



CT1 S1 Anskey AI M - There are important questions in it

Artificial Intelligence (SRM Institute of Science and Technology)



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**CONTINUOUS LEARNING (THEORY) ASSESSMENT– I
EVEN SEMESTER, 2020- 2021**

B.Tech COMPUTER SCIENCE AND ENGINEERING

18CSC305J– ARTIFICIAL INTELLIGENCE

Time: 45Mins

SEMESTER-VI

MAXIMUM MARKS: 25

COURSE LEARNING RATIONALE:

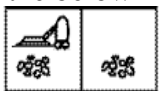
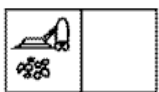
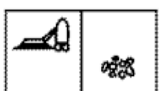
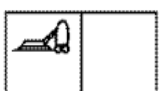
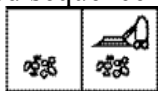
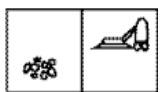
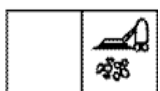
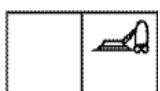
CLR-1 : Provide a broad understanding of the basic techniques for building intelligent computer systems and an understanding of how AI is applied to problems.

CLR-2 : Gain knowledge in problem formulation and building intelligent agents

COURSE LEARNING OUTCOME:

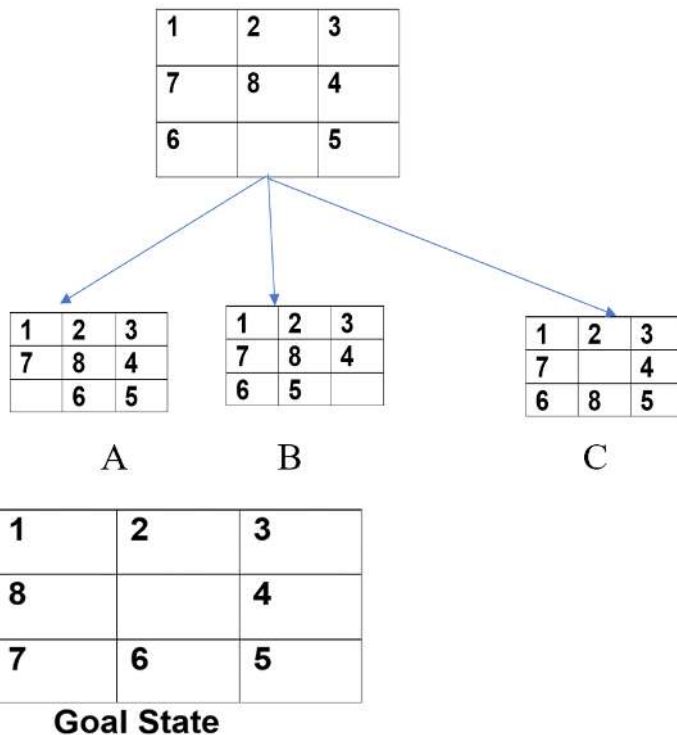
CLO-1 : Formulate a problem and build intelligent agents

CLO-2: Apply appropriate searching techniques to solve a real world problem

Answer the MCQ's PART – A (15 x 1 = 15 Marks)		CLO.	K.N O.
1.	Artificial Intelligence is about____ a) Playing a game on Computer b) Making a machine intelligent c) Programming on Machine with your Own Intelligence d) Putting your intelligence in Machine	CLO1	K1
2.	<p>If the following states in the diagram represents states of a vacuum cleaner , which of the below mentioned sequence helps it to reach the goal state {7 or 8} ?</p> <div style="display: flex; flex-wrap: wrap;"> <div style="width: 50%;"> <p>1 </p> <p>3 </p> <p>5 </p> <p>7 </p> </div> <div style="width: 50%;"> <p>2 </p> <p>4 </p> <p>6 </p> <p>8 </p> </div> </div> <p>Sequences : (1) 2,4,3,7 (2) 1,5,6,8 (3) 4,2,3,8 (4) 1,5,2,8</p> <p>A) 1,2,4 are valid B) 1,2 valid C) 2 and 4 only valid D) 2,3,4 are valid</p>	CLO2	K2

