Unmixing Multitemporal Hyperspectral Images Accounting for Smooth and Abrupt Variations

Pierre-Antoine Thouvenin, Nicolas Dobigeon and Jean-Yves Tourneret

University of Toulouse, IRIT/INP-ENSEEIHT







EUSIPCO 2017. Kos. Greece September 1, 2017

Work funded by the Direction Générale de l'Armement, French Ministry of Defense.

A brief introduction to hyperspectral unmixing

- Airborne/spaceborne hyperspectral (HS) images: high spectral resolution (10 nm), comparatively lower spatial resolution (20 m \times 20 m);
- Observations: mixture of several spectra corresponding to distinct materials (endmembers);
- Endmembers present in unknown proportions in each pixel (abundance, quantitative spatial mapping).

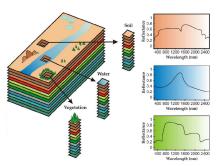


Figure 1: Hyperspectral unmixing: an illustration (taken from [1]).

Introduction

Linear mixture model

Introduction

Linear mixture model

Traditionally, observations are represented by a linear combination of the unknown endmembers [1]

$$\forall n \in \{1, \dots N\}, \quad \mathbf{y}_n = \sum_{r=1}^R a_{rn} \mathbf{m}_r + \mathbf{b}_n \tag{1}$$

$$Y = MA + B \tag{2}$$

Constraints (physical interpretability)

$$\mathbf{A} \succeq \mathbf{0}_{R,N}, \quad \mathbf{A}^T \mathbf{1}_R = \mathbf{1}_N, \quad \mathbf{M} \succeq \mathbf{0}_{L,R}$$
 (3)

- Several models are available in the literature to capture more complex interations between light and matter [2, 3, 4, 5] (e.g. multiple reflections).
- A given material is assumed to be fully characterized by a single signature.

Endmember variability

Introduction

- Endmembers possibly affected by local environmental factors, varying acquisition conditions: spectral variability;
- Spatial variability: significant source of errors when estimating the abundance coefficients;
- Error propagation within unsupervised unmixing procedures ⇒ need for appropriate models.

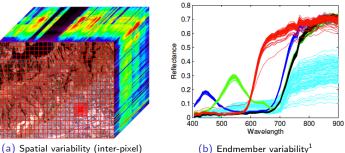


Figure 2: Endmember spatial variability: an illustration.

¹P. Gader, A. Zare, R. Close, J. Aitken, G. Tuell, MUUFL Gulfport Hyperspectral and LiDAR Airborne Data Set, University of Florida, Gainesville, FL, Tech. Rep. REP-2013-570, Oct. 2013.

Temporal endmember variability

- Variability: a prominent issue when considering multi-temporal hyperspectral (MTHS) images
 - > varying acquisition conditions;
 - □ natural evolution of the scene (e.g. water, vegetation).

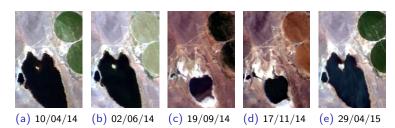


Figure 3: An example of a sequence of hyperspectral images, acquired at different time instants.

Variability accounting methods

Introduction

Essentially two modeling paradigms

- Automated endmember bundles (AEB) [6, 7, 8]
 - □ unmixing relies on spectral libraries, either extracted from the data or a priori available.
- Normal compositional model (NCM) [9, 10], Beta compositional model (BCM) [11]
 - > endmembers modeled as realizations of random vectors

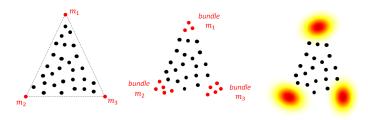


Figure 4: Different representations of endmember variability within the simplex enclosing the data (image taken from [10]).

Overview

- Introduction to hyperspectral unmixing and variability
- Unmixing of multi-temporal hyperspectral images
 - Context and motivations
 - A hierarchical Bayesian model
- Experiments
- 4 Conclusion

Observations:

- some of the observed materials present moderate variations across time (man-made constructions, ...);
- signatures corresponding to materials present in the different images
- abrupt variations may occur (e.g., when water or vegetation are present in the observed scene)
 - \triangleright new material or a sensor default \Rightarrow abrupt spectral changes \Rightarrow outlier w.r.t. the commonly shared materials.

Proposed approach:

- ▶ unmix a reference HS image to obtain an initial estimate for the endmembers:
- ▶ use / refine this result when unmixing the remaining images.

