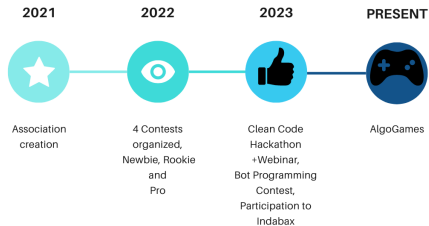


# Graph traversal and Path-finding Algorithms used in Video Games

Marius Rabenarivo



A brief history of AlgoMada



# About me



- ▶ Telecommunications, ESPA Alumni
- ▶ Computer Science, University of Reunion Island Alumni
- ▶ FaceDev Admin since 2012
- ▶ Founder member of AlgoMada
- ▶ Clojure dev
- ▶ Computer Science Enthusiast
- ▶ Current interests: Cryptocurrency, Clojure programming language
- ▶ Side project: BetaX Community

## Motivation: Why I do this?

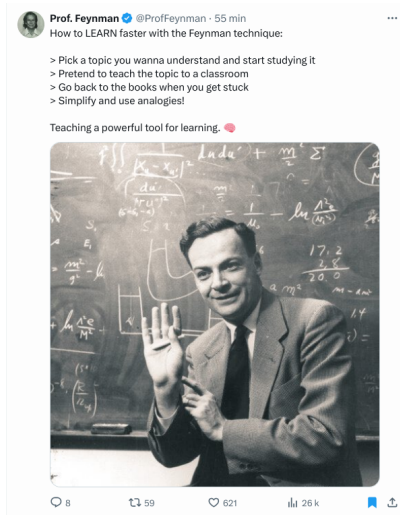


Figure 1: Feynman technique for studying

# Definition of Computer Science

“We are about to study the idea of a computational process. Computational processes are abstract beings that inhabit computers. As they evolve, processes manipulate other abstract things called data. The evolution of a process is directed by a pattern of rules called a program. People create programs to direct processes. In effect, we conjure the spirits of the computer with our spells.” Structure and Interpretation of Computer Programs, Harold Abelson and Gerald J. Sussman



我也有我的法律  
This is my law

# What is a graph?

A data structure to represent link between objects. A graph is defined by a set of nodes  $V$  and a set of edges  $E$ .

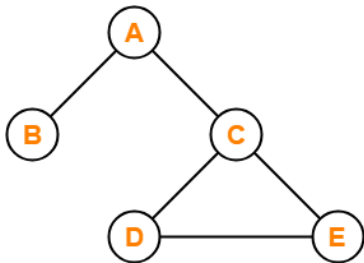
We can summarize this definition by the following formula:

$$G = (E, V)$$

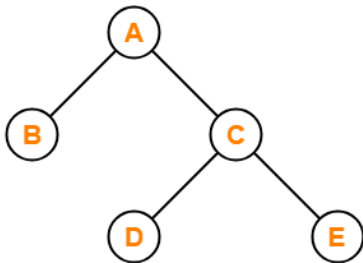
Example: <https://www.redblobgames.com/pathfinding/grids/graphs.html#properties>

# What's the difference between a graph and a tree?

A graph can contain cycles (a node can be visited twice).



**This graph is not a Tree**



**This graph is a Tree**

Figure 2: Tree vs Graph

# Different type of graphs

## ► Acyclic Graph

A graph that has no cycle.

## ► Cyclic Graph

A graph that has at least one cycle.

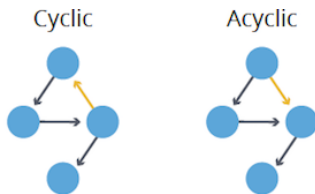


Figure 3: Acyclic vs Cyclic graph



## Different type of graphs

### ► Directed Graph

A graph in which edge has direction. That is the nodes are ordered pairs in the definition of every edge.

### ► Undirected Graph

A graph in which edge are not directed. Meaning, the edges are defined by an unordered pair of nodes.

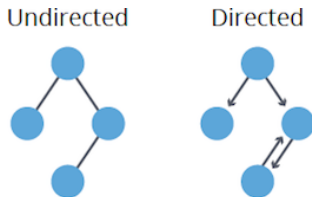


Figure 4: Undirected vs Directed Graph

## Different type of graphs

### ► Directed Acyclic Graph

A graph that is both directed and acyclic.

