

Abstract

The textile industry, using both natural and synthetic materials, often faces defects during production, causing major financial losses. Manual inspection is still common but is slow, inefficient, and error-prone. This paper explores how Machine Vision can automate defect detection more accurately. We analyzed models like YOLOv8n, SSD with VGG16, Faster R-CNN with ResNet-50, and a custom model. We also developed a hybrid two-stage pipeline: YOLOv8l detects defects, and EfficientNet-B0 classifies them. Our pipeline achieved 84.2 precision, 81.9 recall, and 83.0 F1 score. We created a custom dataset of 9,075 images across four defect classes, collected from textile factories to reflect real conditions. Finally, we designed a prototype for industrial automation, demonstrating real-world application with strong accuracy and low computational cost.

Problem Statement

- **Factory Variability:** Different factory setups require the CNN model to be robust and trained to adapt across diverse industrial environments.
- **Image Consistency:** Lighting, shadows, and wrinkles must be controlled during data collection, as they can distort defect detection.
- **Class Imbalance:** Fabric defects occur randomly and at different rates, making it difficult to maintain balanced datasets for effective model training.
- **Preprocessing and Tuning:** Techniques like CLAHE and other image processing methods require careful parameter tuning to avoid introducing artifacts.
- **Real-Time Limitations:** Implementing models in real time is challenged by hardware constraints, high-resolution data, and processing latency, requiring seamless hardware-software integration.

Methodology

Our proposed system utilizes a two-stage pipeline combining YOLOv8l for binary defect detection and EfficientNetB0 for multi-class defect classification. This design ensures efficient computation by applying classification only to regions marked as defective.

Stage 1 – YOLOv8l for binary defect detection

- Detects defect regions using a C2f-based backbone, multi-scale feature fusion, and an anchor-free head.
- Outputs bounding boxes with defect/no-defect labels.

Stage 2 – EfficientNet-B0 for classification

- Cropped defect regions are resized and classified into defect types.
- Uses MBConv blocks with SE modules for high accuracy and efficiency.

This modular pipeline enables scalable and interpretable defect detection with deployment flexibility across resource constrained and industrial environments.

