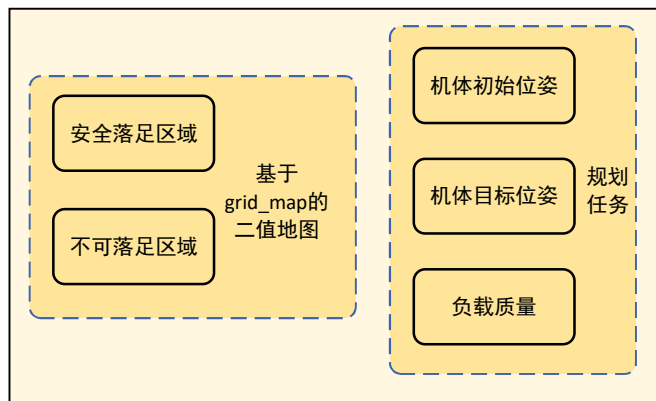
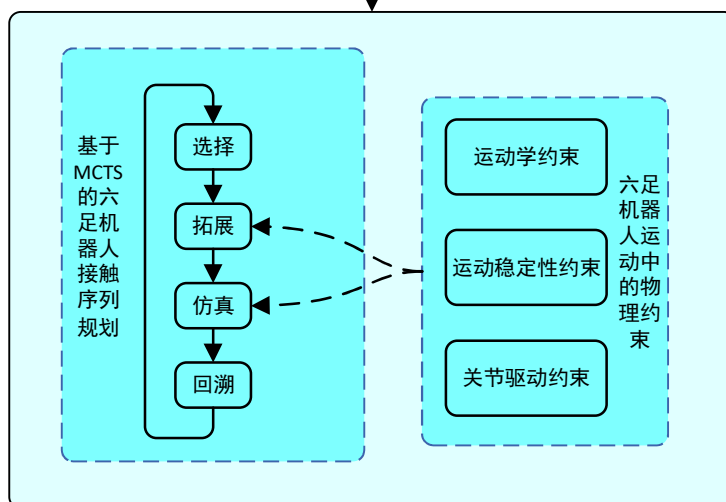


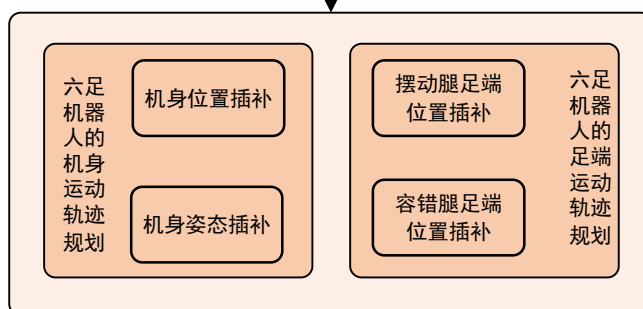
数据输入层



六足机器人接触序列规划层



六足机器人轨迹规划层



可视化层

