

# Trabalho de Grafos

## Parte 2

Grafos ponderados

# Código

- Feito em Go (golang)
  - Compilada (Execução mais rápida)
  - Tipada (Melhor uso de memória)
- Bibliotecas próprias
  - Otimização de estruturas (“classes”)
  - Sintaxe homogênea

```

1 ✓ func dijkstraList(adjacency [][]*Neighbor, start uint32, end uint32) []*TreeNode {
2     // initialize the list
3     list := List{}
4     list.vertexes = make([]*Node, len(adjacency)+1) // 0 is not used
5
6
7
8     list.Update(start, 0, 0)
9
10    // tree
11    tree := make([]*TreeNode, 0, len(adjacency))
12
13    node := list.Pop()
14    for node != nil && node.id != end {
15        // add node to tree
16        tree = append(tree, &TreeNode{node.id, node.father, node.cost})
17
18        // update neighbors
19        for _, v := range adjacency[node.id] {
20            list.Update(v.vertex_id, node.id, node.cost+v.weight)
21        }
22        node = list.Pop() // get the node with the lowest cost
23    }
24
25    if node != nil { // add the end node
26        tree = append(tree, &TreeNode{node.id, node.father, node.cost})
27    }
28
29    return tree
30 }

```

```

1 ✓ func dijkstraHeap(adjacency [][]*Neighbor, start uint32, end uint32) []*TreeNode {
2     // initialize the heap
3     heap := Heap{}
4     heap.vertexPos = make([]int, len(adjacency))
5     for i := range heap.vertexPos { // set all vertexes as unexplored
6         heap.vertexPos[i] = -1
7     }
8     heap.Update(start, 0, 0)
9
10    // tree
11    tree := make([]*TreeNode, 0, len(adjacency)+1) // 0 is not used
12
13    node := heap.Pop()
14    for node != nil && node.id != end {
15        // add node to tree
16        tree = append(tree, &TreeNode{node.id, node.father, node.cost})
17
18        // update neighbors
19        for _, v := range adjacency[node.id] {
20            heap.Update(v.vertex_id, node.id, node.cost+v.weight)
21        }
22        node = heap.Pop() // get the node with the lowest cost
23    }
24
25    if node != nil { // add the end node
26        tree = append(tree, &TreeNode{node.id, node.father, node.cost})
27    }
28
29    return tree
30 }

```

# Dijkstra Lista

Estruturas:

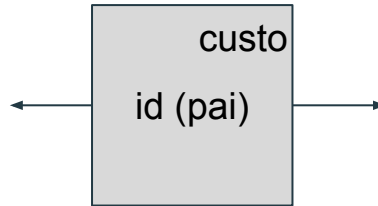
```
13  type List struct {  
14      vertexes []*Node  
15      head     *Node  
16      tail     *Node  
17  }
```

```
5  type Node struct {  
6      id      uint32  
7      father  uint32  
8      cost    float64  
9      prev    *Node  
10     next    *Node  
11 }
```

vértices []\*node  
head \*node  
tail \*node

vértices	n*64	bits
head	64	bits
tail	64	bits

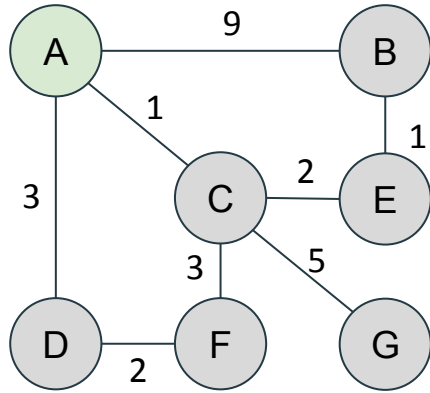
$$(2+n) * 64 \\ \approx 64*n$$



id	32	bits
pai	32	bits
custo	64	bits
ant	64	bits
prox	64	bits

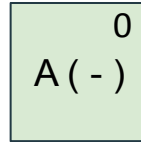
$$32*2 + 64*3 \\ = 256$$

# Dijkstra Lista



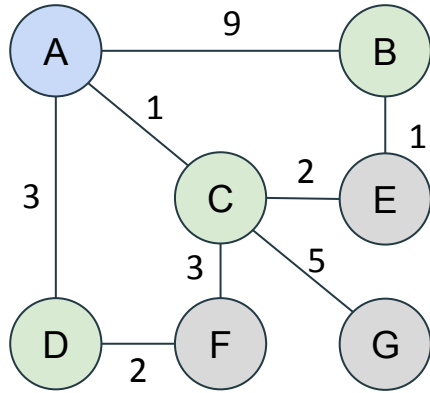
Vértices explorados:

Lista encadeada ordenada dos vértices descobertos:

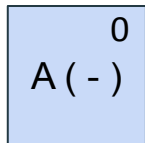


Lista:	A B C D E F G
vértices	[&A, nil, nil, nil, nil, nil, nil]
head	&A
tail	&A

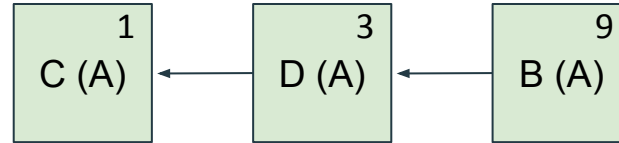
# Dijkstra Lista (pop)



Vértices explorados:

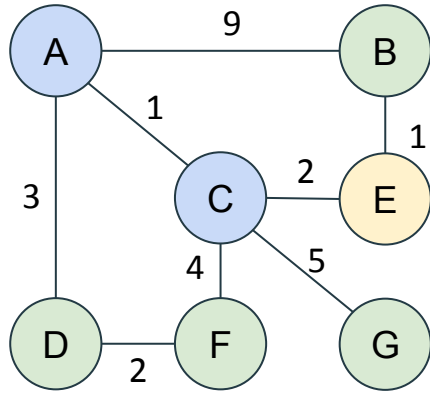


Lista encadeada ordenada dos vértices descobertos:

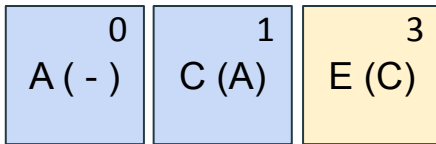


Lista:	A	B	C	D	E	F	G
vértices	[&A,	&B,	&C,	&D,	nil,	nil,	nil]
head	&C						
tail	&B						

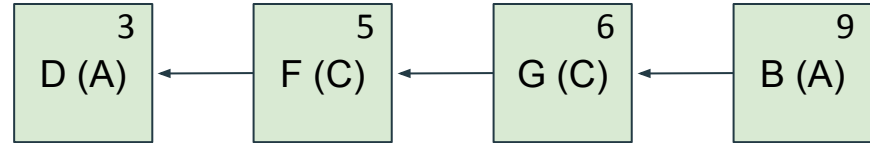
# Dijkstra Lista (update)



Vértices explorados:

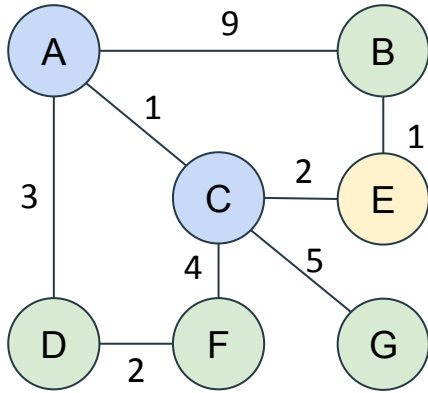


Lista encadeada ordenada dos vértices descobertos:

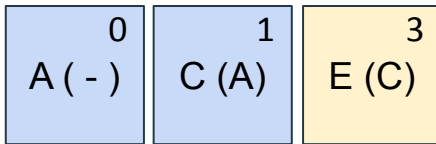


Lista:	A	B	C	D	E	F	G
vértices	[&A, &B, &C, &D, &E, &F, &G]						
head	&D						
tail	&B						

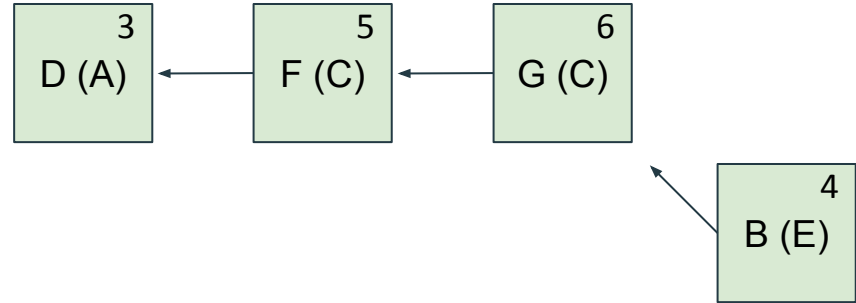
# Dijkstra Lista (update)



Vértices explorados:



