

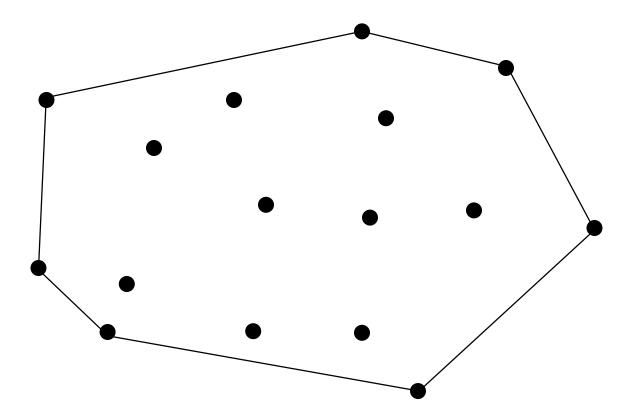
CS133 Computational Geometry

Convex Hull

Convex Hull

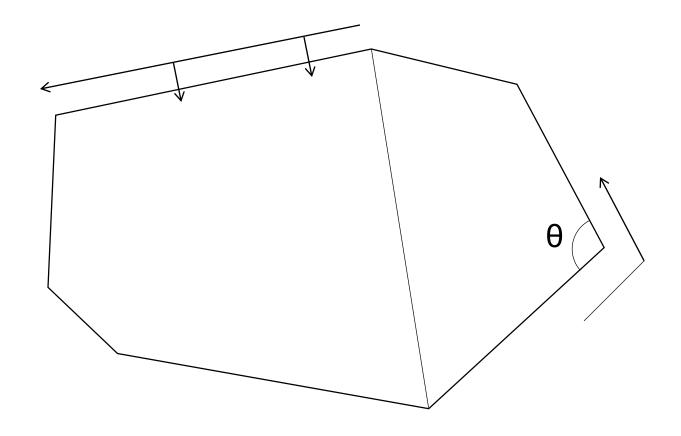


Given a set of n points, find the minimal convex polygon that contains all the points



Convex Hull Properties

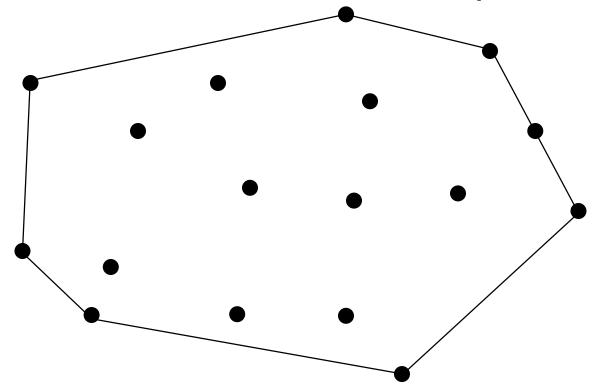




Convex Hull Representation



- The convex hull is represented by all its points sorted in CW/CCW order
- Special case: Three collinear points



Naïve Convex Hull Algorithm



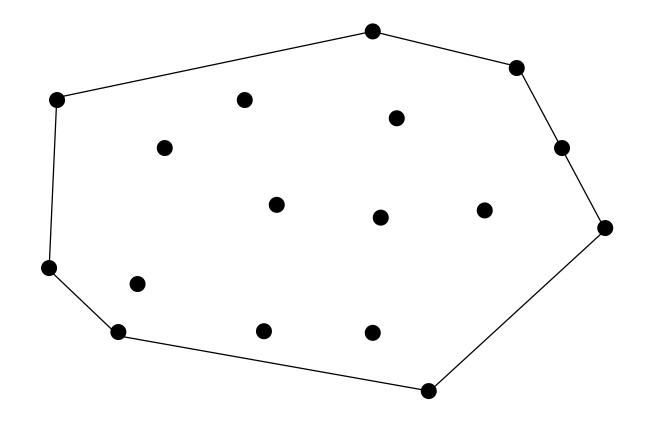
- Iterate over all possible line segments
- A line segment is part of the convex hull if all other points are to its left
- Emit all segments in a CCW order

> Running time $O(n^3)$

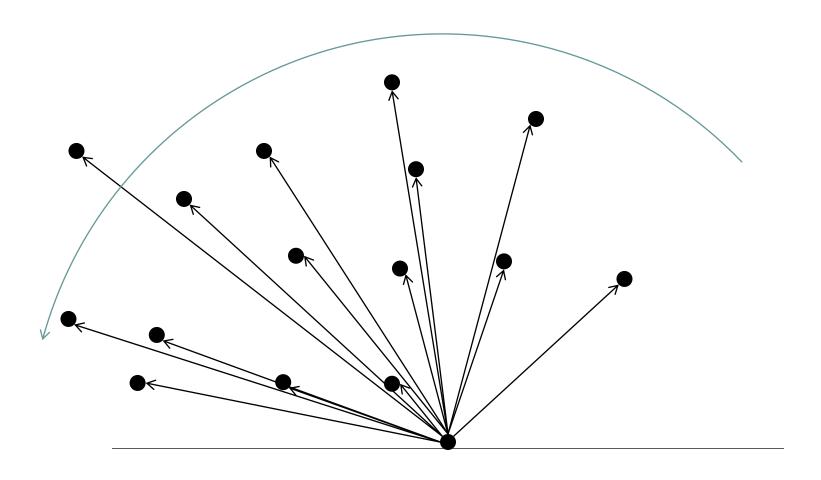
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Naïve Convex Hull Algorithm