Model:

- represent smooth endmember variations as temporal variability;
- ▶ interpret abrupt spectral variations in terms of outliers.

Model and constraints

$$\mathbf{Y}_t = (\mathbf{M} + \mathbf{dM}_t)\mathbf{A}_t + \mathbf{X}_t + \mathbf{B}_t \tag{4}$$

$$\mathbf{A}_{t} \succeq \mathbf{0}_{R,N}, \ \mathbf{A}_{t}^{\mathsf{T}} \mathbf{1}_{R} = \mathbf{1}_{N}, \ \forall t \in \{1, \dots, T\}$$

$$\mathbf{M} \succeq \mathbf{0}_{L,R}, \ \mathbf{M} + \mathbf{dM}_{t} \succeq \mathbf{0}_{L,R}, \ \mathbf{X}_{t} \succeq \mathbf{0}_{L,N}$$

$$(5)$$

Likelihood function

$$p(\mathbf{Y} \mid \Theta) \propto \prod_{t=1}^{T} (\sigma_t^2)^{-NL/2} \exp\left(-rac{1}{2\sigma_t^2} \left\|\mathbf{Y}_t - (\mathbf{M} + \mathbf{dM}_t)\mathbf{A}_t - \mathbf{X}_t
ight\|_{\mathsf{F}}^2
ight)$$

where $\Theta = \{ \mathbf{M}, \mathbf{d}\underline{\mathbf{M}}, \underline{\mathbf{A}}, \mathbf{X}, \mathbf{Z}, \sigma^2, \Psi^2, \mathbf{s}^2 \}$

Objective: infer Θ from **Y** using $p(\Theta \mid \mathbf{Y}) \Rightarrow$ need for priors on the different parameters/hyperparameters involved in the model.

Parameter estimation: MCMC algorithm (Gibbs sampler) used to build estimators of the parameters of interest.

Hierarchical Bayesian model

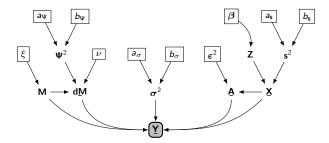


Figure 5: Description of the proposed Bayesian model using a directed acyclic graph (fixed parameters appear in boxes).

Abundance prior

- promotes smooth abundance variations (except when the corresponding pixel contains outliers)
- ▶ abundance sum-to-one constraint relaxed $(\mathbf{a}_{n,t}^\mathsf{T} \mathbf{1}_R \leq 1)$ when outliers are present in the pixel (n, t) (apparition of new materials)

$$egin{aligned} \mathbf{a}_{n,1} \mid \mathbf{x}_{n,t} &= \mathbf{0}_L \sim \mathcal{U}_{\mathcal{S}_R} \ \mathbf{a}_{n,t} \mid \mathbf{x}_{n,t}
eq \mathbf{0}_L \sim \mathcal{U}_{\widetilde{\mathcal{S}}_R}, ext{ for } t = 1, \dots, T \end{aligned}$$

$$p\left(\mathbf{a}_{n,t} \mid \mathbf{x}_{n,t} = \mathbf{0}_{L}, \mathbf{\underline{A}}_{\setminus \{\mathbf{a}_{n,t}\}}\right) \propto \exp\left\{-\frac{1}{2\varepsilon_{n}^{2}}\left(\left[\mathscr{T}_{n,t}^{1} \neq \emptyset\right] \|\mathbf{a}_{n,t} - \mathbf{a}_{n,\tau_{n,t}^{1}}\|_{2}^{2}\right)\right\}$$

$$\mathbb{1}_{S_{D}}(\mathbf{a}_{n,t}), \text{ for } t > 2$$

with

$$\begin{split} \mathcal{S}_R &= \{\mathbf{x} \in \mathbb{R}^R \mid \forall i, x_i \geq 0 \text{ and } \mathbf{x}^\mathsf{T} \mathbf{1}_R = 1\} \\ \widetilde{\mathcal{S}_R} &= \{\mathbf{x} \in \mathbb{R}^R \mid \forall i, x_i \geq 0 \text{ and } \mathbf{x}^\mathsf{T} \mathbf{1}_R \leq 1\} \\ \mathscr{T}_{n,t}^1 &= \{\tau < t \mid z_{n,\tau} = 0\} \,, \quad \tau_{n,t}^1 = \max_{\tau \in \mathscr{T}_{n,t}^1} \tau. \end{split}$$

Experiments

Hierachical Bayesian model: priors (II)

