#### 1

# Assignment 2

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# Download all python codes from

https://github.com/pulkitsaxena92/ EE20MTECH14016\_MatrixEE5609/tree/ master/Assignment2

and python codes from

https://github.com/pulkitsaxena92/ EE20MTECH14016\_MatrixEE5609/tree/ master/Assignment2/code

### 1 Question

If  $\mathbf{A} = \begin{pmatrix} 0 & -\tan\frac{\alpha}{2} \\ \tan\frac{\alpha}{2} & 0 \end{pmatrix}$  and  $\mathbf{I}$  is identity matrix of order 2, show that

$$\mathbf{I} + \mathbf{A} = (I - A) \begin{pmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{pmatrix}$$
 (1.0.1)

### 2 Solution

Since

$$\mathbf{I} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$(2.0.1) \quad \mathbf{T}$$

$$\mathbf{A} = \tan \frac{\alpha}{2} \begin{pmatrix} \cos 90 & -\sin 90 \\ \sin 90 & \cos 90 \end{pmatrix} \quad \mathbf{T}$$

$$(2.0.2)$$

$$\mathbf{I} - \mathbf{A} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} - \tan \frac{\alpha}{2} \begin{pmatrix} \cos 90 & -\sin 90 \\ \sin 90 & \cos 90 \end{pmatrix}$$

$$(2.0.3)$$

$$= \frac{1}{\cos \frac{\alpha}{2}} \begin{pmatrix} \cos \frac{\alpha}{2} & 0 \\ 0 & \cos \frac{\alpha}{2} \end{pmatrix} - \frac{\sin \frac{\alpha}{2}}{\cos \frac{\alpha}{2}} \begin{pmatrix} \cos 90 & -\sin 90 \\ \sin 90 & \cos 90 \end{pmatrix}$$

$$(2.0.4)$$

$$= \frac{1}{\cos \frac{\alpha}{2}} \begin{pmatrix} \cos \frac{\alpha}{2} & 0 \\ 0 & \cos \frac{\alpha}{2} \end{pmatrix} - \frac{1}{\cos \frac{\alpha}{2}} \begin{pmatrix} 0 & -\sin \frac{\alpha}{2} \\ \sin \frac{\alpha}{2} & 0 \end{pmatrix}$$

$$(2.0.5)$$

$$= \frac{1}{\cos \frac{\alpha}{2}} \begin{pmatrix} \cos \frac{\alpha}{2} & \sin \frac{\alpha}{2} \\ -\sin \frac{\alpha}{2} & \cos \frac{\alpha}{2} \end{pmatrix}$$

The matrix  $\mathbf{I} - \mathbf{A}$  is a rotational Matrix with rotation  $-\frac{\alpha}{2}$ 

The Matrix  $\begin{pmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{pmatrix}$  is also a rotational Matrix with an angle  $+\alpha$ .

Multiplying two rotational matrices gives the resultant rotational matrix  $+\alpha - \frac{\alpha}{2} = +\frac{\alpha}{2}$ 

$$RHS = (I - A) \begin{pmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{pmatrix} \quad (2.0.7)$$

$$= \frac{1}{\cos\frac{\alpha}{2}} \begin{pmatrix} \cos\frac{\alpha}{2} & \sin\frac{\alpha}{2} \\ -\sin\frac{\alpha}{2} & \cos\frac{\alpha}{2} \end{pmatrix} \begin{pmatrix} \cos\alpha & -\sin\alpha \\ \sin\alpha & \cos\alpha \end{pmatrix} \quad (2.0.8)$$

$$= \frac{1}{\cos\frac{\alpha}{2}} \begin{pmatrix} \cos\frac{\alpha}{2} & -\sin\frac{\alpha}{2} \\ \sin\frac{\alpha}{2} & \cos\frac{\alpha}{2} \end{pmatrix} \quad (2.0.9)$$

(2.0.10)

Solving LHS= I + A

$$\mathbf{I} + \mathbf{A} = \begin{pmatrix} 1 & \tan\frac{\alpha}{2} \\ \tan\frac{\alpha}{2} & 1 \end{pmatrix}$$
 (2.0.11)

$$= \frac{1}{\cos\frac{\alpha}{2}} \begin{pmatrix} \cos\frac{\alpha}{2} & -\sin\frac{\alpha}{2} \\ \sin\frac{\alpha}{2} & \cos\frac{\alpha}{2} \end{pmatrix}$$
 (2.0.12)

This term is a rotational Matrix with angle  $+\frac{\alpha}{2}$ . Hence both sides evaluates to be a rotational matrix with angle  $+\frac{\alpha}{2}$ .