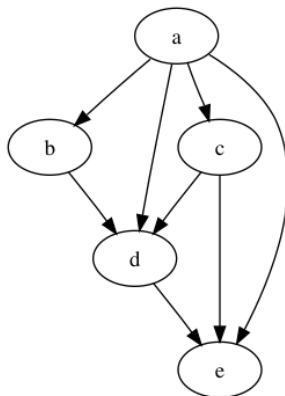


Figure 5: Directed Acyclic Graph

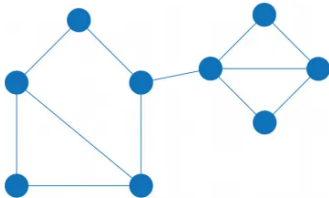
## Different type of graphs

### ► Connected graph

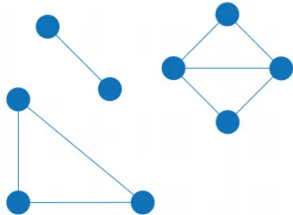
Every pair of nodes has a path linking them. Put in another way, there are no inaccessible node.

### ► Disconnected graph

A graph in which there is at least one inaccessible node.



Connected Graph



Disconnected Graph  
Includes 3 components.

Figure 6: Disconnected vs Connected Graph

## Different type of graphs

### ► A multigraph

A graph that can have multiple edges between the same nodes.

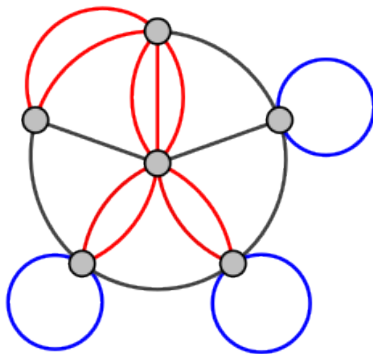


Figure 7: A multigraph with multiple edges (red) and several loops (blue).

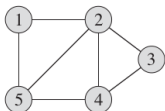
By 0x24a537r9 - Own work, CC BY-SA 3.0,

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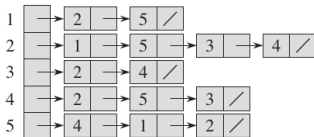
## Different way to represent a graph

There are 2 ways to represent a graph:

- ▶ adjacency list For each node, provide a list of other nodes that are adjacent to it.
- ▶ adjacency matrix A matrix construct by aligning the nodes in the row and the columns and putting a value if the nodes are linked by an edge.



(a)



(b)

	1	2	3	4	5
1	0	1	0	0	1
2	1	0	1	1	1
3	0	1	0	1	0
4	0	1	1	0	1
5	1	1	0	1	0

(c)

Figure 8: (a) Undirected graph with 5 vertices and 7 edges (b) Adjacency-list representation (c) Adjacency-matrix representation

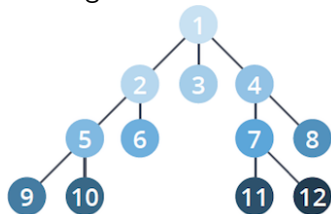
# Graph traversal algorithms

## BFS (Breadth-First Search)

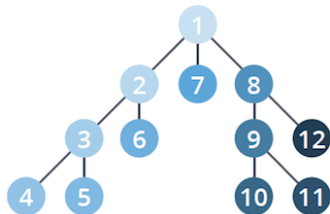
A graph traversal algorithm in which one explore every possible node in the current depth level before going to the next. Usually used to find shortest path distance from the start to a given vertex and the associated predecessor subgraph.

## DFS (Depth-First Search)

A graph traversal algorithm in which one start with a root node (arbitrarily chosen) then explore as far as possible along each branch before backtracking. Usually used as a subroutine in another algorithm.



*Breadth-first search*



*Depth-first search*

# BFS (Breadth-First Search)

```
BFS( $G, s$ )
1  for each vertex  $u \in G.V - \{s\}$ 
2       $u.color = \text{WHITE}$ 
3       $u.d = \infty$ 
4       $u.\pi = \text{NIL}$ 
5   $s.color = \text{GRAY}$ 
6   $s.d = 0$ 
7   $s.\pi = \text{NIL}$ 
8   $Q = \emptyset$ 
9  ENQUEUE( $Q, s$ )
10 while  $Q \neq \emptyset$ 
11      $u = \text{DEQUEUE}(Q)$ 
12     for each  $v \in G.Adj[u]$ 
13         if  $v.color == \text{WHITE}$ 
14              $v.color = \text{GRAY}$ 
15              $v.d = u.d + 1$ 
16              $v.\pi = u$ 
17         ENQUEUE( $Q, v$ )
18      $u.color = \text{BLACK}$ 
```

