# BCM2835 datasheet errata

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# BCM 2835 datasheet errata

The (partial) datasheet was published here: at raspberrypi.org (http://www.raspberrypi.org/wp-content/uploads/2 012/02/BCM2835-ARM-Peripherals.pdf) and a mirror (http://dmkenr5gtnd8f.cloudfront.net/wp-content/upload s/2012/02/BCM2835-ARM-Peripherals.pdf)

It has a couple of typos. Some more serious than others.

Let's gather those datasheet typos and errors here.

The quality of the datasheet is high. It looks like it contains the information that programmers need. Some of the tables from the datasheet have been reproduced here.

It also "does the right thing" with reserved bits. Many datasheets specify "write: don't care, read as zeroes". Broadcom specifies the reserved bits the other way around: "Write zeroes, read: don't care".

This is the correct way to do it. If you expand the hardware the hardware may be enhanced and do "different things" if you write ones to the previously "reserved" bits. If you follow the datasheet, and write zeroes as specified to the reserved bits, the hardware guys can make sure you're not going to run into surprises. And by specifying "read: don't care" you can allow future hardware to provide status bits there.

# the BCM2835 on the RPI

Not really an erratum, but not worth it to make a whole page for this. The Raspberry Pi runs the BCM2835 with a core clock of 250MHz. This is relevant for the peripheral modules like I2C, SPI and Timer (ARM side) for calculating the desired clock rate. The I2C section on page 34 mentions 150MHz as a "nominal core clock".

### **PDF Generation**

Switch on option for linking, so cross-references and table of contents can be jumped through. (RPi\_BCM2835\_GPIOs contains some useful cross-references)

# p7 footnote typo

precuations should be precautions.

# **p8**

The register names are AUX\_SPIo\_.... and AUX\_SPI1\_.... . The "description" is then SPI 1 ... and SPI 2 ....

These modules are in fact SPI1 and SPI2, and NOT SPI0 and SPI1. This is confusing as indeed there is a different module called SPI0 (documented on page 148 and onwards).

Some of the register addresses in the table are incorrect or missing. The values on pages 26 and 27 are correct:

- AUXSPI0\_PEEK is at 0x7E21 508C
- AUXSPI0 IO is at 0x7E21 50A0-0x7E21 50AC
- AUXSPI0\_TXHOLD is at 0x7E21 50B0-0x7E21 50BC
- AUXSPI1\_PEEK is at 0x7E21 50CC
- AUXSPI1 IO is at 0x7E21 50E0-0x7E21 50EC
- AUXSPI1\_TXHOLD is at 0x7E21 50F0-0x7E21 50FC

#### **p10**

It says "Al 16550 register bits" when it should say "All 16550 register bits"

#### **p12**

The title should be AUX\_MU\_IER\_REG. The name in the Synopsis is correct

These are R/W bits not read only

Bits 3:2 are marked as don't care, but are actually required in order to receive interrupts.

Bits 1:0 are swaped. bit 0 is receive interrupt and bit 1 is transmit.

#### **p13**

The title should be AUX\_MU\_IIR\_REG. The name in the Synopsis is correct

#### **p14**

LCR register, bit 1 must be set for 8 bit mode, like a 16550 write a 3 to get 8-bit mode

### **p15**

The CTS status in the AUX\_MU\_MSR\_REG register should be bit 4

#### **p17**

The receiver enable and transmitter enable sections don't match the description in the AUX\_MU\_CNTL\_REG table. They should both read "If this bit **cleared** no new symbols will be..."

### p18

The "Transmitter is idle" row in the table should say "If this bit is clear the transmitter is busy."

#### **p19**

It refers to "the LABD bit" which should be "the DLAB bit"

# p24 table

Either the reserved bits at the top are too few or a field is missing.

With the reserved bits fixed it looks like this:

Bit(s)	Field Name	Description	type	reset
31:11	-	Reserved, write zero, read as don't care		
10:8	CS high time	Additional SPI clock cycles where the CS is high.	R/W	0
7	TX empty IRQ	If 1 the interrupt line is high when the transmit FIFO is empty	R/W	0
6	Done IRQ	If 1 the interrupt line is high when the interface is idle	R/W	0
5:2	-	Reserved, write zero, read as don't care		
1	Shift in MS bit first	If 1 the data is shifted in starting with the MS bit. (bit 15) If 0 the data is shifted in starting with the LS bit. (bit 0)	R/W	0
0	Keep input	If 1 the receiver shift register is NOT cleared. Thus new data is concatenated to old data. If 0 the receiver shift register is cleared before each transaction.	R/W	0

# p25 table

"AUX is IDLE:" should read "SPI is idle". (and for consistency below the line "Interrupts", SPI is Idle should be spelled "SPI is idle".