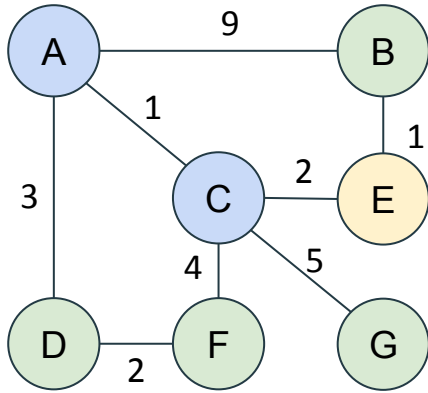
Lista encadeada ordenada dos vértices descobertos:



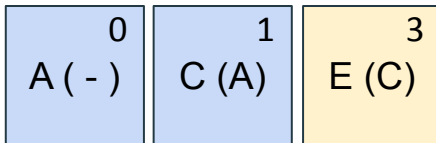
Lista:	A	B	C	D	E	F	G
vértices	&A,	&B,	&C,	&D,	&E,	&F,	&G]
head	&D						
tail	&G						



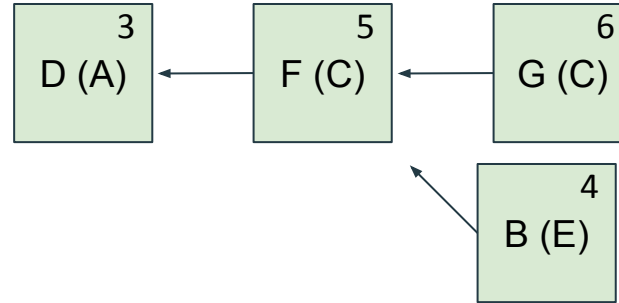
# Dijkstra Lista (reorder)



Vértices explorados:

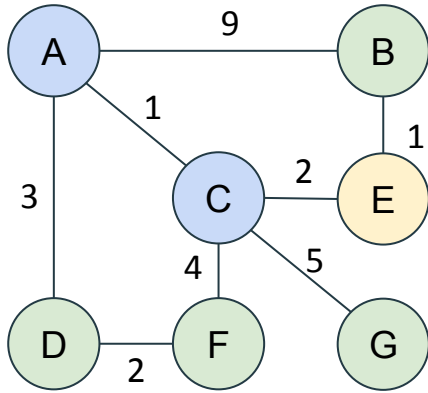


Lista encadeada ordenada dos vértices descobertos:

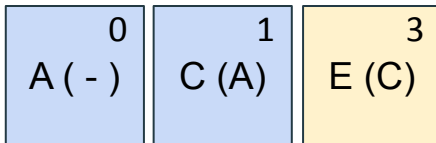


Lista:	A	B	C	D	E	F	G
vértices	[&A, &B, &C, &D, &E, &F, &G]						
head	&D						
tail	&G						

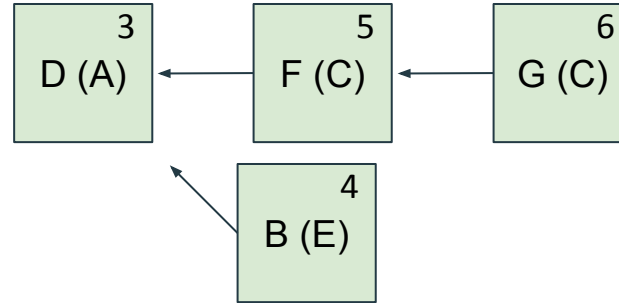
# Dijkstra Lista (reorder)



Vértices explorados:

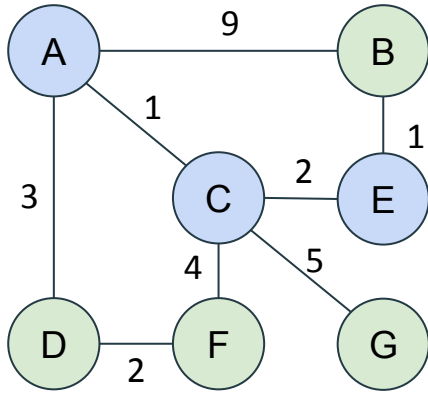


Lista encadeada ordenada dos vértices descobertos:

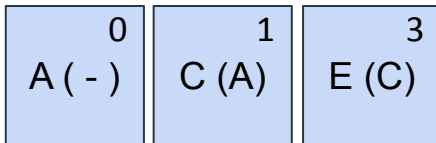


Lista:	A	B	C	D	E	F	G
vértices	[&A, &B, &C, &D, &E, &F, &G]						
head	&D						
tail	&G						