Outlier prior

- ▶ promotes outlier sparsity [12, 13, 14, 15, 16];
- ▶ takes advantage of possible spatial correlations between these outliers by modeling $\mathbf{z}_t \in \mathbb{R}^N$ as Ising-Markov random fields (correlations likely to occur when new materials appear).

$$p(\mathbf{x}_{n,t} \mid z_{n,t}, s_t^2) = (1 - z_{n,t})\delta(\mathbf{x}_{n,t}) + z_{n,t} \mathcal{N}_{\mathbb{R}^L_+}(\mathbf{0}_L, s_t^2)$$

Variability prior

▶ promotes smooth endmember variations from an image to another [17, 18]

$$dm_{\ell,r,1} \mid m_{\ell,r} \sim \mathcal{N}_{\mathcal{I}_{\ell,r}}(0,\nu), \ \mathcal{I}_{\ell,r} = [-m_{\ell,r}, +\infty)$$

$$dm_{\ell,r,t}|m_{\ell,r},dm_{\ell,r,(t-1)},\psi_{\ell,r}^2 \sim \mathcal{N}_{\mathcal{I}_{\ell,r}}\left(dm_{\ell,r,(t-1)},\psi_{\ell,r}^2\right)$$

- \bullet ν penalizes the variability energy in the first image;
- $\psi_{\ell,r}^2$ controls the temporal evolution of the variability.

Experiments

Parameter estimation

Algorithm 1: Proposed Gibbs sampler.

```
Input: N_{\text{bi}}, N_{\text{MC}}, \Theta^{(0)}, \beta, \xi, a_{\text{W}}, b_{\text{W}}, a_{\text{S}}, b_{\text{S}}, a_{\sigma}, b_{\sigma}, \nu, \varepsilon^2.
for a = 1 to N_{MC} do
         for (n, t) = (1, 1) to (N, T) do
                 Draw \mathbf{a}_{n,t}^{(q)} \sim p(\mathbf{a}_{n,t} \mid \mathbf{y}_{n,t}, \Theta_{\setminus \{\mathbf{a}_{n,t}\}});
         for r = 1 to R do
           Draw \mathbf{e}_r^{(q)} \sim p(\mathbf{e}_r \mid \mathbf{Y}, \Theta_{\backslash \{\mathbf{e}_r\}});
         for t = 1 to T do
                 Draw dM_t^{(q)} \sim p(dM_t \mid \mathbf{Y}_t, \Theta_{\setminus \{dM_t\}});
         for (n, t) = (1, 1) to (N, T) do
                 Draw z_{n,t}^{(q)} \sim \mathbb{P}[z_{n,t} \mid \mathbf{y}_{n,t}, \Theta_{\setminus \{z_{n,t}\}}];
                Draw \mathbf{x}_{n,t}^{(q)} \sim p(\mathbf{x}_{n,t} \mid \Theta_{\setminus \{\mathbf{x}_{n,t}\}});
         for t = 1 to T do
                  Draw s_t^{2(q)} \sim p(s_t^2 \mid \Theta_{\setminus \{s_t^2\}});
         for t = 1 to T do
                 Draw \sigma_t^{2(q)} \sim p(\sigma_t^2 \mid \Theta_{\setminus \{\sigma_t^2\}});
         for (\ell, r) = (1, 1) to (L, R) do
               Draw \psi_{\ell,r}^{2(q)} \sim p(\psi_{\ell,r}^2 \mid \Theta_{\setminus \{\psi_{\ell,r}^2\}}) ;
```

Result: $\{\Theta^{(q)}\}_{q=1}^{N_{MC}}$

Experiments

Overview

- Experiments
 - Experiments on synthetic data
 - Results on synthetic data

Experiments on synthetic data

Data generation:

• MTHS image composed of 20 HS images of size 30 \times 30, L=212 bands, affected by smooth time-varying variability and additive white Gaussian noise:

Experiments

• renders the emergence of a previously undetected material in a few pixels within specific images \Rightarrow outliers.

Algorithmic setting:

•
$$\mathbf{X}_t^{(0)} = \mathbf{0}_{L,N}$$
, $\mathbf{dM}_t^{(0)} = \mathbf{0}_{L,R}$, $z_{n,t}^{(0)} = 0$, $\sigma_t^{2(0)} = 10^{-4}$, $\psi_{\ell,r}^{2(0)} = 10^{-6}$, $s_t^{2(0)} = 5 \times 10^{-3}$;

- numerical constants: $\beta_t = 1.9$, $\varepsilon_n = 10^{-4}$, $\nu = 10^{-5}$:
- $N_{MC} = 400$ M-C iterations, with $N_{bi} = 350$ burn-in iterations.