Figure 10: Breadth-first search pseudo-code

# BFS (Breadth-First Search)

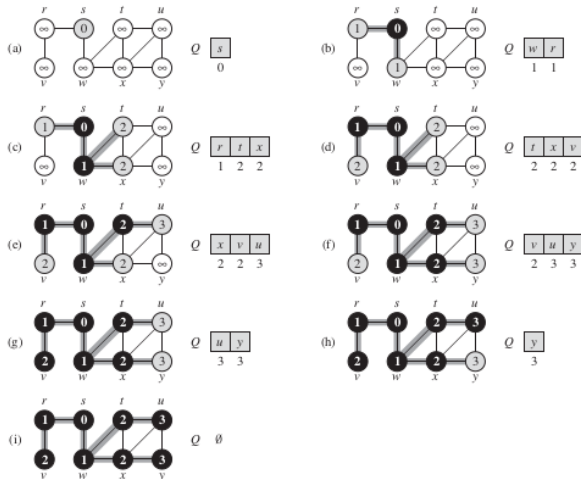


Figure 11: Operation of BFS on an undirected graph



# Depth-First Search

DFS( $G$ )

```
1  for each vertex  $u \in G.V$ 
2       $u.color = \text{WHITE}$ 
3       $u.\pi = \text{NIL}$ 
4   $time = 0$ 
5  for each vertex  $u \in G.V$ 
6      if  $u.color == \text{WHITE}$ 
7          DFS-VISIT( $G, u$ )
```

DFS-VISIT( $G, u$ )

```
1   $time = time + 1$            // white vertex  $u$  has just been discovered
2   $u.d = time$ 
3   $u.color = \text{GRAY}$ 
4  for each  $v \in G.Adj[u]$       // explore edge  $(u, v)$ 
5      if  $v.color == \text{WHITE}$ 
6           $v.\pi = u$ 
7          DFS-VISIT( $G, v$ )
8   $u.color = \text{BLACK}$          // blacken  $u$ ; it is finished
9   $time = time + 1$ 
10  $u.f = time$ 
```

Figure 12: Depth-First Search Pseudocode

# Depth-First Search

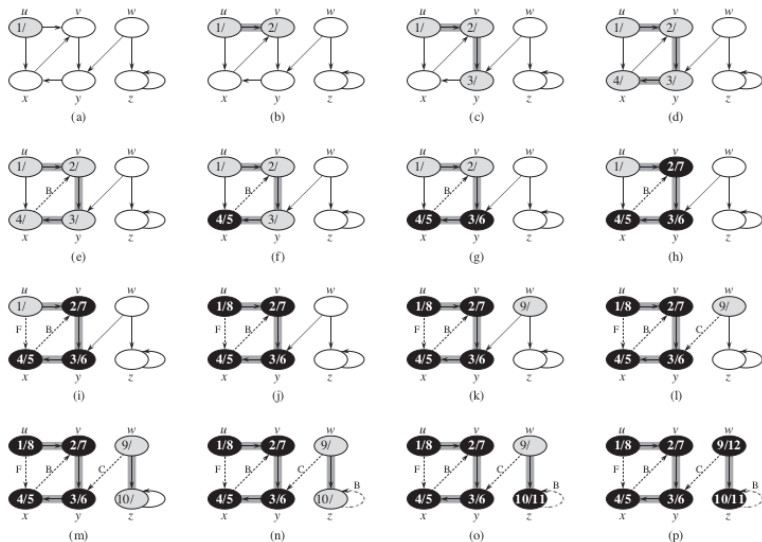


Figure 13: Depth-First Search progress on a directed graph

# Path finding algorithms

## A\* algorithm

A\* (pronounced “A-Star”) is a graph traversal and path-finding algorithm. Given a source and a goal node, the algorithm find the shortest-path (with respect to given weights) from source to goal.

## Dijkstra algorithm

Dijkstra algorithm solves the single-source shortest-paths problem on a weighted directed graph for the case in which all weights are non-negative.