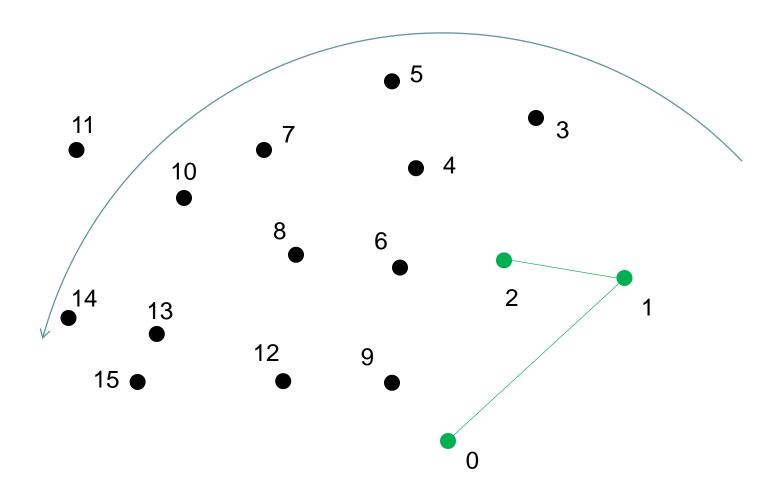




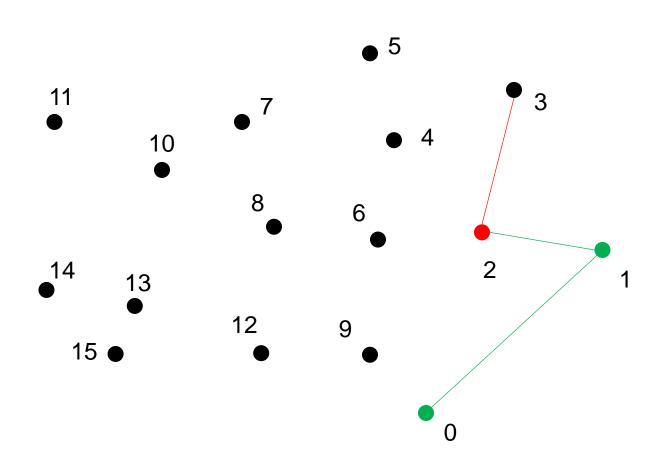




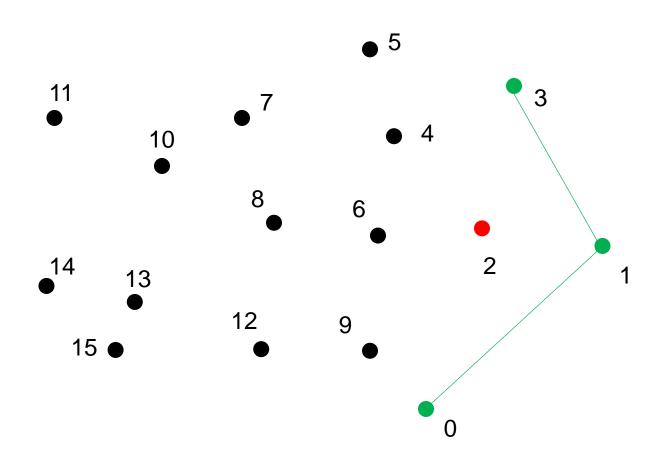




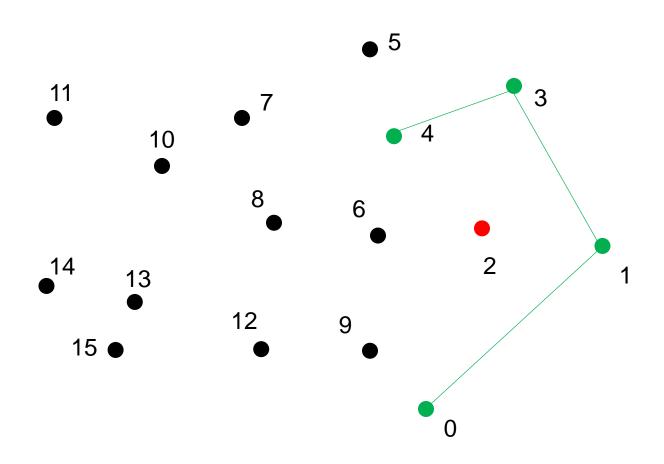




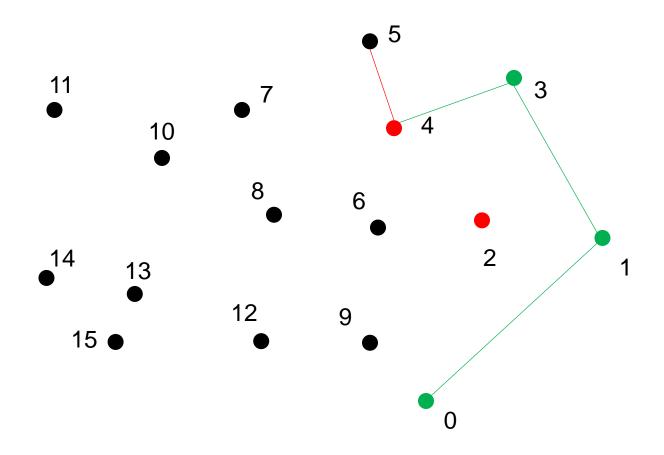




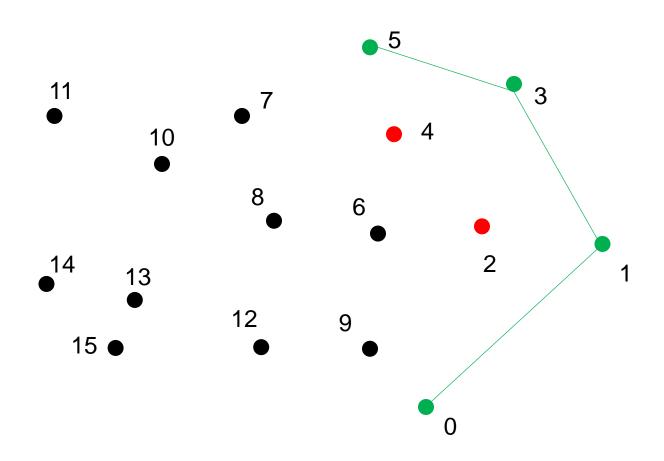




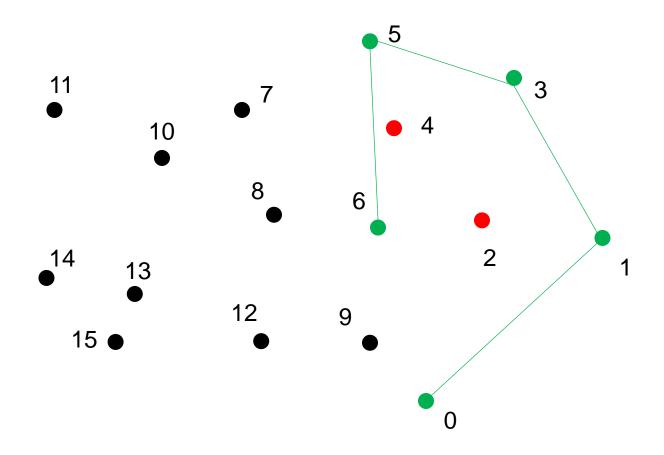




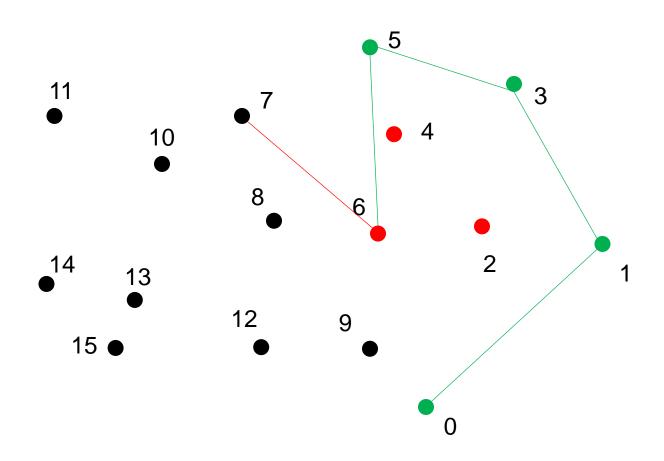




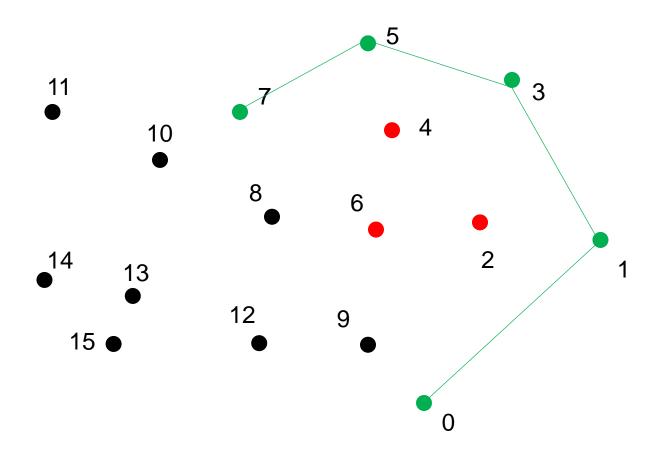




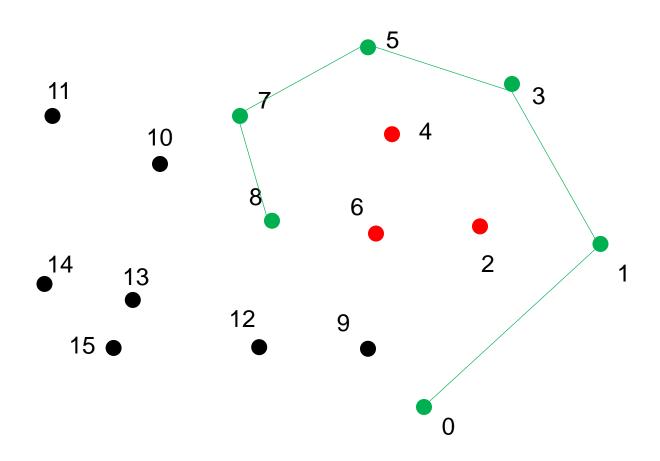




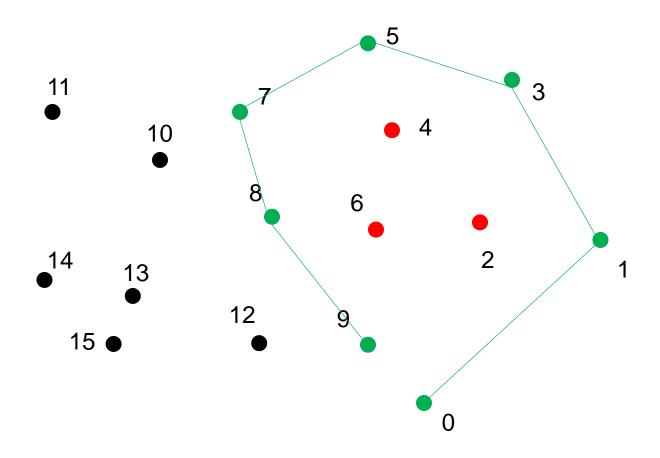




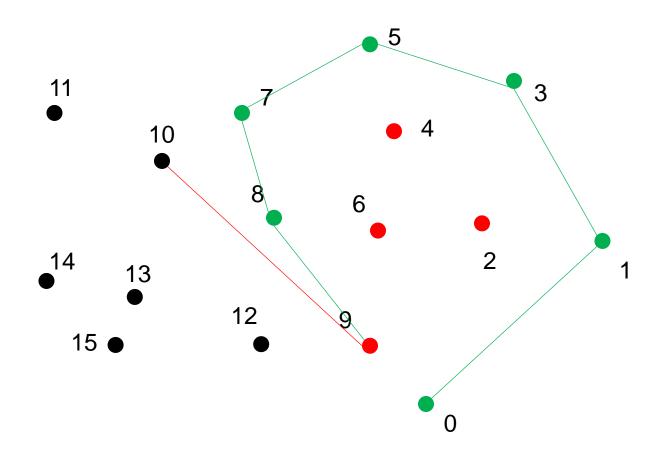




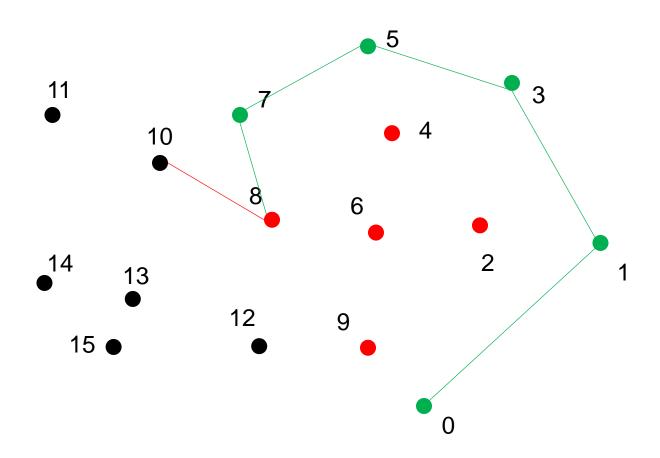




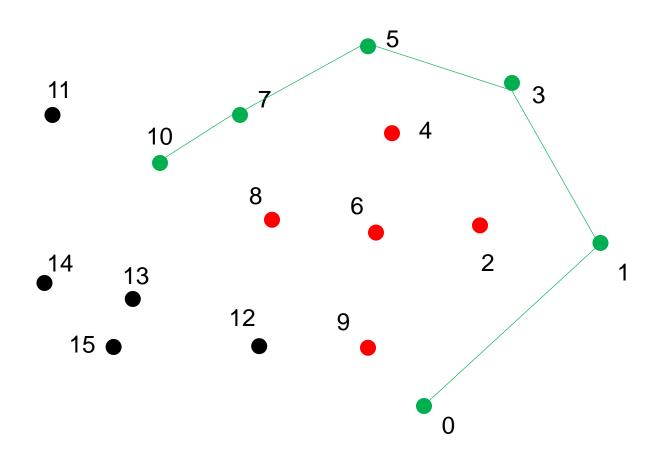




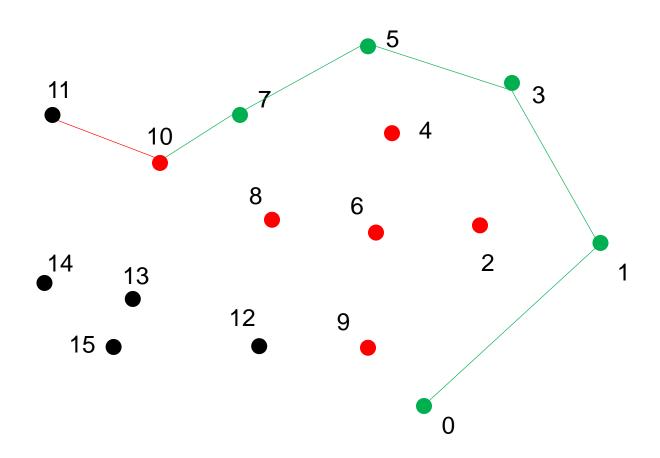




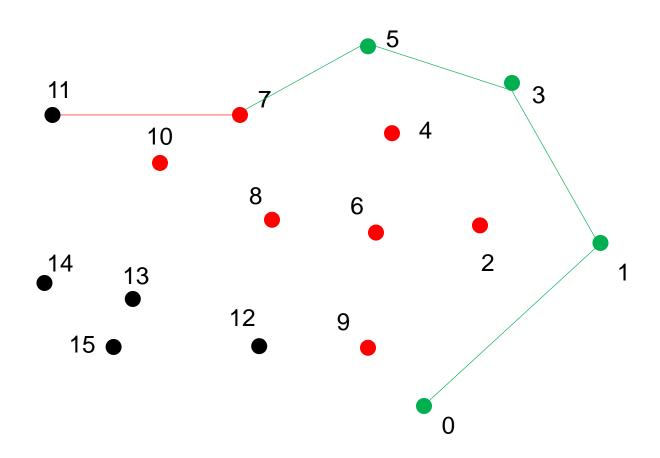




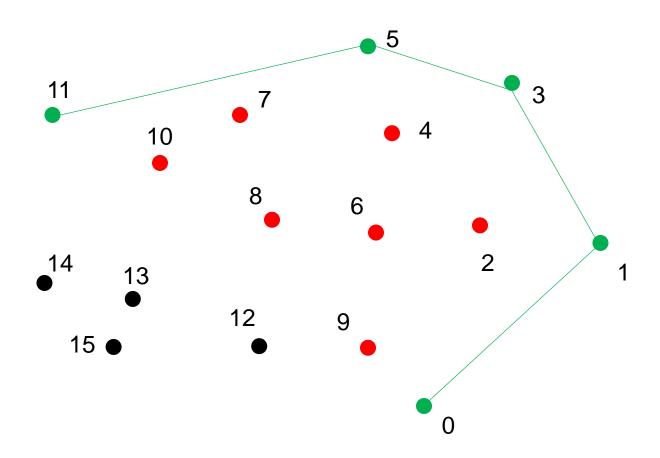




