

Observation Filters - Optimal, Noisy

#	Γ	% Obs	Ω	Γ^*	$\delta_{\text{HC}}\text{F0}$			$\delta_{\text{HC}}\text{F1}$			$\delta_{\text{HC}}\text{F2}$		
					AGR	ACC	Γ^h	AGR	ACC	Γ^h	AGR	ACC	Γ^h
BLOCKS	20.3	10	1.25	8.0	0.43	86.1	8.08	0.43	86.1	8.11	0.4	100.0	17.67
		30	3.08	3.97	0.42	75.0	3.64	0.41	88.9	7.67	0.4	91.7	7.22
		50	4.42	2.5	0.48	72.2	3.14	0.35	91.7	8.69	0.5	80.6	3.67
		70	6.67	1.94	0.75	91.7	2.19	0.51	94.4	5.36	0.72	94.4	2.39
		100	8.83	1.83	0.69	83.3	1.75	0.65	100.0	4.25	0.74	83.3	1.67
IPC-GRID	7.5	10	1.63	2.71	0.82	91.7	2.75	0.8	91.7	2.94	0.62	95.8	5.15
		30	4.0	1.21	0.84	91.7	1.25	0.83	93.8	1.35	0.7	91.7	1.54
		50	6.19	1.13	0.88	97.9	1.4	0.88	97.9	1.44	0.85	97.9	1.46
		70	8.69	1.04	0.94	97.9	1.17	0.92	97.9	1.21	0.94	97.9	1.13
		100	11.88	1.0	0.97	100.0	1.06	0.97	100.0	1.06	0.97	100.0	1.06
LOGISTICS	10.0	10	2.0	2.83	0.75	94.4	4.06	0.71	94.4	4.47	0.47	97.2	6.67
		30	5.75	1.19	0.8	97.2	1.78	0.67	100.0	2.67	0.75	97.2	1.89
		50	9.42	1.06	0.88	97.2	1.31	0.79	97.2	1.61	0.88	97.2	1.31
		70	13.25	1.03	0.96	100.0	1.11	0.89	100.0	1.39	0.96	100.0	1.11
		100	18.17	1.0	1.0	100.0	1.0	0.96	100.0	1.08	1.0	100.0	1.0
MICRONIC	6.0	10	2.0	2.53	0.77	91.7	2.81	0.77	91.7	2.81	0.51	97.2	5.0
		30	5.42	1.22	0.74	88.9	1.58	0.67	100.0	2.58	0.66	94.4	2.03
		50	8.42	1.06	0.88	94.4	1.19	0.59	100.0	2.39	0.88	94.4	1.19
		70	11.92	1.0	0.88	94.4	1.14	0.61	97.2	2.11	0.9	97.2	1.17
		100	16.33	1.0	0.88	100.0	1.25	0.75	100.0	2.08	0.88	100.0	1.25
ROVERS	6.0	10	1.67	2.28	0.63	83.3	2.97	0.63	83.3	2.97	0.47	100.0	5.14
		30	3.67	1.31	0.71	80.6	1.69	0.7	83.3	1.81	0.53	83.3	2.36
		50	5.75	1.19	0.73	77.8	1.28	0.72	86.1	1.67	0.71	80.6	1.39
		70	8.17	1.0	0.8	86.1	1.14	0.77	97.2	1.5	0.77	86.1	1.19
		100	10.83	1.0	0.96	100.0	1.08	0.9	100.0	1.25	0.96	100.0	1.08
SATELLITE	6.0	10	1.42	3.53	0.81	94.4	3.89	0.81	94.4	3.89	0.63	100.0	5.69
		30	3.42	2.39	0.78	83.3	2.44	0.76	83.3	2.72	0.61	91.7	3.61
		50	5.75	1.58	0.71	83.3	2.0	0.63	91.7	3.03	0.7	88.9	2.11
		70	8.08	1.31	0.76	91.7	1.64	0.59	91.7	2.61	0.75	97.2	1.83
		100	10.75	1.25	0.79	91.7	1.42	0.69	91.7	1.83	0.83	91.7	1.5
SOKOBAN	8.7	10	2.33	2.11	0.35	52.8	2.78	0.33	69.4	4.03	0.34	72.2	4.36
		30	6.5	1.25	0.61	75.0	1.53	0.47	91.7	3.25	0.51	88.9	2.89
		50	10.33	1.22	0.61	88.9	2.72	0.42	94.4	4.97	0.79	100.0	2.08
		70	14.67	1.03	0.65	94.4	3.44	0.5	100.0	4.56	0.78	97.2	2.33
		100	20.17	1.0	0.77	91.7	2.5	0.64	100.0	3.75	0.92	91.7	1.0
Avg					0.75	89.17	2.18	0.68	93.75	3.12	0.72	92.78	2.88

Table 1: Results for each filtering k , with optimal observations. F0 for no filter, F1 for $k = 1$ and F2 for $k = 2$.

