Assignment 2

Pulkit Saxena

Download all python codes from

https://github.com/pulkitsaxena92/EE20MTECH14016 MatrixEE5609/tree/master/Assignment2

and python codes from

https://github.com/pulkitsaxena92/EE20MTECH14016 MatrixEE5609/tree/master/Assignment2/code

1 Question

If $\mathbf{A} = \begin{pmatrix} 0 & -\tan\frac{\alpha}{2} \\ \tan\frac{\alpha}{2} & 0 \end{pmatrix}$ and \mathbf{I} is identity matrix of order 2, show that

$$\mathbf{I} + \mathbf{A} = \begin{pmatrix} I - A \end{pmatrix} \begin{pmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{pmatrix}$$
 (1.0.1)

2 Solution

Since

$$\mathbf{I} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \tag{2.0.1}$$

$$\mathbf{A} = \tan\frac{\alpha}{2} \begin{pmatrix} \cos 90 & -\sin 90 \\ \sin 90 & \cos 90 \end{pmatrix} \tag{2.0.2}$$

$$\mathbf{I} - \mathbf{A} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} - \tan \frac{\alpha}{2} \begin{pmatrix} \cos 90 & -\sin 90 \\ \sin 90 & \cos 90 \end{pmatrix}$$
 (2.0.3)

$$\mathbf{I} - \mathbf{A} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} - \tan \frac{\alpha}{2} \begin{pmatrix} \cos 90 & -\sin 90 \\ \sin 90 & \cos 90 \end{pmatrix}$$

$$= \frac{1}{\cos \frac{\alpha}{2}} \begin{pmatrix} \cos \frac{\alpha}{2} & 0 \\ 0 & \cos \frac{\alpha}{2} \end{pmatrix} - \frac{\sin \frac{\alpha}{2}}{\cos \frac{\alpha}{2}} \begin{pmatrix} \cos 90 & -\sin 90 \\ \sin 90 & \cos 90 \end{pmatrix}$$

$$(2.0.3)$$

$$= \frac{1}{\cos\frac{\alpha}{2}} \begin{pmatrix} \cos\frac{\alpha}{2} & 0\\ 0 & \cos\frac{\alpha}{2} \end{pmatrix} - \frac{1}{\cos\frac{\alpha}{2}} \begin{pmatrix} 0 & -\sin\frac{\alpha}{2}\\ \sin\frac{\alpha}{2} & 0 \end{pmatrix}$$
 (2.0.5)

$$= \frac{1}{\cos\frac{\alpha}{2}} \begin{pmatrix} \cos\frac{\alpha}{2} & \sin\frac{\alpha}{2} \\ -\sin\frac{\alpha}{2} & \cos\frac{\alpha}{2} \end{pmatrix}$$
 (2.0.6)

The matrix (I – A is a rotational Matrix with rotation $-\frac{\alpha}{2}$

The Matrix $\begin{pmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{pmatrix}$ is also a rotational Matrix with an angle $+\alpha$.

Multiplying two rotational matrices gives the resultant rotational matrix $+\alpha - \frac{\alpha}{2} = +\frac{\alpha}{2}$

$$RHS = (I - A) \begin{pmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{pmatrix}$$
 (2.0.7)

$$RHS = (I - A) \begin{pmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{pmatrix}$$

$$= \frac{1}{\cos \frac{\alpha}{2}} \begin{pmatrix} \cos \frac{\alpha}{2} & \sin \frac{\alpha}{2} \\ -\sin \frac{\alpha}{2} & \cos \frac{\alpha}{2} \end{pmatrix} \begin{pmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{pmatrix}$$
(2.0.7)
$$(2.0.8)$$

$$= \frac{1}{\cos\frac{\alpha}{2}} \begin{pmatrix} \cos\frac{\alpha}{2} & -\sin\frac{\alpha}{2} \\ \sin\frac{\alpha}{2} & \cos\frac{\alpha}{2} \end{pmatrix}$$
 (2.0.9)

(2.0.10)

Solving LHS= I + A

$$\mathbf{I} + \mathbf{A} = \begin{pmatrix} 1 & \tan\frac{\alpha}{2} \\ \tan\frac{\alpha}{2} & 1 \end{pmatrix}$$
 (2.0.11)

$$= \frac{1}{\cos\frac{\alpha}{2}} \begin{pmatrix} \cos\frac{\alpha}{2} & -\sin\frac{\alpha}{2} \\ \sin\frac{\alpha}{2} & \cos\frac{\alpha}{2} \end{pmatrix}$$
 (2.0.12)

This term is a rotational Matrix with angle $+\frac{\alpha}{2}$. Hence both sides evaluates to be a rotational matrix with angle $+\frac{\alpha}{2}$.