The section on page 25 about Interrupts also duplicates information already seen on page 21.

The table on page 25 has the bit numbers wrong. Some bits are mentioned twice, some not at all.

It should be something like:

Bit(s)	Field Name	Description	type	reset
II I	TX FIFO level	The number of data units in the transmit data FIFO	R/W	0
19:16	RX FIFO level	The number of data units in the receive data FIFO.	R/W	0
15:11	-	Reserved, write zero, read as don't care	R/W	0
10	X   <b>-</b>	If 1 the transmit FIFO is full If 0 the transmit FIFO can accept at least 1 data unit.	R/W	0
9	TX Empty	If 1 the transmit FIFO is empty If 0 the transmit FIFO holds at least 1 data unit.	R/W	0
8		If 1 the receiver FIFO is full If 0 the receiver FIFO can accept at least 1 data unit.	R/W	0
7		If 1 the receiver FIFO is empty If 0 the receiver FIFO holds at least 1 data unit.	R/W	0
6	Busy	Indicates the module is busy transferring data.	R/W	0

5:0		The number of bits still to be processed. Starts with 'shift-length' and counts down.	R/W	0
-----	--	---	-----	---

The register reads as 0x280 after reset. Two bits high would be consistent with TX empty and RX empty.

### **p26**

The Peek register is documented here as being at 0x7e21508e, whereas the table on page 8 shows 0x7e215094.

The IO register is documented as 0x7e2150a0 (with automatic deassert) and 0x7e2150b0, whereas the table on page 8 shows 0x7e215090.

The addresses on page 26 are correct, it's the table on page 8 which is wrong (see corrections above).

"Reading whilst the receive FIFO is **empty** will return the last data received."

### p34 off-by-one?

I strongly suspect that the CDIV counter is only 14 bits wide. The bottom bit doesn't work as per specifications, and because the "o" results in 32768, the top bit doesn't either. An easy implementation would implement the o value as the maximum divisor. Not as "half the maximum".

Another option is that SCL = cor clock \* 2 / CDIV and that the counter is 15 bits after all. (only the lowest bit missing).

The CDIV register appears to function as documented, see bcm2835\_i2c\_set\_divider in <a href="https://github.com/raspberrypi/linux/blob/rpi-4.19.y/drivers/i2c/busses/i2c-bcm2835.c">https://github.com/raspberrypi/linux/blob/rpi-4.19.y/drivers/i2c/busses/i2c-bcm2835.c</a> for details.

### p35 I2C clock stretching

There is a bug in the I2C master that it does not support clock stretching at arbitrary points. It does support clock stretching in I2C-Reads directly after the ACK phase, if the stretching-delay is  $\geq 0.5$  clock period (i.e. the low-period is  $\geq 1$  clock period).

See: http://www.raspberrypi.org/phpBB3/viewtopic.php?f=44&t=13771

A detailed analysis of this bug can be found at <a href="http://www.advamation.com/knowhow/raspberrypi/rpi-i2c-bug.html">http://www.advamation.com/knowhow/raspberrypi/rpi-i2c-bug.html</a>

### p38 typo

harware instead of hardware (second paragraph)

### p52 error

INTEN: a DMA interrupts only get triggered when the control block requesting the interrupt is the last in the chain (so next is NULL).

Otherwise no interrupt gets triggered.

Workaround is to use a second DMA chain just for triggering the interrupt.

To do this one needs to create a control-block (possibly length=0) on the second DMA channel. Link to it via two

control blocks on the primary chain. The first control block sets the control-block\_address of the "second DMA". The second starts the "unused" DMA by writing 1 to CS of the "second DMA", which then starts the "second DMA" and subsequently the interrupt gets triggered. After this the "primary" DMA can continue its work with other transfers without further interaction by the CPU.

### **p56**

The DMA LITE engines don't have SRC\_IGNORE and DEST\_IGNORE modes, so bits 7 and 11 should be marked as Reserved.

