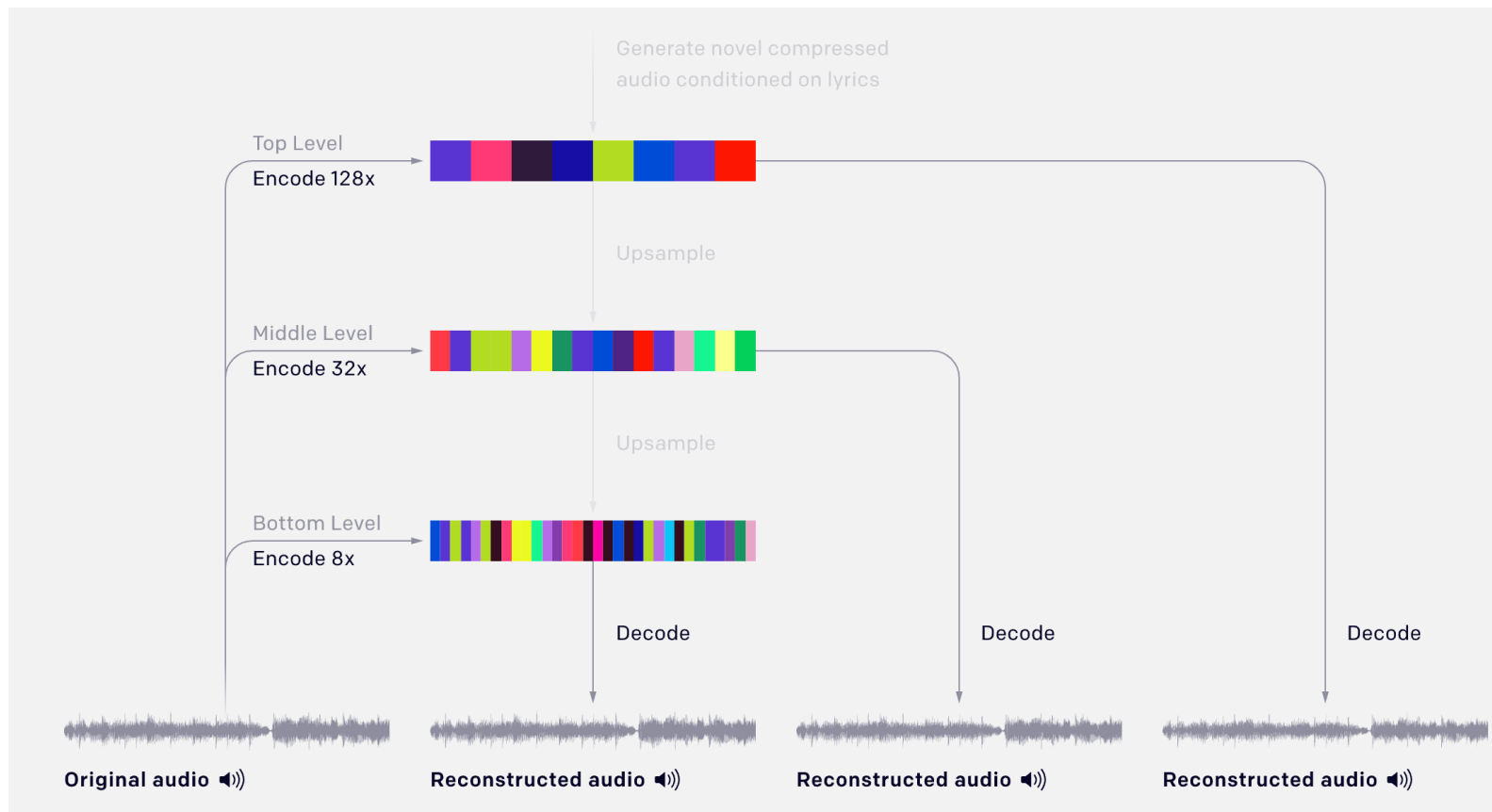
- Hierarchical Quantization of sound from coarse-grained input to fine-grained layers
- Codebook entries are **finite**



Jukebox: A Generative Model for Music. Dhariwal et. al. 2020.