Table 1: Simulation results obtained on synthetic data (GMSE(A) \times 10⁻², GMSE(**dM**) $\times 10^{-3}$, RE $\times 10^{-3}$).

		aSAM(M) (°)	GMSE(A)	GMSE(dM)	RE	time (s)
R=3	VCA/FCLS	14.0	1.23	/	3.20	1
	SISAL/FCLS	11.9	2.40	/	0.47	2
	rLMM	14.5	1.52	/	0.04	238
	OU	12.9	0.30	1.64	0.26	58
	Proposed (MCMC)	8.03	0.17	0.20	0.11	1590

Results on synthetic data (I)

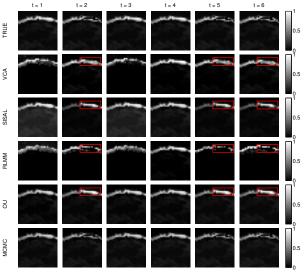


Figure 6: Abundance maps estimated for the third endmember for t=1 to 6. The areas corrupted by outliers are delineated in red.

roduction Unmixing of MTHS images Experiments Conclusion

Results on synthetic data (II)

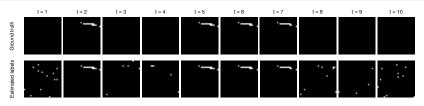


Figure 7: Ground truth (first row) and estimated labels (second row) obtained with the proposed method for t=1 to 10, where each column corresponds to a time instant [0 in black, 1 in white].



Figure 8: Map of the re-scaled abundance estimation errors for the third endmember at time t=2 (from left to right: true abundances, estimation error of VCA/FCLS, SISAL/FCLS, rLMM, OU and the proposed method). Except for the proposed method, the results exhibit notable errors in pixels corrupted by outliers (area in red).

Results on synthetic data (III)

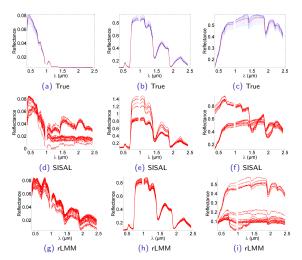


Figure 9: Endmembers (red lines) and endmember + variability (blue dotted lines) extracted from the synthetic mixture by the compared methods (in row).

Results on synthetic data (IV)

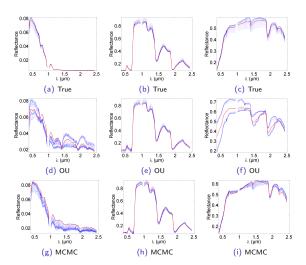


Figure 10: Endmembers (red lines) and endmember + variability (blue dotted lines) extracted from the synthetic mixture by the compared methods (in row).

Overview

- 1 Introduction to hyperspectral unmixing and variability
- 2 Unmixing of multi-temporal hyperspectral images
- Experiments
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Conclusion and perspectives

Proposed approach

▶ development of an unmixing approach accounting for both smooth and abrupt spectral variations, formulated within a Bayesian framework.

Experiments

Research perspectives

- > application to real datasets in various contexts;
- > development of unmixing algorithms scaling with the problem's dimension (e.g., distributed optimization algorithms): ongoing work;
- ▷ incorporating data from different sensors to improve unmixing results [19] (possibly relying on fusion techniques [20]).

Thank you for your attention!

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Backup slides

- Prior assigned to the remaining parameters Priors

Endmember prior

- ▶ endmembers can be *a priori* considered to live in a subspace of dimension $K \ll L$ (PCA or rPCA [21]);
- ▶ considering the decomposition used in [22] leads to

$$\mathbf{m}_r = (\mathbf{I}_L - \mathbf{U}\mathbf{U}^\mathsf{T})\mathbf{\bar{y}} + \mathbf{U}\mathbf{e}_r, \quad \mathbf{U}^\mathsf{T}\mathbf{U} = \mathbf{I}_K$$

where U is a basis of the subspace and \bar{y} is the sample mean of \underline{Y} ;

ightharpoonup projected endmembers \mathbf{e}_r are assigned a truncated multivariate Gaussian prior to ensure the non-negativity of \mathbf{m}_r

$$\mathbf{e}_r \sim \mathcal{N}_{\mathcal{E}_r}(\mathbf{0}_K, \xi \mathbf{I}_K), \text{ for } r = 1, \dots, R.$$
 (6)