### p92 to 95 & 102 to 103

The GPIO Alternate function select Registers. This shows a bit pattern of 111 as alternative function 3. If you look at the values after boot up the Pi's SPI interface pins connected to the SD card have this value in them. This does not match the diagram on page 102 - 103 which shows this function is selected with alternative function 4. So either the bit pattern / function information is wrong or Table 6-31 is wrong.

#### **p90**

The second column in the table is labelled "Field Name" whereas it's actually "Register Name" address 0x7e20 0000 is listed twice as gpfselo.

#### **p95**

There is a spurious ) in "..clear registers) are used..."

# **p**96

Instead of "1 = Set GPIO pin n" for GPIO Output Clear Register 1, it should be "1 = Clear GPIO pin n"

The level registers have "o = GPIO pin n is HIGH" which should be "1 = GPIO pin n is HIGH"

The level registers are listed as R/W but the table on page 90 states that they are only readable, which makes more sense.

#### **p98**

The "GPIO Falling Edge Detect Enable Registers" header says "(GPRENn)" but it should say "(GPFENn)"

#### p100 typo

Instead of "when all register contents is lost." it should say "when all register contents are lost."

#### **p101** typo

Table 6-28 says "Use in conjunction with GPPUDCLKo/1/2" but there is no GPPUDCLK2 register

### p102 typos

Instead of "Up to 6 alternate function are" it should say "Up to 6 alternate functions are"

Instead of "a quick over view." it should say "a quick overview."

### p103 typo

In the "BSCSL SDA / MOSI" row of the "Special function legend" table, it says "salve" instead of "slave"

Where it says "BSC ISP slave" it should actually say "BSC/SPI slave"

### p104 table

The table, legend for table 6-31, started on page 103 shows twice in red: TXDo, RXDo, CTSo, RTSo. The second block, with functions starting: UART 1 should be: TXD1, RXD1, CTS1, RTS1.

The table, legend for table 6-31, has no mention of any of the SD1\_x functions included in the previous table

# p105 table

In table 6-32 the values in columns "min output freq" and "max output freq" should be in each others. That is the values in column "min output freq" are the maximum output frequency values and the values in column "max output freq" are the minimum output frequency values [check: source/(DIVI) > source/(DIVI+1) as dividing by a larger value yields a smaller result!].

The best source of clarification from overview to detailed operation is the i2s\_test.c code written by Simon Hughes available here:

```
git clone https://github.com/arisena-com/rpi_src.git
```

These comments are reproduces from the README file:

**Introduction** This test application is intended to present a simple to understand user space test application that can be used to control the output of the Raspberry PI I2S bus. See the i2s\_test.c comments for detailed explanation.

There are a number of deficiencies with the main source of Raspberry Pi technical documentation (REF1) with regard to the I2S Bus:

```
The PCM/I2S clock registers CM_PCM_CTRL and CM_PCM_DIV are not documented.

The Clock Manager (CM) clock source oscillator frequencies have not been documented (as they are selected by the board designer)

REF1 Sec 6.3 Table 6-32 equation for I2S_BCLK average output frequency (4th column) incorrectly documents 1024 as the divisor to DIVF rather than the correct value of 4096. Incorrect values of DIVI and DIVF to achieve a desired I2S_BCLK bit clock frequency are computed using the documented equation.
```

This had lead to a confusing picture. Therefore, the aim of this small test application project is to:

```
    provide a stand—alone, simple, working code sample that solves all the problems as a whole, so you can start using the Raspberry Pi I2S bus as quickly as possible.
    provide references to documentation errata for the CM_PCM_CTRL and CM_PCM_DIV configuration registers.
    provide a spreadsheet that shows you how to calculate the correct values of DIVI and DIVF to achieve the desired PCM_CLK/I2S_BLCK target frequency.
```