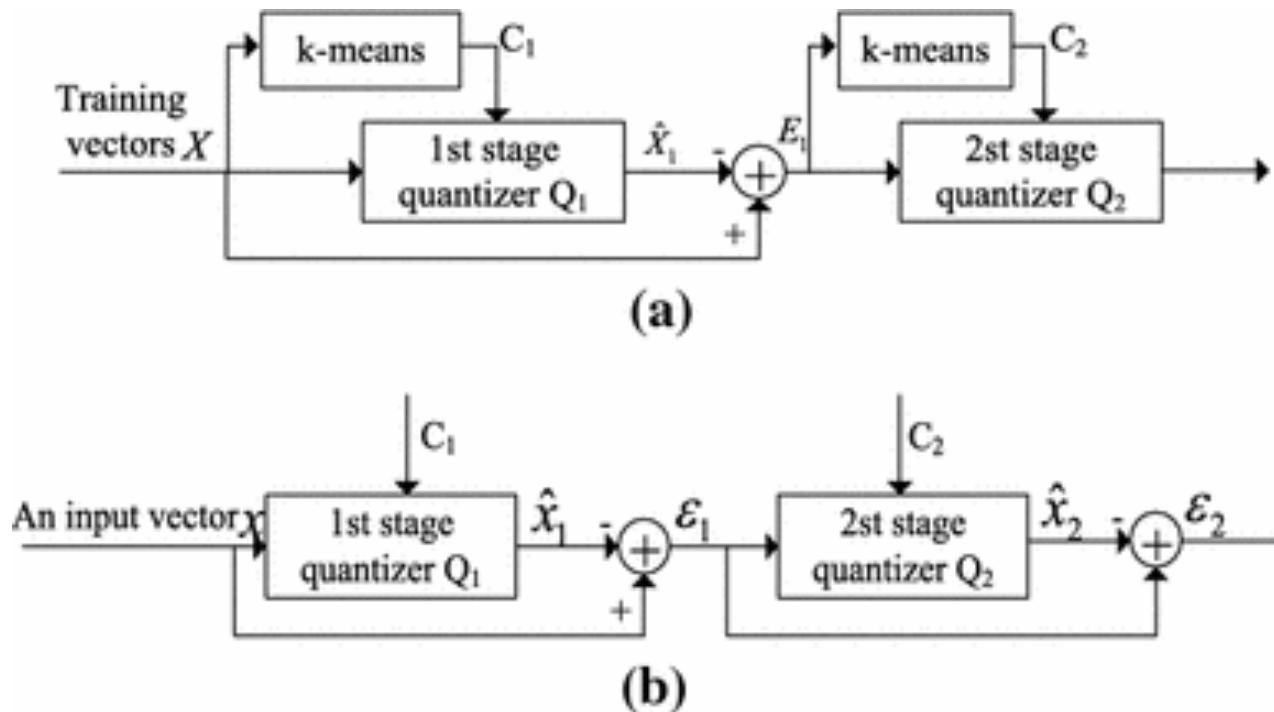
Hierarchical Prediction – Jukebox (OpenAI)

- Conditional generation of coarse-grained input to fine-grained layers



Residual Vector Quantization

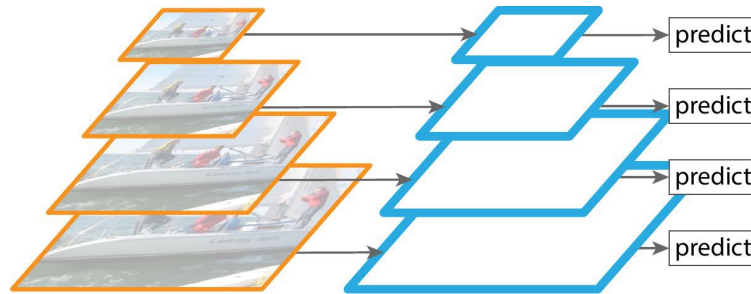
- Hierarchical Quantization from coarse-grained input to fine-grained layers
- Akin to compositionality?