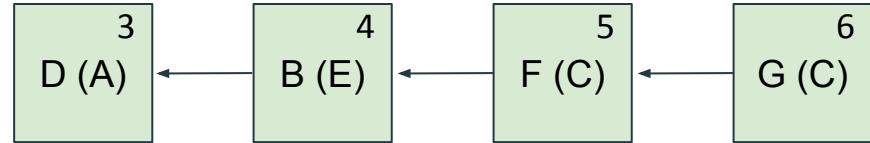
# Dijkstra Lista (reorder)



Vértices explorados:



Lista encadeada ordenada dos vértices descobertos:

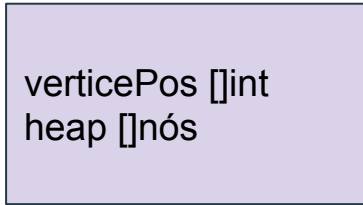


Lista:	A	B	C	D	E	F	G
vértices	[&A, &B, &C, &D, &E, &F, &G]						
head	&D						
tail	&G						

# Dijkstra Heap

Estruturas:

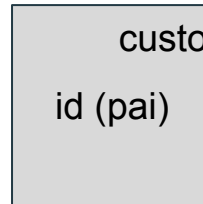
```
9  type Heap struct {  
10  |   vertexPos []int  
11  |   heap      []HeapNode  
12  | }  
13
```



vertexPos n\*64 bits  
heap n\*128bits

$$(128 + 64) * n = 192 * n$$

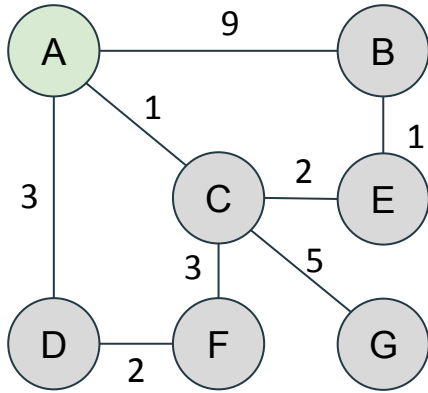
```
2  
3  type HeapNode struct {  
4  |   id      uint32  
5  |   father  uint32  
6  |   cost    float64  
7  | }  
8
```



id 32 bits  
pai 32 bits  
custo 64 bits

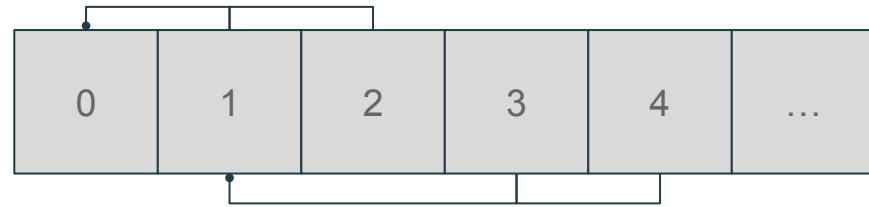
$$(32 * 2 + 64) = 128$$

# Dijkstra Heap



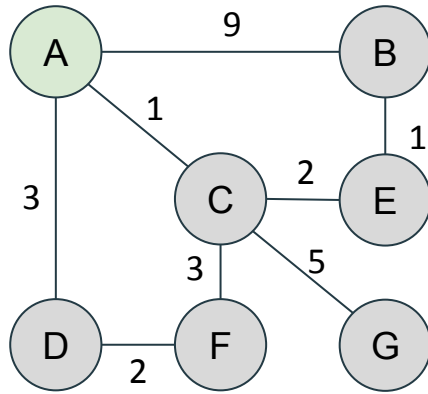
Vértices explorados:

Árvore de Heap:



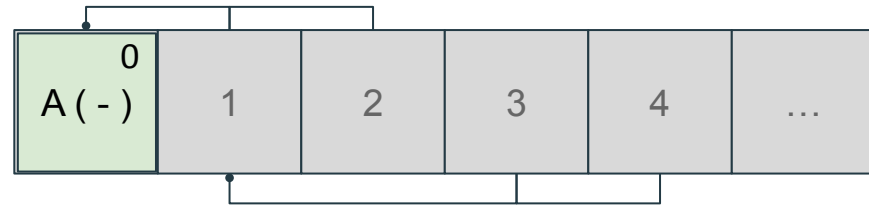
	A	B	C	D	E	F	G
verticePos	-1	-1	-1	-1	-1	-1	-1
heap							

