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B.Tech DEGREE EXAMINATION, DECEMBER 2023

Fourth, Fifth and Sixth Semester

18EIO133T - INDUSTRIAL AUTOMATION SYSTEMS

(For the candidates admitted during the academic year 2020 - 2021 & 2021 - 2022)

Note:

i. **Part - A** should be answered in OMR sheet within first 40 minutes and OMR sheet should be handed over to hall invigilator at the end of 40th minute.

11. F	'art - B and Part - C should be answered in	answer booklet.			
Tin	ne: 3 Hours		Max.	Marks	s: 100
	PART - A $(20 \times 1 = 20 \text{ Marks})$ Answer all Questions			Marks BL	
1.	The first company to make PLC was (A) Seimens (C) Mitsubishi	(B) Ford (D) Modicon	1	2	1
2.	PLC are designed to operate in the(A) Home (C) Industrial	environment (B) Lab (D) Office	1	1	1
3.	separates the higher AC input (A) Transistor (C) Optical Isolator	t voltage from logic circuits in PLC (B) Switch (D) Diode	1	2	1
4.	The high-speed counter module is capable (A) 1000 (C) 100000	e of counting pulses per second. (B) 1000000 (D) 10000	1	2	1
5.	Which of the following statement is true for (A) Accumulates time whenever it receives power	for a retentive timer? (B) Retains time when it loses power	1	1	2
	(C) Reset accumulator to zero when it loses power	(D) Accumulates time whenever it receives power and Retains time when it loses power			
6.	An example of a discrete control is (A) Varying the volume of a music system	(B) Varying the brightness of a lamp	1	2	2
	(C) Turning ON or OFF a lamp	(D) Controlling the speed of a fan			
7.	The Boolean expression A B Y A B	for Y is	1	1	2
	(A) $Y = (A+B')(A'+B)$ (C) $Y = AA'+BB'$	(B) $Y = AB' + A'B$ (D) $Y = (A+A')(B+B')$			
8.	Which of the following counts time-based from a true to false condition. (A) ON delay timer (C) Retentive timer	(B) OFF delay timer (D) Pulse timer	1	2	2

9.	Choose the number of logic function bloc DCS		1	1	3
	(A) 40 (C) 640	(B) 160 (D) 1280			
10.	Control complexity ratio of a control system (A) Number of function blocks/Number of inputs (C) Number of function blocks/Number of outputs	n is defined as (B) Number of outputs/number of inputs (D) Number of outputs/Number of function blocks	1	2	3
11.	The function of high level computing device (A) To do closed loop control (C) To interface with process	te of a DCS is (B) To interact with LCU (D) To perform plant management	1	2	3
12.	When was the first DCS introduced in the r (A) 1975 (C) 1985	market (B) 1960 (D) 2000	1	2	3
13.	An operator interface should be designed the particular task effectively with minima the system (A) Ecology (C) Ergonomics	in such a way that the operator performs l error; this is in short referred to as of (B) Economics (D) Efficiency	1	2	4
14.	In order to ensure safe backup of critical preferred (A) In order to ensure safe backup of critical information, one of the following step is preferred (C) Store relatively less amounts of data	information, one of the following step is (B) Run from a redundant power supply (D) operator	1	2	4
15.	Maximum number of group displays that c (A) 50-100 (C) 400-500	can be configured in a universal station is (B) Less than 200 (D) More than 500	1	2	4
16.	Identify the hardware element in a process (A) Controller (C) comparator	that is needed for alerting the operator. (B) Annunciator (D) Error detector	. 1	2	4
17.	What does SCADA stand for? (A) Supervisory Control and Data Analysis (C) Supervisory Control and Data Acquisition	(B) System Control and Data	1	2	5
18	In a SCADA system, what is the role of th(A) To regulate data flow(C) To provide a graphical interface for operators to interact with the system	e Human-Machine Interface (HMI)? (B) To analyze data patterns (D) To send commands to remote devices	1	2	5
19	. Which component of a SCADA system is (A) Historian (C) HMI (Human-Machine Interface)	responsible for data storage and retrieval? (B) RTU (Remote Terminal Unit) (D) PLC (Programmable Logic Controller)	1	2	5