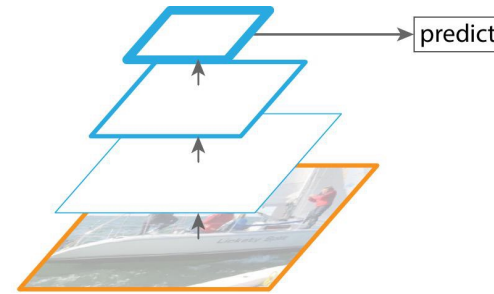
Optimized residual vector quantization for efficient approximate nearest neighbor search. Ai et al. 2015.

Hierarchical Prediction - Feature Pyramid Network

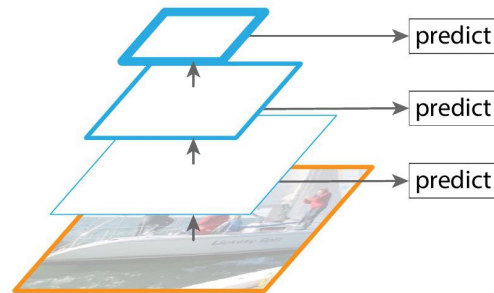
- Hierarchical prediction from coarse-grained image to fine-grained image



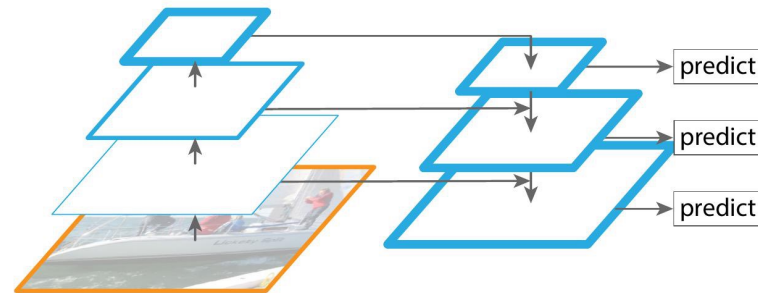
(a) Featurized image pyramid