Hyperparameter priors

lacktriangle conjugate inverse-gamma priors assigned to the noise (σ^2) , the variability (Ψ^2) and the outlier (\mathbf{s}^2) variances, i.e.,

$$\sigma_t^2 \sim \mathcal{IG}(a_{\sigma}, b_{\sigma}), \ \psi_{\ell,r}^2 \sim \mathcal{IG}(a_{\Psi}, b_{\Psi}), \ s_t^2 \sim \mathcal{IG}(a_s, b_s)$$
 (7)

where $a_{\sigma} = b_{\sigma} = a_{W} = b_{W} = a_{S} = b_{S} = 10^{-3}$.

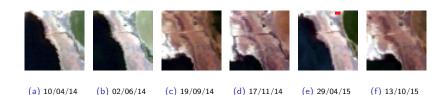


Figure 11: Scenes used in the experiment, given with their respective acquisition date. The area delineated in red in Fig. 11e highlights a region known to contain outliers (this observation results from a previous analysis led on this dataset in [23]).

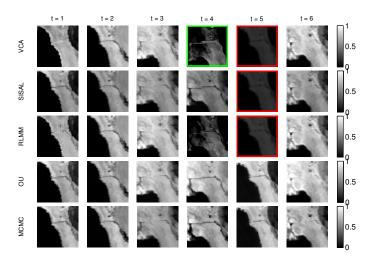


Figure 12: Soil abundance map recovered by the different methods (in row) at each time instant (in column) [VCA/FCLS, SISAL/FCLS, rLMM, OU, MCMC].

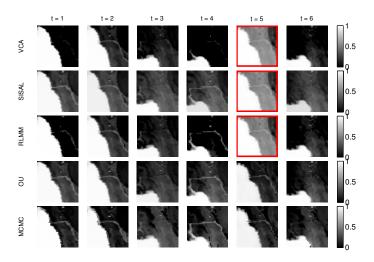


Figure 13: Water abundance map recovered by the different methods (in row) at each time instant (in column) [VCA/FCLS, SISAL/FCLS, rLMM, OU, MCMC].

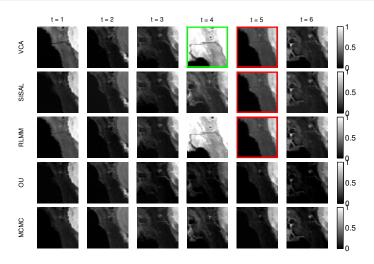


Figure 14: Vegetation abundance map recovered by the different methods (in row) at each time instant (in column) [VCA/FCLS, SISAL/FCLS, rLMM, OU, MCMC].

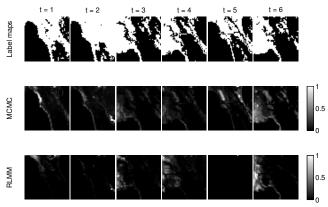


Figure 15: Outlier energy recovered by rLMM [24] and the proposed MCMC method.

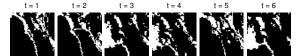
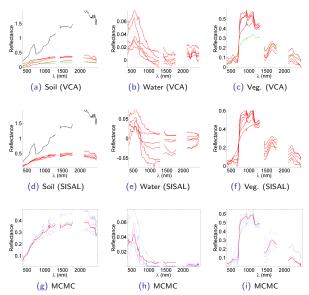


Figure 16: Non-linearity maps estimated by [25] applied to each image with the SISAL-extracted endmembers.



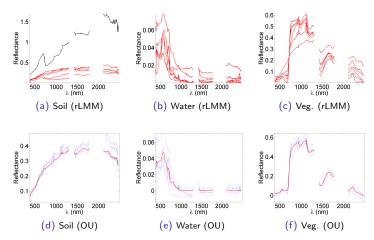


Figure 18: Extracted endmembers (\mathbf{m}_r , red lines) and perturbed endmembers ($\mathbf{m}_r + \mathbf{dm}_{r,t}$, blue dotted lines).

Table 2: Simulation results on real data (RE $\times 10^{-4}$).

	RE	time (s)
VCA/FCLS	11.73	1
SISAL/FCLS	2.38	2
rLMM	0.66	106
OU	2.08	26
Proposed	0.19	3700
	SISAL/FCLS rLMM OU	VCA/FCLS 11.73 SISAL/FCLS 2.38 rLMM 0.66 OU 2.08

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