

### Simulation 1

The objective of this simulation was to apply Frank-Wolfe to solve the leading eigenvector of a matrix.

The leading eigenvector of a matrix  $Q \succ 0$  is given by the constraint problem

$$\min_{\|x\|_2 \leq 1} f(x) = -x^T Q x$$

An  $n \times n$  random matrix with all entries given by  $N(0,1)$  was generated for matrix A.

A matrix Q was generated using  $Q = A^T A + \varepsilon I$ , where  $\varepsilon = 0.75$ .

The following algorithm was done iteratively to obtain the leading eigenvalue.

$$x_{k+1} = (1 - \eta)x_k + \frac{\eta Q x_k}{\|Q x_k\|_2}$$

A python built-in function was used to compute the largest eigenvalue and was used to compare against the algorithm's results to verify findings.

The following results were found using the these conditions:  $\eta = 1.75e-2$ , a randomized  $x_0$  vector, and 3000 iterations.

Python Leading Eig Vector	Frank-Wolfe Leading Eig Vector	Direct Comparison of Equality
<code>[[-5.97168691]</code>	<code>[[-5.97168691]</code>	<code>[[ True]</code>
<code>[23.99733709]</code>	<code>[23.99733709]</code>	<code>[ True]</code>
<code>[ 6.09843162]</code>	<code>[ 6.09843162]</code>	<code>[ True]</code>
<code>[ 9.36544919]</code>	<code>[ 9.36544919]</code>	<code>[ True]</code>
<code>[ 7.20608523]</code>	<code>[ 7.20608523]</code>	<code>[ True]</code>
<code>[20.41032491]</code>	<code>[20.41032491]</code>	<code>[ True]</code>
<code>[ 0.561812 ]</code>	<code>[ 0.561812 ]</code>	<code>[ True]</code>
<code>[-4.16843667]</code>	<code>[-4.16843667]</code>	<code>[ True]</code>
<code>[ 3.00190146]</code>	<code>[ 3.00190146]</code>	<code>[ True]</code>
<code>[-1.45504237]]</code>	<code>[-1.45504237]]</code>	<code>[ True]]</code>

Both the python and Frank-Wolfe method returned the same results, verifying that the Frank-Wolfe algorithm was properly implemented.

### Simulation 2

The objective of this simulation was to apply projected gradient descent to solve the constrained least-mean-square problem defined as:

$$\min_{\|x\|_\infty \leq 1} f(x) = \frac{1}{2} \|Ax - b\|_2^2, \text{ where } x \in \mathbb{R}^n, A \in \mathbb{R}^{m \times n}, b \in \mathbb{R}^m.$$

The projection operator is as follows:

$$P_{\{x: \|x\|_\infty \leq 1\}}(z) := \operatorname{argmin}_{\{x: \|x\|_\infty \leq 1\}} \|x - z\|_2$$

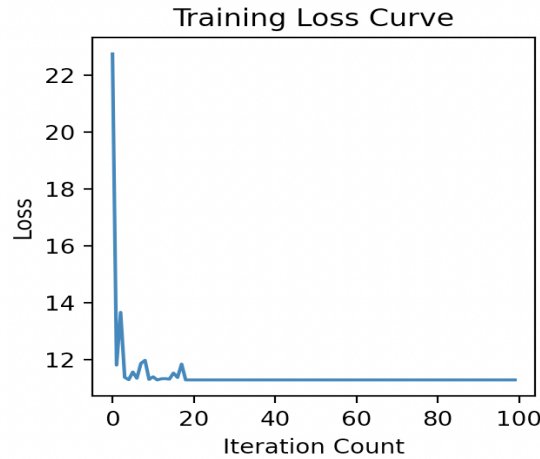
$$\Leftrightarrow \sum_{i=1}^n \operatorname{argmin}_{\{x_i: |x_i| \leq 1\}} (x_i - z_i)^2$$

The gradient update was applied using

$$x_{k+1} = P_{\{x: \|x\|_\infty \leq 1\}}(x_k - \eta \nabla f(x_k)).$$

The gradient for the LMS is  $\nabla f(x) = A^T(Ax - b)$ . The initialization of  $x_0$  was generated randomly using the `numpy.random.randn` function.

Using  $n = 100$ ,  $m = 10$ ,  $\eta = 1e-3$ , and an iteration count of 100, the training loss curve of the implementation is shown below.



The training loss curve follows an expected trajectory. There is a bit of fluctuation in the way that the curve converges, but it does decrease as iterations move forward. I would make the assumption that the fluctuation has to do with the projections onto the constrained set.

In addition, the  $x_k$  values were checked on each iteration to verify that they are in the constrained set. Once all iterations were complete, a quick check was done to verify that all values were within the constraint. The terminal result for that evaluation is printed below.

```
All  $x_k$  in constraint? : True
```