3.	<p>What is state space?</p> <ol style="list-style-type: none"> The whole problem Your Definition to a problem Problem you design Representing your problem with variable and parameter 	CLO1	K1
4.	<p>An AI agent perceives from the environment using_____.</p> <ol style="list-style-type: none"> Sensors Perceiver Actuators Both a and c 	CLO1	K1
5.	<p>The “imitation game” was originally called by its creator as</p> <ol style="list-style-type: none"> LISP Cybernetics Turing Test Logic Theorist 	CLO2	K1
6.	<p>Given below are the Production Rules for Water Jug Problem.</p> <ol style="list-style-type: none"> $(x,y) \rightarrow (4,y)$ Fill the 4-gallon jug $(x,y) \rightarrow (x,3)$ Fill the 3-gallon jug $(x,y) \rightarrow (x-d, y)$ Pour water out from the 4-gallon jug $(x,y) \rightarrow (x,y-d)$ Pour water from the 3-gallon jug $(x,y) \rightarrow (0,y)$ Empty the 4-gallon jug $(x,y) \rightarrow (x,0)$ Empty the 3-gallon jug $(x,y) \rightarrow (4,y-(4-x))$ Pour water from the 3-gallon jug into the 4-gallon jug until the 4-gallon jug is full $(x,y) \rightarrow (x-(3-y), 3)$ Pour water from the 4-gallon jug into the 3-gallon jug until the 3-gallon jug is full. $(x,y) \rightarrow (x+y, 0)$ Pour all water from the 3-gallon jug to the 4-gallon jug $(x,y) \rightarrow (0, x+y)$ Pour all water from the 4-gallon jug to the 3-gallon jug $(0,2) \rightarrow (2,0)$ Pour 2 Gallon of water from the 3-gallon jug to the 4-gallon jug $(2, y) \rightarrow (0,y)$ Pour 2 Gallon of water from the 4-gallon jug to ground. <p>Given the initial state is (0,0) and goal state is (2,0) . Identify the correct sequence to solve the problem .</p> <ol style="list-style-type: none"> (0,0),R9,R7,R2,R3,R6,R8 (0,0),R1,R2,R5,R7,R11,R12 (0,0),R1,R8,R6,R10,R1,R7,R8 (0,0),R2,R9,R2,R7,R5,R9 	CLO2	K2
7.		CLO2	K2

Consider the 8-Puzzle problem given below.



To reach the Goal state, the “h value” for the states A,B and C are:

- a) 4,5,6
- b) 6,4,5**
- c) 5,4,6
- d) 5,5,4

8.	A fully observable problem belongs to the category of A. Multi-state problem B. Two-state problem C. Single-state problem D. Three-state problem	CLO1	K1
9.	A production rule has a. A set of Rule b. A sequence of steps c. Both (a) and (b) d. Arbitrary representation to problem	CLO2	K1
10.	The action ‘STACK(A, B)’ of a robot arm specify to _____ a. Place block B on Block A b. Place blocks A, B on the table in that order c. Place blocks B, A on the table in that order d. Place block A on block B	CLO2	K2
11.	While playing Toy problem, its environment is controlled. Consider the following statements with regard to Tic-tac-toe problem,	CLO2	K2