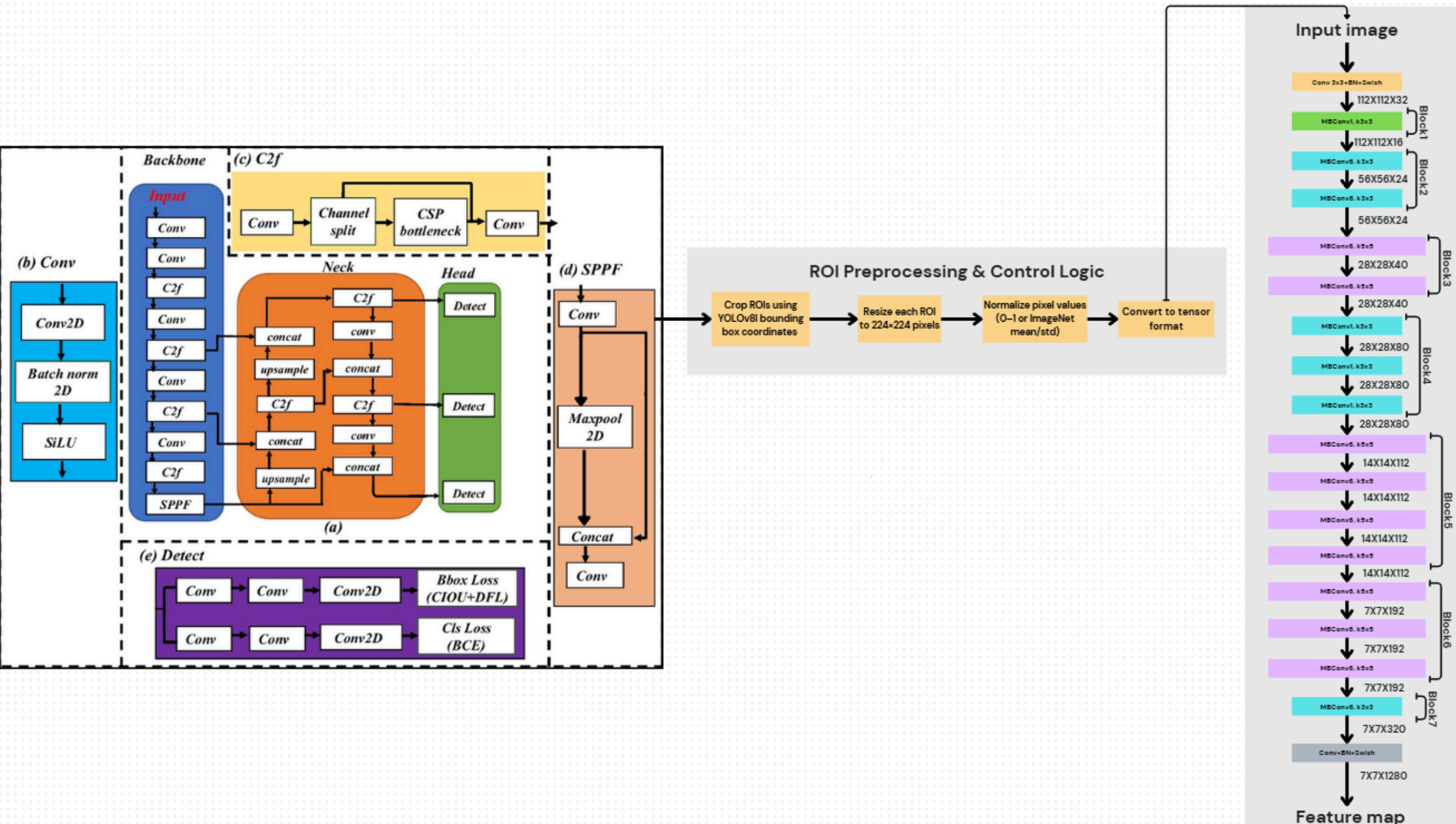


Figure: Proposed pipeline workflow integrating YOLOv8l and EfficientNet B0.