# Dijkstra Heap



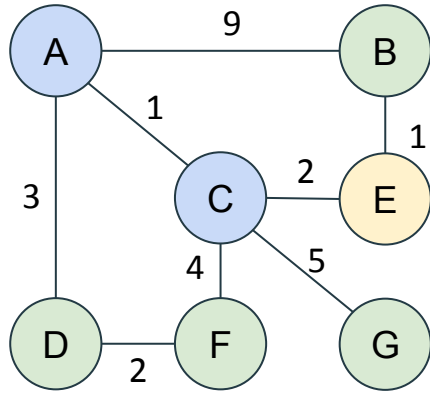
Vértices explorados:

Árvore de Heap:



	A	B	C	D	E	F	G
verticePos	[0, -1, -1, -1, -1, -1, -1]						
heap	[ ]						

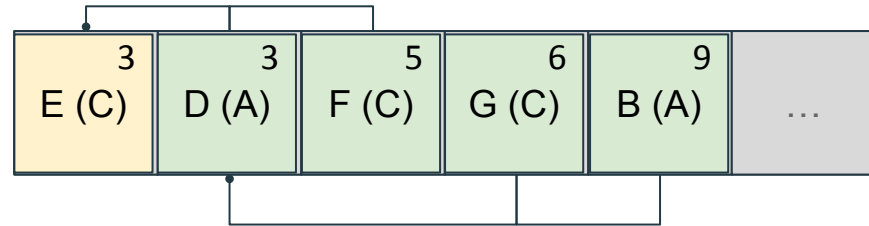
# Dijkstra Heap (pop)



Vértices explorados:

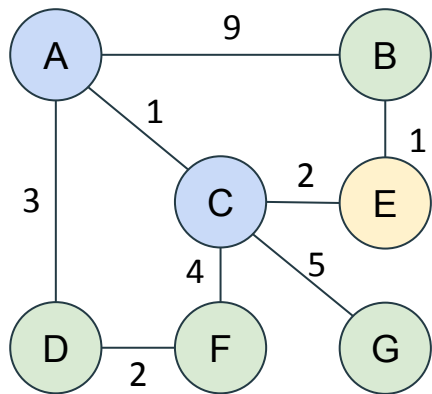
0	1
A (-)	C (A)

Árvore de Heap:

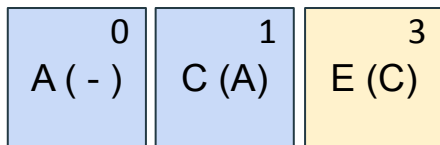


	A	B	C	D	E	F	G
verticePos	[-2	4	-2	1	0	2	3]
heap	[						]

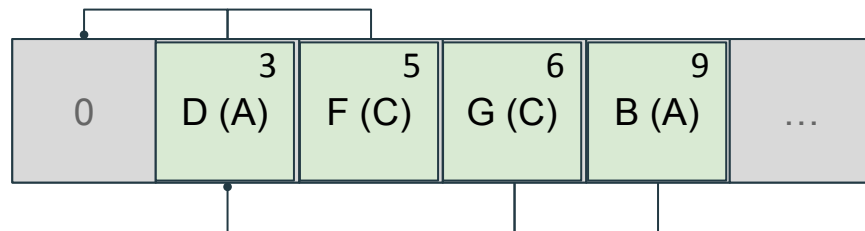
# Dijkstra Heap (pop)



Vértices explorados:



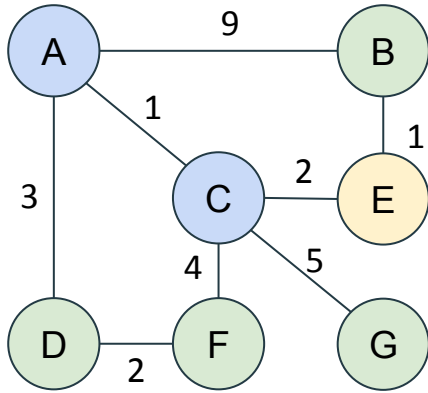
Árvore de Heap:



	A	B	C	D	E	F	G
verticePos	[-2, 4, -2, 1, -2, 2, 3]						
heap	[ ]						



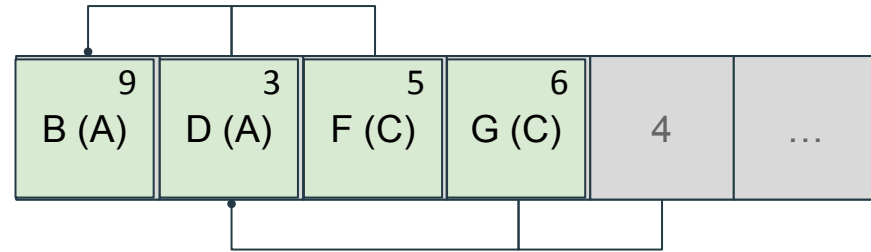
# Dijkstra Heap (bubbleDown)