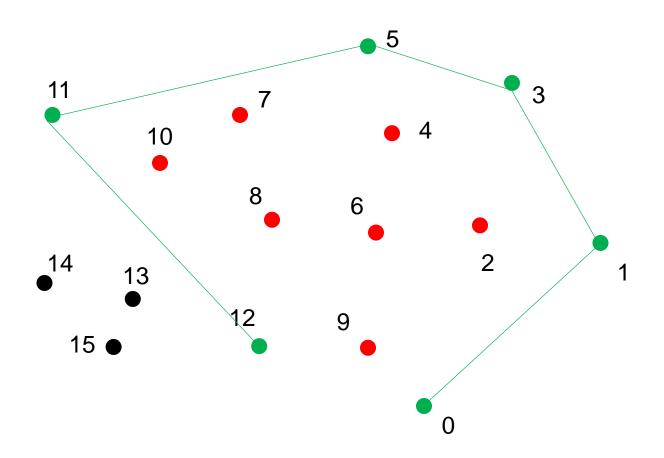




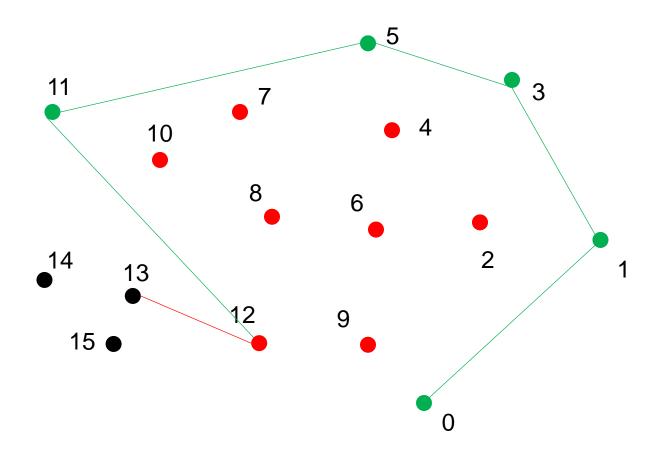




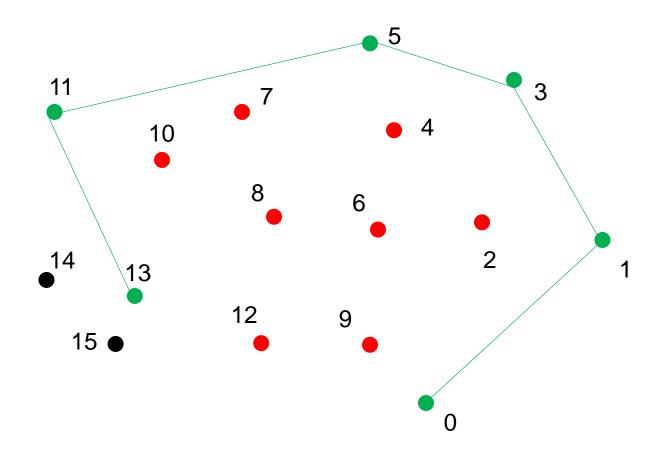




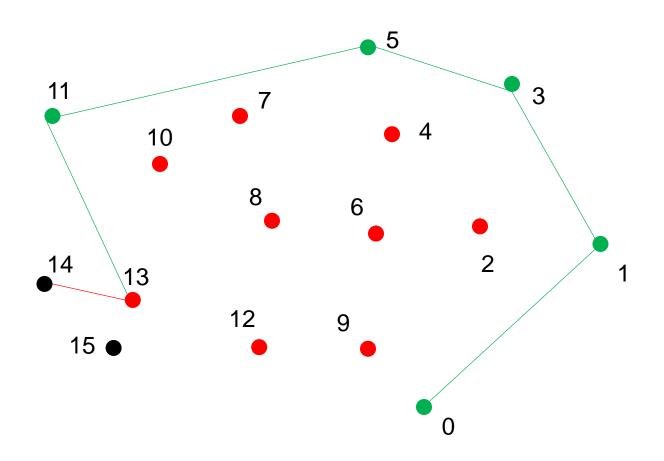




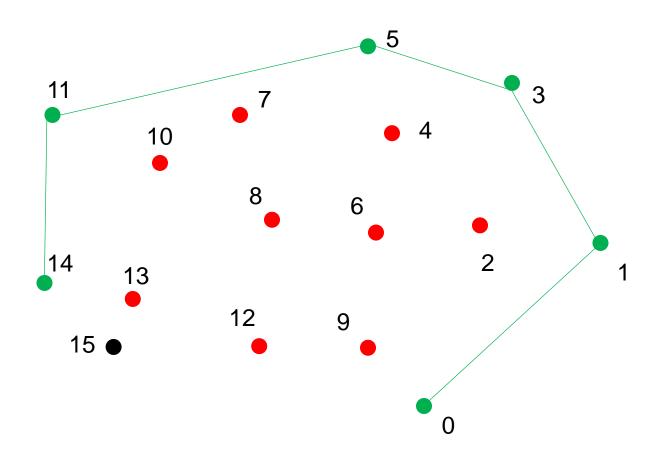




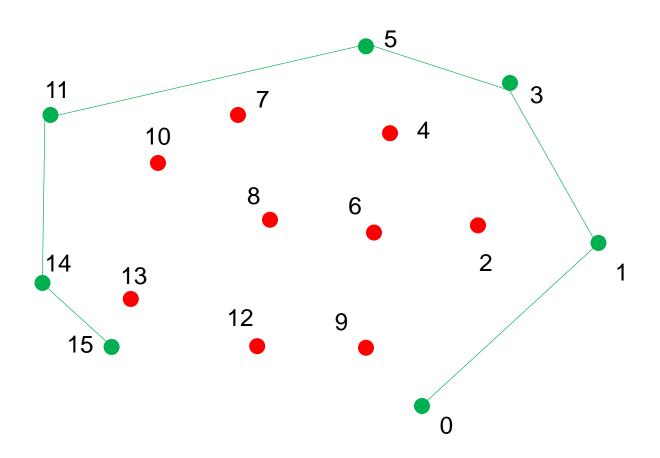




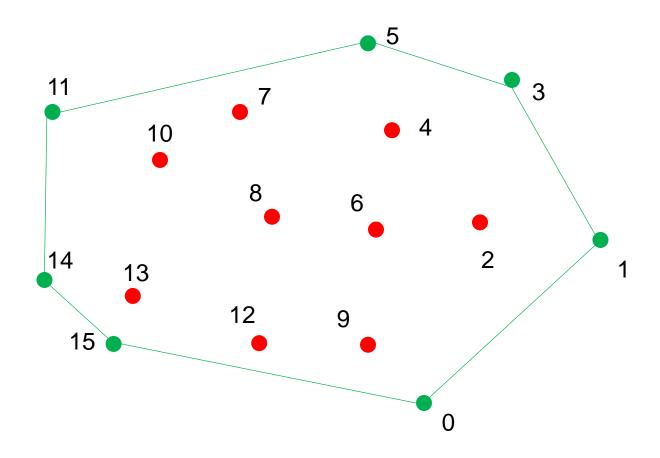






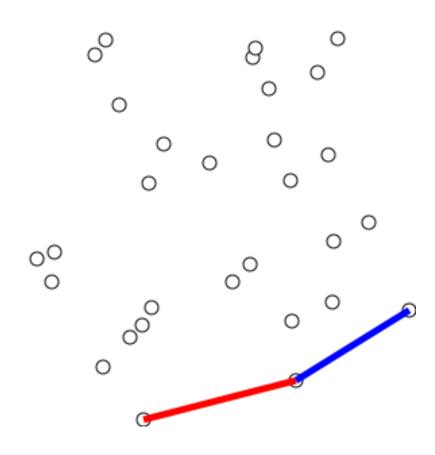






Example





Graham Scan Pseudo Code

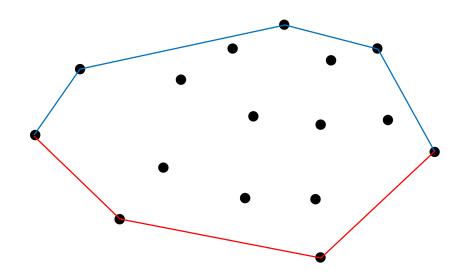


- Select the point with minimum y
- Sort all points in CCW order {p₀,p₁,...,p_n)
- $> S = \{p_0, p_1\}$
- \rightarrow For i=2 to n
 - While $|S| > 2 \&\& p_i$ is to the right of S_{-2}, S_{-1}
 - S.pop
 - \rightarrow S.push(p_i)

Monotone Chain Algorithm



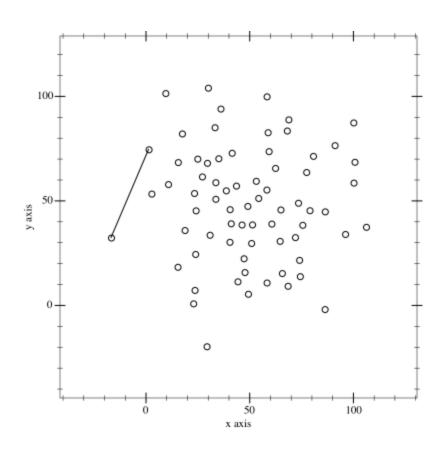
- Has some similarities with Graham scan algorithm
