# Computational topology: Image classification using Vietoris-Rips complex

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### Obtaining and preprocessing data

Listing 1 shows a Perl script.

Listing 1: Sample Perl Script With Highlighting

```
#!/usr/bin/perl
use strict;
use warnings;

for (1..99) { print $_." Luftballons\n"; }

# This is a commented line

my $string = "Hello World!";

print $string."\n\n";

$string =~ s/Hello/Goodbye/;

print $string."\n\n";

test();

exit;

sub test { print "All good.\n"; }
```

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#### The classification model

**Definition 1** (Vietoris-Rips complex). Let X be a set of m-dimensional points  $X \in \mathbb{R}^m$  and let d be a metric. Pick a parameter r > 0. Construct a simplicial complex as follows:

- Add a 0-simplex for each point in X.
- For  $x_1, x_2 \in X$  add a 1-simplex between  $x_1, x_2$  if  $d(x_1, x_2) \leq r$ .
- For  $x_1, x_2, x_3 \in X$  add a 2-simplex with vertices  $x_1, x_2, x_3$  if  $d(x_1, x_2), d(x_1, x_3), d(x_2, x_3) \leq r$ .
- ...
- For  $x_1, x_2, ..., x_m \in X$ , add a (m-1)-simplex with vertices  $x_1, x_2, ..., x_m$  if  $d(x_i, x_j) \le r$  for  $0 \le i, j \le m$ ; that is, if all the points are within a distance of r from each other.

The simplicial complex is called the Vietoris-Rips complex and is denoted  $V_r(X)$ .

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#### Relation to single linkage clustering algorithm

Our intuition tells us, that the model we build using the Vietoris-Rips complex to classify the images, produces the same results as the well known single linkage clustering algorithm. In this section we aim to prove or at least give a strong intuition that this is indeed the case.

**Definition 2.** A connected component in a graph G(V, E) (V is a set of vertices, E a set of edges) is a set of vertices C such that between every two points  $a, b \in C$  there exists a path in the graph G between them.

Both algorithms take a set X of n samples with m features as input. We can think of a sample x in the set X as a point in the m-dimensional space  $x \in \mathbb{R}^m$ . The algorithms then constructs a graph with points X as the vertices (V) and edges E. The k connected components in the constructed graph corespond to the classes of samples.

Single linkage algorithm. The algorithm starts with n connected components (no edges in the graph). n each step the algorithm chooses the two connected components that are closest to each according to some distance metric d (in our case the euclidean distance) and joins them into one by adding an edge between their closest two vertices.

**Definition 3.** The distance D between two connected components A and B is defined as the distance of the pair of vertices (one from A and one from B) that are closest to each other. More formally

$$D(A,B) = \min_{a \in A, b \in B} d(a,b).$$

The algorithm stops when there are only k connected components left.

**Vietoris-Rips classification algorithm.** The algorithm builds a 1-dimensional Vietoris-Rips complex  $V_r(X)$  with parameter r. We choose the biggest r such that the Vietoris-Rips complex  $V_r(X)$  has k connected components.

## Testing

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