

Assignment 15

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1 PROBLEM HOFFMAN PG 230 Q2

Let T be a linear operator on \mathbb{R}^3 which is represented in standard ordered basis by matrix

$$\begin{pmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & -1 \end{pmatrix} \quad (1.0.1)$$

Prove that T has no cyclic vector. What is the T -cyclic subspace generated by the vector $\begin{pmatrix} 1 \\ -1 \\ 3 \end{pmatrix}$?

2 THEOREMS

Theorem 1	<p>T be a linear operator on vector space \mathbb{V} of n dimensional.</p> <p>There exist a cyclic vector for T if and only if minimal polynomial and characteristic polynomial are same.</p> <p>Characteristics Polynomial:-</p> $f(x) = (\mathbf{x} - \lambda_1)^{d_1} \dots (\mathbf{x} - \lambda_k)^{d_k}$ <p>Minimal Polynomial:-</p> $p_a(x) = (\mathbf{x} - \lambda_1) \dots (\mathbf{x} - \lambda_k) \text{ for the given eigen values } \lambda_1 \dots \lambda_k$
Theorem 2	<p>$\mathbb{Z}(\mathbf{a}; T)$ is the subspace spanned by vectors $T^k \mathbf{a}$, $k \geq 0$, and \mathbf{a} is a cyclic vector for T if and only if these vector span \mathbb{V}, the \mathbf{a} is called cyclic vector of T.</p>
Theorem 3 Cyclic Base	<p>Let \mathbf{a} be any non-zero vector in \mathbb{V} and let $p_a(\text{minimal polynomial})$ be the T-annihilator of \mathbf{a}</p> <p>If the degree of p_a is k, then vectors $\mathbf{a}, T\mathbf{a}, T^2\mathbf{a}, \dots, T^{k-1}\mathbf{a}$ form of a basis for $\mathbb{Z}(\mathbf{a}; T)$.</p>

TABLE 1: Illustration of theorem.

3 SOLUTION

proof of T doesn't have cyclic vector	<p>Characteristics polynomial of the matrix is $\det(x\mathbf{I} - \mathbf{A})$</p> $\det(x\mathbf{I} - \mathbf{A}) = \begin{vmatrix} (x-2) & 0 & 0 \\ 0 & (x-2) & 0 \\ 0 & 0 & (x+1) \end{vmatrix}$ <p>Characteristic Polynomial = $(x-2)^2(x+1)$</p> <p>Minimal Polynomial = $p_a(x) = (x-2)(x+1)$ degree = 2</p> <p>Minimal Polynomial \neq Characteristic Polynomial</p> <p>Thus from Theorem 1 T doesn't have cyclic vector.</p>
Cyclic subspace	<p>For the given matrix $\begin{pmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & -1 \end{pmatrix}$</p> <p>$T(\mathbf{x}, \mathbf{y}, \mathbf{z}) = (2\mathbf{x}, 2\mathbf{y}, -\mathbf{z})$</p> $T \begin{pmatrix} 1 \\ -1 \\ 3 \end{pmatrix} = \begin{pmatrix} 2 \\ -2 \\ -3 \end{pmatrix}$ <p>Since we know $T^2\mathbf{a} = T(T\mathbf{a})$</p> $T^2 \begin{pmatrix} 1 \\ -1 \\ 3 \end{pmatrix} = T \begin{pmatrix} 2 \\ -2 \\ -3 \end{pmatrix} = \begin{pmatrix} 4 \\ -4 \\ 3 \end{pmatrix}$ <p>$\begin{pmatrix} 4 \\ -4 \\ 3 \end{pmatrix}$ is a linear combination of $\begin{pmatrix} 1 \\ -1 \\ 3 \end{pmatrix}$ and $\begin{pmatrix} 2 \\ -2 \\ -3 \end{pmatrix}$.</p> <p>Degree of minimal polynomial is 2 therefore from Theorem 3</p> <p>Thus cyclic subspace of $\mathbb{Z}(\mathbf{a}; T)$ spans $\{\mathbf{a}, T\mathbf{a}\}$</p> <p>Hence T-cycle subspace generated by $\begin{pmatrix} 1 \\ -1 \\ 3 \end{pmatrix}$</p> $= \text{span} \left(\begin{pmatrix} 1 \\ -1 \\ 3 \end{pmatrix}, \begin{pmatrix} 2 \\ -2 \\ -3 \end{pmatrix} \right)$

TABLE 2: Solution Table