LP-Based Approaches for Goal Recognition as Planning
Supplemental Material

Paper #6100

#	$|\mathcal{G}|$	% Obs	$|O|$	δ_{HC}			δ_{HCU}		
				Time	Acc %	S in $\mathcal{G}$	Time	Acc %	S in $\mathcal{G}$
¡TABLE$_L$$P_R$$ESULTS > Average$				¡AVG$_A$$PPROACH_0 >$	¡AVG$_A$$PPROACH_1 >$	¡AVG$_A$$PPROACH_2 >$	¡AVG$_A$$PPROACH_3 >$	¡AVG$_A$$PPROACH_4 >$	¡AVG$_A$$PPROACH_5$

Table 1: Results comparing the state-of-the-art in goal recognition as planning for partial and full observability.