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## **Module: High Frequency Trading**

### **Week 8: Optimal Liquidation**

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## Stochastic Case: Almgren-Chriss

Imagine that between time  $t = 0$  and  $T$  an agent wants to liquidate  $Q$  shares. To find an optimal execution strategy, we must first assume:

- ▶ a model for the stock price dynamics
- ▶ how the agent moves prices against himself

We can then formulate the optimization problem faced by the agent. The solution will provide us with the optimal policy for the agent.

**Stock Dynamics:** Let the stock price  $S(t)$  satisfy the Stochastic Differential Equation (SDE):

$$dS(t) = \sigma dW(t) \quad (1)$$

where  $\sigma > 0$  and  $W(t)$  is a standard Brownian motion. Note that we assume the dynamics of the price change follow an arithmetic Brownian motion, allowing prices to become negative. Although this is not a realistic feature, it makes the problem mathematically tractable.

# Adverse Price Impact

Adverse price impact occurs when liquidating (acquiring) shares. We assume the agent's trade creates a temporary adverse move in prices, so the price at which the agent will transact ( $\hat{S}(t)$ ) is given by:

$$\hat{S}(t) = S(t) + kv(t) \quad (2)$$

$k$  denotes the adverse impact that the agent's trading action incurs (negative if liquidating or positive if acquiring), and  $v(t) = -\frac{dq(t)}{dt}$  (3), where  $v(t)$  is the positive liquidation rate, and  $q(t)$  is the amount of outstanding inventory at time  $t$ .

# Objective Function

The objective function, representing the cash value of liquidating  $Q$  shares, can be expressed as:

$$R = E \left[ \int_0^T \hat{S}(t) v(t) dt \right] \quad (4)$$

where  $E$  denotes the expectation. This formula captures the expected amount of money that the agent receives over the time period  $[0, T]$  when selling shares at the obtained prices.

# Dynamic Optimal Control

The agent's objective is to choose the rate at which he liquidates  $Q$  shares to obtain the maximum revenue from the sale. The corresponding value function is given by:

$$J(0, S, q) = \max_v E \left[ \int_0^T (S(t) + kv(t))v(t) dt \right] \quad (5)$$

subject to the stochastic differential equation  $dS(t) = \sigma dW(t)$  and  $v(t) = -\frac{dq}{dt}$ , where  $q(0) = Q$  is the initial amount of shares to be liquidated, and recall that  $k < 0$ .

# HJB Equation

To solve this dynamic optimal control problem, we use the dynamic programming principle to write:

$$J(0, S, q) = \max_v E \left[ \int_0^{\Delta t} (S(t) + kv(t))v(t) dt + J(t + \Delta t, S + \Delta S, q + \Delta q) \right]$$

$$J(0, S, q) = \max_v E \left[ S(\Delta t') + kv(\Delta t')v(\Delta t')\Delta t + J(0, S, q) + J_t(0, S, q)\Delta t + J_S(0, S, q)\Delta S + J_q(0, S, q)\Delta q + \frac{1}{2}\sigma^2 J_{SS}(0, S, q)\Delta t \right]$$

$$0 = \max_v E \left[ S(\Delta t') + kv(\Delta t')v(\Delta t')\Delta t + J_t(0, S, q)\Delta t + \sigma J_S(0, S, q)\Delta W - J_q(0, S, q)v(t)\Delta t + \frac{1}{2}\sigma^2 J_{SS}(0, S, q)\Delta t \right]$$

$$0 = \max_v \left[ (S(0) + kv(0))v(0) + J_t(0, S, q) - J_q(0, S, q)v(0) + \frac{1}{2}\sigma^2 J_{SS}(0, S, q) \right]$$