- Instead of sorting in CCW order, it sorts by one coordinate (e.g., x-coordinates)



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Example





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Pseudo Code

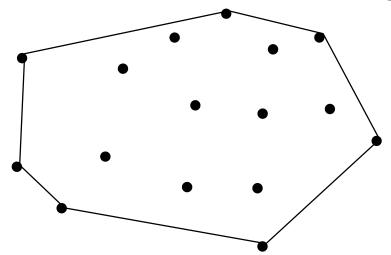


- Sort S by x
- $V = \{S_0\}$
- \rightarrow For i = 1 to n
 - while $|U| > 1 \&\& S_i$ is to the left of $\overline{U_{-2}U_{-1}}$
 - U.pop
 - U.push(S_i)
- $L = \{S_0\}$
 - While $|L| > 1 \&\& S_i$ is to the right of $\overline{L_{-2}L_{-1}}$
 - L.pop
 - L.push(S_i)

Gift Wrapping Algorithm

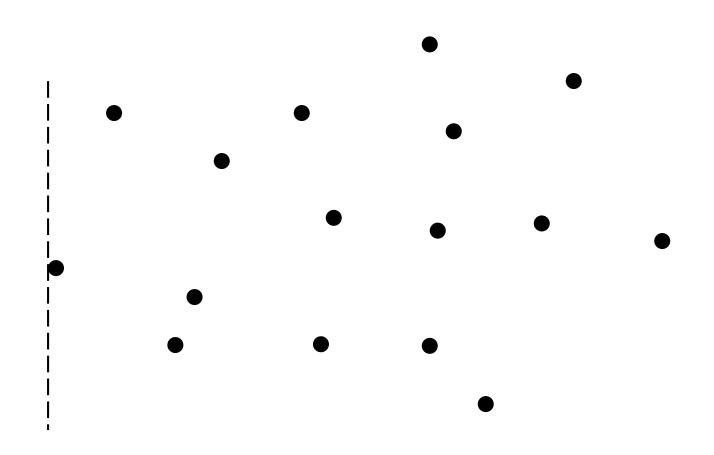


- Start with a point on the convex hull
- Find more points on the hull one at a time
- Terminate when the first point is reached back
- Also knows as Jarvi's March Algorithm