From the i2s\_test.c header comments:

```
* REFERENCES
* REF1
    BCM2835 ARM Peripherals 6 Feb 2012 Broadcom Europe
    BCM2835-ARM-Peripherals.pdf
**
    BCM2835_Audio_PWM_Clocks_errata_Geert_Van_Loo.doc which is images
    captured from http://www.scribd.com/doc/127599939/BCM2835-Audio-clocks
*
  REF3
   http://raspberrypi.stackexchange.com/questions/1153/what-are-the-different-
*_* *_*
       clock-sources-for-the-general-purpose-clocks
   which reports the following:
¦*
          0 Hz
                   Ground
*_* *_*
    1
          19.2 MHz oscillator
          0 Hz
                    testdebug0
    3
          0 Hz
                    testdebua1
          0 Hz
                    PLLA
_* * _* _*_*
          1000 MHz PLLC (changes with overclock settings)
    6
          500 MHz PLLD
          216 MHz HDMI auxiliary
    8-15 0 Hz
                    Ground
<u>'</u>*
   The REF1 table 6-34 doesn't report the clock frequencies
<u>|</u>*
  REF4
'*
   i2s_test4_test_vector_vy.yy.xls computes values for test vectors
   see docs dir for latest version
```

### p107-108 table 6-35

Documentation relating to the PCM/I2S clock in missing. This is from Geert Van Loos at the page below:

http://www.raspberrypi.org/forums/viewtopic.php?t=8496

There are two PCM/I2S clock control registers (Like with most peripherals)

CM\_PCM\_CTRL @ 0x7E101098 Enable bit = 4 Clock source is bits 3:0. I assume you want the cleanest clock source which is the XTAL (19.2MHz) crystal. (Clock source code = 0001b)

```
CM_PCM_DIV @ 0x7E10109C
```

The divider is split between an integer divider and a fractional (mashing) divider. The mashing dividers are build such that clock artifacts should be pushed out of the audio frequency domain. Bits 11:0 are the mashing divider Bits 23:12 are the integer divider. You must write the MS 8 bits as 0x5A.

See the errata under P105 and the following i2s\_test.c code sample for detailed information:

```
git clone https://github.com/arisena-com/rpi_src.git
```

# p111 spelling

top line: device should be devise.

### p113

IRQ 0-3 are system timer interrupts 0-3.

IRQ 62 is the interrupt from the Arasan EMMC controller. It's quite useful.

# p113-115 register name duplication

The registers at offsets 0x200, 0x204 and 0x208 all have the identical name of "IRQ pend base"

### p119 I2S clock

Allusions to the APB clock domain are made. However the exact speed of the APB clock is never explained.

http://infocenter.arm.com/help/index.jsp?topic=/com.arm.doc.ddio301h/Cbaifdib.html explains "APB" as the Advanced Peripheral Bus, but that doesn't help much either.

See the errata under P105 and the following i2s\_test.c code sample for detailed information:

```
git clone <a href="https://github.com/arisena-com/rpi_src.git">https://github.com/arisena-com/rpi_src.git</a>
```

### p125

Perhaps "There is only PCM module in the BCM2835." is supposed to be "There is only one PCM module in the BCM2835."?

### p126

There is amiguity on what register bits can be modified while the I2S system is active. p126 states that only the bottom three bits of CS\_A can be modified. However p122 suggests to use the SYNC bit in CS\_A for waiting. Does this mean, that the SYNC bit can also be changed at runtime as well?

#### p139

The "good" algorithm in the box-out appears truncated:

```
1. Set context = 0
2. context = context + N
3. if (context >= M)
    context = context - M
    send 1
    else
```

"the pwm algorithm explained in section 1.3." should probably be "the pwm algorithm explained in section 9.3."

#### **p141**

There is no base address listed for this register block. Should be: 0x7E20C000

# p142/143 register table

The CTL register controls both PWM channels 1 and 2, but in the description column, only channel 1 is mentioned. Bits 8 to 15, PWEN2 to MSEN2 should be described as controlling PWM channel 2, not 1. (I think- not confirmed)

### p145 and 147

Instead of "... only the first PWM\_RNGi bits are sent ..." it should say "... only the first PWM\_DATi bits are sent ..." on both pages.

### **p147**

In the DAT2 Register synopsis "USEFi is 1" should be "USEFi is 0"

#### **p153**

Typo: wrirng -> writing.

Near the bottom of the page RXR. This bit would be useful if it signified more than half full. There is a space in "(full)" that would hint at that the word "half" was taken away. Another hint is that it says that the bit clears when "sufficient" data is read from the FIFO. The word sufficient is redundant when this is the "full and active" bit.

The way it is written now, this bit is just the same as bit RXF, except that the TA bit is anded into this one.

Two options. The hardware was changed (detecting "half full" was difficult?) and the documentation was changed accordingly. Or the hardware does what I expect: set this bit when more than half full.

