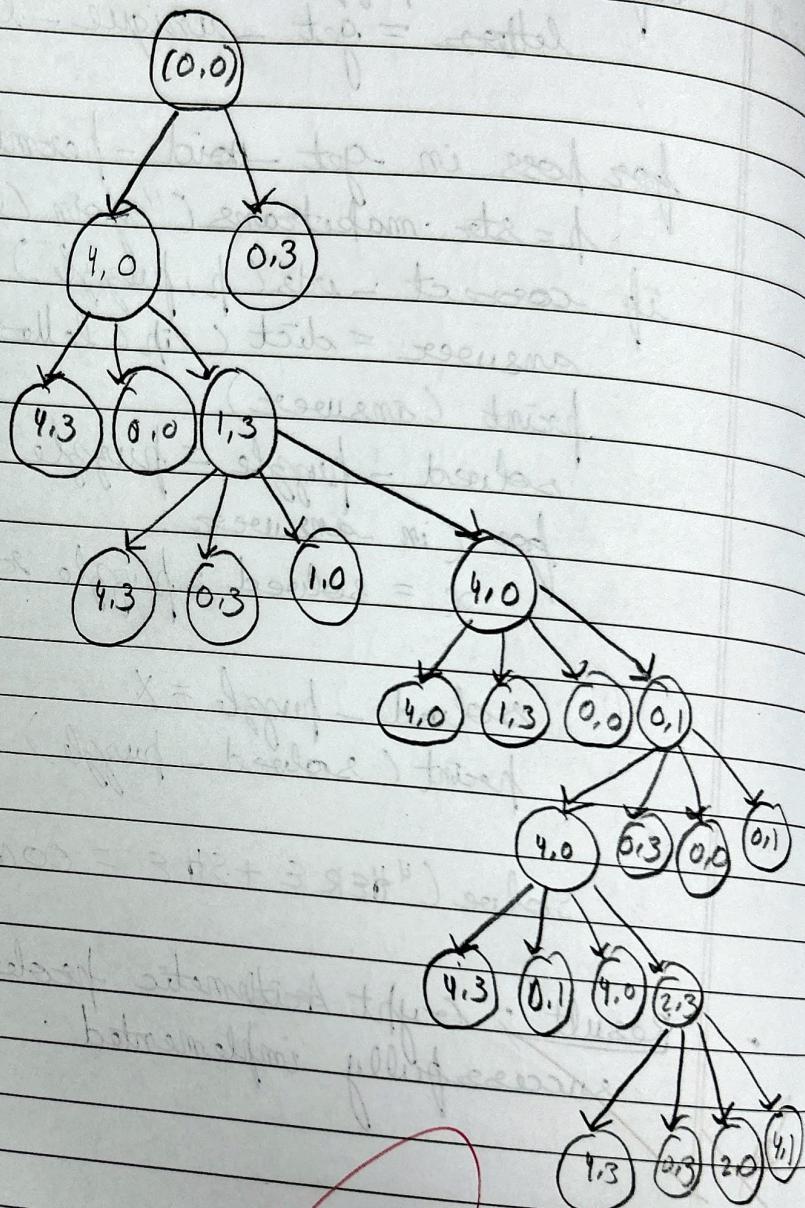


A decorative banner featuring five large, bold letters: 'I', 'N', 'D', 'E', and 'X'. Each letter is enclosed in a white square frame with a black border, and the letters are arranged horizontally.

NAME: Utkit Shringi STD.: _____ SEC.: II ROLL NO.: 596 SUB.: Artificial Intelligence

State space tree

$$X = 4, Y = 3, Z = 2$$

 (x, y) 

Eng - 4

Breadth - First search

Aim :

To implement BFS and elaborate the search space tree for water jug problem

Water jug :

$$\text{jug } 1(x) = 5 \text{ liters}$$

$$\text{jug } 2(y) = 3 \text{ liters}$$

$$\text{Target} = 4 \text{ liters} \therefore \text{state } (4, 0)$$

Operations :

1) Fill (y)

current state (0, 3)

2) Pour (y \rightarrow x)

current state (3, 0)

3) Fill (y)

current state : (3, 3)

4) Pour ($x \rightarrow y$)

current state : (5, 1)

5) Empty (y)

current state (0, 1)

6) Pour (y \rightarrow x)

current state : (1, 0)

7) Fill (y)

current state : (1, 3)

8) Pour (y \rightarrow x)

current state : (4, 0)

target reached.

Output:

Path from initial state to solution state ::

(0, 0)

(0, 3)

(4, 0)

(4, 3)

(3, 0)

(1, 3)

(3, 3)

(4, 2)

(0, 2)

observed
your
initial.

code:

from collections import deque

def BFS(a, b, target):
 m = {}

is_solvable = False

Put x = []

q = deque([])

q.append((0, 0))

while (len(q) > 0):

u = q.popleft()

if ((u[0], u[1]) in m):

continue

if ((u[0] > a or u[1] > b or

u[0] < 0 or u[1] < 0)): continue

path.append((u[0], u[1]))

m[(u[0], u[1])] = 1

~~if (u[0] == target or u[1] == target):~~

is_solvable = True

if (u[0] == target):

if (u[1] == target):

if (u[1] != 0):

path.append((u[0], 0))

else

if (u[0] != 0):

path.append((0, u[1]))

```
s2 = len (path)
for i in range (s2):
    print ("\"", path[i][0])
    break
q.append (ca, 0)
q.append (co, 0)
```