(b) Single feature map



(c) Pyramidal feature hierarchy

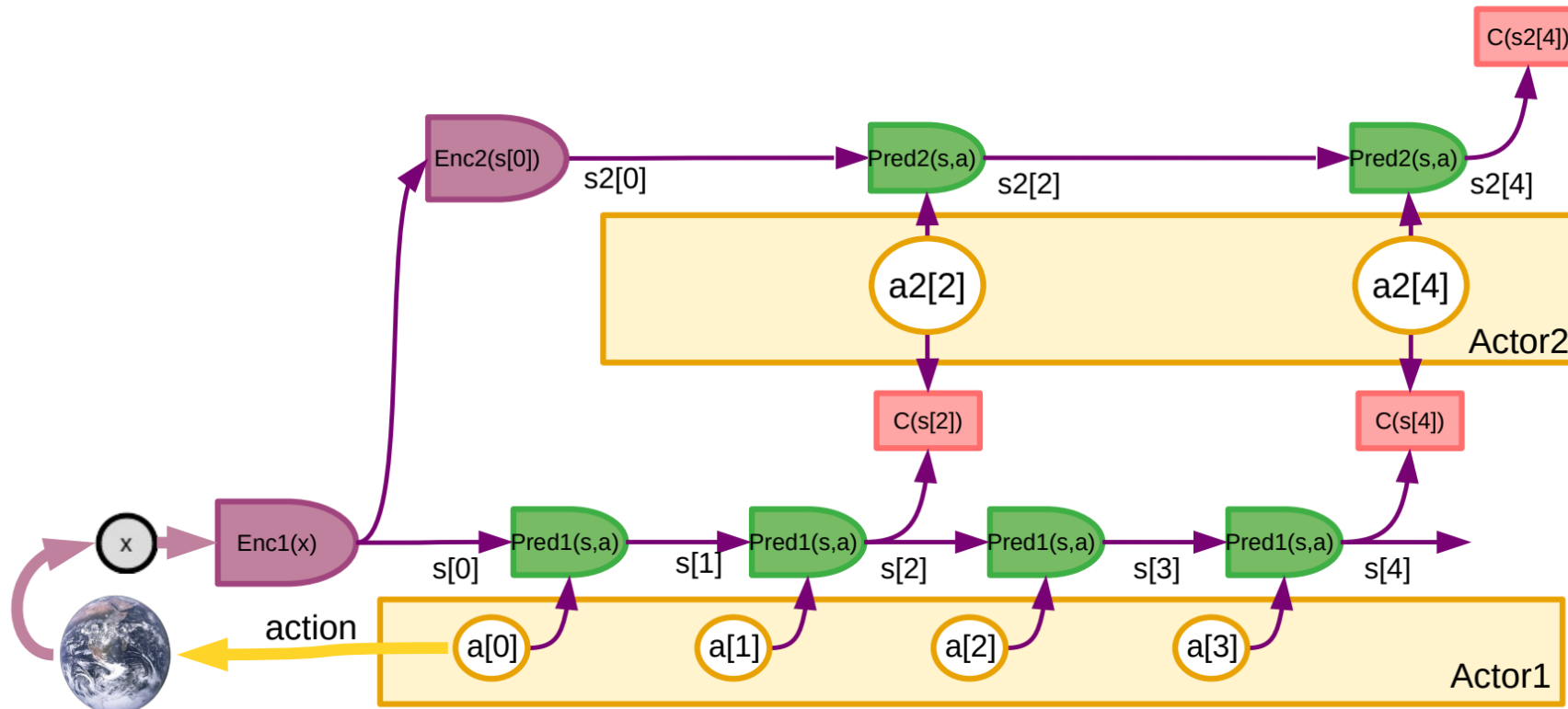


(d) Feature Pyramid Network

Feature Pyramid Networks for Object Detection. Lin et al. 2017.

Hierarchical JEPA

- Hierarchical prediction of actions from the highest level action to the lowest level action



A Path towards Autonomous Machine Intelligence. Yann LeCun. 2022.