Observation Filters - Suboptimal, Noisy

#	Γ	% Obs	Ω	Γ^*	$\delta_{\text{HC}}\text{F0}$			$\delta_{\text{HC}}\text{F1}$			$\delta_{\text{HC}}\text{F2}$		
					AGR	ACC	Γ^h	AGR	ACC	Γ^h	AGR	ACC	Γ^h
BLOCKS	20.3	10	1.42	7.61	0.4	77.8	8.11	0.4	80.6	8.83	0.4	94.4	15.61
		30	3.83	3.58	0.38	63.9	3.17	0.34	91.7	9.31	0.39	69.4	3.69
		50	5.92	3.19	0.49	80.6	3.22	0.3	100.0	9.33	0.49	80.6	3.25
		70	8.5	2.53	0.51	69.4	2.11	0.35	100.0	9.11	0.51	69.4	2.11
		100	11.83	2.25	0.66	91.7	2.08	0.58	100.0	3.67	0.66	91.7	2.08
IPC-GRID	7.5	10	2.06	1.58	0.64	87.5	2.29	0.6	91.7	3.02	0.53	91.7	3.27
		30	5.56	1.4	0.81	100.0	1.4	0.73	100.0	2.04	0.83	100.0	1.35
		50	8.88	1.35	0.79	91.7	1.17	0.75	100.0	1.73	0.78	91.7	1.19
		70	12.56	1.31	0.87	100.0	1.1	0.75	100.0	1.44	0.87	100.0	1.1
		100	17.25	1.5	0.88	100.0	1.13	0.74	100.0	1.5	0.88	100.0	1.13
LOGISTICS	10.0	10	2.67	2.0	0.79	100.0	3.33	0.75	100.0	3.72	0.52	100.0	5.42
		30	7.5	1.14	0.83	100.0	1.56	0.67	100.0	3.11	0.76	100.0	1.75
		50	11.92	1.06	0.79	94.4	1.47	0.68	100.0	2.44	0.8	97.2	1.5
		70	16.67	1.03	0.94	100.0	1.17	0.82	100.0	1.56	0.94	100.0	1.17
		100	23.17	1.0	1.0	100.0	1.0	0.9	100.0	1.25	1.0	100.0	1.0
MICRONIC	6.0	10	3.0	1.83	0.69	91.7	2.83	0.65	94.4	3.28	0.5	94.4	3.97
		30	7.67	1.25	0.69	88.9	1.58	0.43	100.0	3.78	0.64	86.1	1.69
		50	12.25	1.03	0.79	86.1	1.17	0.5	100.0	3.14	0.81	88.9	1.19
		70	17.33	1.0	0.81	88.9	1.19	0.37	100.0	3.5	0.82	88.9	1.17
		100	24.0	1.0	0.92	91.7	1.0	0.57	100.0	2.83	0.92	91.7	1.0
ROVERS	6.0	10	1.83	2.39	0.73	80.6	3.0	0.74	83.3	3.03	0.52	94.4	4.64
		30	4.5	1.39	0.82	83.3	1.39	0.66	86.1	2.28	0.66	86.1	2.08
		50	7.17	1.11	0.72	77.8	1.28	0.61	86.1	2.06	0.7	75.0	1.28
		70	10.0	1.06	0.81	86.1	1.22	0.64	97.2	2.33	0.79	86.1	1.31
		100	13.67	1.0	0.88	91.7	1.08	0.83	100.0	1.58	0.88	91.7	1.08
SATELLITE	6.0	10	2.0	3.25	0.74	88.9	3.86	0.75	88.9	3.89	0.61	94.4	4.86
		30	4.33	1.78	0.61	77.8	2.33	0.6	91.7	3.36	0.58	80.6	2.61
		50	6.75	1.36	0.7	86.1	1.83	0.54	94.4	3.33	0.74	86.1	1.69
		70	9.42	1.33	0.67	91.7	2.08	0.55	100.0	3.53	0.71	91.7	1.97
		100	12.75	1.25	0.92	100.0	1.42	0.73	100.0	2.5	0.92	100.0	1.42
SOKOBAN	8.7	10	3.33	1.83	0.41	52.8	1.92	0.35	69.4	3.67	0.39	55.6	2.19
		30	8.67	1.28	0.64	80.6	2.14	0.4	97.2	5.19	0.66	75.0	1.36
		50	13.75	1.33	0.54	75.0	2.08	0.38	88.9	4.69	0.65	83.3	1.67
		70	19.33	1.36	0.5	88.9	4.0	0.27	94.4	6.0	0.6	88.9	2.97
		100	27.0	1.33	0.47	91.7	4.67	0.33	91.7	5.67	0.72	100.0	2.75
Avg					0.71	87.34	2.18	0.58	95.08	3.76	0.69	89.29	2.53

Table 2: Results for each filtering k , with suboptimal observations. F0 for no filter, F1 for $k = 1$ and F2 for $k = 2$.