### p<sub>155</sub>

There is a CSPOL bit described here, wereas there are also CSPOL[0,1,2] described on page 153. How do these combine??? (I dunno the official answer to this, but the community-written SPI drivers here (https://github.com/raspberrypi/linux/blob/rpi-3.12.y/drivers/spi/spi-bcm2708.c#L273) and here (https://github.com/raspberrypi/linux/blob/rpi-3.12.y/drivers/spi/spi-bcm2835.c#L211) set them both at the same time)

If CLEAR\_TX\_FIFO is set there is at least a slight chance (~4%) that a selected CS will get de-asserted for a short period of time (<63ns). This may happen every time this bit is set, but it is not measurable every time when sampling at 16MHz (higher sampling speeds would be needed to confirm that). Testing shows that CLEAR\_RX\_FIFO set alone does not exhibit such behavior.

Potential workaround is to assign CS as the "reserved" chip\_select 3 and toggling the corresponding CSPOL pin for the cs that is really in use.

```
# assume the cs you want to set is in cs
|cs^=(1<<(cs&0x03+21);
|cs|=0x03|CLEAR_FIFO_RX|CLEAR_FIFO_TX;
|writel(cs,0x7E204000);
```

It is not fully confirmed, if this does not introduce other glitches...

### p156

The CDIV value is documented as "must be a power of 2". This is not true. I can perfectly set the register to 833 (not a power of 2) and get 250MHz/833 = 300kHz.

Maybe "must be a multiple of 2" was meant???

### p<sub>158</sub>

SPI\_FIFO is misspelled as SPIFIFO in the last line of 10.6.2.

10.6.3: The presented flow works in principle. But there are some limitations:

ADCS is required to be set (not optional as per j )- otherwise no SPI-Clock shows on pins

- also the "described" first 4 byte of the transfer described in I-i) also impact the other bits of CS besides the 8 bit that can get set with this transfer - so the CSPolarity for all 3 chip selects get reset to 0.
- TX/RX fifos have to be reset if there was an earlier transfer of say 3 bytes in length via DMA.

In this example there is still 1 byte left which will get sent first.

The way around this is to configure CS, CDIV and DLAN via explicit DMA control blocks and only then do the RX/TX DMAs (always making use of the WAIT\_RESPONSE flag in the DMA config register!). Note that using TDMODE for setting LEN and CS in one transfer may result in a reordering of the writes, which will start the SPI device before the length is set, so the original register value is used. Note also that it is NOT recommended resetting FIFO while starting SPI by setting TA Flag in SPI\_CS. Under rare situations this may result in "lost" clocks while MOSI still shifts out the data! (so resetting FIFO needs another DMA control-block prior to setting DLEN and CS)

### **p160**

"The BCS controller" should be "The BSC controller"

"The registers base addresses is" -> "The registers' base addresses are" or "The base address of the registers is".

### p161, p162, p166

Multiple references to "FX FIFO" which should be "RX FIFO"

### **p**175

top line. Two typos:

,	
On mini UART and and PL011 UART	
should be	
One mini UART and one PL011 UART	į
<b>p1</b> 77	
13.4 register view	
First line:	
The PL011 USRT is mapped on base adderss	
should be:	
The PL011 UART is mapped on base address	- ;

The base address is listed as 0x7e20100. This should be 0x7e201000.

### p196

SP804 not AP804

#### **p197**

Top Unused bits should be 31:24 (not 31:10)

bit 1, 32 bit counter not 23 bit counter

typo: "BC2835M" should be "BCM2835"

### p198

neither are register 0x40C raw is 0x410, masked is 0x414

#### **p202**

The last entry of section 15.1.

The entries in the table should specify the choice that Broadcom made when instantiating the USB controller IP from Synopsys.

Possibly the "choice" hasn't been specified. Or maybe the "0=32, 1..5=512, 6,7=768" is the option that was chosen?

"Video core bus structure" should be "VideoCore bus structure"

### **p203**

The table entry that says USB\_MDIO\_GEN should be USB\_MDIO\_DATA, and the table entry that says USB\_VBUS\_DRV should be USB\_VBUS

### **p204**

The "Drive VBUS" and "Discharge VBUS" cells in the Description column of the USB\_VBUS table should be the other way around. The Field Name values are correct.

Table 15-3 is mislabelled as "USB MDIO data". It should be "USB Vbus"

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