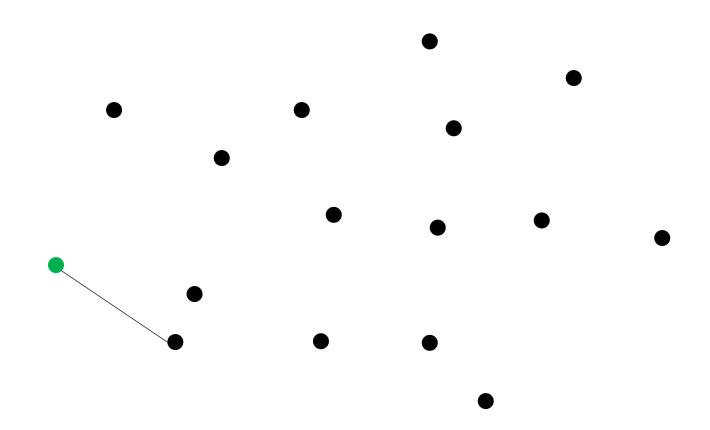


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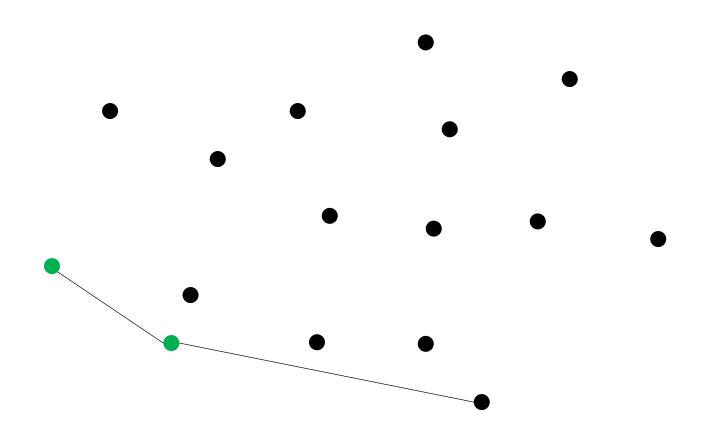




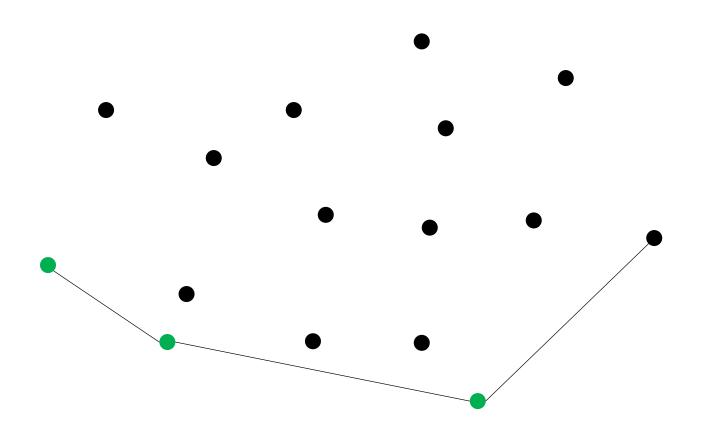




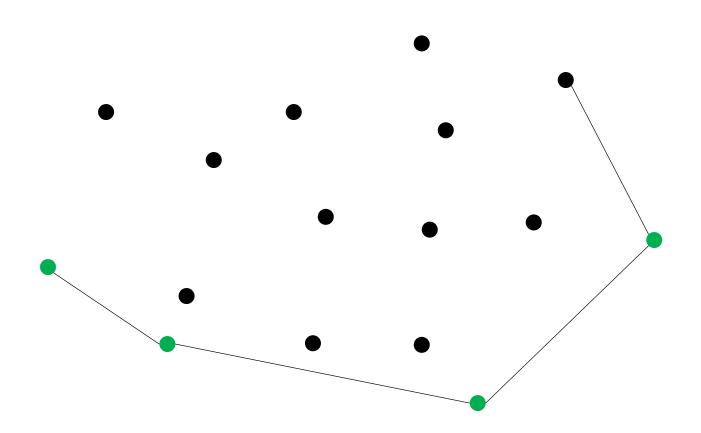




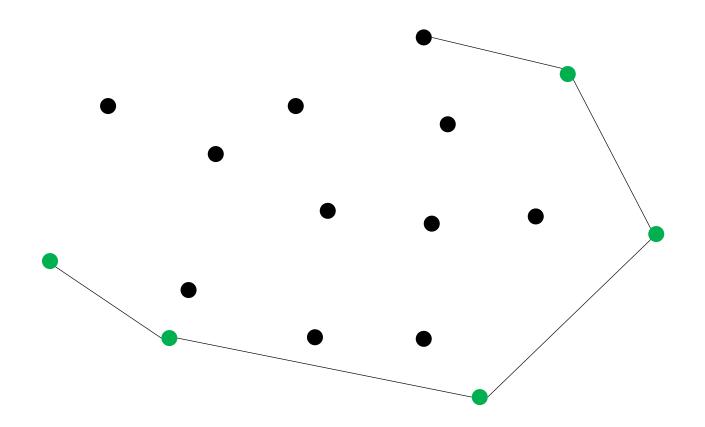




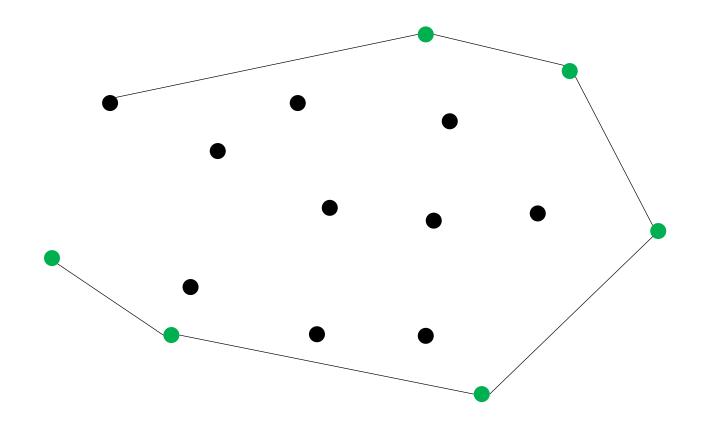




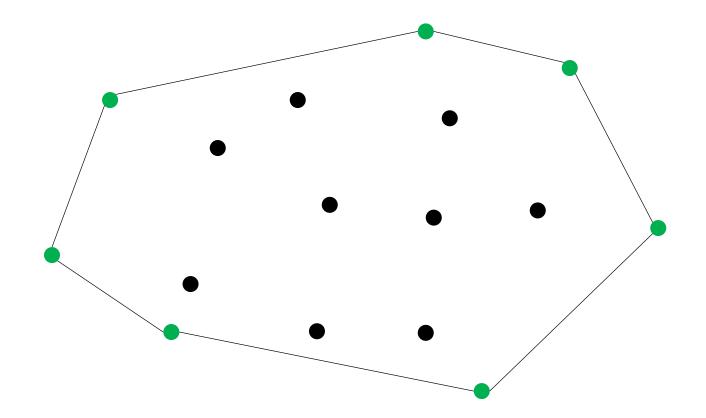




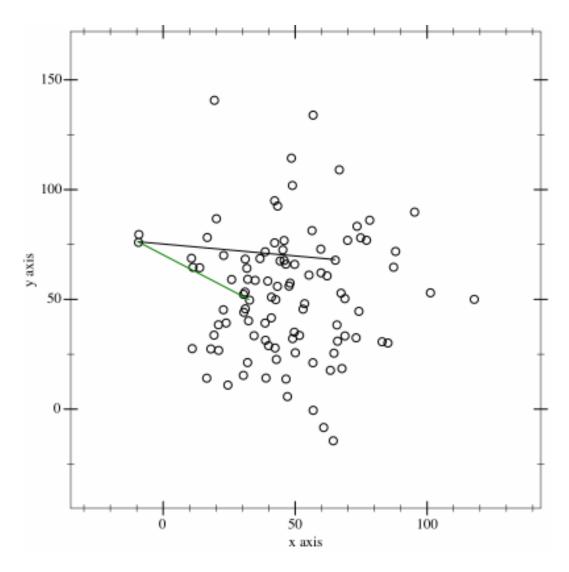












Gift Wrapping Pseudo Code

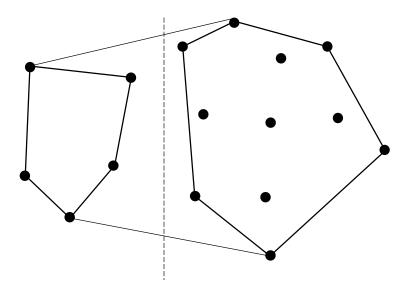


- Gift Wrapping(S)
 - > CH = {}
 - CH << Left most point</p>
 - do
 - Start point = CH.last
 - End point = CH[0]
 - For each point s ∈ S
 - > If Start point = End Point OR s is to the left of $\overrightarrow{Start\ point}$, $End\ point$
 - End point = s
 - CH << End point</p>
- Running time O(n.k)