# Path-finding

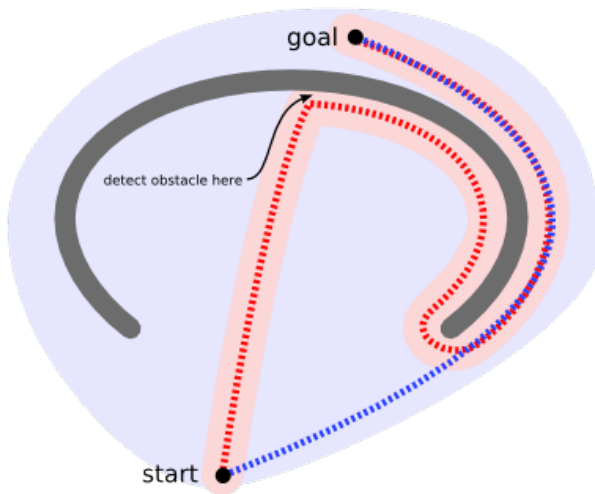


Figure 14: Example path-finding situation

# Path-finding

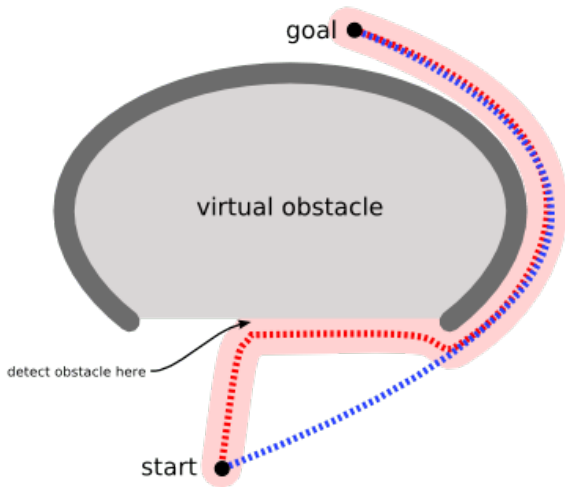


Figure 15: Example path-finding situation

# A\* Algorithm History

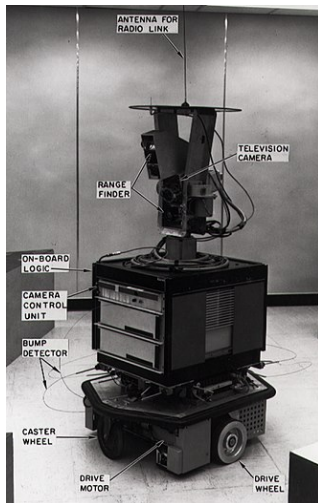


Figure 16: A\* was invented by researchers working on Shakey the Robot's path planning.

## Application in Video Games

For 2D video games, a tile map can be transformed into a graph. Each cell of the grid will be a node in the graph and the edges are going to be the four directions: east, north, west, south.

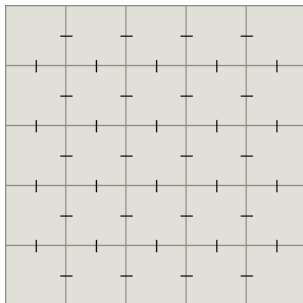


Figure 17: Map as graph

Example: [https:](https://www.redblobgames.com/pathfinding/grids/graphs.html#grids)

[//www.redblobgames.com/pathfinding/grids/graphs.html#grids](https://www.redblobgames.com/pathfinding/grids/graphs.html#grids)

# Dijkstra's Algorithm

Dijkstra's Algorithm works by visiting vertices in the graph starting with the object's starting point. It then repeatedly examines the closest not-yet-examined vertex, adding its vertices to the set of vertices to be examined.

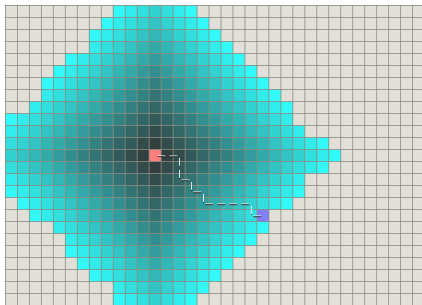


Figure 18: Dijkstra algorithm







# Dijkstra's Algorithm and Best-First-Search

Greedy Best-First-Search on the other hand does less work but its path is clearly not as good:

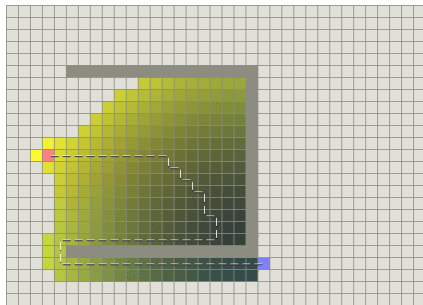


Figure 21: Greedy Best-First Search with trap

# The A\* Algorithm

A\* is like Dijkstra's Algorithm in that it can be used to find a shortest path. A\* is like Greedy Best-First-Search in that it can use a heuristic to guide itself. In the simple case, it is as fast as Greedy Best-First-Search:

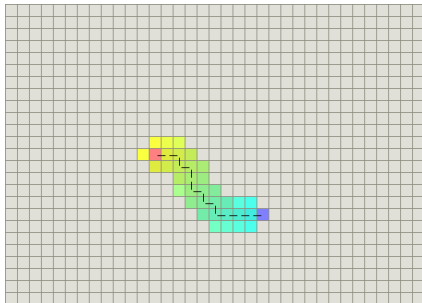


Figure 22: A\* algorithm

# References



[https://en.wikipedia.org/wiki/A\\*\\_search\\_algorithm](https://en.wikipedia.org/wiki/A*_search_algorithm)



<http://theory.stanford.edu/~amitp/GameProgramming/AStarCompa>