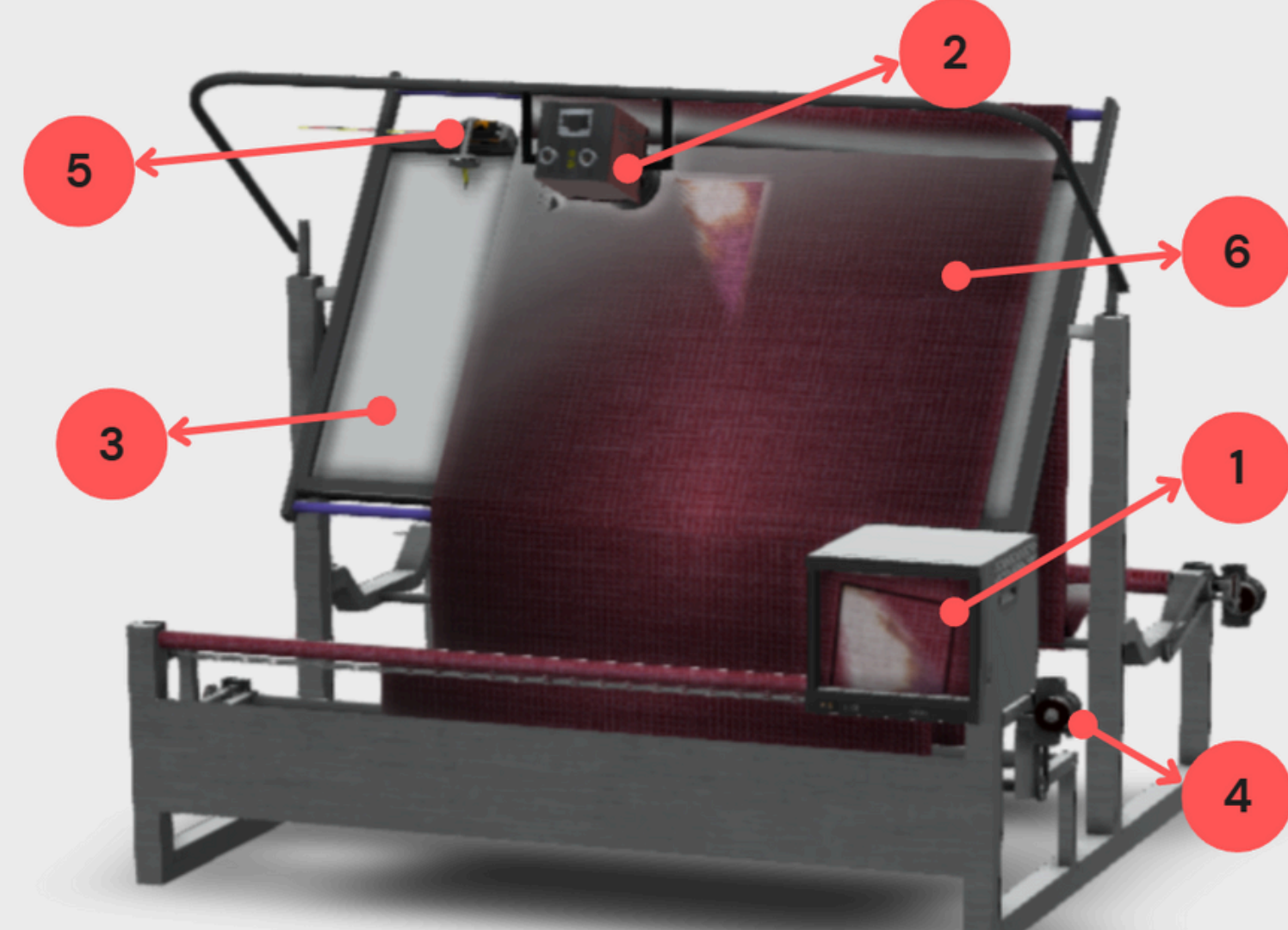


Figure: System structure.

Num	Label
1	Host PC
2	Camera
3	Lightbox enclosure
4	Brushed DC windshield wiper motor
5	Servo motor for marker
6	Fabric roll

Figure: System overview with component labels.

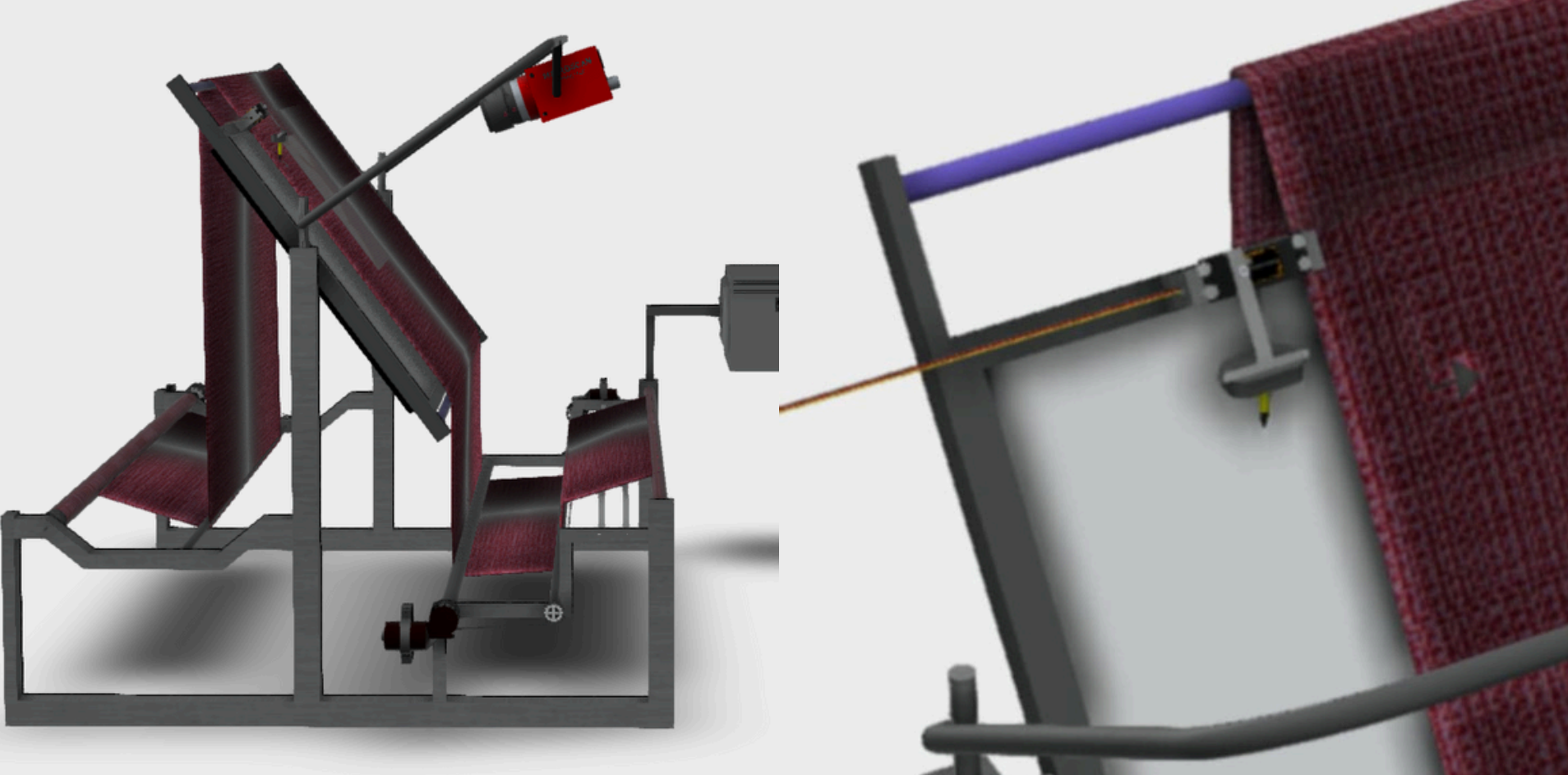


Figure: Marker mechanism overview.

