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Lab 4

MATLAB Code:

```
1
         disp('1.');
 2
          syms y(t)
 3
          eqn=diff(y,t,2)+4*diff(y,t,1)+4*y==exp(-2*t); % differential squation
 4
          Dy=diff(y,t); % derivative
 5
          cond=[y(0)==0, Dy(0)==4];% initial conditions
 6
          ysol(t) dsolve(eqn,cond)
 7
 8
          disp('2.');
 9
          syms y(t)
10
11
          eqn=diff(y,t,2)+y==sin(t);
12
13
          Dy=diff(y,t);
14
15
          cond=[y(0)==0, Dy(0)==4];
16
17
         ysol(t)=dsolve(eqn,cond)
18
19
          disp('3.');
20
          syms y(t)
21
22
          eqn=diff(y,t,2)-6*diff(y,t,1)+9*y==t*exp(3*t);
23
24
          Dy=diff(y,t);
25
26
          cond=[y(0)==0, Dy(0)==4];
27
28
         ysol(t) dsolve(eqn,cond)
29
          disp('4.');
30
```

```
30
          disp('4.');
31
          syms y(t)
32
33
          eqn=diff(y,t,2)+2*diff(y,t,1)+10*y==-6*exp(-t)*sin(3*t);
34
35
          Dy=diff(y,t);
36
37
          cond=[y(0)==0, Dy(0)==1];
38
39
          ysol(t) dsolve(eqn,cond)
40
41
          disp('5.');
42
          syms y(x) z(x)
43
          equations \frac{1}{z} [diff(y,x)+ diff(z,x) - 3*z == 0, diff(y, x, 2) + diff(z,x)== 0]
44
45
          Dy =diff(y,x);
46
47
          intitialConditions = [y(0)==0,Dy(0)==0, z(0)==4/3];
48
49
50
          [ySol, zSol] = dsolve(equations,intitialConditions)
```

MATLAB Code Output:

```
>> Lab4
1.
ysol(t) =
(exp(-2*t)*(t^2 + 8*t))/2
2.
ysol(t) =
(35*sin(t))/8 - sin(3*t)/8 - cos(t)*(t/2 - sin(2*t)/4)
3.
ysol(t) =
4*t*exp(3*t) + (t^3*exp(3*t))/6
4.
ysol(t) =
(exp(-t)*(sin(3*t) + sin(9*t) + 12*t*cos(3*t) - 2*cos(3*t)*sin(6*t)))/12
```

```
5. equations(x) =  [diff(y(x), x) - 3*z(x) + diff(z(x), x) == 0, diff(y(x), x, x) + diff(z(x), x) == 0]  ySol = x - exp(4*x)/4 + 1/4  zSol = exp(4*x) + 1/3
```