Hierarchical Action Prediction

- Hierarchical prompting of actions from broad action to specific actions

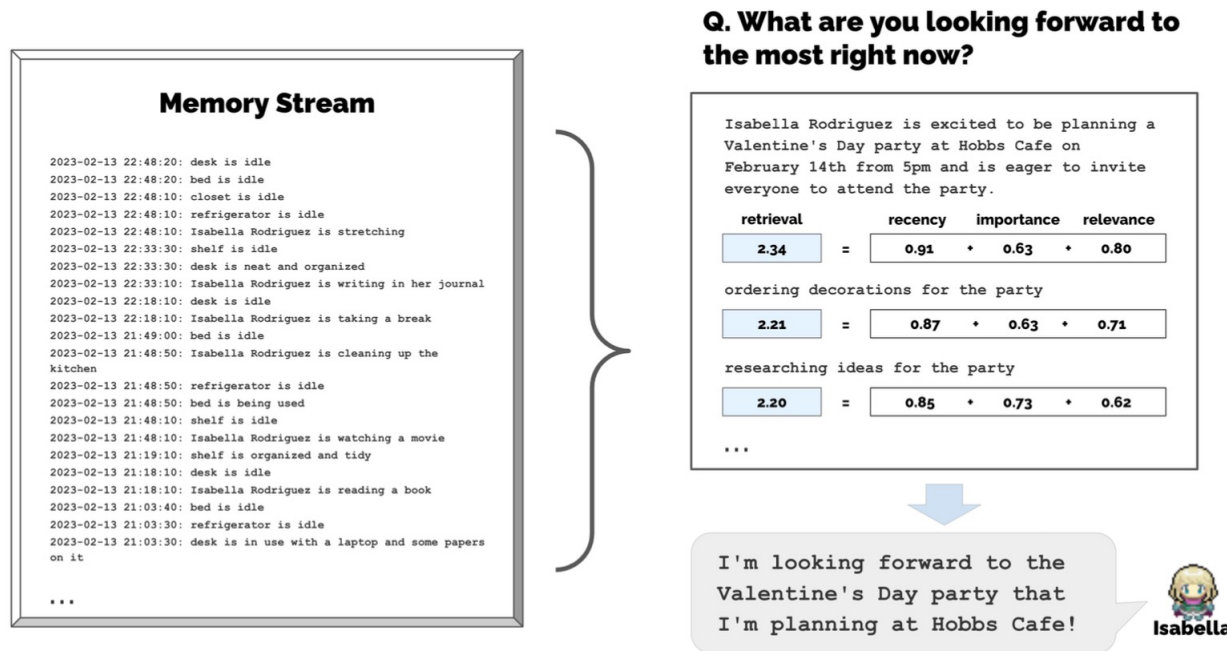


Figure 6: The memory stream comprises a large number of observations that are relevant and irrelevant to the agent's current situation. Retrieval identifies a subset of these observations that should be passed to the language model to condition its response to the situation.

Sequential Prompting

- You are a day-to-day activity planner. Here are the requirements:
- Objectives:
 - Buy **bread** for tomorrow's breakfast
 - Give a **2 hour lecture on Large Language Models** and prompting
 - Have time for **breakfast, lunch, dinner**
 - Have a **one hour games session** at night
 - Have time for some **3 hour group discussion** with students in the afternoon
- Constraints:
 - Only awake from 8am to 10pm, and the rest of the time will be sleeping
- Give the broad overview of the plan for the day
- Give a detailed breakdown of the plan, highlighting any special requirements or preparations and things to take note of

LLM's answer (ChatGPT - Broad)

- Here's a broad overview of the day's plan:

8:00 AM - Wake up and get ready.

8:30 AM - Have breakfast.

9:00 AM - Go out and buy bread for tomorrow's breakfast.

9:30 AM - Prepare for the 2-hour lecture on Large Language Models and prompting.

10:00 AM - Start the lecture.

12:00 PM - Finish the lecture and take a break for lunch.

12:30 PM - Have lunch.

1:00 PM - Gather with students for a 3-hour group discussion.

4:00 PM - End the group discussion and take a short break.

4:15 PM - Review and prepare for the evening game session.

5:00 PM - Start the one-hour game session.

6:00 PM - Wrap up the game session.

6:15 PM - Take a break and relax.

7:00 PM - Prepare and have dinner.

8:00 PM - Engage in personal activities or leisure time.

10:00 PM - Start winding down for bedtime.

LLM's answer (ChatGPT – Detailed)

- Now, let's break down the plan with more details, considering the special requirements and preparations:

8:00 AM - Wake up and get ready:

1. Set an alarm to wake up at 8:00 AM.
2. Ensure you have a comfortable sleep environment to get a good night's rest.

8:30 AM - Have breakfast:

1. Plan a nutritious and fulfilling breakfast to start the day.
2. Consider having bread or other breakfast options along with your preferred choices.

9:00 AM - Go out and buy bread for tomorrow's breakfast:

1. Make a shopping list to ensure you don't forget anything.
2. Check nearby grocery stores or bakeries for fresh bread.
3. If necessary, bring cash or payment methods for the purchase.

9:30 AM - Prepare for the 2-hour lecture on Large Language Models and prompting:

1. Gather your lecture materials, including slides, notes, and any relevant examples.
2. Review the content to ensure you're well-prepared to deliver the lecture effectively.

10:00 AM - Start the lecture:

1. Allocate sufficient time for the lecture, keeping in mind that it should last for approximately 2 hours.
2. Engage with the audience, encourage questions, and facilitate discussions as appropriate.