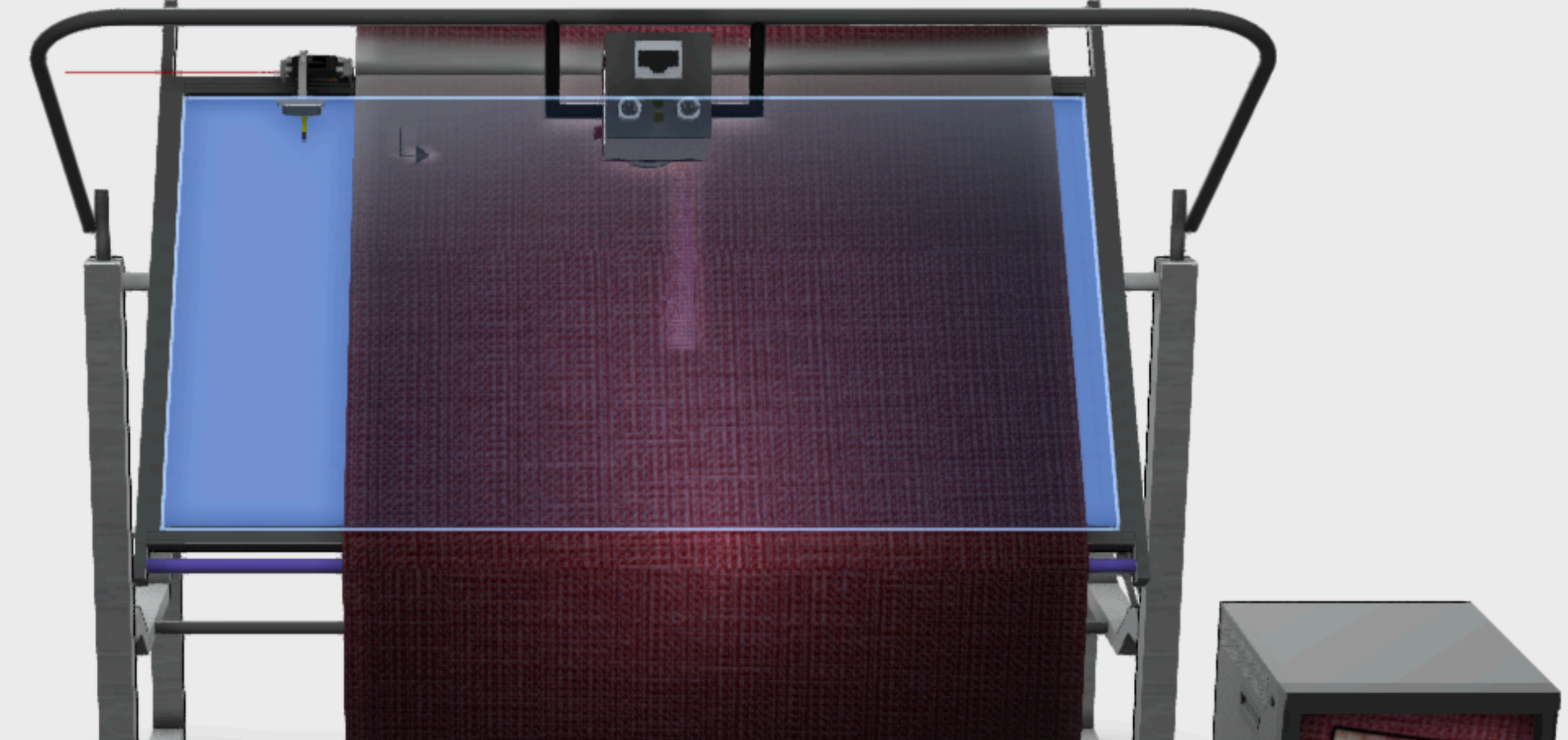


Figure: Camera position with illuminated lightbox.

For the system to work following equations are used

Capture Time: $\Delta t = \frac{RPM \times 2\pi}{60} \dots\dots\dots 1$

Linear Velocity of Roller: $v_m = \frac{RPM \times 2\pi}{60} \dots\dots\dots 2$

Response Time: $T_m = \frac{D}{v_m}$ Where: $D = \frac{Lightbox\ Width}{2} \dots\dots\dots 3$

Total Marking Time:

Total Marking Time, $M_\tau = \text{Capture Time} + \text{Detection Time} + \text{Response Time} \dots\dots\dots 4$