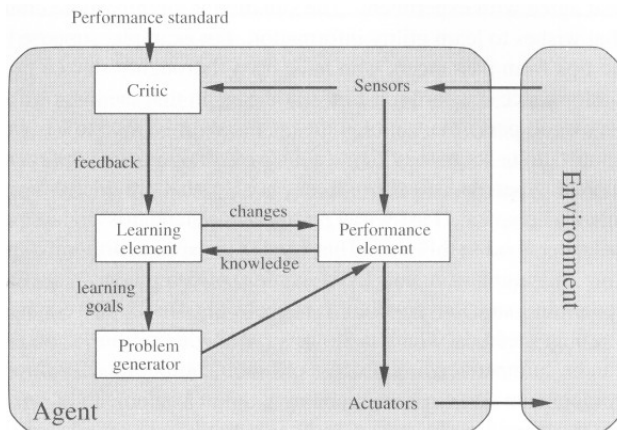
	<p>i. The player who puts respective mark in a horizontal or vertical line only wins the game</p> <p>ii. The player who puts respective mark in a horizontal or vertical or diagonal line wins the game</p> <p>iii. It is a 3*3 grid & three player game</p> <p>iv. It is a two-player game</p> <p>a. Statements (ii),(iii) are correct</p> <p>b. Statements (ii),(iv) are correct</p> <p>c. Statements (i),(iii) are correct</p> <p>d. Statements (i),(ii),(iv) are correct</p>		
12.	<p>The PEAS in the task environment is about _____</p> <p>a) Peer, Environment, Actuators, Sense</p> <p>b) Performance, Environment, Actuators, Sensors</p> <p>c) Perceiving, Environment, Actuators, Sensors</p> <p>d) Performance, Environment, Actual, Sensing</p>	CLO1	K1
13.	<p>Which agent deals with the happy and unhappy state?</p> <p>a. Utility-based agent</p> <p>b. Model-based agent</p> <p>c. Goal-based Agent</p> <p>d. Learning Agent</p>	CLO1	K1
14.	<p>Which of the Following problems can be modeled as CSP?</p> <p>a. Monkey Banana Problem</p> <p>b. Camel Banana Problem</p> <p>c. Map coloring Problem</p> <p>d. Missionaries and Cannibal Problem</p>	CLO2	K2
15.	<p>To overcome the need to backtrack in constraint satisfaction problem can be eliminated by _____</p> <p>a. Forward Searching</p> <p>b. Constraint Propagation</p> <p>c. Backtrack after a forward search</p> <p>d. Omitting the constraints and focusing only on goals</p>	CLO2	K2
<p style="text-align: center;">PART – B</p> <p>Answer all questions (5 x 2 = 10 Marks)</p>			
16.	<p>What are the components of a problem ? List the problem characteristics .</p> <p><u>Components of problem</u></p> <ul style="list-style-type: none"> The initial state that the agent starts in /Starting state which agent knows itself. A description of the possible actions/operators available to the agent. 	CLO1	K1

	<ul style="list-style-type: none"> • successor refer to any state reachable from a given state by a single action. • state space of the problem—the set of all states reachable from the initial state by any sequence of actions. • A path in the state space is a sequence of states connected by a sequence of actions. • goal test, which determines whether a given state is a goal state. • A path cost function that assigns a numeric cost to each path. • The step cost of taking action <i>a</i> to go from one state 's' to reach state 'y' is denoted by $c(s, a, y)$. <p><u>problem characteristics</u></p> <ol style="list-style-type: none"> 1. Is the problem decomposable ? 2. Can Solution steps be ignored or undone ? 3. Is the Universe Predictable? 4. Is a good solution absolute or relative ? 5. Is the solution a state or a path? 6. What is the role of knowledge? 7. Does the task require interaction with a person ? 		
17.	<p>Write the agent program for model – based reflex agent.</p> <pre> function REFLEX-AGENT-WITH-STATE(<i>percept</i>) returns <i>action</i> static: <i>state</i>, a description of the current world state <i>rules</i>, a set of condition-action rules <i>state</i> ← UPDATE-STATE(<i>state</i>, <i>percept</i>) <i>rule</i> ← RULE-MATCH(<i>state</i>, <i>rules</i>) <i>action</i> ← RULE-ACTION[<i>rule</i>] <i>state</i> ← UPDATE-STATE(<i>state</i>, <i>action</i>) return <i>action</i> </pre>	CLO1	K2
18.	<p>Solve the crypt arithmetic puzzle. EAT + HOT =OATS</p>	CLO2	K2

EAT	T-3
HOT	A-2
<u>OATS</u>	O-1
	E-5
523	H-7
713	5-6
<u>1236</u>	
OATS	

19. Give the structure of a learning agent.

CLO2 K1



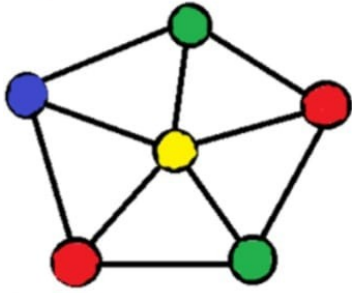
20. Solve the given map coloring problem using backtracking.
Colors that can be used to color the graph are {Red, Green, Blue}

CLO2 K2



Variables : G,R,UP,MP,M,C

$D_1 = \{\text{Red, Green, Blue}\}$



Given graph cannot be colored with given 3 colors – Red , Green , Blue

K1- Remember, K2 - Understand, K3 – Apply, K4 - Analyse, K5 – Evaluate, K6 – Create