Vértices explorados:

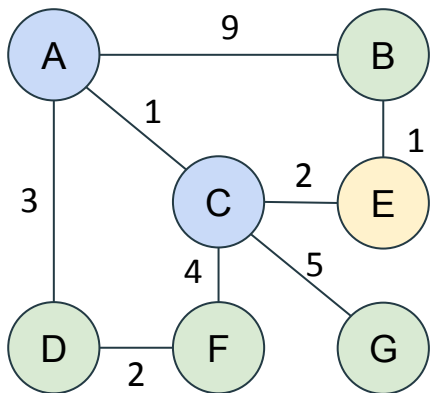
0	1	3
A (-)	C (A)	E (C)

Árvore de Heap:

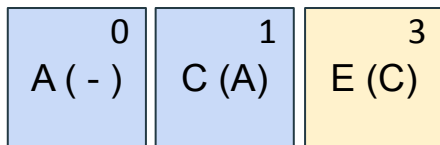


	A	B	C	D	E	F	G
verticePos	[-2,	0,	-2,	1,	-2,	2,	3]
heap	[						]

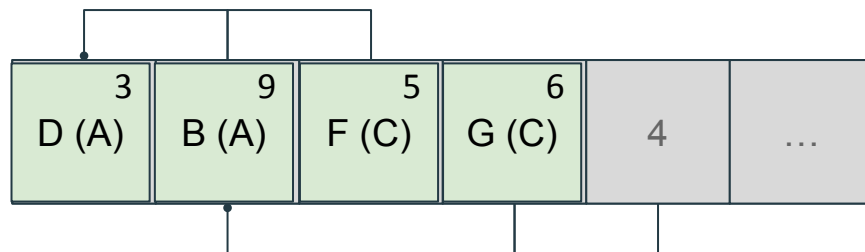
# Dijkstra Heap (bubbleDown)



Vértices explorados:

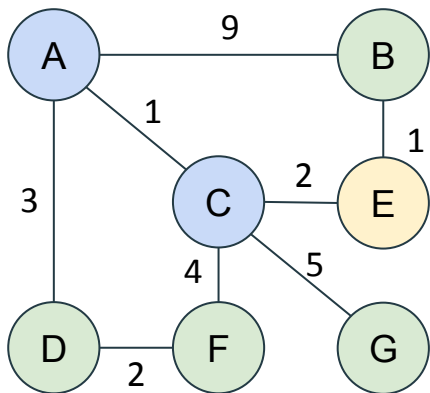


Árvore de Heap:

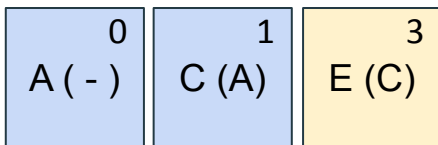


	A	B	C	D	E	F	G
verticePos	[-2, 2, -2, 1, -2, 0, 3]						
heap	[ ]						

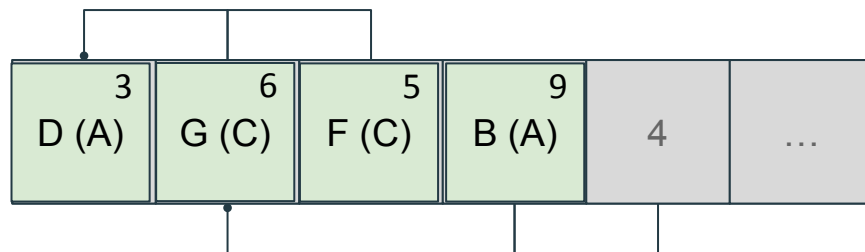
# Dijkstra Heap (bubbleDown)



Vértices explorados:

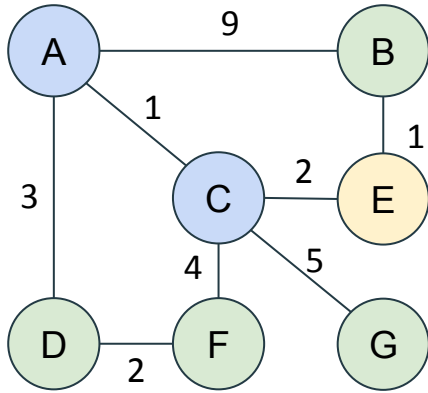


Árvore de Heap:

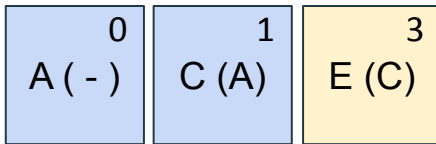


	A	B	C	D	E	F	G
verticePos	[-2, 3, -2, 0, -2, 2, 1]						
heap	[ ]						

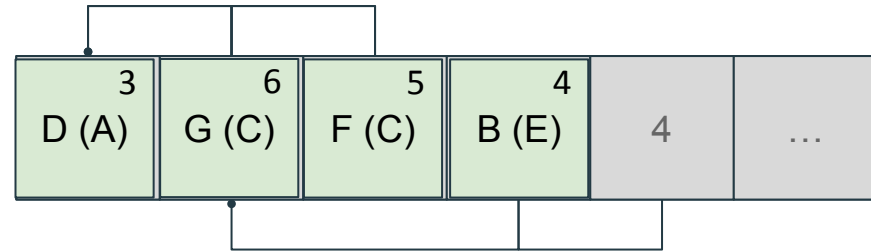
# Dijkstra Heap (update)



Vértices explorados:

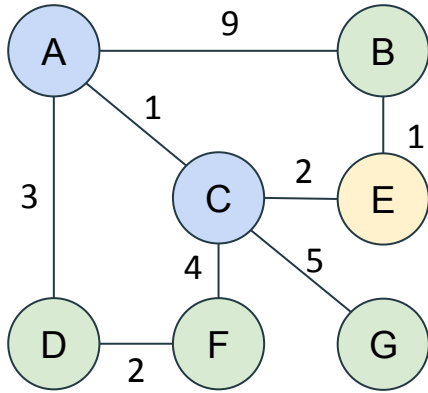


Árvore de Heap:



	A	B	C	D	E	F	G
verticePos	[-2, 3, -2, 0, -2, 2, 1]						
heap	[ ]						

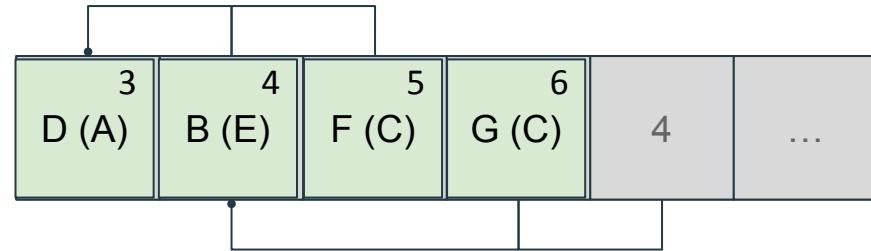
# Dijkstra Heap (bubbleUp)



Vértices explorados:

0	1	3
A (-)	C (A)	E (C)

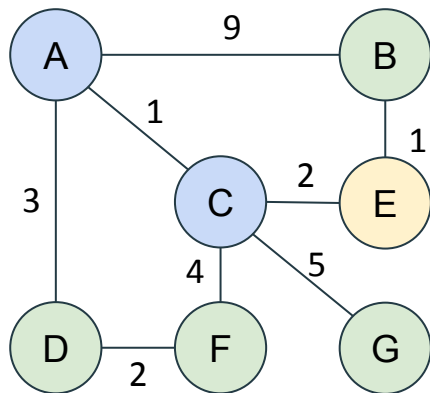
Árvore de Heap:



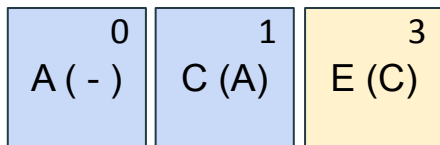
	A	B	C	D	E	F	G
verticePos	[-2,	1,	-2,	0,	-2,	2,	3]
heap	[						]

# Árvore Mínima (Prim)

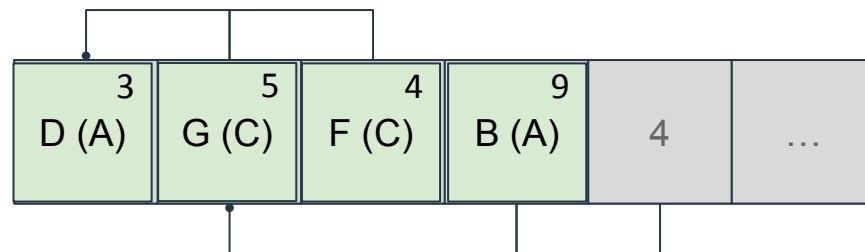
Muito parecido com o que acabamos de ver



