Project 2

Release 1.0

Jodok Vieli¹, Puck van Gerwen², Felix Hoppe³

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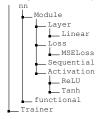
¹SCIPER: 336284 ²SCIPER: 283530 ³SCIPER: 276062

1.0 Project2

Project2 is a minimal tensor library for deep learning using CPUs. Our current version can:

- · Build networks combining fully connected layers, Tanh and ReLU
- Run forward and backward passes
- · Optimize parameters with SGD and Adam optimizers for MSE

The deep learning functionality is in the nn module and the Trainer can be used to facilitate training models. The library has the following structure:



A short example of how to use Trainer can be found in section 1.1.1. A test file test.pv uses the library to train a fully connected network with 3 hidden layers on a toy 2D dataset of 1000 randomly generated points where points inside a circle of radius $1/\sqrt{2\pi}$ are labelled 1, and all others labelled 0. Training for 100 epochs using SGD or Adam optimizers yields a test error rate of 6.01% or 3.71% respectively on average over 10 rounds of random data and weight reinitalization.

1.1 Python API

1.1.0 nn package

1.1.0.0 Submodules

1.1.0.1 nn.activation module

```
class nn.activation.Activation
```

Bases: nn.module.Modul

Class to compute activation functions

backward (dy)

Compute gradients of input.

Parameters dy (torch.tensor) - Backpropagated gradient from the next layer.

Return type torch.tensor

forward(x)

Compute the activation.

Parameters x (torch.tensor) - Input tensor.

class nn.activation.ReLU

Bases: nn.activation.Activation

forward(x)

Compute ReLU(x)

Parameters \mathbf{x} (torch.tensor) - Input tensor.

Returns Computed ReLU.

Return type torch.tensor

class nn.activation.Tanh

Bases: nn.activation.Activation

forward(x)

Compute tanh(x)

Parameters x (torch.tensor) - Input tensor.

Returns Computed tanh(x).

Return type torch.tensor

1.1.0.2 nn.functional module

functional.py contains the concrete implementations of specific functionals.

nn.functional. \mathbf{d} _ \mathbf{mse} (x, y)

Compute the gradient of the mean squared error.

Parameters

- x (torch.tensor) Input tensor.
- y (torch.tensor) Target tensor.

Returns Gradient of mean squared error.

Return type float

nn.functional.d relu(x) Compute gradient of ReLU(x)

Parameters x (torch.tensor) - Input tensor

Returns Output tensor

Return type torch.tensor

nn.functional.d_tanh(x)

Compute gradient of tanh(x) Parameters \mathbf{x} (torch.tensor) - Input tensor

Returns Output tensor

Return type torch.tensor

nn.functional.mse(x, y)

Compute the mean squared error.

Parameters

- x (torch.tensor) Input tensor.
- y (torch.tensor) Target tensor.

Returns Mean squared error.

Return type torch.tensor

nn.functional.relu(x) Compute ReLU(x)

Parameters x (torch.tensor) - Input tensor

Returns Output tensor Return type torch.tensor

nn.functional.tanh(x)

Compute tanh(x)

Parameters x (torch.tensor) - Input tensor

Returns Output tensor Return type torch.tensor

1.1.0.3 nn.linear module

```
class nn.linear.Layer
```

Bases: nn.module.Module

Layer implements layers that can be used in a network architecture

Return the params of the Layer

 $\begin{array}{c} \textbf{update_param} \, (*args, **kwargs) \\ \hline \textbf{Update the params of the Layer based on the cached gradients} \end{array}$

class nn.linear.Linear(dim_in, dim_out)

backward(dy)

Compute gradients of input and parameters.

 $\textbf{Parameters} \quad \textbf{dy} \; (\textit{torch.tensor}) - Backpropagated \; \textit{gra-}$ dient from the next layer.

Returns Gradient.

Return type torch.tensor

forward(x)

Calculate output of Linear layer.

Parameters x (torch.tensor) - Input tensor of size (batch_size, input_dim)

Returns Output tensor of size (batch_size, output_dim) Return type torch.tensor

Get parameters of the linear layer from the cache.

Returns weight and bias of linear layer.

Return type torch.tensor, torch.tensor

1.1.0.4 nn.loss module

class nn.loss.Loss

Bases: nn.module.Module

The Loss Module is used to implement a node in the network that computes the loss. For the computation of any function the respective functional from functional.py should be used.

 ${\tt backward}\,(\,)$

Backward pass.