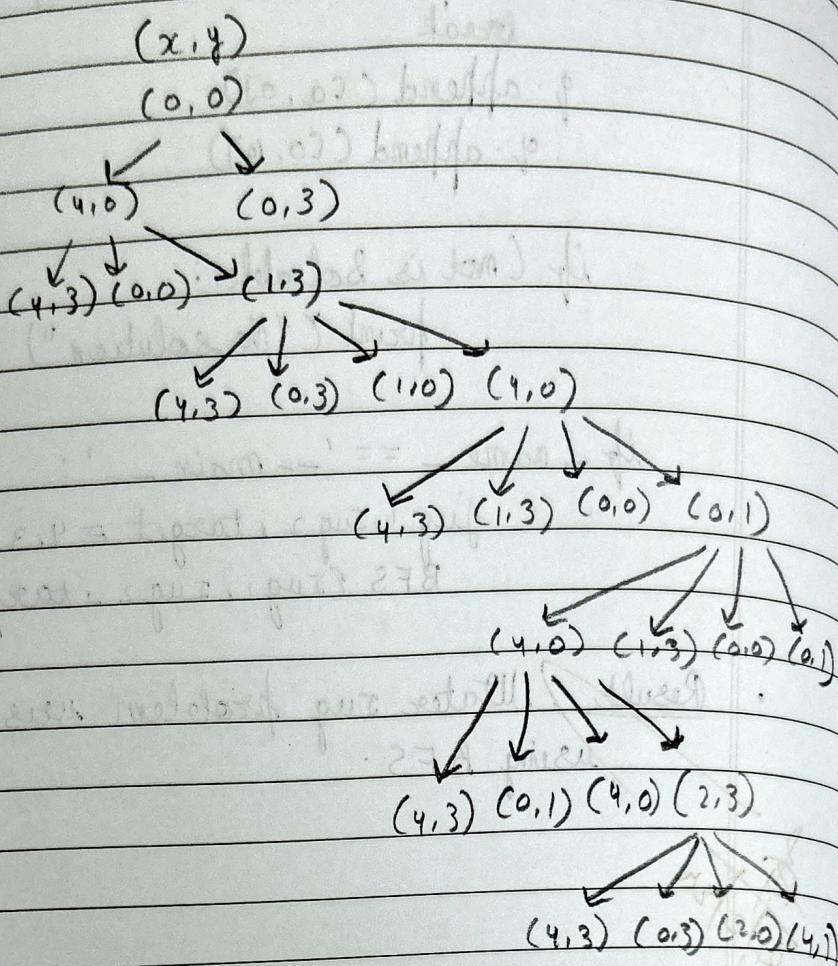
```
if (not is Solvable):
    print ("No solution")
```

```
if __name__ == '__main__':
    jug1, jug2, target = 4, 3, 2
    BFS (jug1, jug2, target)
```

- Result: Water jug problem was executed using BFS.

~~Water Jug Problem~~

State Space tree : $x=4, y=3, z=2$



Erc - 48

Depth first searchAim :

To implement the DFS and elaborate the search space tree for water jug problem

Code :

```
def point_path(mp, u):
    if u[0] == 0 and u[1] == 0:
        print("0,0")
        return
    print("mp, m.p(u[1])")
    print(u[0], u[1])
```

```
def DFS(a, b, target):
```

```
m = {}
```

```
is_solvable = False
```

```
mp = {}
```

```
stack = [{}0, 0{}]
```

```
while stack:
```

```
u = stack.pop()
```

```
if m.get(u, 0) == 1:
```

```
continue;
```

```
if u[0] == target and u[1] == target:
```

```
is_solvable = True
```

```
print_path(mp, u)
```

```
if u[0] != 0:
```

```
print(u[0], 0)
```

```
else
```

Output :-

$$\text{Jug}_1 = 4, \text{Jug}_2 = 3, \text{Target} = 2$$

Path from initial state to solution state using DFS:

(0, 0)

(0, 3)

(4, 3)

(4, 0)

(1, 3)

(1, 0)

(0, 1)

(4, 1)

(2, 3)

(2, 0)

Optimized
Goal

$|u[0]| = 0$;

print($o, u[i:j]$)

return

$m[u] = 1$

if $(u[0], o)$ not in m :

stack.append($((u[0], o))$)

$mp[(u[0], o)] = u$

if $(o, u[i:j])$ not in m :

stack.append($((o, u[i:j]))$)

$mp[(o, u[i:j])] = 4$

if $(a, u[i:j])$ not in m :

stack.append($((a, u[i:j]))$)

$mp[(a, u[i:j])] = 4$

$x = m \text{ in } (u[0], b = u[1])$

if $(u[0]-x, u[1]+x)$ not in m

stack.append($((u[0]-x, u[1]+x))$)

$mp[((u[0]-x, u[1]+x))] = 4$

If not is-solvable:

print("No solution")

Jug₁, Jug₂, target = 4, 3, 2;

DFS(Jug₁, Jug₂, target);

~~Result: DFS was successfully implemented.~~

~~21-11-2023~~