Vértices explorados:



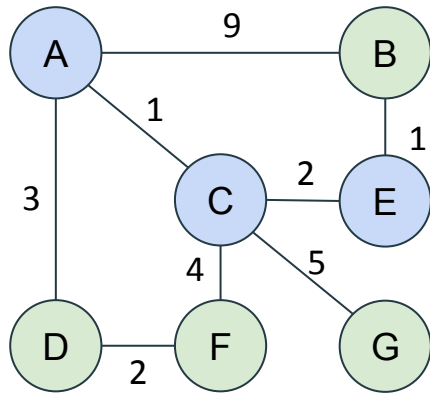
Árvore de Heap:



	A	B	C	D	E	F	G
verticePos	-2	3	-2	0	-2	2	1
heap							

# Árvore Mínima (Prim)

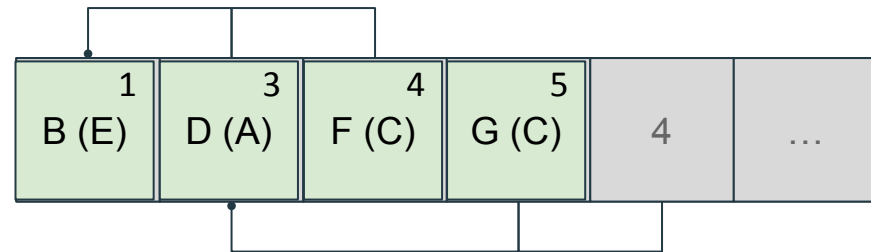
Muito parecido com o que acabamos de ver



Vértices explorados:

0	1	3
A ( - )	C (A)	E (C)

Árvore de Heap:



	A	B	C	D	E	F	G
verticePos	[-2,	0,	-2,	1,	-2,	2,	3]
heap	[ ]						

# Resultados

Grafo	Tempo médio das distâncias (seg)	Distância (10, 20)	Distância (10, 30)	Distância (10, 40)	Distância (10, 50)	Distância (10, 60)	Peso da MST
grafo 1	$7.95 * 10^{-4}$	1.52	1.48	1.52	1.39	1.38	220.11
grafo 2	$8.91 * 10^{-3}$	2.08	1.92	1.61	1.34	1.69	2247.07
grafo 3	0.173	1.98	2.08	2.14	1.82	2.23	22218.71
grafo 4	3.23	2.46	2.43	2.33	2.36	2.61	221937.54
grafo 5	4.40	14.03	12.01	13.66	9.22	14.47	4785814.85



# Resultados

Pesquisador	Distância (até Dijkstra)	Caminho mínimo (com os nomes)
Alan M. Turing	-	(sem caminho)
J. B. Kruskal	3.48 (8 arestas)	<b>Edsger W. Dijkstra</b> > John R. Rice > Dan C. Marinescu > Howard Jay Siegel > Edwin K. P. Chong > Ness B. Shroff > R. Srikant > Albert G. Greenberg > <b>J. B. Kruskal</b>
Jon M. Kleinberg	2.71 (9 arestas)	<b>Edsger W. Dijkstra</b> > A. J. M. van Gasteren > Gerard Tel > Hans L. Bodlaender > Dimitrios M. Thilikos > Prabhakar Ragde > Avi Wigderson > Eli Upfal > Prabhakar Raghavan > <b>Jon M. Kleinberg</b>
Eva Tardos	2.75 (11 arestas)	<b>Edsger W. Dijkstra</b> > A. J. M. van Gasteren > Gerard Tel > Hans L. Bodlaender > Jan van Leeuwen > Mark H. Overmars > Micha Sharir > Haim Kaplan > Robert Endre Tarjan > Andrew V. Goldberg > Serge A. Plotkin > <b>Eva Tardos</b>
Daniel R. Figueiredo	2.94 (8 arestas)	<b>Edsger W. Dijkstra</b> > John R. Rice > Dan C. Marinescu > Chuang Lin > Bo Li > Y. Thomas Hou > Zhi-Li Zhang > Donald F. Towsley > <b>Daniel R. Figueiredo</b>

# Resultados

	Lista encadeada	Árvore de heap	k
<b>grafo 1</b>	169.50ms	61.48ms	100
<b>grafo 2</b>	33.38s	1.44s	100
<b>grafo 3</b>	2h 25m 43s	31.00s	100
<b>grafo 4</b>	14h 45m 27s (~61d)	5.45s (9m 5s)	1
<b>grafo 5</b>	+48h	13.95s (23m 15s)	1