

Spanning trees

Trees are the minimal connected graphs. Spanning trees are minimal subgraphs that contain all the vertices but are connected.

Definition

Let G be a connected graph. A *spanning tree* of G is a subgraph $T \subseteq G$ such that T is a tree, and T contains every vertex of G .

Side point: Kirkchoff's Matrix Tree Theorem

Spanning trees of K_n are the same thing as labelled trees on n vertices.

As a generalization of Cayley's formula, can compute the number of spanning trees of any graph G as the determinant of a matrix.

Weighted graphs

Edges often have a “cost” associated to them – the time, money, or distance of the corresponding route/connection.

Definition

Weighted graph A *weighted graph* is a graph G together with a weight function $w : E(G) \rightarrow \mathbb{R}$. Normally we assume $w(e) \geq 0$ for all edges e .

Weighted graphs are often encoded in tables:

A				
4	B			
5	7	C		
9	8	8	D	
5	5	5	8	E

Minimal spanning trees

Motivating problem:

Suppose that the vertices of a weighted graph G represented cities, and the weight $w(e)$ of an edge was the cost of building a road between the cities. What's the cheapest way to connect all the cities?

Definition

Let $T \subseteq G$ be a spanning tree of a weighted graph. The weight of T is the total weight of all its edges:

$$w(T) = \sum_{e \in T} w(e)$$

Problem becomes: find the minimal weight spanning tree

Checking every spanning tree too slow: K_n has n^{n-2}

Many solutions. Two: Kruskal and Prim

Loose concept: Greedy Algorithms

A *greedy algorithm* doesn't plan ahead, but just does the best it can at each stage.

Definition (Kruskal's algorithm)

Start with T having no edges. Iteratively:

- ▶ Look at cheapest remaining edge e
- ▶ If adding e to T creates a loop, discard e
- ▶ Otherwise, add e to T

Fairly clear: produces a spanning tree

But it's *not* clear this spanning tree is *minimal*.

Another approach: Prim

Kruskal: a global view, “avoid cycles”

- ▶ Kruskal’s algorithm looks at all edges at start
- ▶ T may be disconnected at intermediate steps

Prim: local view, “build tree”

Start at one vertex and explore out

Definition (Prim’s algorithm)

Start $T = v$, a single vertex. Iteratively:

- ▶ Find the cheapest edge $e = vw$ from $v \in T$ to $w \notin T$
- ▶ Add e and w to T

Fairly clear: produces a spanning tree

But it’s *not* clear this spanning tree is *minimal*.

Why do Kruskal and Prim work?

Exchange principle:

Let T be a spanning tree of G , and $e = xy$ an edge not in T .
Then:

- ▶ Unique path P from x to y using only edges of T
- ▶ If f any edge in P , then $T' = T \setminus f \cup e$ a spanning tree
i.e., can exchange edges in P for e .

Basic idea of proofs:

- ▶ Let T be spanning tree produced by algorithm
- ▶ Let T_m be a minimal spanning tree
- ▶ Transform T_m to T edge by edge using exchange principle
- ▶ Show each step is a minimal spanning tree

Key: always add cheapest edge in T but not T_m .

Finding *all* minimal spanning trees

All edges have distinct weights:

- ▶ Never have to make an arbitrary choice
- ▶ Unique minimal weight spanning tree

All edges have the same weight:

- ▶ Any spanning tree is minimal
- ▶ Probably too many to write down

A few edges have repeated weights:

- ▶ Only a few places we have to make a choice
- ▶ Can find them with case by case analysis breaking ties