Hierarchical Representation of Actions

- Hierarchical chunking of sets of commonly done actions can help reduce sequence length to goal state

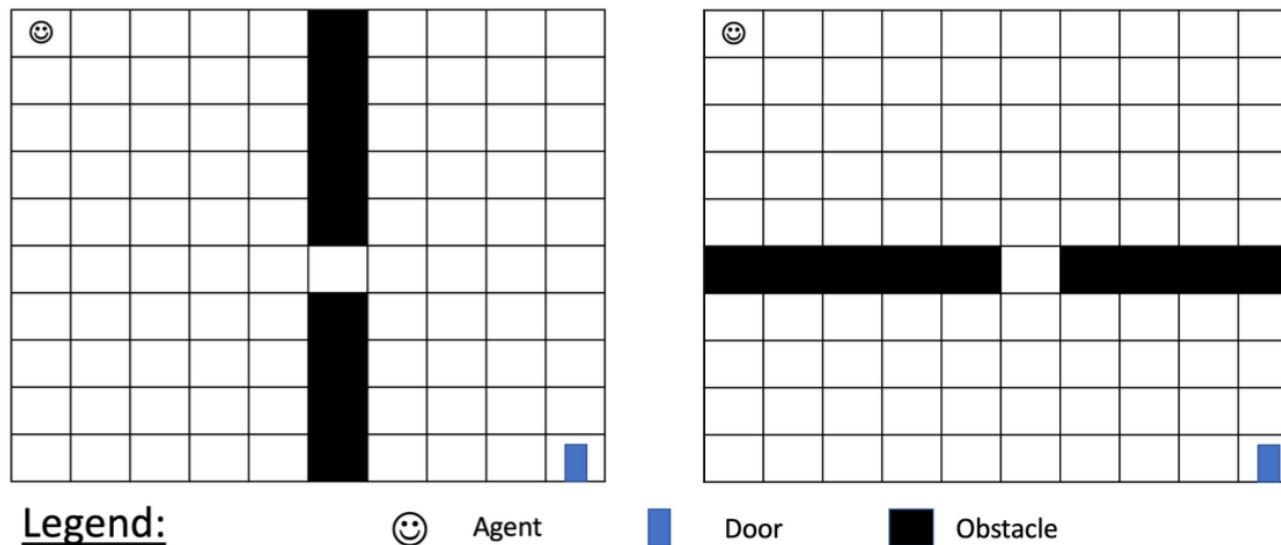
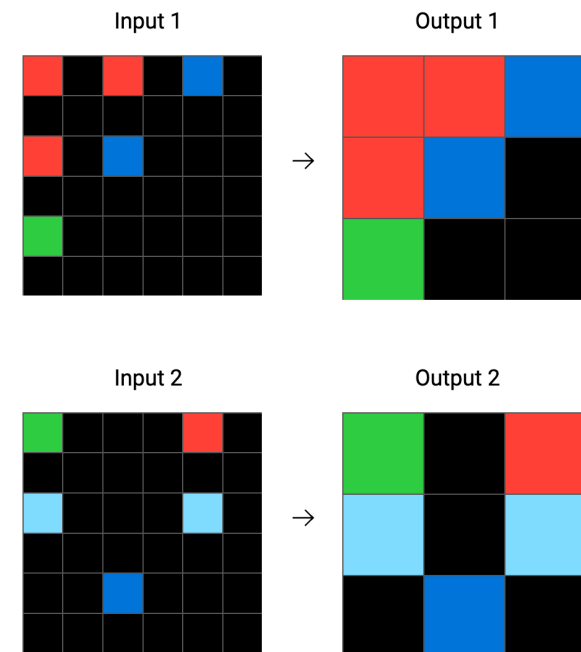


Figure 6: A sample maze environment of size 10x10. By default, the agent's start state is at the top left and the door is at the bottom right, but it can be varied. **(Left)** Obstacles before episode 50 form a vertical wall with a gap in the center across the mid-point. **(Right)** Obstacles after episode 50 form a horizontal wall with a gap in the center across the mid-point.