Divide & Conquer Convex Hull



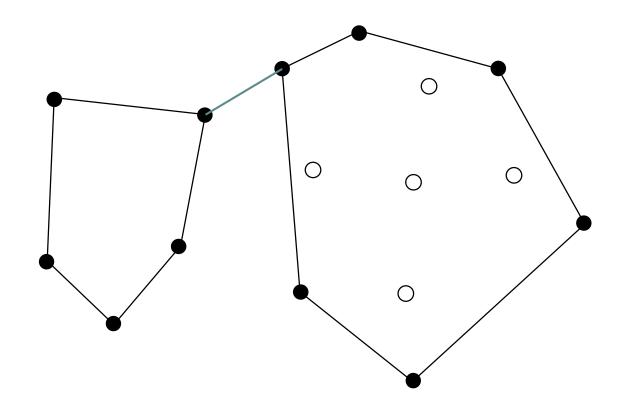
- ConvexHull(S)
 - Splits S into two subsets S1 and S2
 - Ch1 = ConvexHull(S1)
 - Ch2 = ConvexHull(S2)
 - Return Merge(Ch1, Ch2)



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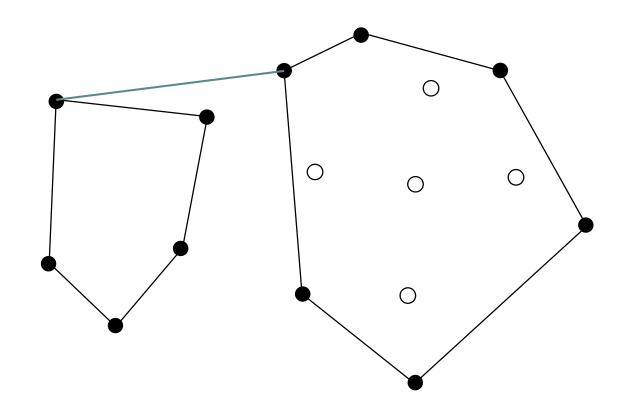
Merge: Upper Tangent





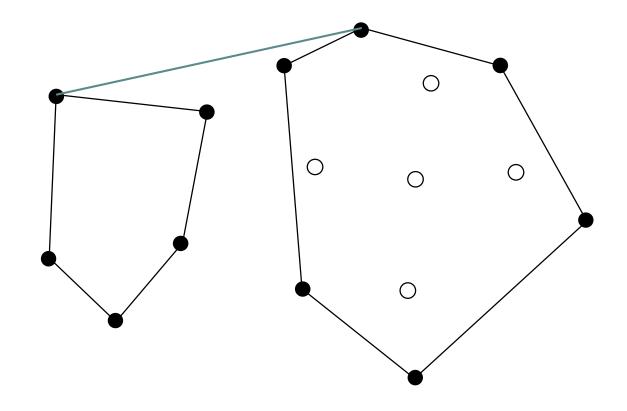
Merge: Upper Tangent



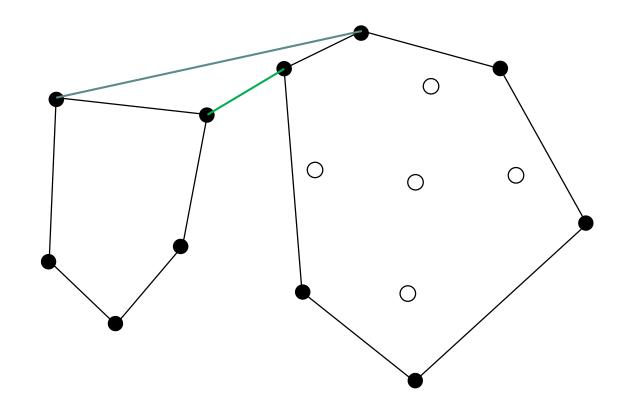


Merge: Upper Tangent

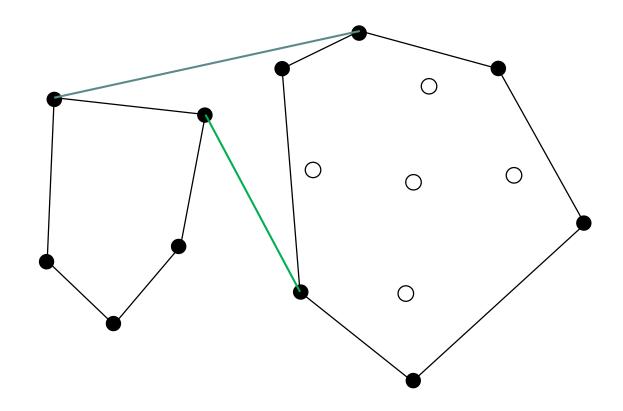




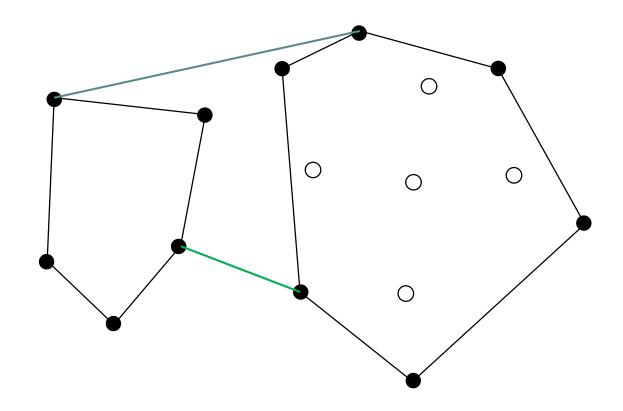




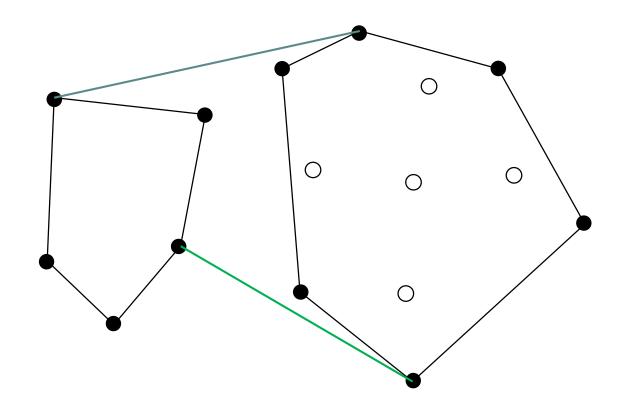




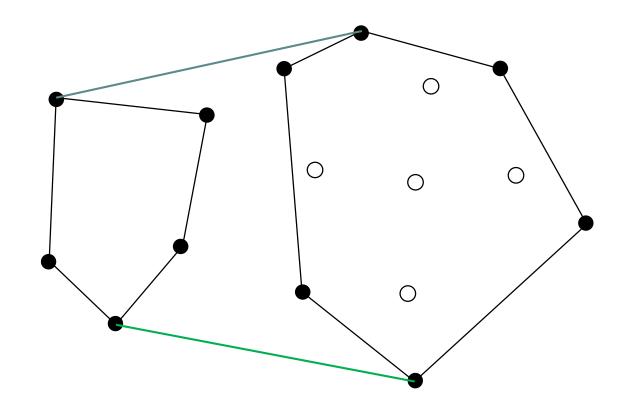




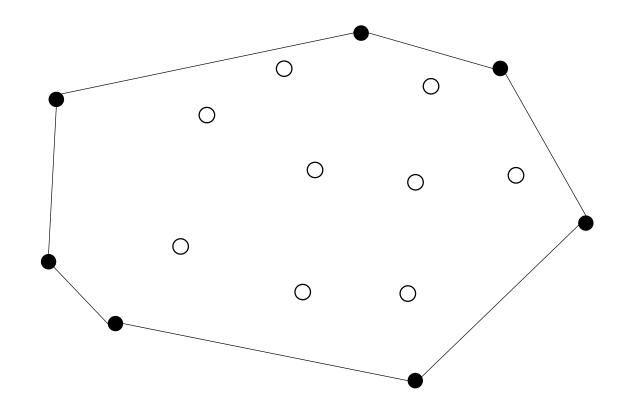












Merge Step



- Upper Tangent(L,R)
 - P_i = Right most point in L
 - P_j = Left most point in R
 - Do
 - Done = true
 - > While P_{i+1} is to the right of $\overrightarrow{p_j}\overrightarrow{p_i}$
 - i++; done = false
 - > While P_{j-1} is to the left of $\overrightarrow{p_ip_j}$
 - j--; done = false

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Analysis



- Sort step: O(n log n)
- Merge step: O(n)
- Recursive part
 - T(n)=2T(n/2)+O(n)
 - T(n)=O(n log n)
- Overall running time O(n log n)

Incremental Convex Hull

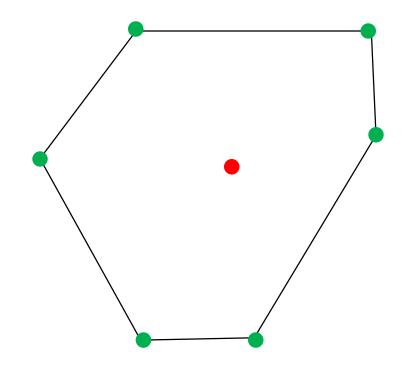


- Start with an initial convex hull
- Add one additional point to the convex hull
- Siven a convex hull CH and a point p, how to compute the convex hull of {CH, p}?