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		(B) Remote monitoring and control of distributed processes				
	engily designed for	(B) Remote monitoring and control of				
CCADA system	as are primarily design	(B) Remote montores				
0. SCADA mol	nitoring and control	distributed processes (D) Local monitoring and control within				
(A) Global mul	tiple continents	(D) Local monitoring and so				
across mu	conitoring and control	a single room	Marks	BL C	0	
(C) Regional I	nonitoring and control		4			
within a ci	ity	- 20 Marks)				
		Organions	4	2	1	
	Angwer any 3	Ques	4			
		rovimity sensor	4	2	1	1
	operation of an inductive p	IOAIIII		1	2	
21. Illustrate the	operation.		4	1	_	
- PI	allu Comp		4	2	2	
22. Compare 12	notes on Timer in PLC		-			
22 Write short	notes on Timer in PLC of the following equations a A'B+C'D' ii) Y= A+BC+D	as a ladder logic program			3	
25. 11.	of the following equations	EE,	4	2	3	
24. Show each	A'B+C'D' ii) $Y=A+BC+D$	D1		2	4	
1) 1 22	- contra 17.00	l allu De-	4	2		
T ist the dif	A'B+C'D' ii) Y=A+DC 'D' ference between centralized fferent types of displays in C	Overator Display	4	2	5	
25. List the	times of displays in	Sperator Dist			60	
26 List the dif	ferent types of	ents of SCADA	M	arks BL	CO	
20	fferent types of displayers that notes on System components	5110				
27. Write shor	-= C (5 ×	12 = 60 Marks)				
	PARI-C(S	II Questions	13	2 2	1	
	Answer a	etween capacitive and inductive				
	was mas h	etween capacitive and industry				
: \ C	ummarize the differences of					
28. (a) 1)3	oximity sensors List the functions of discrete	e IO module				
iil	ist the functions of discret	(OR)				
	CT	of C with a near ing. 1 in a DT C			2	
	Emplain the architecture of I	on a processing line A, B, C. After the process of the start 30 seconds after B. All then remain a start 30 seconds after B. All then remain a start 30 seconds after B. All then remain a start 30 seconds after B. All then remain a start 30 seconds after B. All then remain a start 30 seconds after B. All then remain a start 30 seconds after B. All then remain a start 30 seconds after B. All then remain a start 30 seconds after B.	225	12 3	<u>ت</u>	
(b) 1)J	Discuss the working of any	on a processing line A, B, C. After the processing line A, B, C. After the processing on a processing line A, B, C. After the processing in a processing line A, B, C. After the processing on a processing line A, B, C. After the processing on a processing line A, B, C. After the processing on a processing line A, B, C. After the processing on a processing line A, B, C. After the processing line A, B, C. After the processing on a processing line A, B, C. After the proc	20			
11	Discuss devices	on a processing mext mixer- B is to start	NC			
20 (a) T	here are 3 mixing deviations aft	er 10 seconds elapso, after B. All then remain	and			
29. (a) b	egins mixer-A is to star	to start 30 seconds to PLC ladder diagram,				
S	econd after A. Wilker switch	on a processing line R, ext mixer-B is to start er 10 seconds elapse, next mixer-B is to start to start 30 seconds after B. All then remain (h is turned off. Write PLC ladder diagram, and the start and the seconds after B. All then remain (h is turned off. Write PLC ladder diagram, and the seconds after B. All then remain (h is turned off.)				
Ü	intil a mass		Thon			
ı	ealize the same.	(OR) In for a one way traffic light control system. We have a significant will be ON for 30s after which yellow that is ON for 25s and this process continues. The control the system.	ight			
	11 diagram	for a one way traffic fight	here			
(1-)	Develop the ladder diagram	light will be ON 101 303 are continues. I	Here			
(0)	start button is pressed, ite	n for a one way traine figure which yellow it light will be ON for 30s after which yellow it light will be ON for 30s after which yellow it light will be on the system.		12	2	3
	is ON for 5s then green lig is a start and stop button to	control the system.		1.4	-	
	is a start and stop button	ocontrol the systems nponents of a DCS with neat sketch. (OR) (OR)				
	1 daylore (1)	110012-				
30. (a)	Illustrate the na-	of LCU and explain its hardware of operators in distributed control system?		12	2	4
	- functions	of LCU and explain its new of operators in distributed control system? (OR) (OR)		12	_	
(h	Show the basic functions	6 control systems in distributed control systems				
(0	- 1 in the responsibility	of operators as food				
31. (8	a) Explain the resp	(OK) Shigh level operator interface		12	2	5
	A -ahitectura	(OR) 1 Alternatives of high level operator interface 2 on Communications and computers in SCAD	A	14	_	
14	b) Explain the Architecture	Communications and computers in Service				
,	Tain the Dependence	on Collination				
32.	(a) Explain the Bop	Alternatives of high level operations on Communications and computers in SCAD (OR)				
	(b) Explain the operation o	f Remote terminal unit				
	(b) Explain the operation of	* * * * *				
	X=2= -					