So, the Hamilton-Jacobi-Bellman (HJB) equation we need to solve is:

$$0 = \max_v (S + kv)v + J_t - vJ_q + \frac{1}{2}\sigma^2 J_{SS} \quad (6)$$

## Optimal Solution

The optimal  $v$  is given by:

$$v^*(t) = \frac{J_q - S}{2k} \quad (7)$$

Plugging this into the HJB equation (8), we obtain:

$$0 = \left( S + \frac{J_q - S}{2} \right) \frac{J_q - S}{2k} + J_t - \frac{J_q - S}{2k} J_q + \frac{1}{2} \sigma^2 J_{SS}$$

$$0 = \frac{1}{4k} ((J_q)^2 - S^2) + J_t + \frac{1}{2k} S J_q - \frac{1}{2k} (J_q)^2 + \frac{1}{2} \sigma^2 J_{SS}$$

$$0 = \frac{1}{4k} ((J_q)^2 - S^2) + \frac{2S J_q - 2(J_q)^2}{4k} + 4kJ_t + 2k\sigma^2 J_{SS}$$

$$0 = (J_q)^2 - S^2 + 2S J_q - 2(J_q)^2 + 4kJ_t + 2k\sigma^2 J_{SS}$$

$$0 = -(J_q - S)^2 + 4kJ_t + 2k\sigma^2 J_{SS} \quad (8)$$

# Partial Differential Equation (PDE) and Trial Solution

In this case, we know that at time  $T$ ,  $J(T, S(T), q(T)) = q(T)S(T)$ , hinting that the trial solution of the value function is linear in  $S(t)$ , which means  $J_{SS} = 0$ . Thus, our problem reduces to solving the PDE:

$$4kJ_t = (J_q - S)^2 \quad (9)$$

To solve this PDE, we look for a separable solution. First, we let  $V(t, q) = J(t, q) - q(t)S(t)$ , so that we can write:

$$4kV_t = (V_q)^2 \quad (10)$$

We try  $V(t, q) = g(t)h(q)$ . Substituting this trial solution into (10), we obtain:

$$4k \frac{g_t(t)}{g^2(t)} = \frac{h_q^2(q)}{h(q)}$$



$$4k \frac{g_t(t)}{g^2(t)} = c \quad (11)$$

$$\frac{h_q^2(q)}{h(q)} = c \quad (12)$$

$$4k \int_t^T \frac{dg}{g^2} = c \int_t^T dt \quad \text{and} \quad 4k \left( \frac{1}{g(t)} - \frac{1}{g(T)} \right) = c(T - t)$$

$$\int_t^T \frac{dh(q)}{\sqrt{h(q)}} = \int_t^T \sqrt{c} dq \quad \text{and} \quad 2 \left( \sqrt{h(q(T))} - \sqrt{h(q(t))} \right) = -\sqrt{c}q(t)$$

$$h(q(t)) = \frac{1}{4}cq^2(t)$$

$$V(q, t) = g(t)h(q) \quad \text{and} \quad V_q(q, t) = g(t)h_q(q)$$

$$\frac{J_q(q, t) - S(t)}{2k} = \frac{g(t)h_q(q)}{2k}$$

$$\frac{q(t)}{T - t} = \frac{g(t)h_q(q)}{2k}$$

$$\frac{q(t)}{T - t} = \frac{g(t)}{2k} \frac{cq(t)}{2} \quad \text{and} \quad g(t) = \frac{4k}{c(T - t)} \quad (13)$$

Hence,  $\frac{1}{g(T)} = 0$  and we write (for all  $t$ )  $g(t) = \frac{4k}{c(T - t)}$

$$V(t, q) = \frac{4k}{c(T-t)} \cdot \frac{1}{4}cq^2(t) = \frac{kq^2(t)}{T-t} \quad (14)$$

so that

$$J(t, S, q) = \frac{4k}{c(T-t)} \cdot \frac{1}{4}cq^2(t) + q(t)S(t) = \frac{kq^2(t)}{T-t} + q(t)S(t) \quad (15)$$

$$v^*(t) = \frac{J_q - S}{2k} = \frac{\frac{2kq(t)}{T-t} + S(t) - S(t)}{2k} = \frac{q(t)}{T-t} \quad (16)$$

The answer is quite simple and intuitive. The shares must be liquidated at a constant rate. This strategy is the same as that of the time-weighted average price (TWAP).