Think: Insert an element into a sorted list

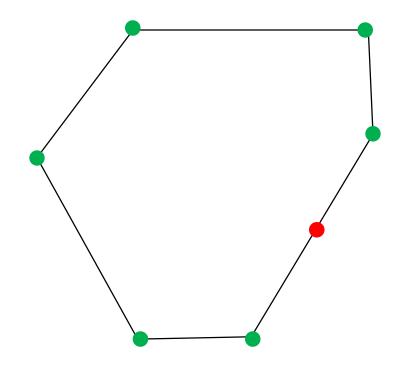
Case 1: p inside CH





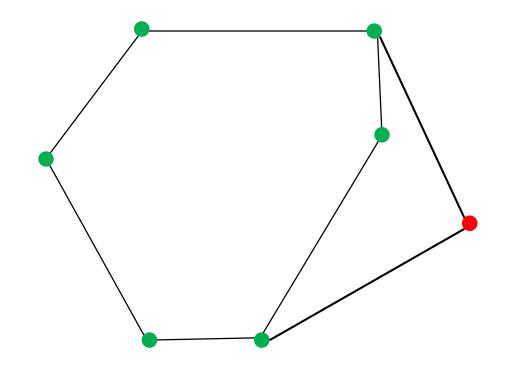
Case 2: p on CH





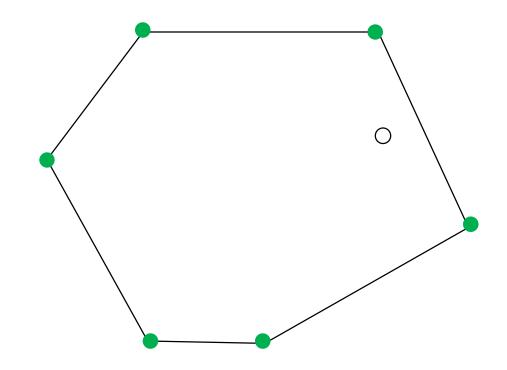
Case 3: p outside CH





Case 3: p outside CH





Analysis of the Insert Function



- Test whether the point is inside, outside, or on the polygon O(n)
- Find the two tangents O(n)

A more efficient algorithm can have an amortized running time of O(log n)

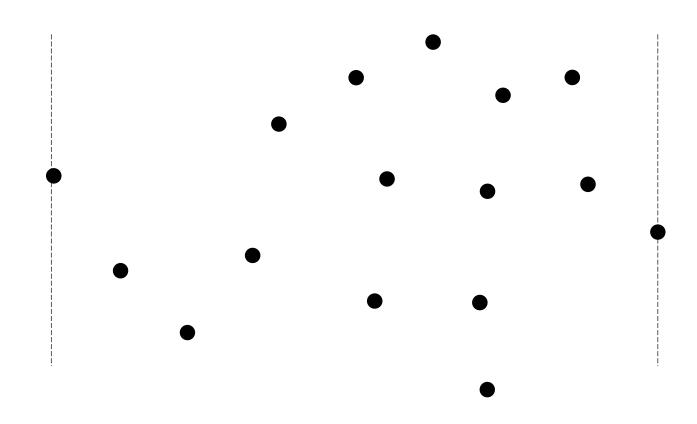
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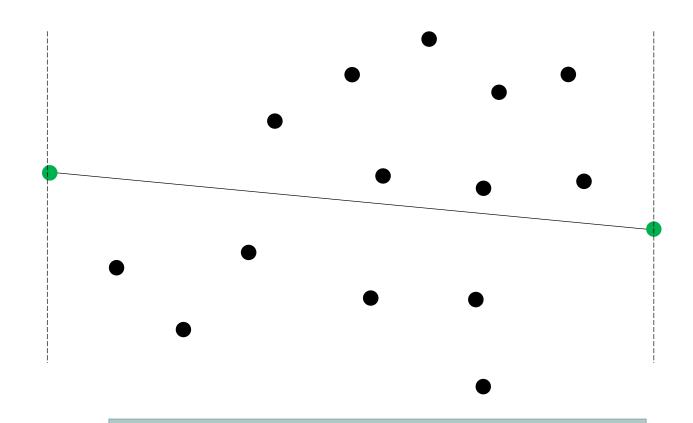
- If we can have a divide-and-conquer algorithm similar to merge sort ...
- why not having an algorithm similar to quick sort?
- > Sketch
 - Find a pivot
 - Split the points along the pivot
 - Recursively process each side

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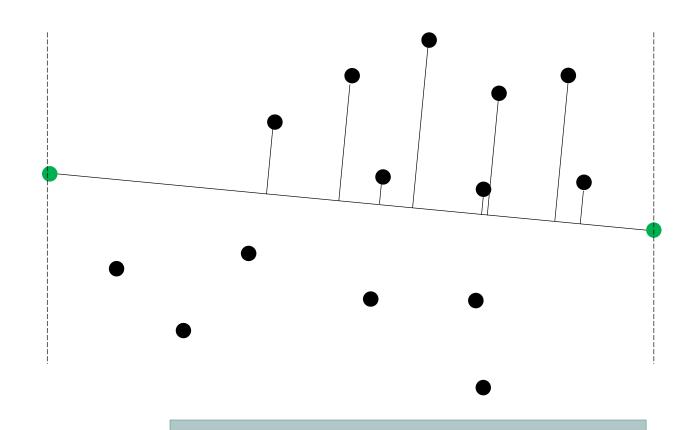






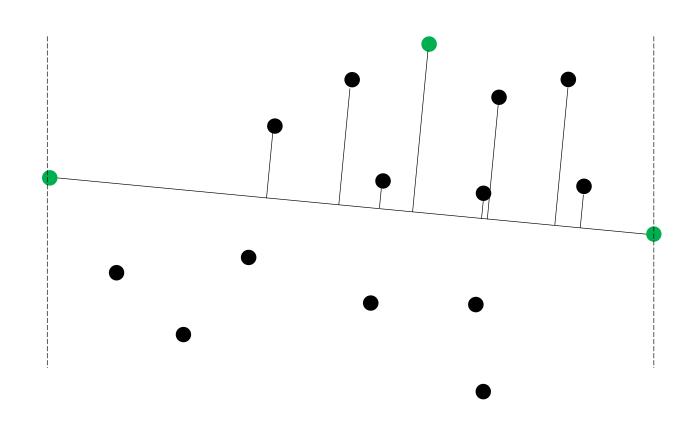
How to split the points across the line segment?



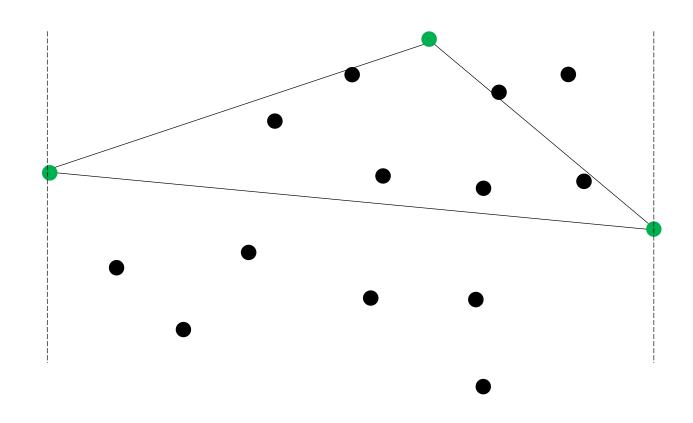


How to select the farthest point?