Returns Backpropagated gradient from the next layer.

Return type torch.tensor

forward(x, y)

Compute the loss.

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```
• x (torch.tensor) - Input tensor.

    v(torch.tensor) - Target tensor.

class nn.loss.MSELoss
         Bases: nn.loss.Loss
         forward(x, y)
                 Compute the mean squared error.
                       Parameters
                              • x (torch.tensor) - Input tensor.
                               • y (torch.tensor) - Target tensor.
                       Returns Mean squared error.
                       Return type torch.tensor
1.1.0.5 nn.module module
class nn.module.Module
         Bases: object
         Base Module with core functionality
         backward(*args, **kwargs)
                 Compute backward pass
         forward(*args, **kwargs)
                Compute forward pass
1.1.0.6 nn.sequential module
class nn.sequential.Sequential(modules, loss_fn)
         Sequential allows multiple layers to be combined in a network architecture.
         backward()
                Perform backward pass.
         forward(x)
                 Perform forward pass.
                       Parameters x (torch.tensor) - Input tensor
                       Returns Output tensor
                       Return type torch.tensor
         loss(x, y)
                 Compute loss between two tensors.
                       Parameters
                              • x (torch.tensor) - Input tensor
                              • y (torch.tensor) - Target tensor
                       Returns Loss
                       Return type torch.tensor
         print()
                 str: Print model architecture.
         test step(x, v)
                 Test step. Wrapper for validation_step.
                       Parameters
                              • x (torch.tensor) - Input tensor
                              • y (torch.tensor) - Target tensor
                       Returns Loss
                       Return type torch.tensor
         training_step(x, y)
                 Training step.
                       Parameters
                              • x (torch.tensor) - Input tensor
                              • y (torch.tensor) - Target tensor
                       Returns Loss
                       Return type torch.tensor
         {\tt update\_params}\;(optim,lr)
```

Update the parameters of the network iteratively according to the

• optim(string) - The optimizer to use. options

cached gradients at each module.

are 'adam' or 'sgd'

Parameters

```
• lr (float) - Learning rate
```

```
validation_step (x, y) Validation step.
```

Parameters

- **x** (torch.tensor) Input tensor
- y (torch.tensor) Target tensor

Returns Loss

Return type torch.tensor

1.1.1 trainer module

```
class trainer.Trainer(nb_epochs)
```

Bases: object

fit (model, x_train, y_train, x_val, y_val, batch_size=32, lr=0.01, optim='sgd', verbose=True, print_every=32)

Train the model on the specified data and print the training and validation loss and accuracy.

Parameters

- model (nn.Module) Model to train
- x_train (torch.tensor) Training data
- y train (torch.tensor) Training labels
- x val (torch.tensor) Validation data
- v val (torch.tensor) Validation labels
- batch_size (int) Batch sizes for training
- and validation
 lr (float) Learning rate for optimization (De-
- fault is 0.01)
- optim (str) Optimizer (options are 'sgd' or 'adam'. Default is 'sgd')
- **verbose** (bool) Whether or not to output training information (Default is True)
- **print_every** (str) How often to print progress (Default is every 32 steps)

Example

Use the trainer to fit a new nn model.

```
>>> from trainer import Trainer
>>> from torch import empty
>>> from nn.sequential import Sequential
>>> ... f Read data into x_train, y_train, x_test, y_

->> test
>>> LinNet = Sequential((Linear(2, 1), MSELoss())
>>> trainer = Trainer(nb_epochs=25)
>>> loss_train, loss_val = trainer.fit(LinNet, x_train, _

->> y_train, x_test, y_test, batch_size=32, lr=0.1, print_

->> every=10, optim='sgd')
```

 $\verb+test+ (model, x_test, y_test, batch_size=32, test_verbose=True)$

Test the model on the specified data.

Parameters

- model(nn.Module) Model to train
- x_test (torch.tensor) Test data
- **y_test** (torch.tensor) Test labels
- batch_size (int) Batch size for testing
- **test_verbose** (bool) Whether the test result should be printed

Example

Use the trainer to test an existing nn model.

```
>>> from trainer import Trainer
>>> from torch import empty
>> ... # Train model LinNet
>>> ... # Read data into x_train, y_train, x_test, y_

+test
>>> trainer = Trainer(nb_epochs=25)
>>> loss_test = t.test(LinNet, x_test, y_test, batch_
+size=32, test_verbose=True)
loss_test=0.17
```

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