



## Pontifícia Universidade Católica do Rio Grande do Sul FACULDADE DE INFORMÁTICA PROGRAMA DE PÓS-GRADUAÇÃO EM CIÊNCIA DA

PROGRAM: MSc and PhD in Computer Science

MODULE: Artificial Intelligence Planning

CODE: 54667-02 CREDITS: 02 TOTAL HOURS: 30 hours

VALID: From 2020/II

### GOALS: A student who completes this course should be able to:

- **1.** Understand the main formalisms used for automated planning and the assumptions behind these formalisms.
- **2.** Understand modern algorithms to solve automated planning problems and basic optimization techniques that can be applied to these algorithms.
- **3.** Apply automated planning systems to solve real-world problems

#### SYLLABUS:

Automated planning: formalisms and assumptions. Classical planning: formalisms and algorithms. HTN Planning: formalism and algorithms. Non-deterministic planning: formalisms and algorithms. Applications of automated planning.

UNIT: 01

CONTENT: Introduction and context

- **1.1.** Search algorithms
- **1.2.** Complexity of planning problems
- **1.3.** Classical planning
- 1.4. Planning Heuristics

UNIT: 02

**CONTENT: Hierarchical Planning** 

- **2.1** Hierarchical task network formalism
- **2.2** Problem formalization
- 2.3 Total Order and Partial Order forward decomposition Algorithms

UNIT: 03

**CONTENT: Stochastic Planning** 

- **3.1** Decision Theory
- **3.2** Markov Decision Processes (MDP)
- **3.3** MDP solvers

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### **3.4** Reinforcement Learning

UNIT: 04

CONTENT: Applications of automated planning

- 4.1 Problem modeling
- 4.2 Planning in agent programming languages
- **4.3** Goal and Plan Recognition

#### **REFERENCES**

- TEXTBOOK(S)
- 1. GHALLAB, Malik; NAU, Dana and TRAVERSO, Paolo. Automated Planning: Theory and Practice. San Francisco: Morgan Kaufmann, 2004. 635 p.
- REFERENCE BOOK(S)
- 2. RUSSELL, S. J.; NORVIG, P. Artificial Intelligence a Modern Approach. 3ed. New Jersey: Prentice Hall, 2003. 932p.
- 3. GEFFNER, H.; BONET, B. A Concise Introduction to Models and Methods for Automated Planning. Morgan & Claypool, 2013, 143p.
- 4. HASLUM, P.; LIPOVETZKY, N.; MAGAZZENI, D.; MUISE, Christian. An Introduction to the Planning Domain Definition Language. Morgan & Claypool, 2019, 168p.
- OTHER REFERENCES
- 5. Selected papers
- 6. Websites related to the course
- 7. https://github.com/pucrs-automated-planning
- SOFTWARE
- 8. Planning domains <a href="http://editor.planning.domains">http://editor.planning.domains</a>
- 9. PDDL4J http://pddl4j.sf.net
- 10. JSHOP2 <a href="http://www.cs.umd.edu/projects/shop/">http://www.cs.umd.edu/projects/shop/</a>
- 11. JavaGP http://emplan.sourceforge.net

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