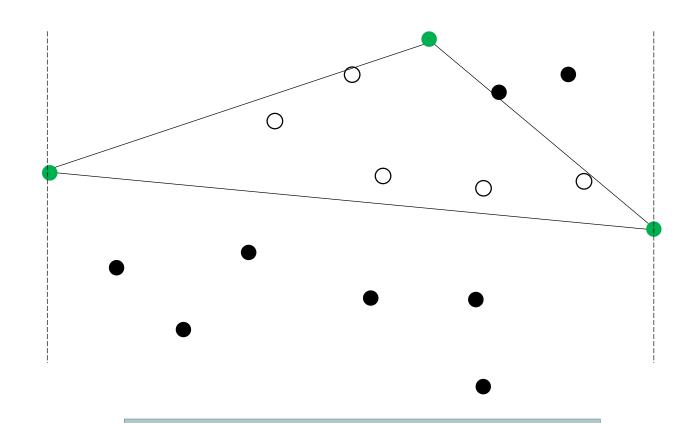






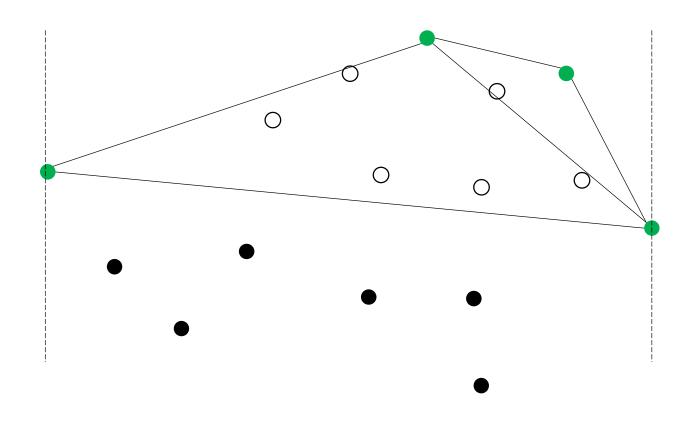




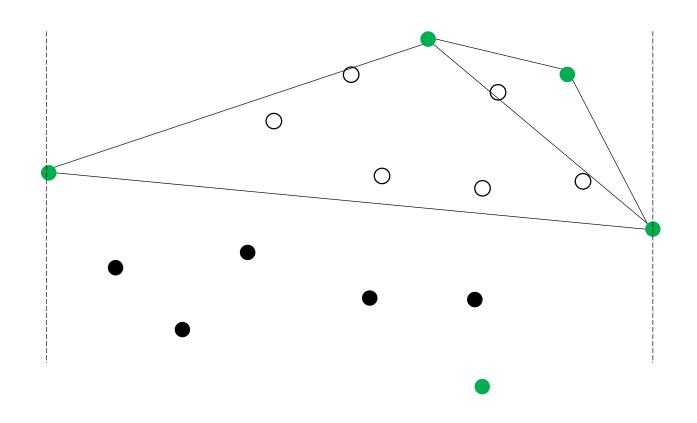


How to split the points into three subsets?

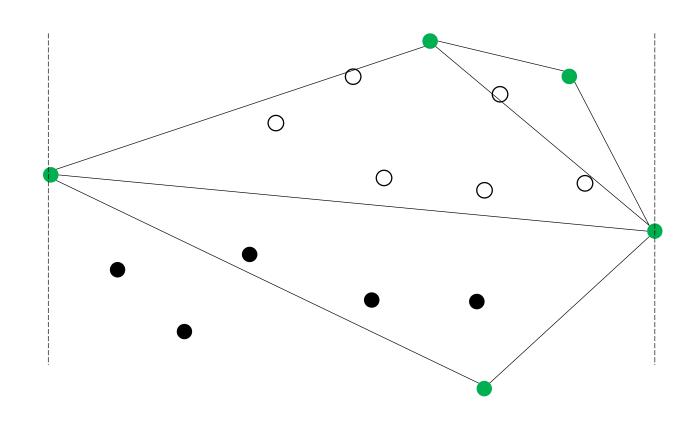




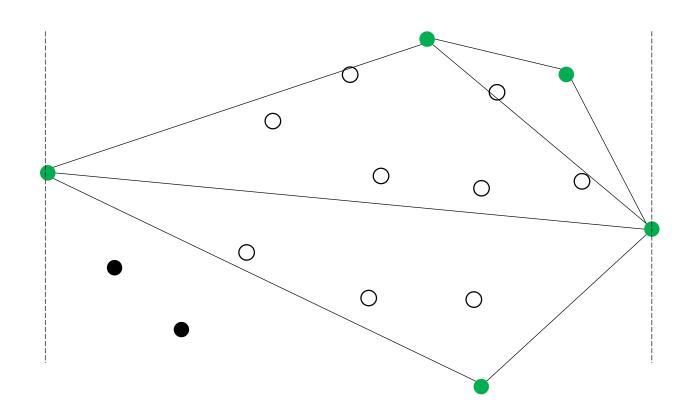




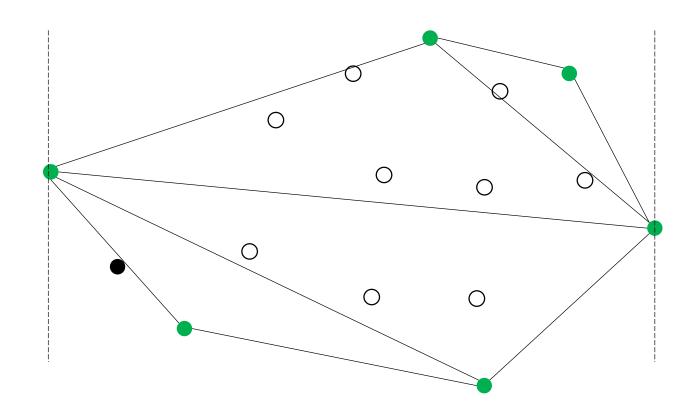




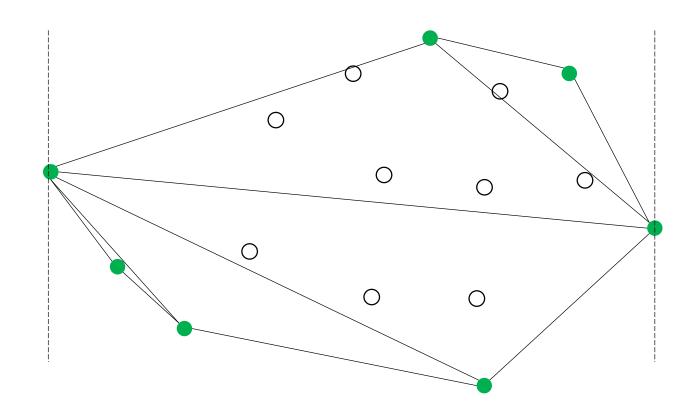




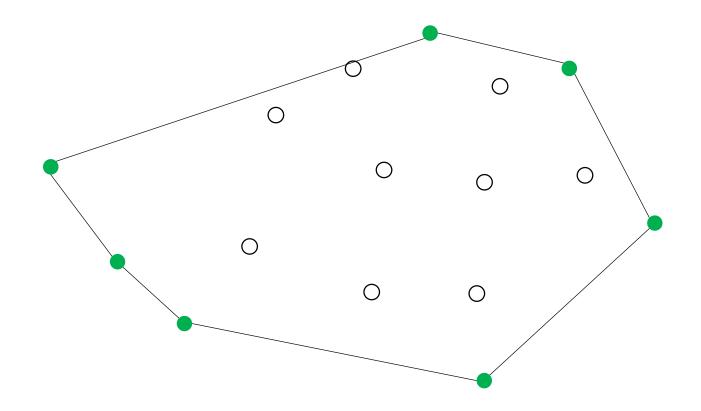






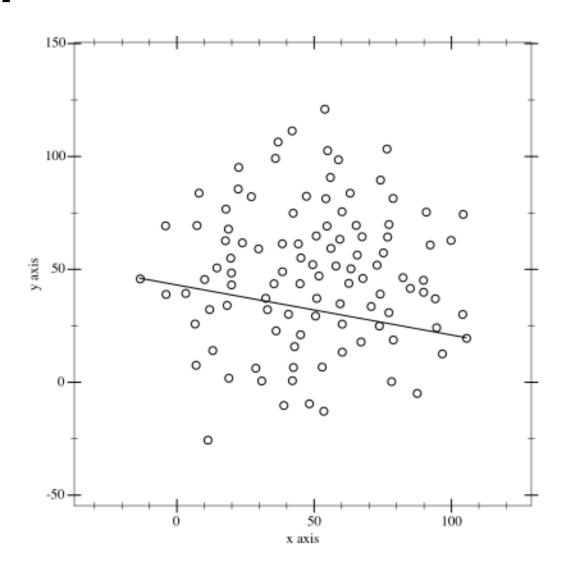






Example





Running Time Analysis



- $T(n) = T(n_1) + T(n_2) + O(n)$
- > Worst case $n_1 = n k$ or $n_2 = n k$, where k is a small constant (e.g., k=1)
 - $T(n) = O(n^2)$
- > Best case $n_1 = k$ and $n_2 = k$, where k is a small constant
 - In this case, most of the points are pruned
 - T(n) = O(n)
- > Average case, $n_1=\alpha n$ and $n_2=\beta n$, where $\alpha < 1$ and $\beta < 1$
 - $T(n) = O(n \log n)$