Hierarchical Memory Referencing in Text (my idea)

- Abstraction and Reasoning Corpus (ARC) Challenge
- **Broad Intent:** Reduce the input grid to a smaller size
 - Can reference/recite similar broad intents from memory to refine broad intent
- **Detailed Steps (conditioned on Broad Intent):**
Remove every other square from the row and columns of the grid
 - Can reference/recite similar detailed steps from memory to refine detailed steps
- Execution: Perform the detailed steps on the test input to get the answer



Transformers:

Can a Transformer perform hierarchical generation?

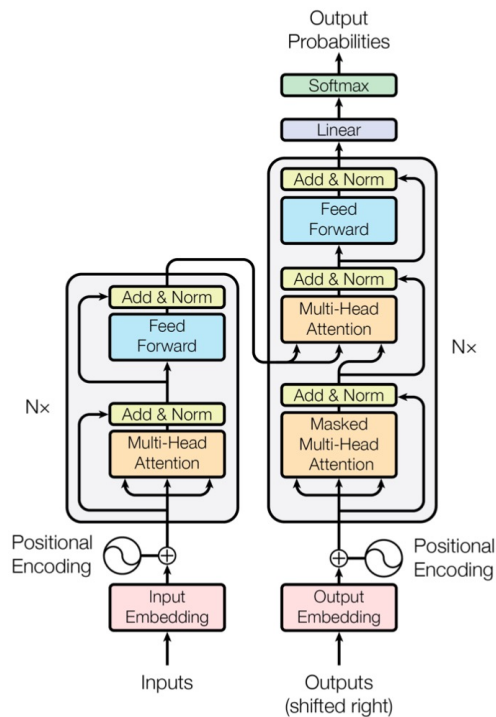
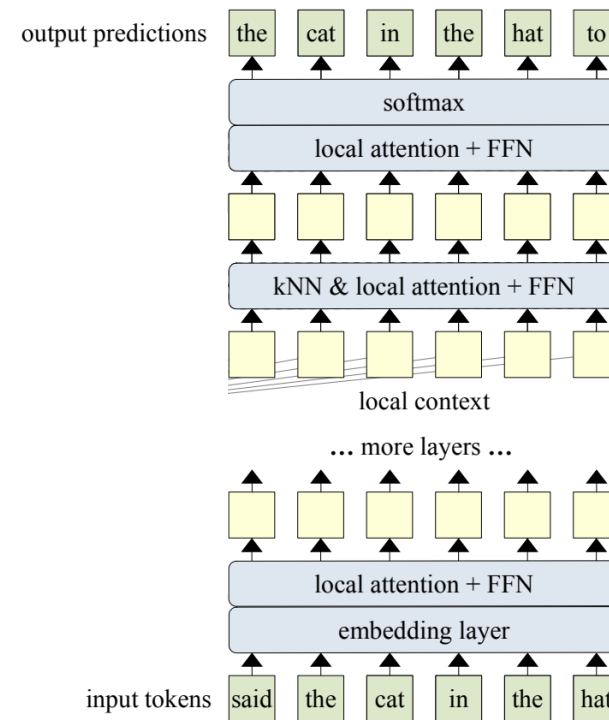


Figure 1: The Transformer - model architecture.

Attention is all you need. Vaswani et al. (2017)



Memorizing Transformers. Wu et al. 2022.

Questions to Ponder

- Do we learn from experience, or from natural fixed bias? Or both?
- Should we do prediction whereby we map back to input space (like tokens in Transformers), or should we just predict the latent space? What are the benefits and drawbacks?
- Should we use hierarchical generation? Is our brain hierarchical or more flat like what Jeff Hawkins proposes in “Thousand Brains Theory”?
- How do we structure hierarchical abstractions? Could chunking or vector quantization help?
- For a given problem, how would we know which is the right hierarchy of abstraction to use?
- Should we represent latent space as continuous or discrete? Would an unbounded length of discrete tokens be sufficient to represent continuous spaces?