

" dQt = MtdP"

Mt = dQt (Radon - Nikedym]

If set and A & Fs then A & Ft, and Qt(A) = E [1A Mt] Ving Conditional Expectation E[E[1AMt/Fs]] = E[1AE[Mt/fs]] = E[1AMS] since My is Martingale $= Q_s(A)$ We can define the probineasure Q by: if A & Ft, then Q(A) = E(1AME) $M_1 = e^{m\beta_1} e^{-m^2/2}$ Theorem: In the new measure Q, Bt is a brownban motion with drift in and variance parameter 1. Under the new measure Q: $|\cdot|$ $|\cdot|$ $|\cdot|$ $|\cdot|$ $|\cdot|$ $|\cdot|$ $|\cdot|$ $|\cdot|$ 2. If set, then By-Bs is independent of Fs 3. If set, then By-By N(m(t-s), t-s) 9 · Paths are continuous 2×3 The conditional distribution of BL+s -Bs given &

Recall >> IP YNN(mt, t)

is N(mt,t)

In the new measure Q, By is not som in Q but som in P By is Som with drift λ & variance parameter= 1 that is $B_t = \lambda t + W_t$ som in Q but not som in P

where Ut is a standard BM with respect to Q $dB_t = \lambda dt + dW_t$, $\lambda = -m$ dxt = [mat + o (\ladt + dwt)]Xt $= \int (m+\varepsilon \lambda) dt + \varepsilon dwt/Xt$ Non Negative martingale Mt satisfying $dM_t = A_t M_t dB_t$, $M_0 = 1$ $M_{t} = e^{mt - \frac{m^{2}}{2}t}$ $dM_t = mM_tdB_t$ $M_t = \exp\left(\int_0^t A_s dB_s - \frac{1}{2}\int_0^t A_s^2 ds\right)$ = e Yt where Yt = JAsdBs - 1 JAs ds $E[M_{t_i}] = E[M_0] = 1$ Let Qt be the prob measure on Ft given by $Q_t[A] = E[1_AMt]$ $E_{0}[X] = E[XMt]$ if X is Ft measurable If sct, and A is F,-measurable Then $Q_s(A) = Q_t(A)$

Q measure if A is Ft-measurable then $Q(A) = E[1_AMt]$

Girsanov Theorem t Let $W_t = B_t - \int A_s ds$ then Wt is a standard BM wrt Q. dWt = dBt - Atoll dBt = Atalt + dwt Example: bet Bt -> SBM where Bo = 1 T= min { t : B+= 0} [Niw Ma is bigger than or equal) to 0)
50 non-negative mentingale Mt = Btat At=B dMt = AtMtdBt

$$P(T < O) = 1$$
, $Q(T < O) = 0$